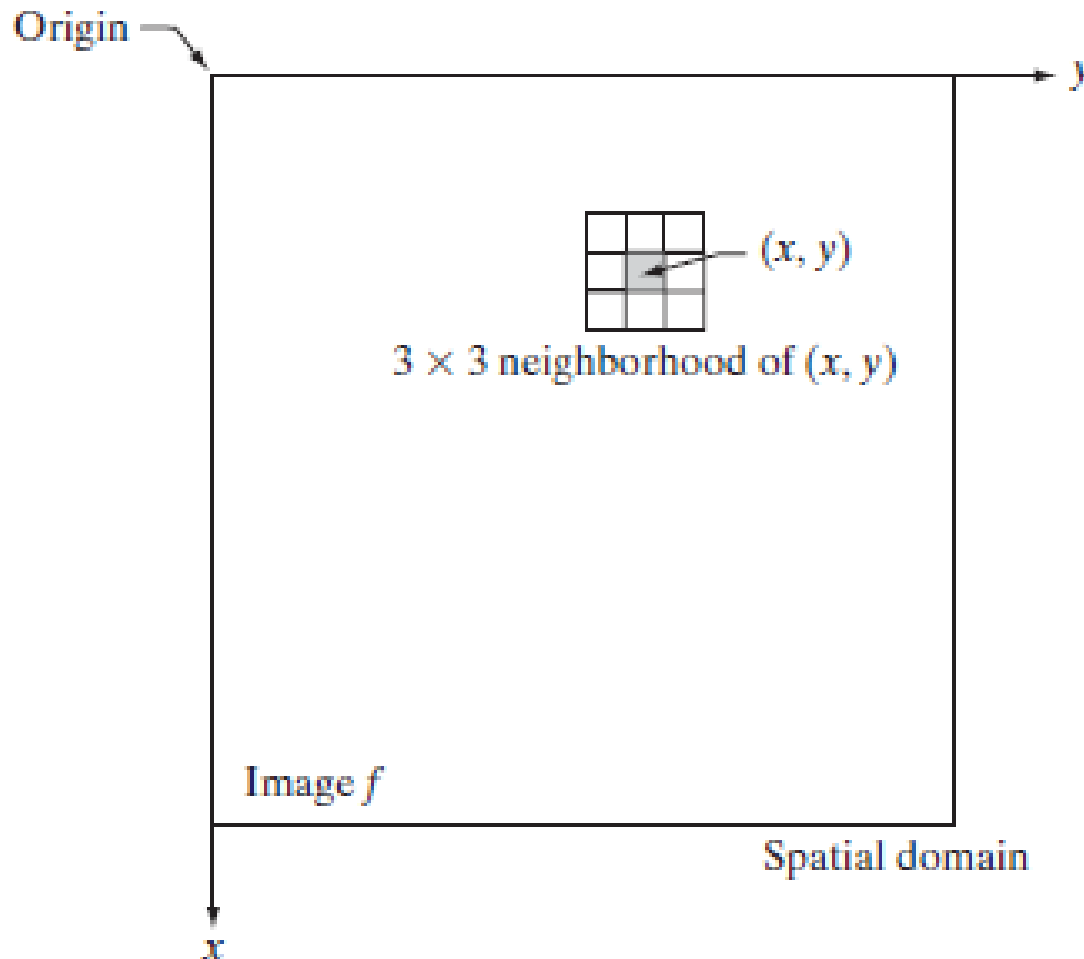


EE610 – Image Processing

Amit Sethi
asethi, 7483

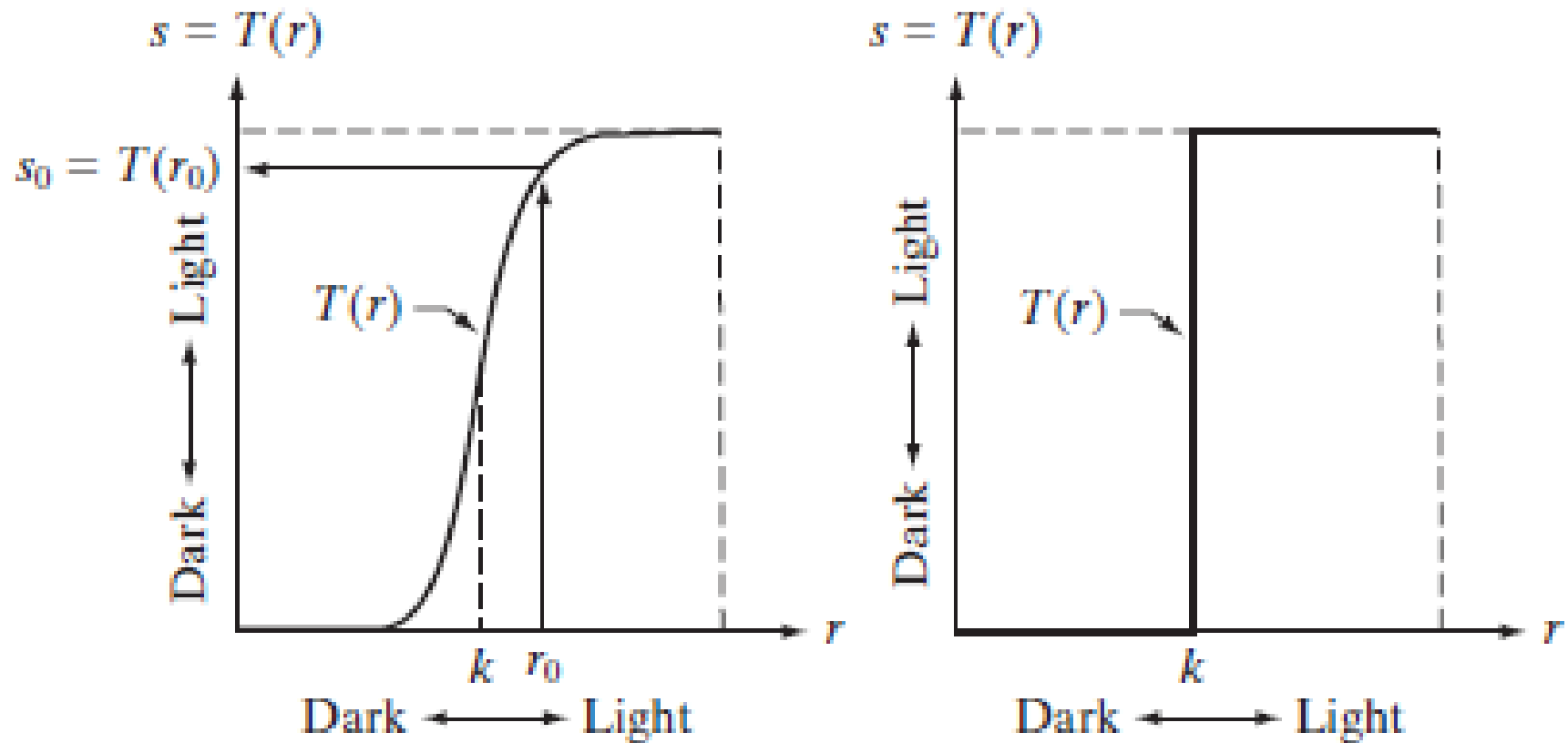
Spatial domain is defined as the domain of pixels in the image grid



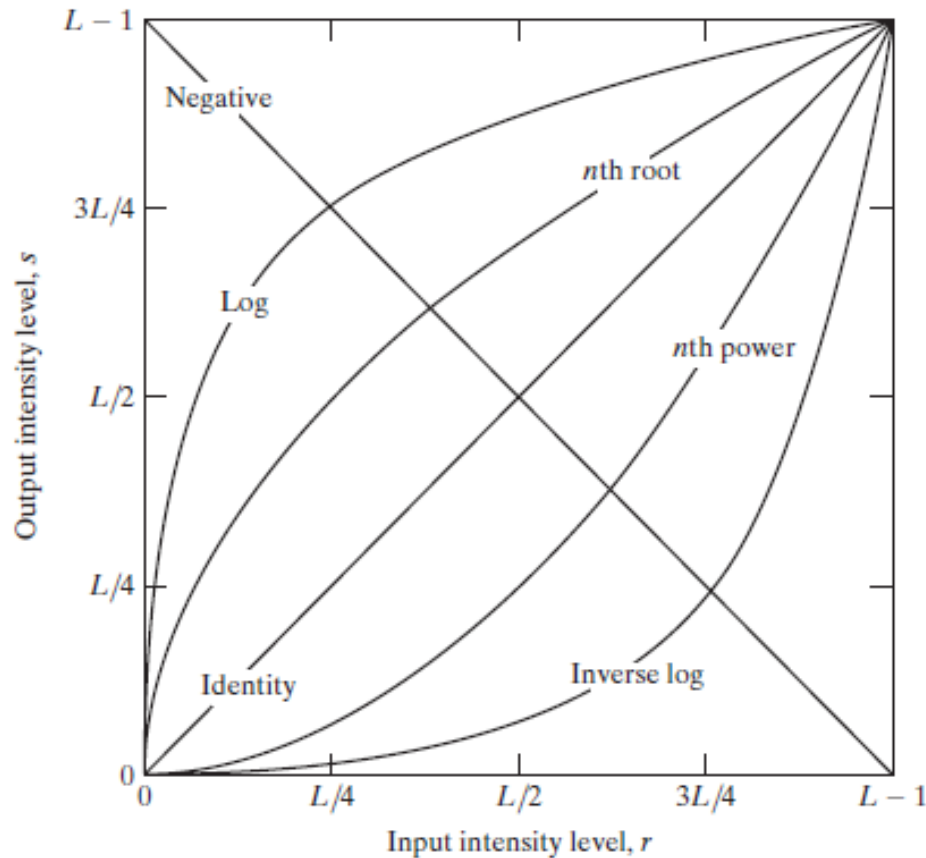
A special case

- Process each pixel with a $W \times W$ window around it
- $W = 2M + 1$
- When $M = 0$,
 - $g(x, y) = T [f(x, y)]$ a.k.a. Intensity Transform
- Else,
 - $g(x, y) = T [N_f(x, y)]$

