

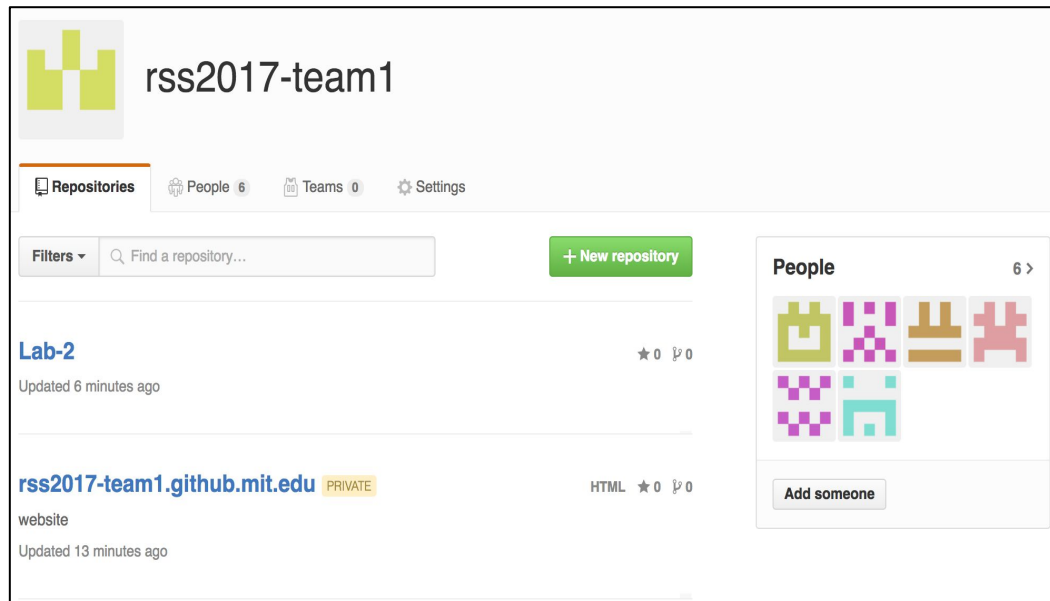
# Team 1 Lab 2 Oral Briefing

Clementine Mitchell, Martina Stadler, Nick Villanueva, Samir Wadhwania, Jake Liguori, Jose Gomez

# Setting up GitHub

Three steps:

- Set up git environment in terminal
  - Access tokens
- Create team organization
  - rss2017-team1
- Create repositories for labs and website
  - Lab-2
  - rss2017-team1.github.mit.edu



# Creating the Team Website

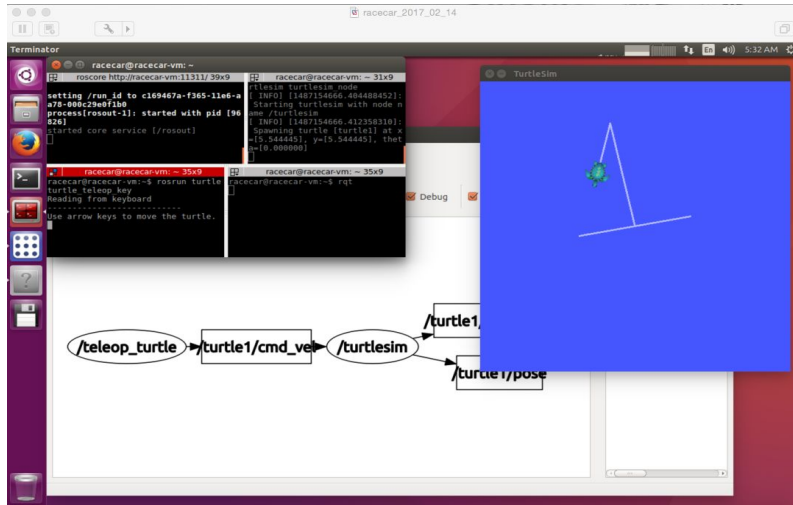
Three pages: Home/About/Labs

- Home: Links to department, class, and team Github repository.
- About: Team introduction and individual member bios.
- Labs: Page per Lab containing embedded report and oral briefing