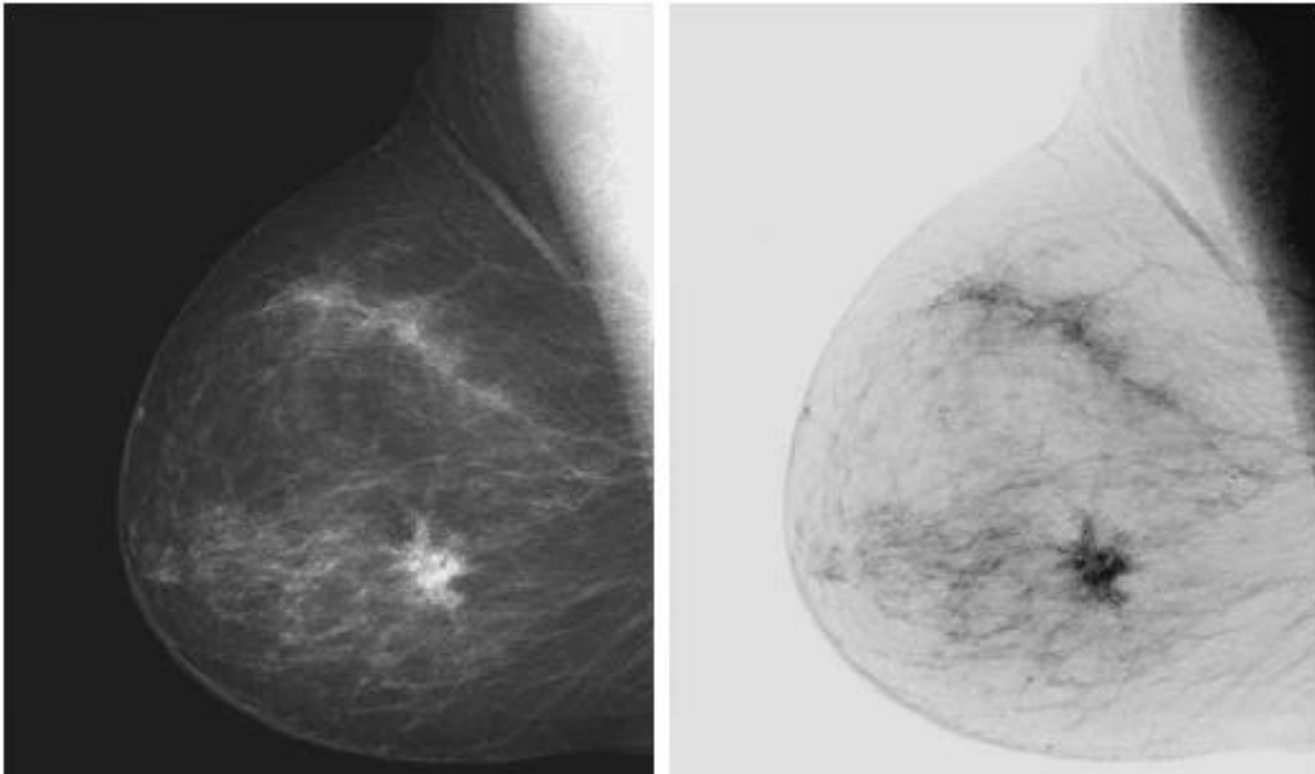
Contrast stretching and thresholding



Some basic intensity transformations

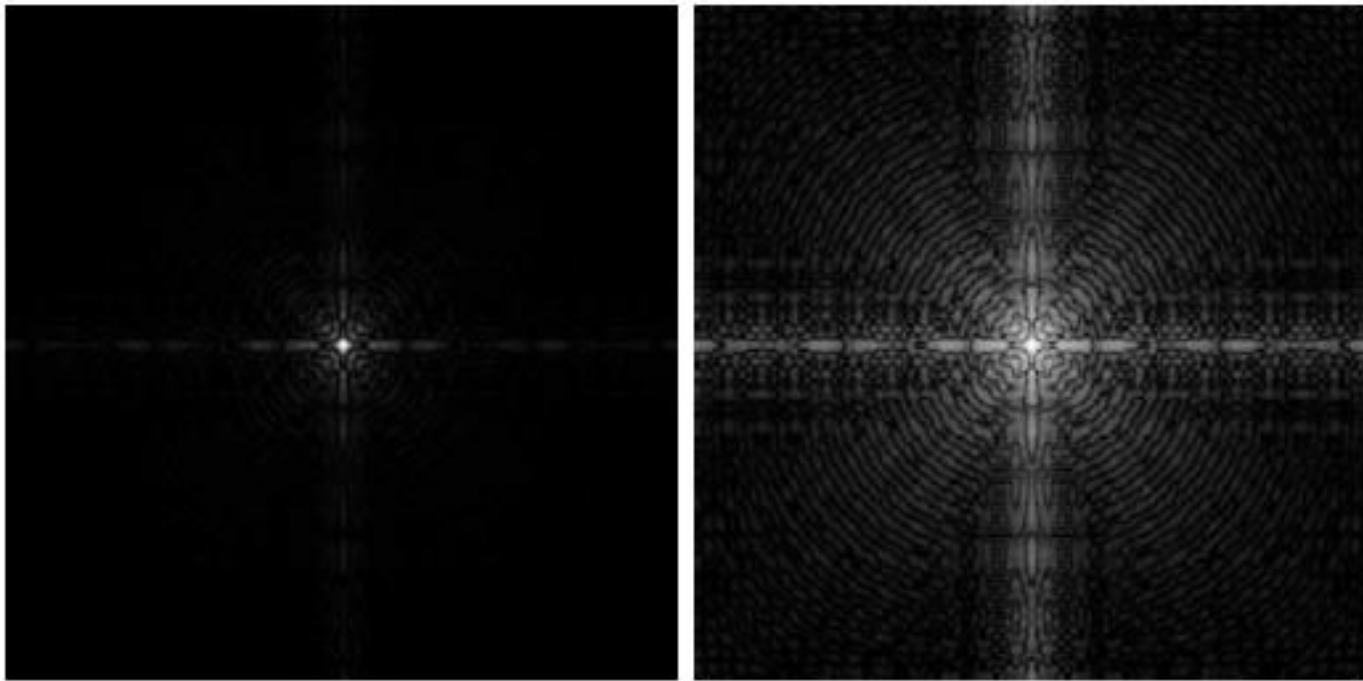


Negative of an image



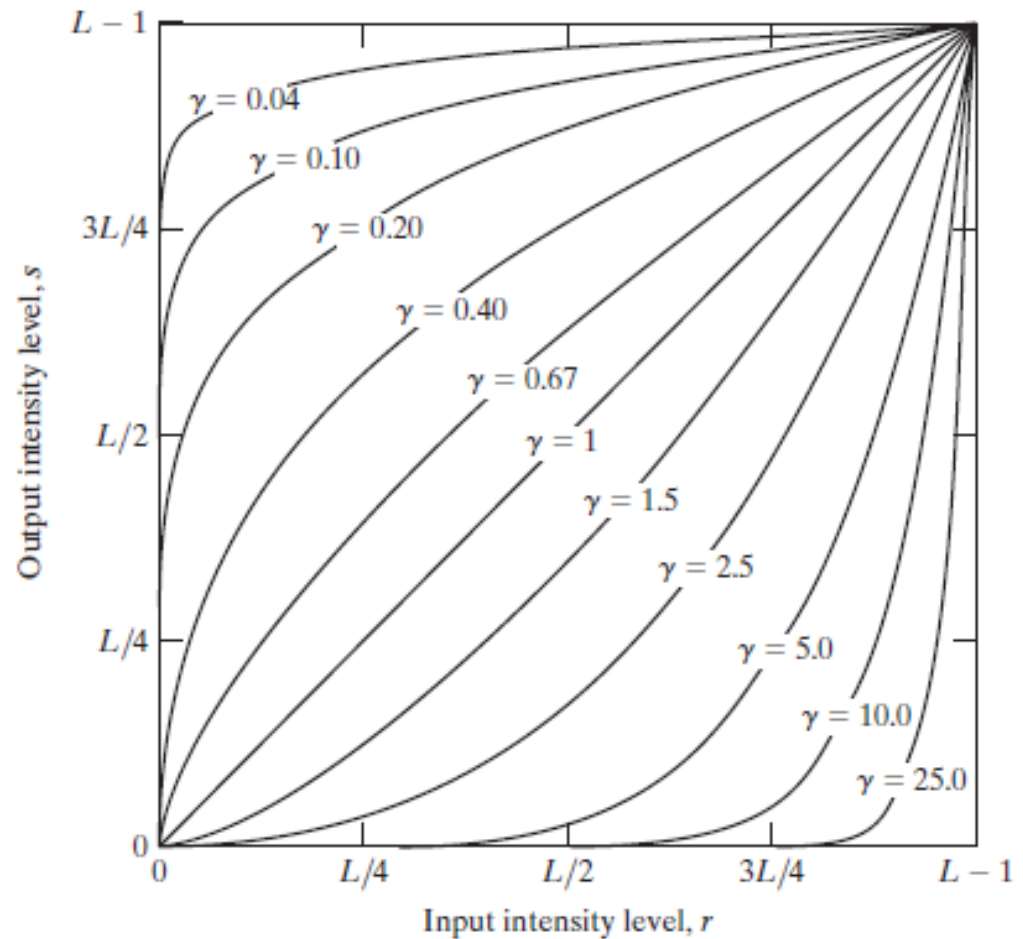
Log transformation in log domain

- $s = c \log (1+r)$

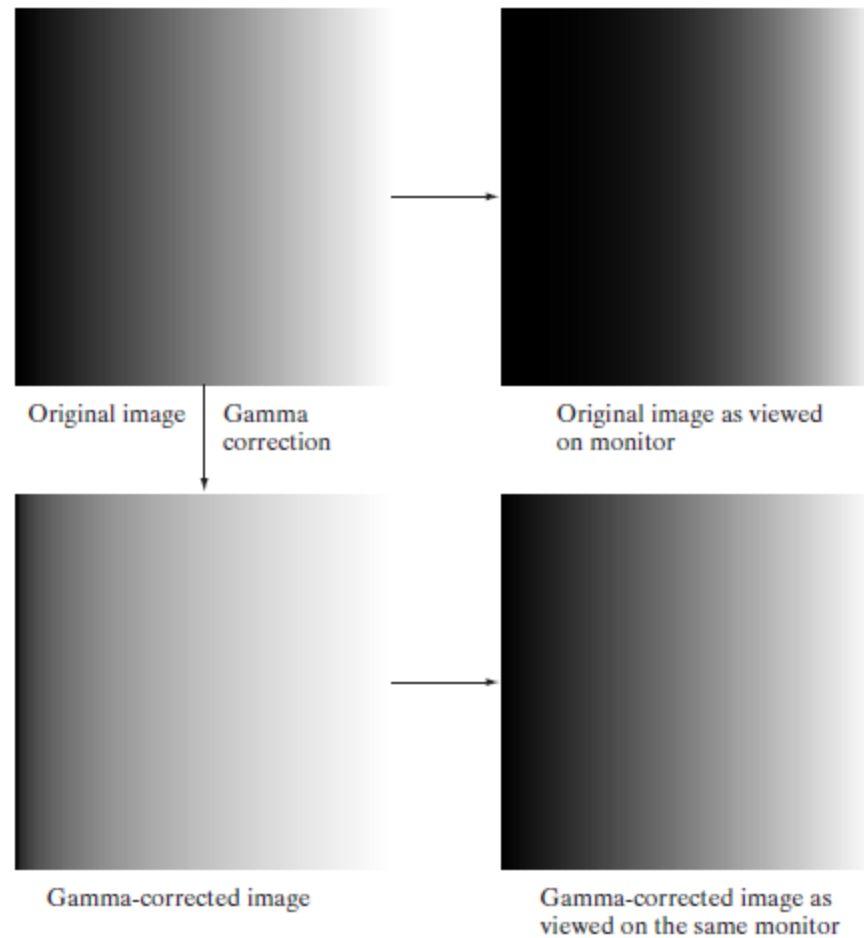


Power-law (gamma transformation)

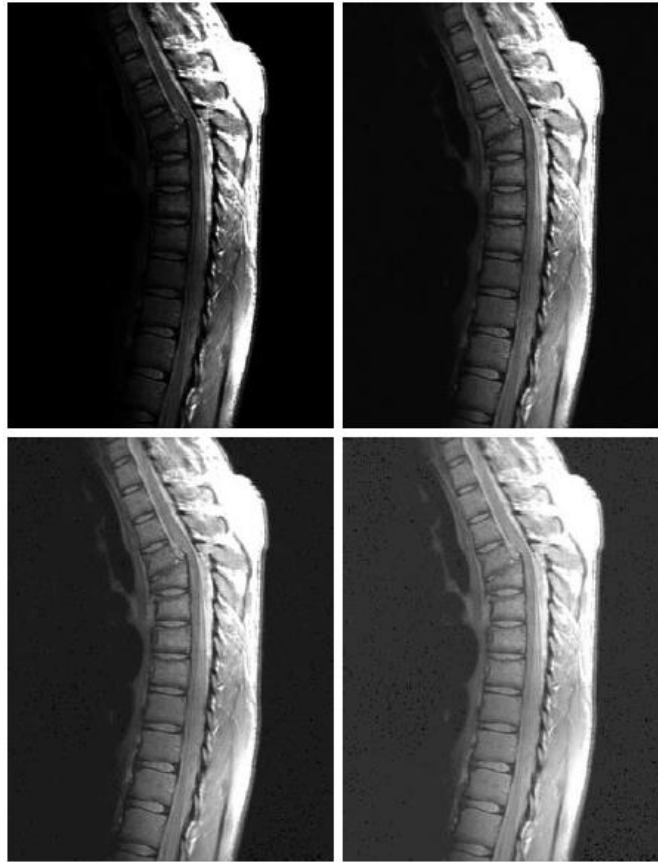
- $s = c r^\gamma$



CRT's needed gamma correction



Gamma 1, .6, .4, .3

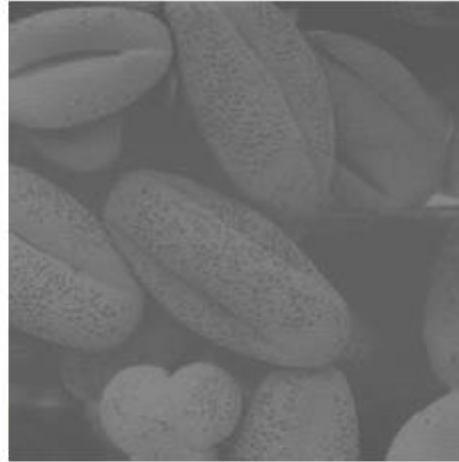
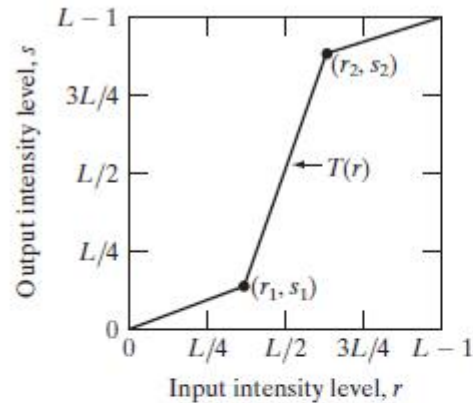