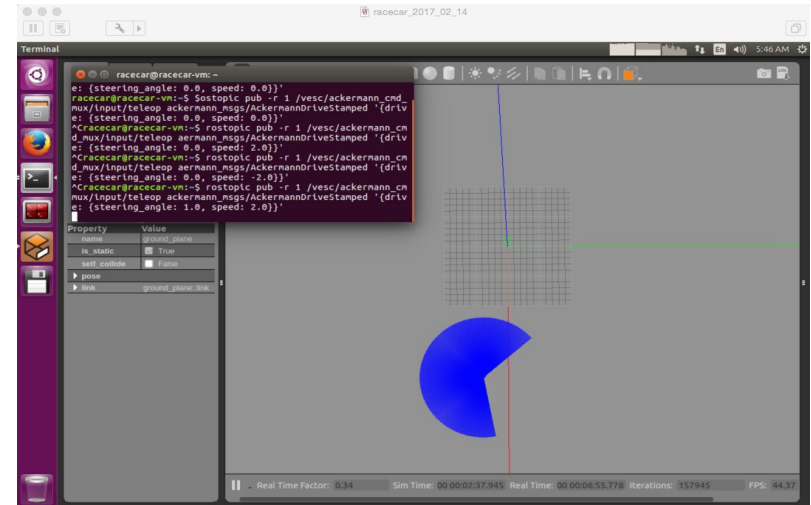


# Running the Simulation

Familiarity Using TurtleSim, Node Graph



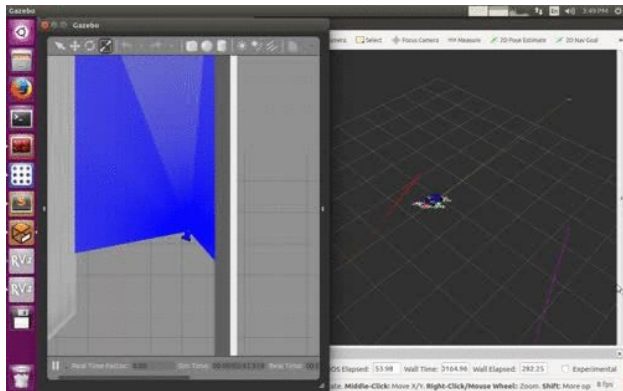
Experience Using Race Car Simulation



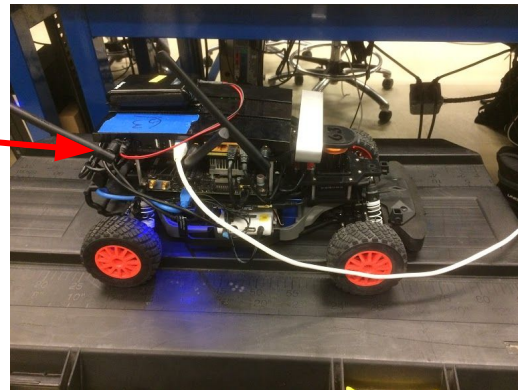
# Running the Simulation with the Joypad

We remapped the topic `/ackermann_cmd_mux/input/teleop` to the topic `/vesc/ackermann_cmd_mux/input/teleop` in order to be able to control the racecar with the joypad.

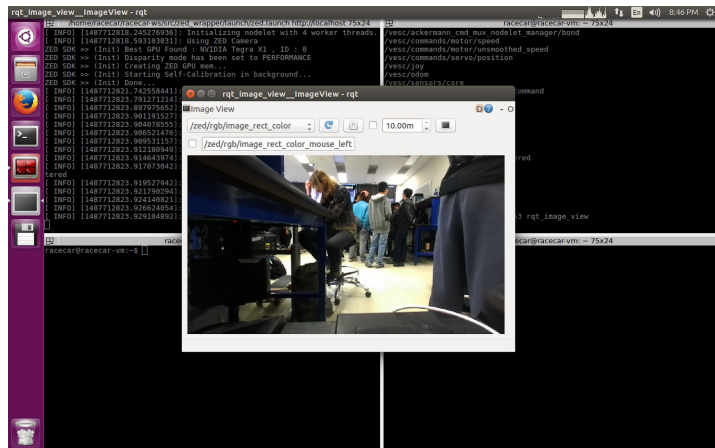
We did this first in the simulator and then confirmed functionality on the hardware.



Joypad receiver  
was inserted into  
the back of our  
racecar.

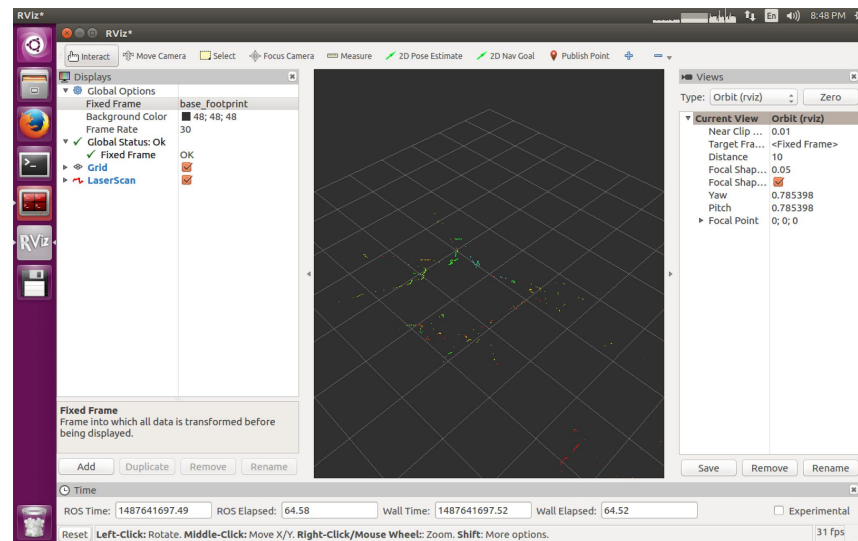


# Streaming and Collecting Data



← Zed image streaming

Laserscanner data →



# Lessons Learned

- Technical:
  - Jiggle cables
  - Create test cases to define and analyze expectations
    - Controller issue
- CI:
  - Meeting is a schedule challenge
  - Clearly articulate goals, priorities, and expectations
  - Define individual tasks
    - Allows for parallelization
  - Ensure everyone is aware what is happening
  - Use platform for communication
    - Slack

Questions?