Gamma 1, 3, 4, 5

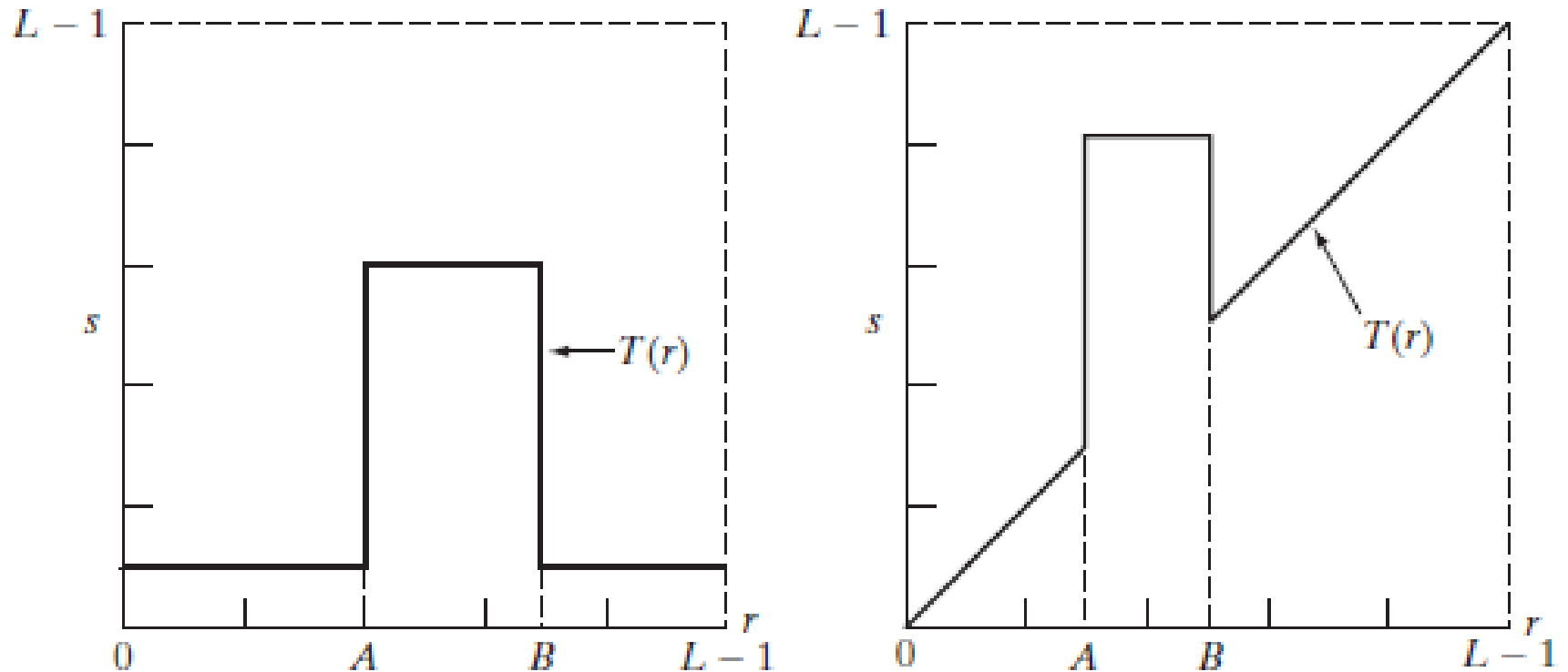


Source: Digital Image Processing, Gonzalez and Woods, Prentice Hall

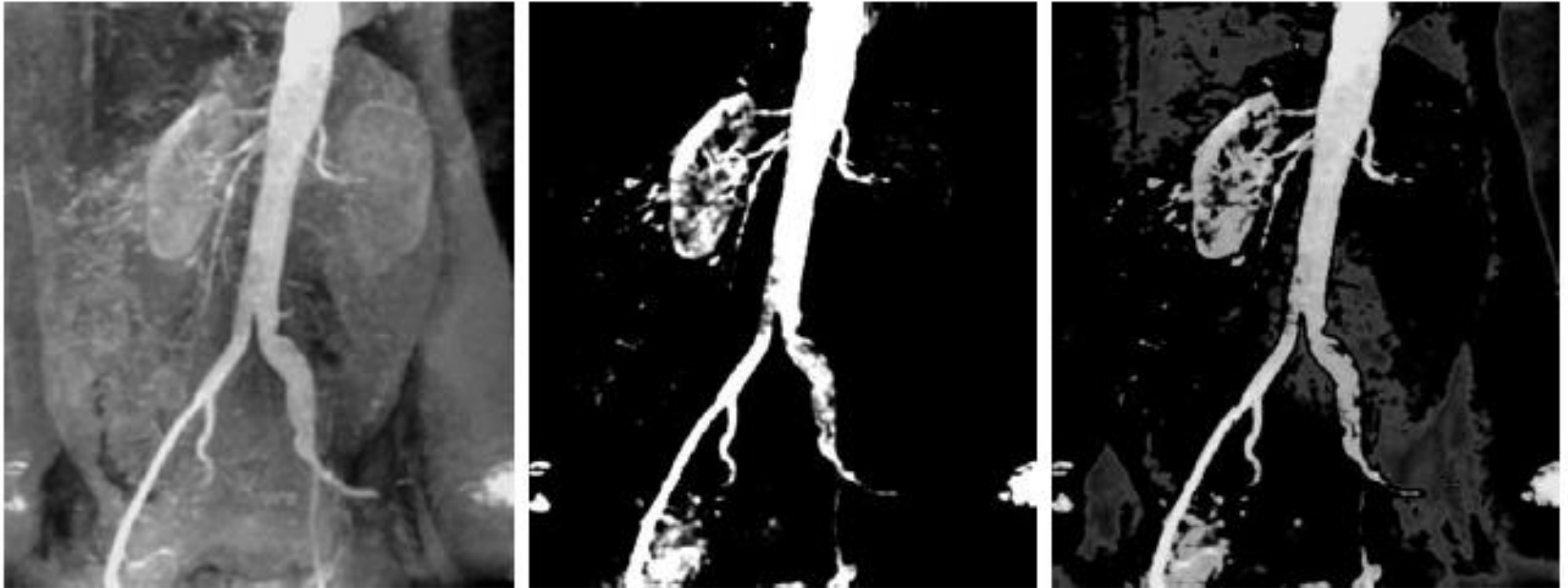
Contrast stretching vs. thresholding



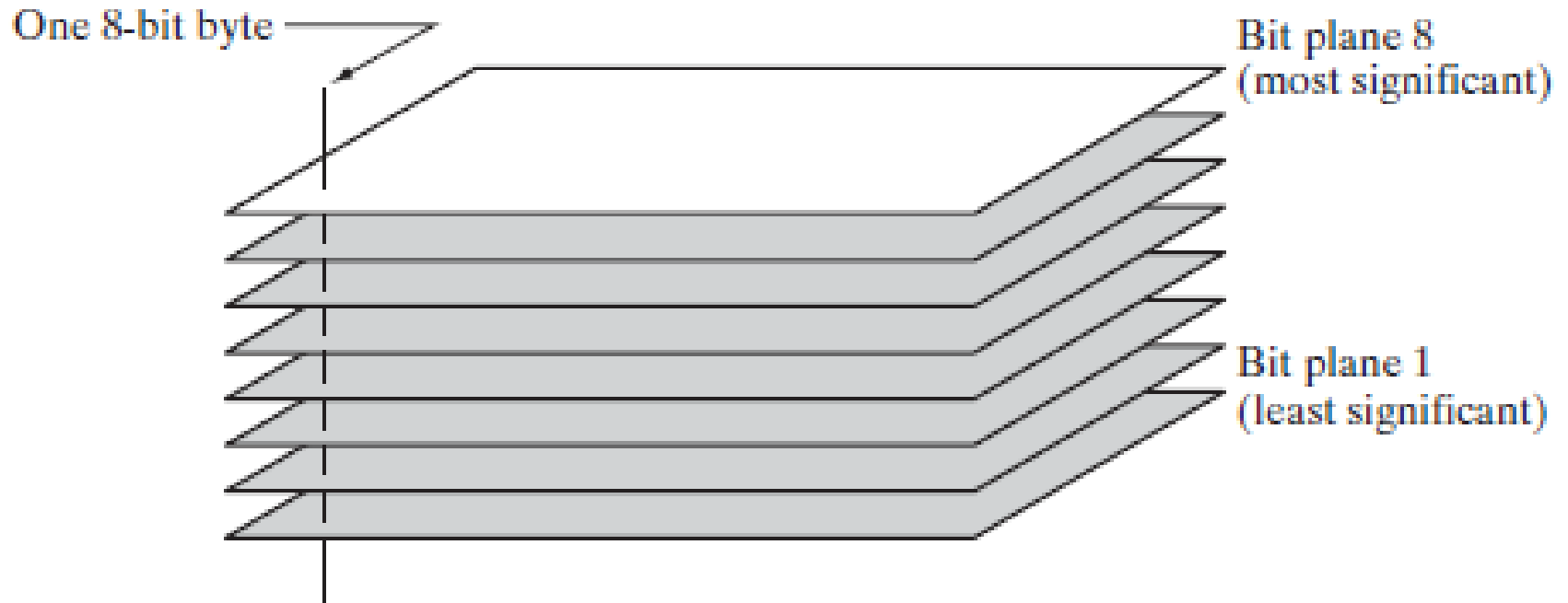
Highlighting a range of intensities



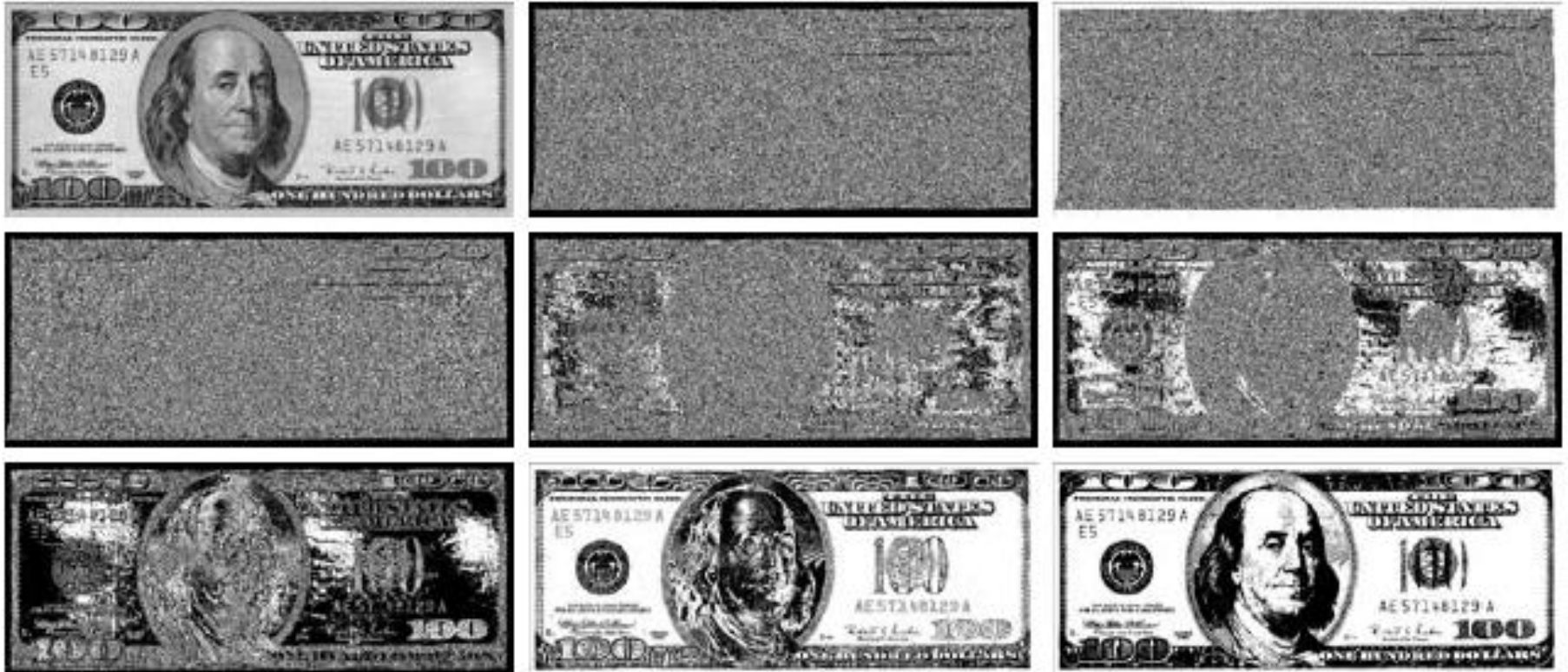
Some results of intensity highlighting



Bit-plane splicing



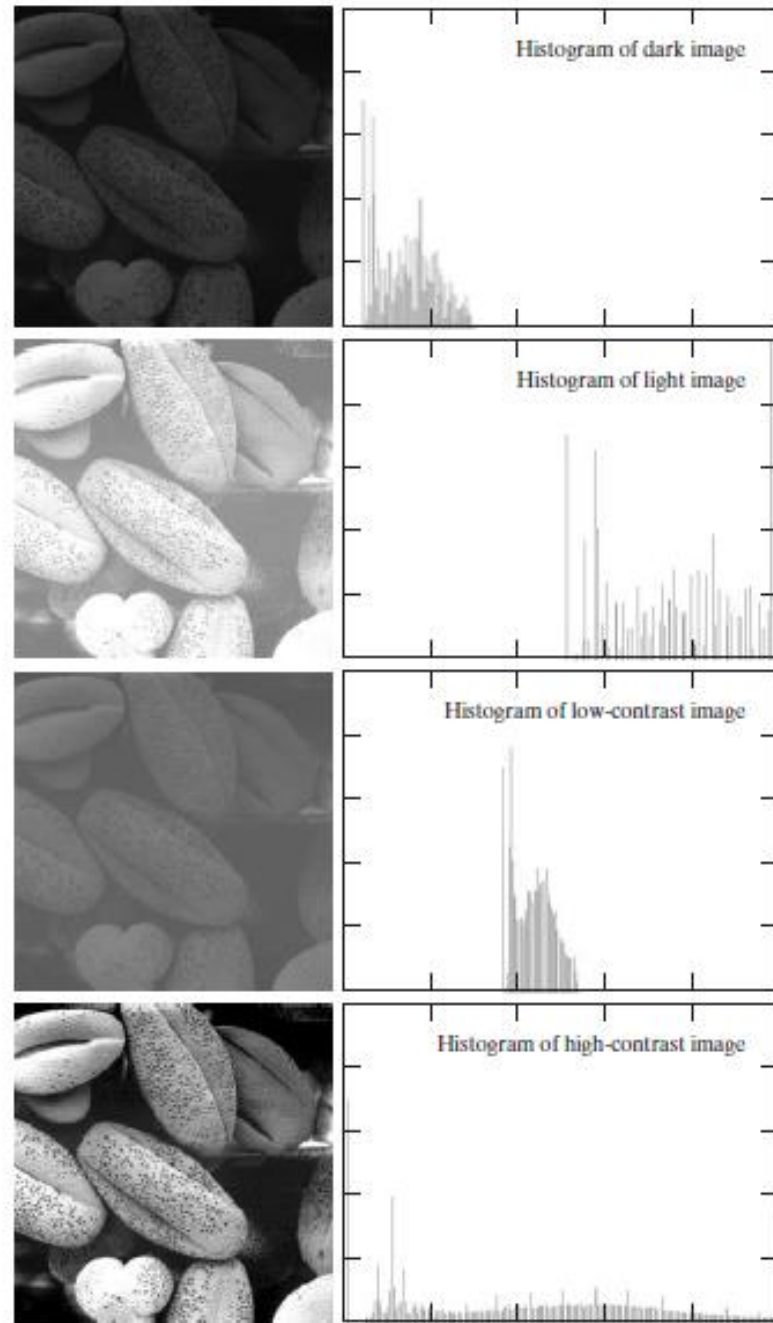
Different bit planes of an image



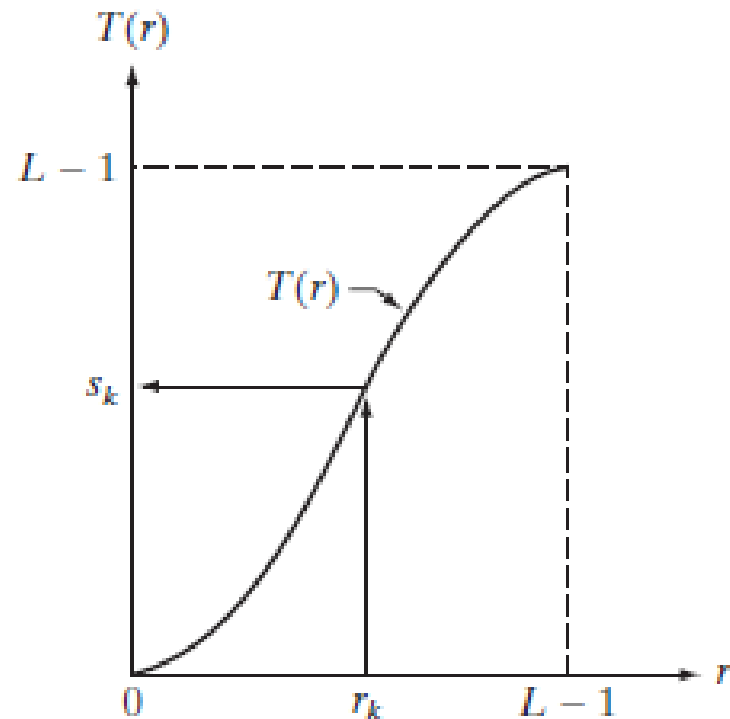
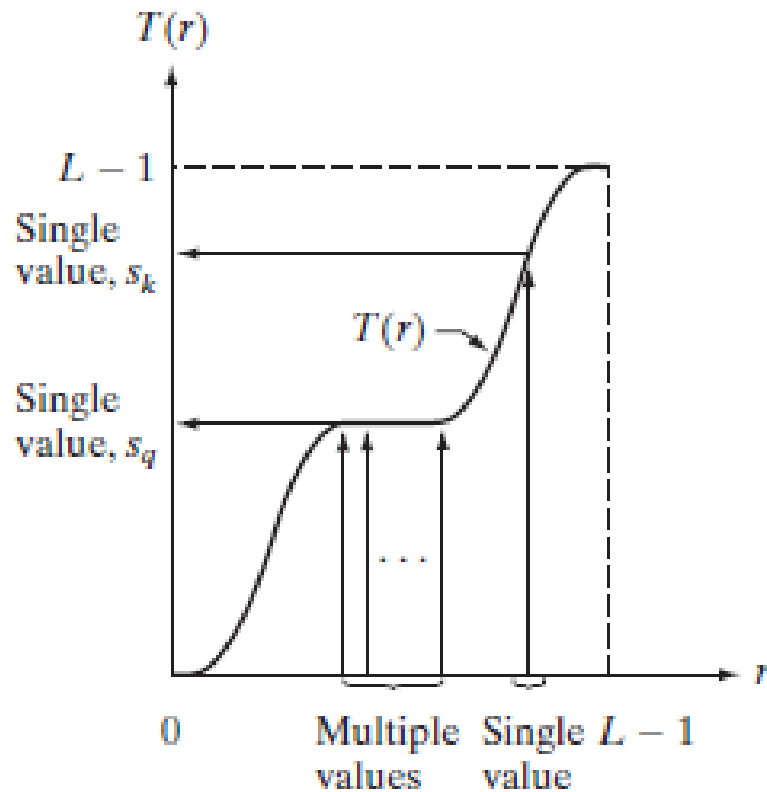
Higher bit planes contain the most information



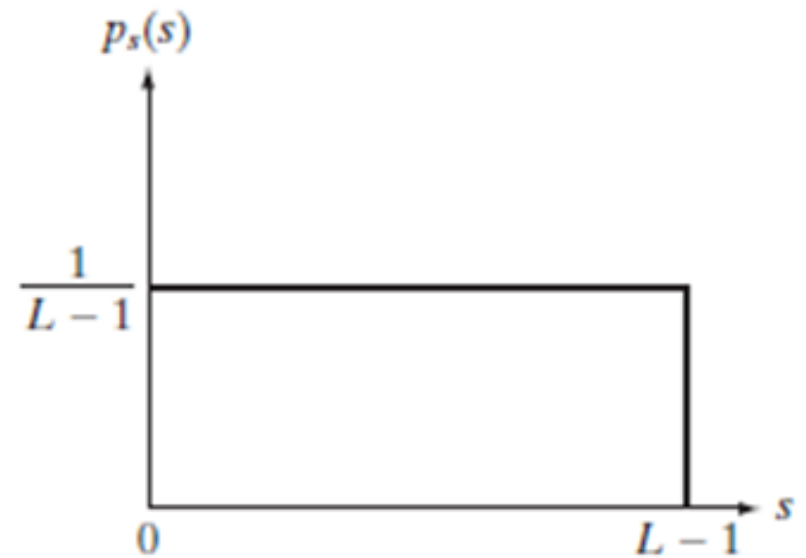
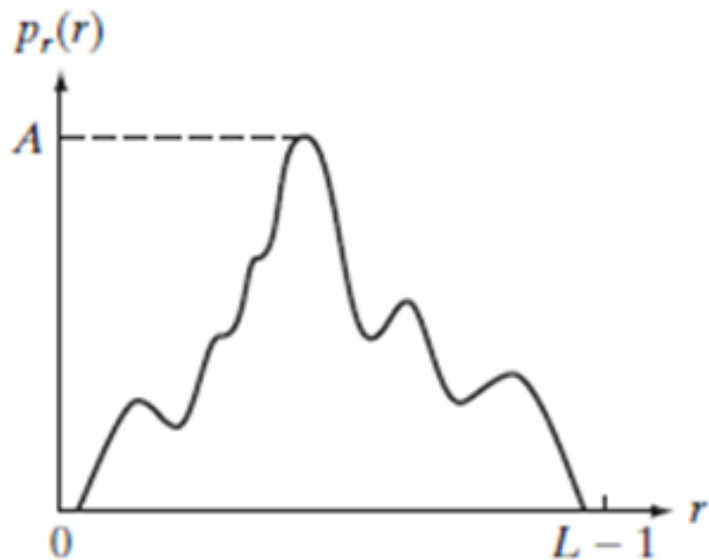
Image versions and their histograms



(Strictly) monotonically increasing functions for intensity transformations



Goal of histogram equalization



Relation between # pixels and probability of an intensity

r_k	n_k	$p_r(r_k) = n_k/MN$
$r_0 = 0$	790	0.19
$r_1 = 1$	1023	0.25
$r_2 = 2$	850	0.21
$r_3 = 3$	656	0.16
$r_4 = 4$	329	0.08
$r_5 = 5$	245	0.06
$r_6 = 6$	122	0.03
$r_7 = 7$	81	0.02

Relation between a random variable and its transform

$$s = T(r)$$

$$\frac{ds}{dr} = \frac{dT(r)}{dr}$$

$$p_s(s) = p_r(r) \left| \frac{dr}{ds} \right|$$

Transform for equalization

$$s = T(r) = (L - 1) \int_0^r p_r(w) dw$$

$$\frac{ds}{dr} = \frac{dT(r)}{dr}$$

$$= (L - 1) \frac{d}{dr} \left[\int_0^r p_r(w) dw \right]$$

$$= (L - 1) p_r(r)$$

$$p_s(s) = p_r(r) \left| \frac{dr}{ds} \right|$$

$$= p_r(r) \left| \frac{1}{(L - 1) p_r(r)} \right|$$

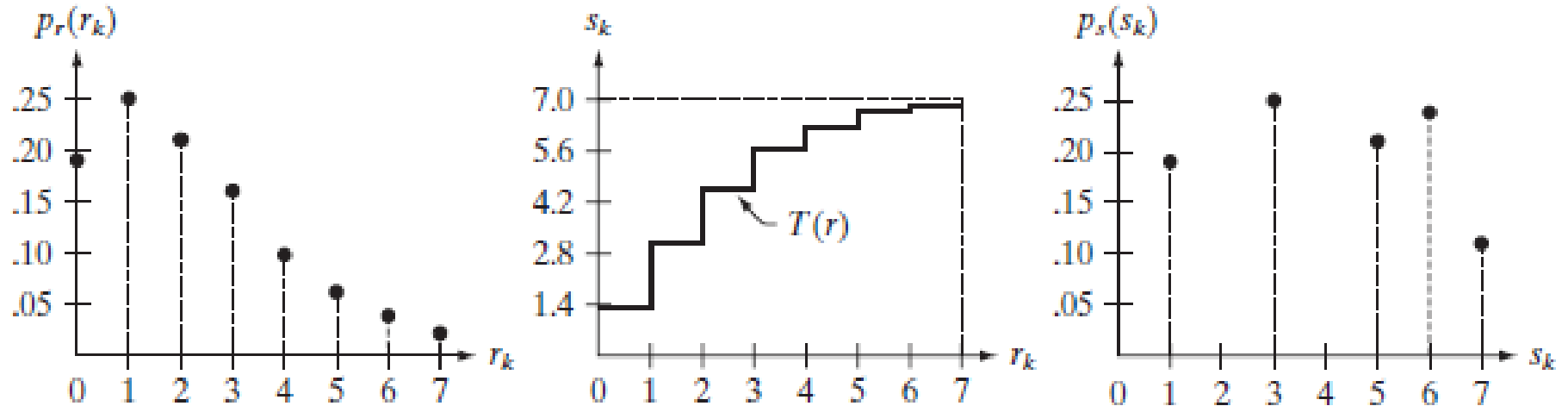
$$= \frac{1}{L - 1} \quad 0 \leq s \leq L - 1$$

Discrete version of equalizing transformation

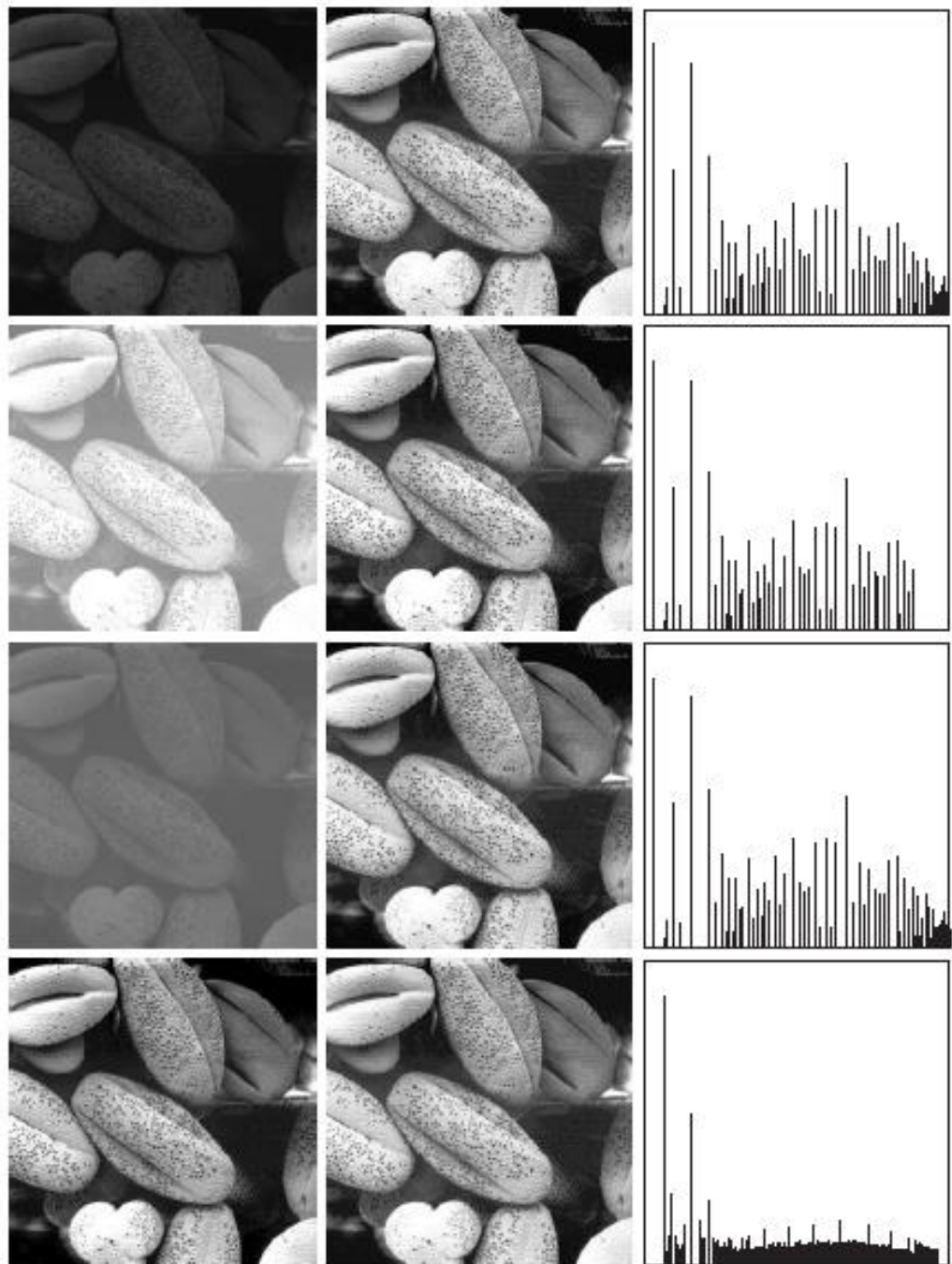
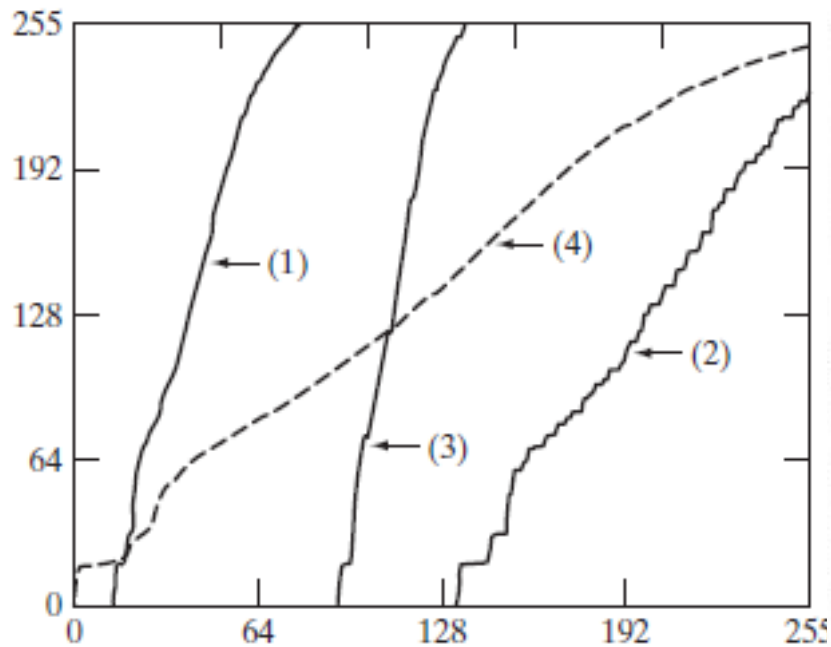
$$s_k = T(r_k) = (L - 1) \sum_{j=0}^k p_r(r_j)$$
$$= \frac{(L - 1)}{MN} \sum_{j=0}^k n_j \quad k = 0, 1, 2, \dots, L - 1$$

$$s = T(r) = (L - 1) \int_0^r p_r(w) dw$$

Equalizing a discrete histogram

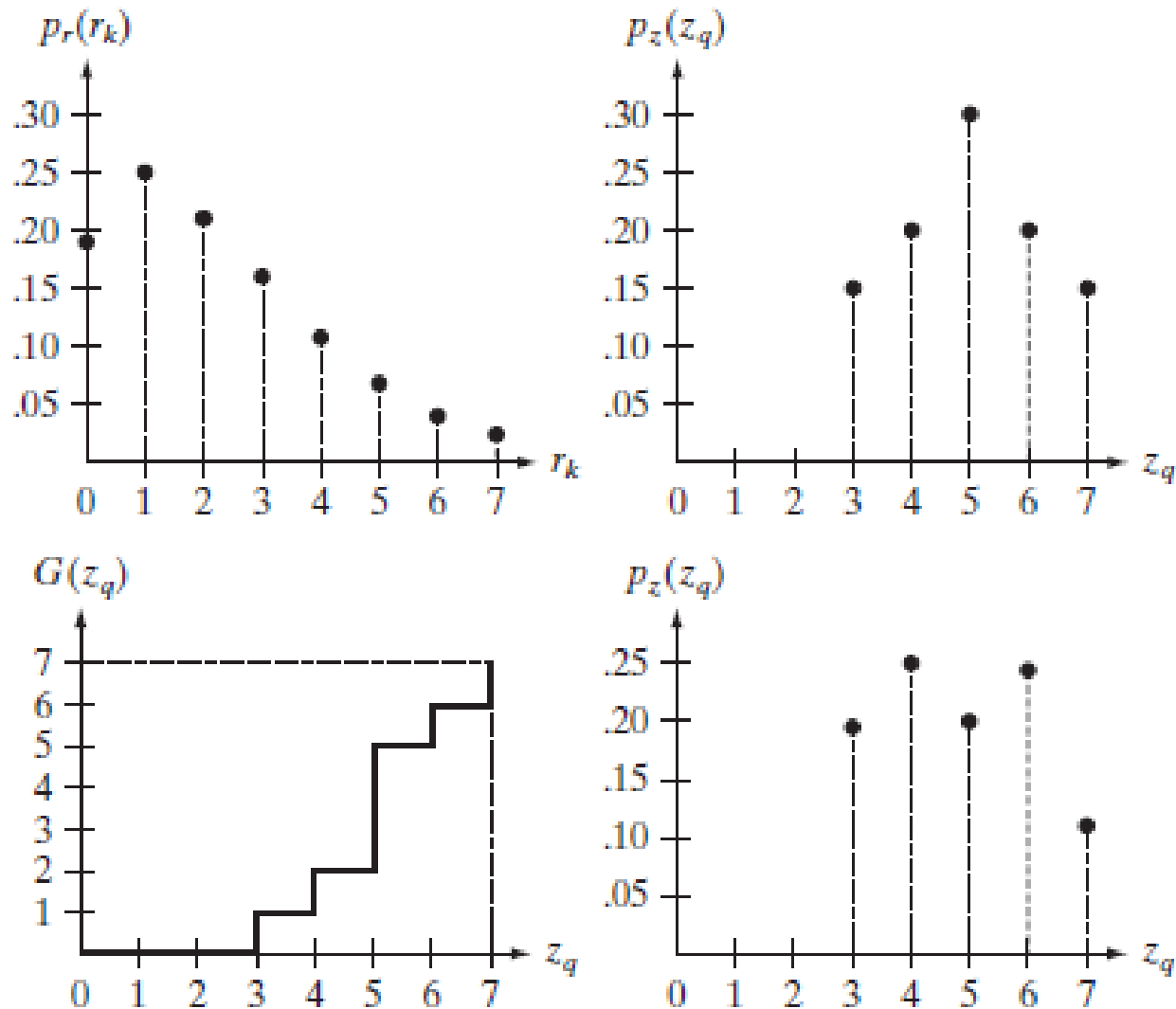


Histogram equalization on different starting images



Source: Digital Image Processing, Gonzalez and Woods, Prentice Hall

One can also specify a histogram



Now we need two transformations

$$s = T(r) = (L - 1) \int_0^r p_r(w) dw$$

$$G(z) = (L - 1) \int_0^z p_z(t) dt = s$$

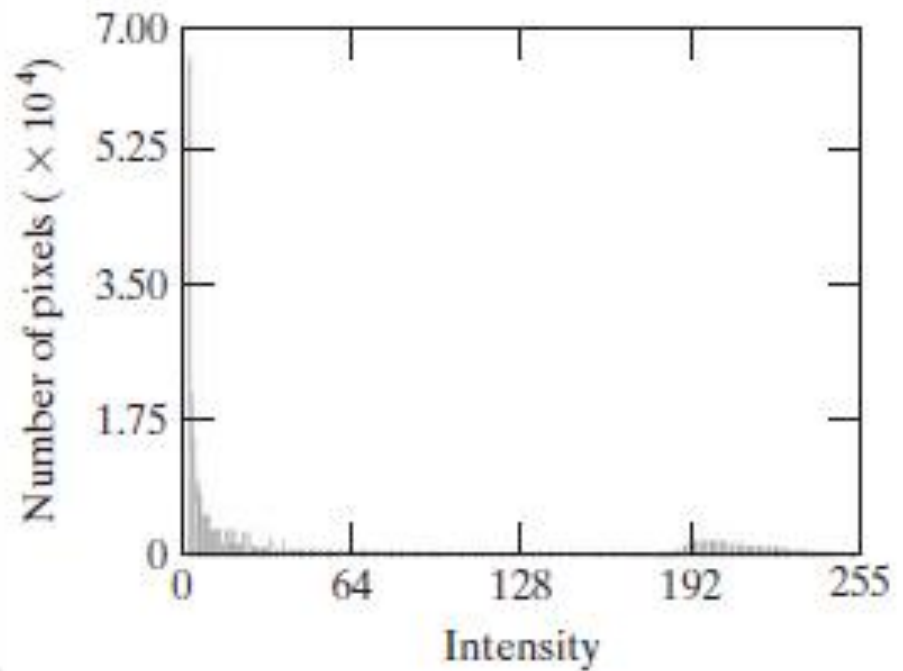
$$z = G^{-1}[T(r)] = G^{-1}(s)$$

- Obtain pdf
- Compute $G(z)$
- Compute $G^{-1}(s)$
- First equalize, then apply $G^{-1}(s)$

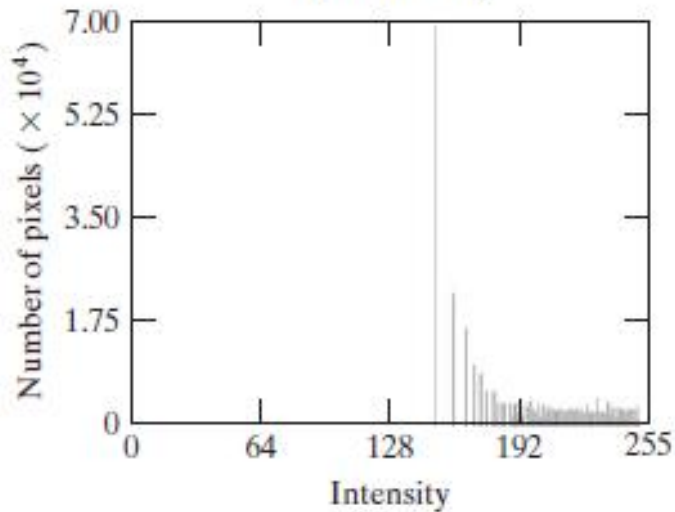
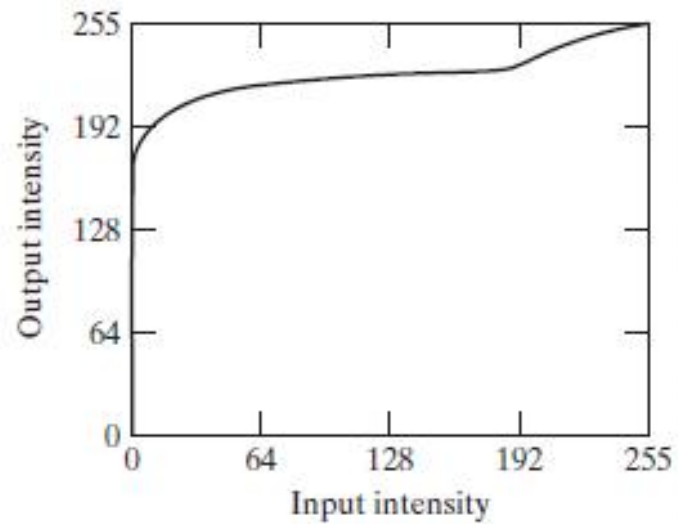
For discrete values, it cannot be perfect

z_q	Specified $p_z(z_q)$	Actual $p_z(z_k)$
$z_0 = 0$	0.00	0.00
$z_1 = 1$	0.00	0.00
$z_2 = 2$	0.00	0.00
$z_3 = 3$	0.15	0.19
$z_4 = 4$	0.20	0.25
$z_5 = 5$	0.30	0.21
$z_6 = 6$	0.20	0.24
$z_7 = 7$	0.15	0.11

Original image



Equalized image



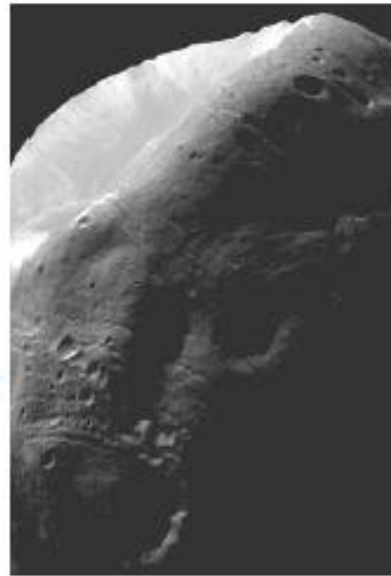
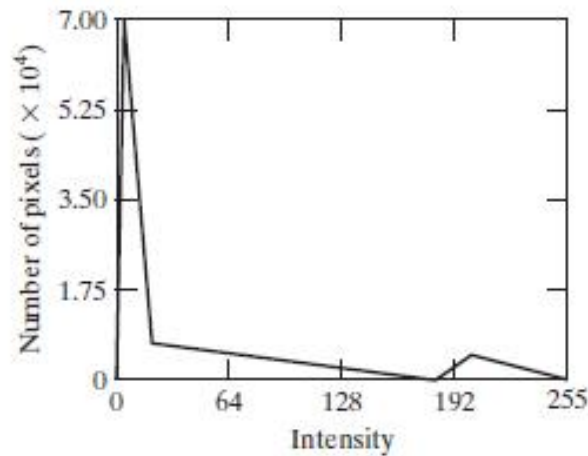
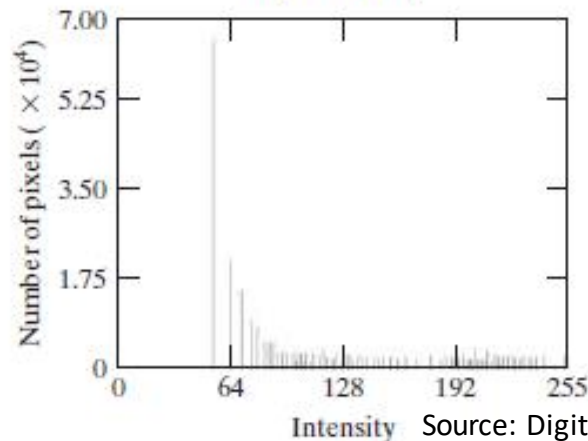
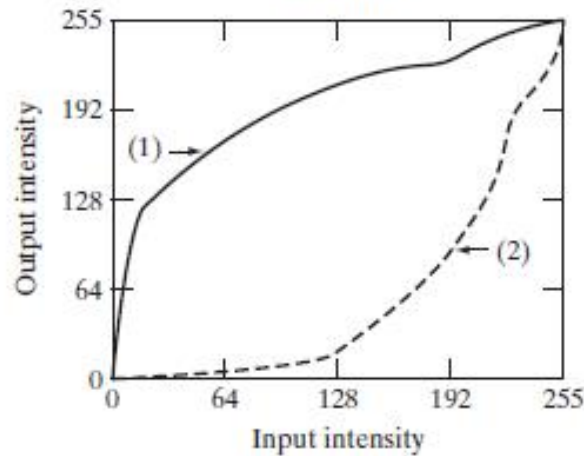
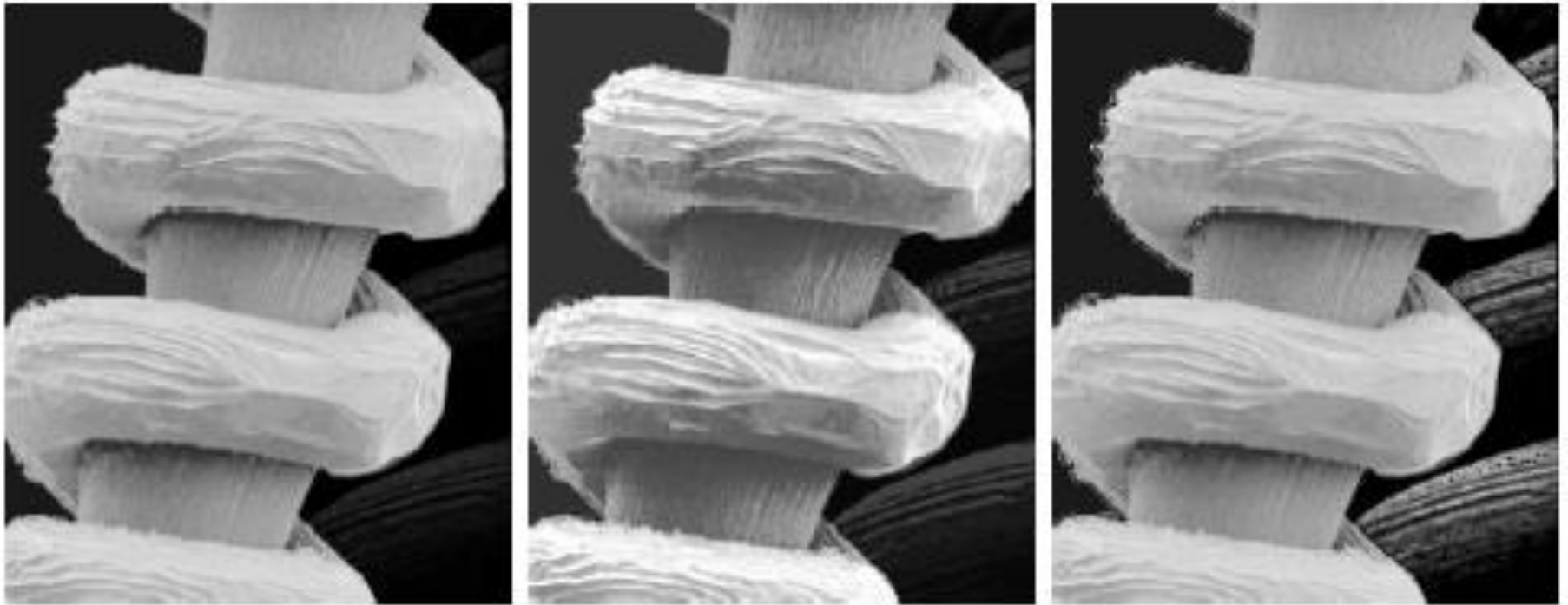
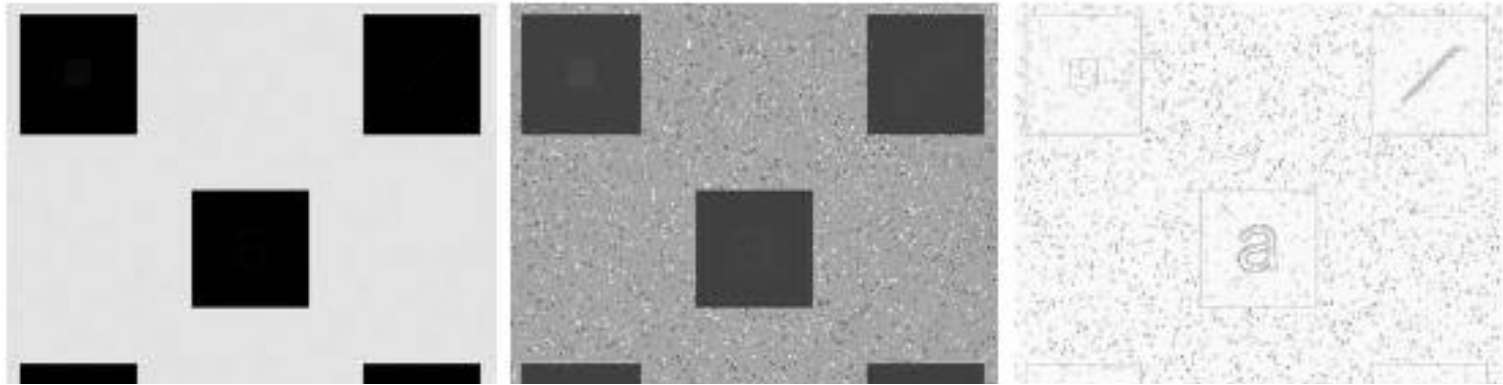


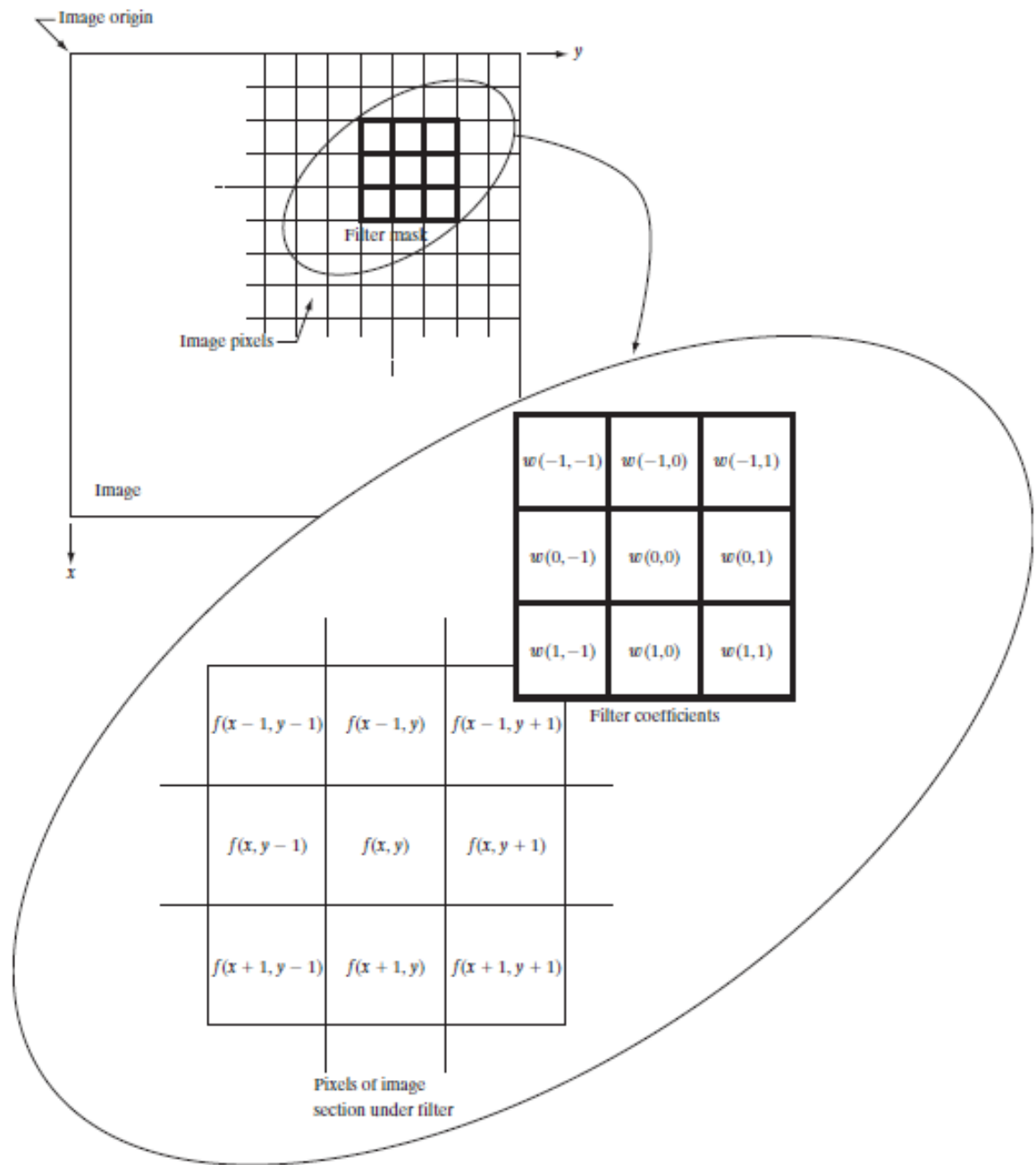
Image with histogram specification



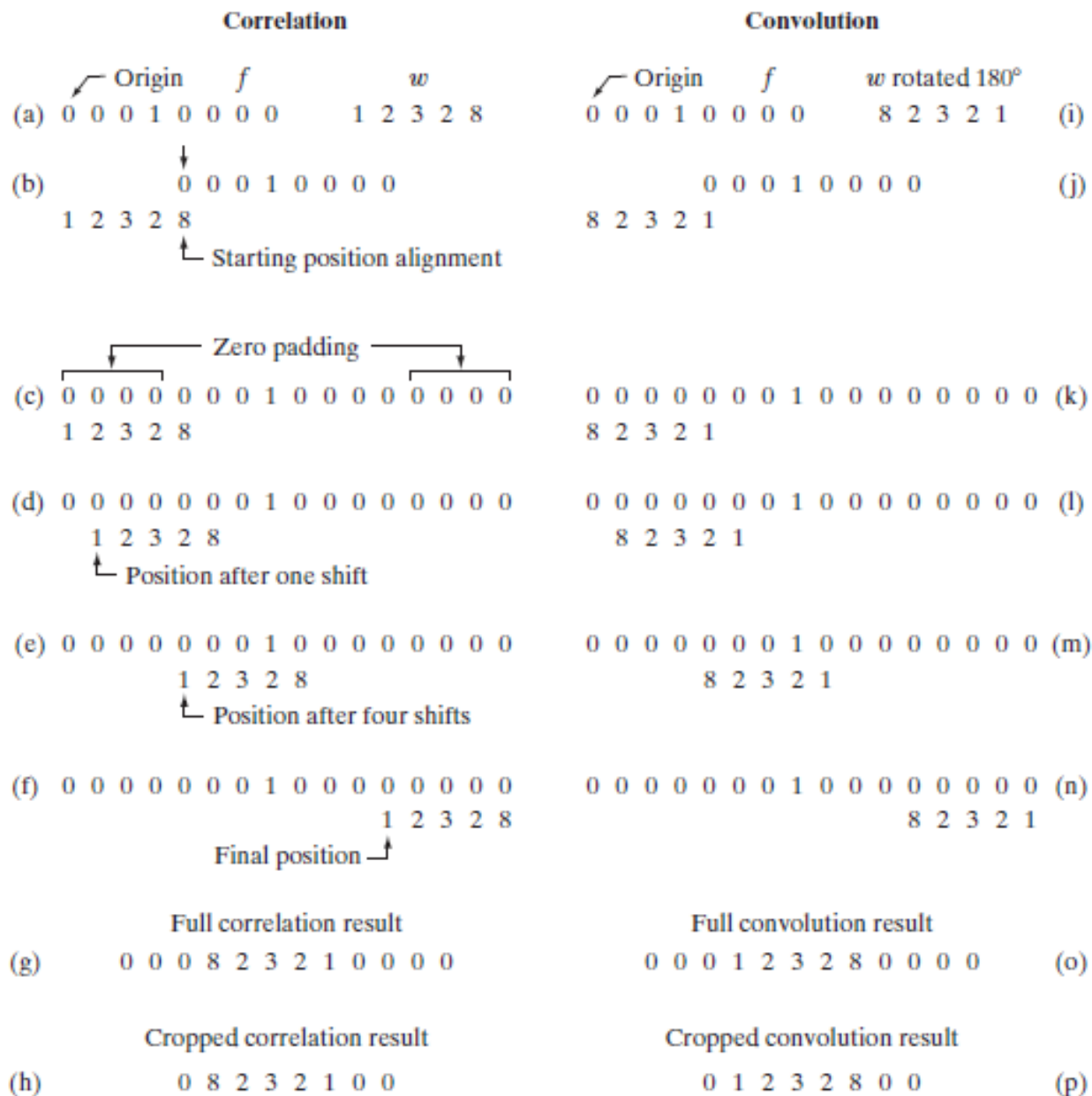
Global vs local histogram equalization



Basics of spatial filtering



Correlation vs convolution



Correlation and convolution in 2-D

Figure 1 illustrates the steps of a 2D correlation operation. The figure is divided into eight sub-figures labeled (a) through (h).

- (a) Original image $f(x, y)$ and kernel $w(x, y)$. $f(x, y)$ is a 5x5 grid of zeros. $w(x, y)$ is a 3x3 grid with values 1, 2, 3 in the first row and 4, 5, 6 in the second row.
- (b) Padded f . The original image is padded with a padding of 1, resulting in a 7x7 grid. The value 1 is placed at the center (3,3) position.
- (c) Initial position for w . A 3x3 region of the padded image is highlighted, corresponding to the initial position of the kernel.
- (d) Full correlation result. The result of the correlation operation is shown as a 7x7 grid. The value 9 is at the center (3,3) position, which corresponds to the initial position of the kernel.
- (e) Cropped correlation result. The result is cropped to a 3x3 grid, showing the values 9, 8, 7 in the first row and 6, 5, 4 in the second row.
- (f) Rotated w . The kernel is rotated 90 degrees clockwise, resulting in a 3x3 grid with values 3, 2, 1 in the first row and 6, 5, 4 in the second row.
- (g) Full convolution result. The result of the convolution operation is shown as a 7x7 grid. The value 4 is at the center (3,3) position, which corresponds to the initial position of the rotated kernel.
- (h) Cropped convolution result. The result is cropped to a 3x3 grid, showing the values 4, 5, 6 in the first row and 7, 8, 9 in the second row.

Correlation vs. convolution in 2-D

$$w(x, y) \star f(x, y) = \sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x + s, y + t)$$

$$w(x, y) \star f(x, y) = \sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x - s, y - t)$$

Correlation as a vector operation

w_1	w_2	w_3
w_4	w_5	w_6
w_7	w_8	w_9

$$\begin{aligned} R &= w_1 z_1 + w_2 z_2 + \dots + w_{mn} z_{mn} \\ &= \sum_{k=1}^{mn} w_k z_k \\ &= \mathbf{w}^T \mathbf{z} \end{aligned}$$

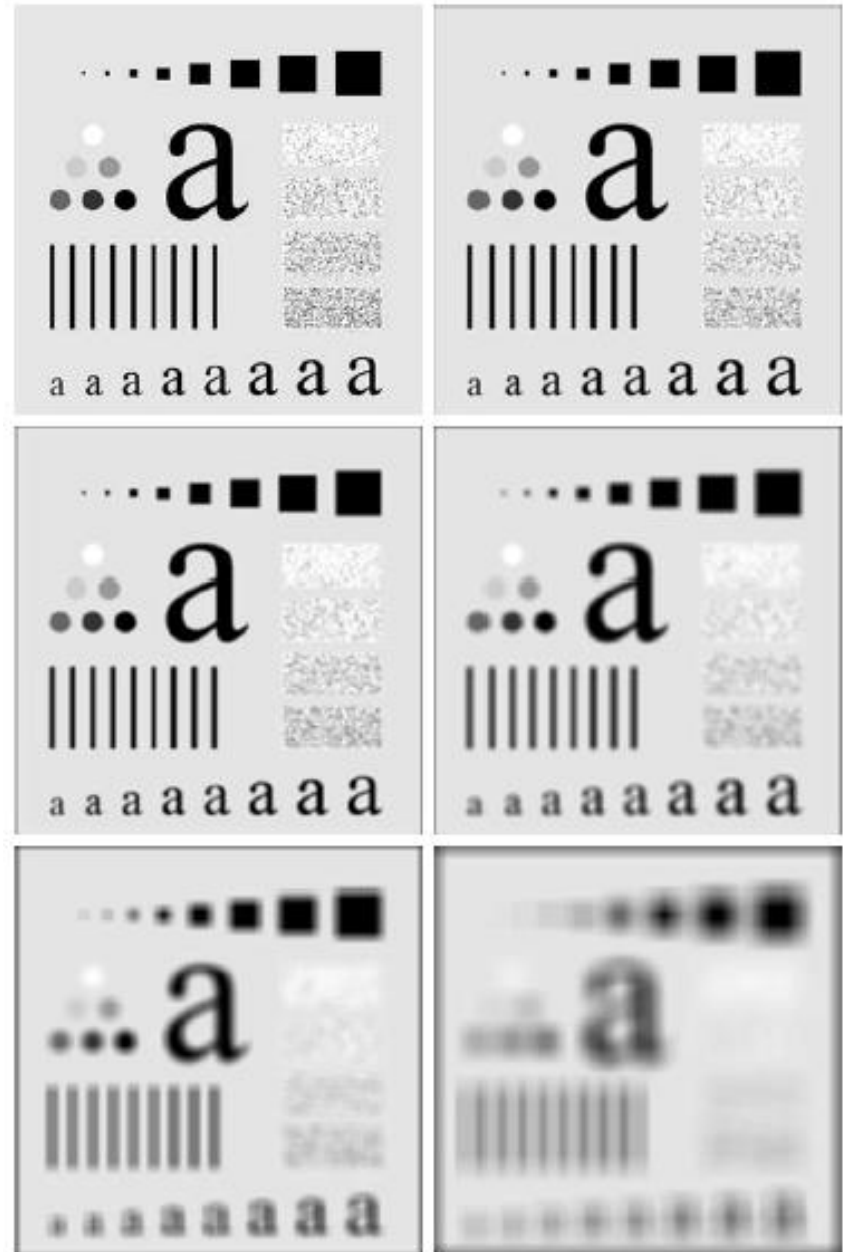
Smoothing (low pass filters)

$$\frac{1}{9} \times \begin{array}{|c|c|c|} \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline \end{array}$$

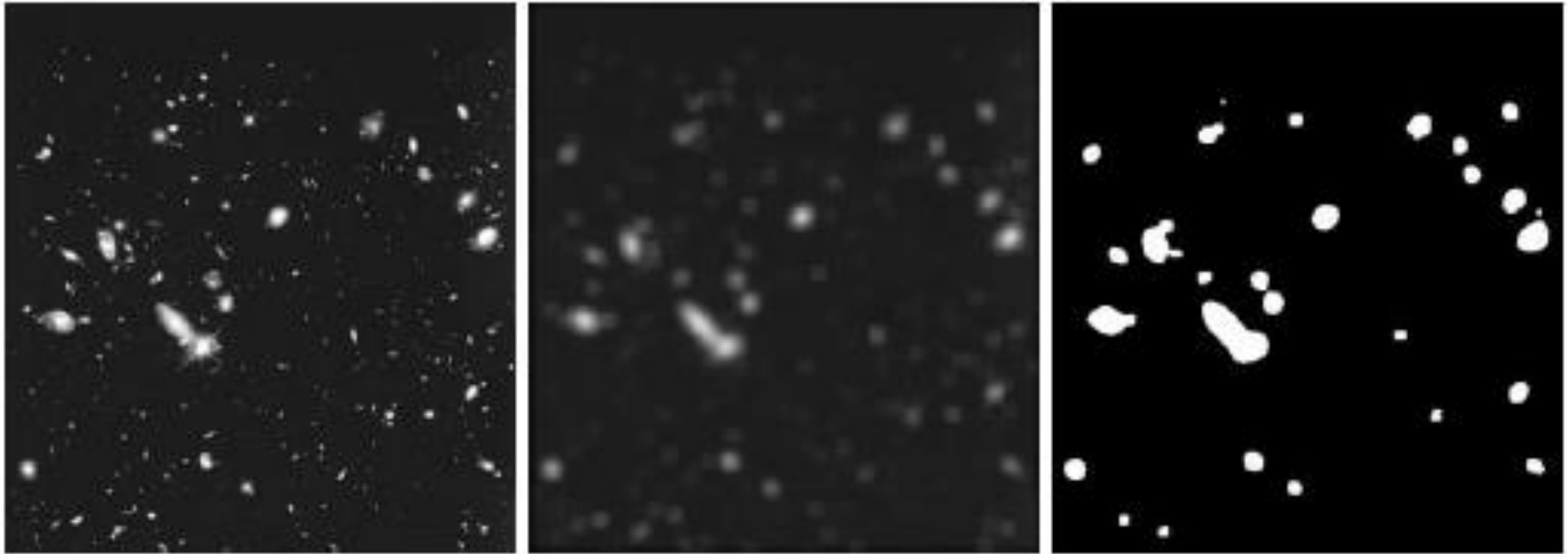
$$\frac{1}{16} \times \begin{array}{|c|c|c|} \hline 1 & 2 & 1 \\ \hline 2 & 4 & 2 \\ \hline 1 & 2 & 1 \\ \hline \end{array}$$

$$h(x, y) = e^{-\frac{x^2 + y^2}{2\sigma^2}}$$

Averaging with
box filters of
sizes 1, 3, 5, 9,
15, and 35



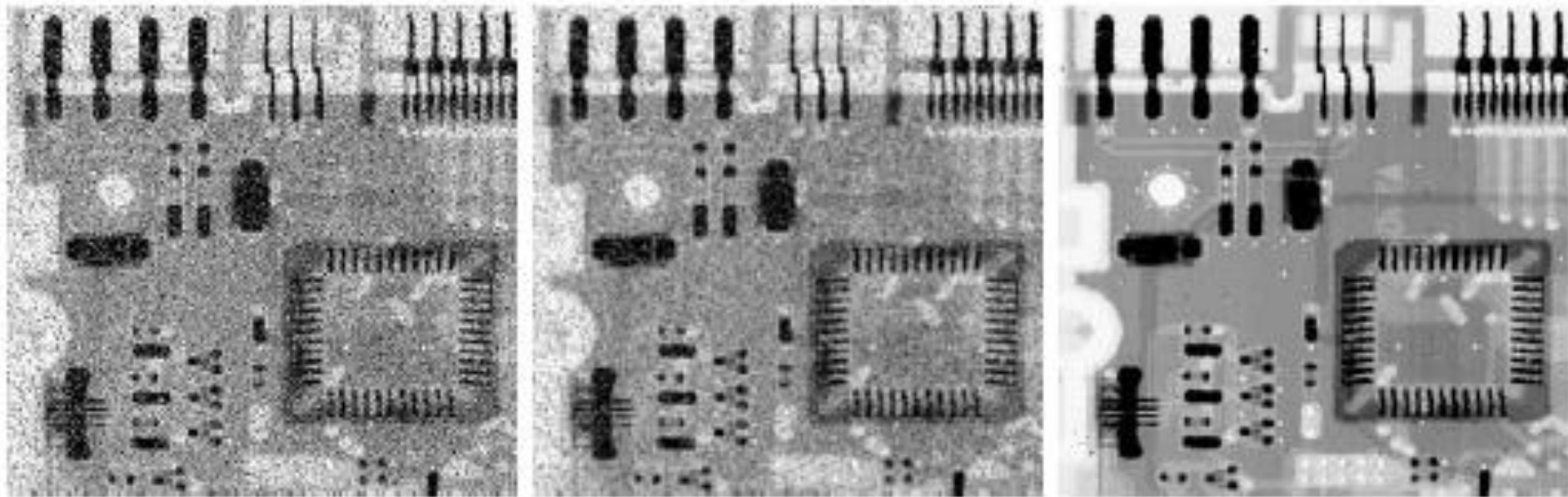
Filtering followed by thresholding



Filtering as weighted average

$$g(x, y) = \frac{\sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x + s, y + t)}{\sum_{s=-a}^a \sum_{t=-b}^b w(s, t)}$$

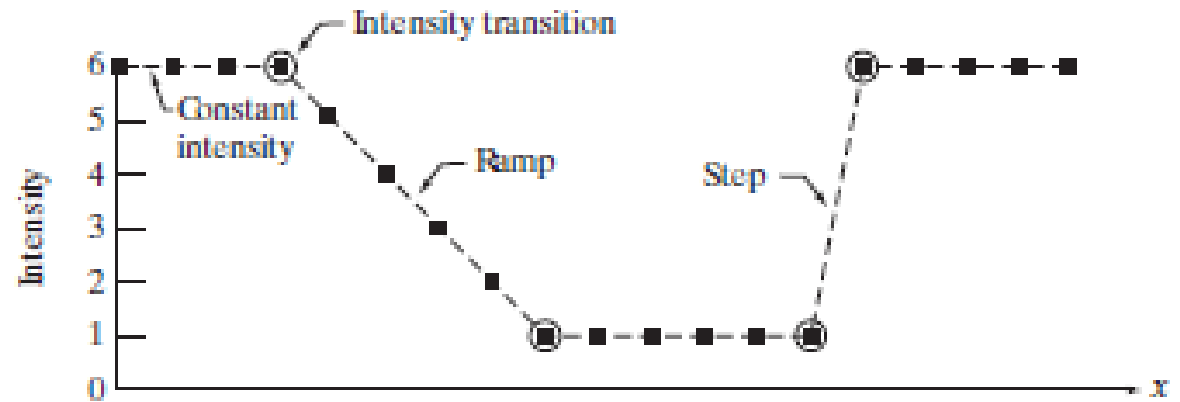
Nonlinear filters such as median filter
(right) are better suited many times



Derivatives of intensity profiles

$$\frac{\partial f}{\partial x} = f(x + 1) - f(x)$$

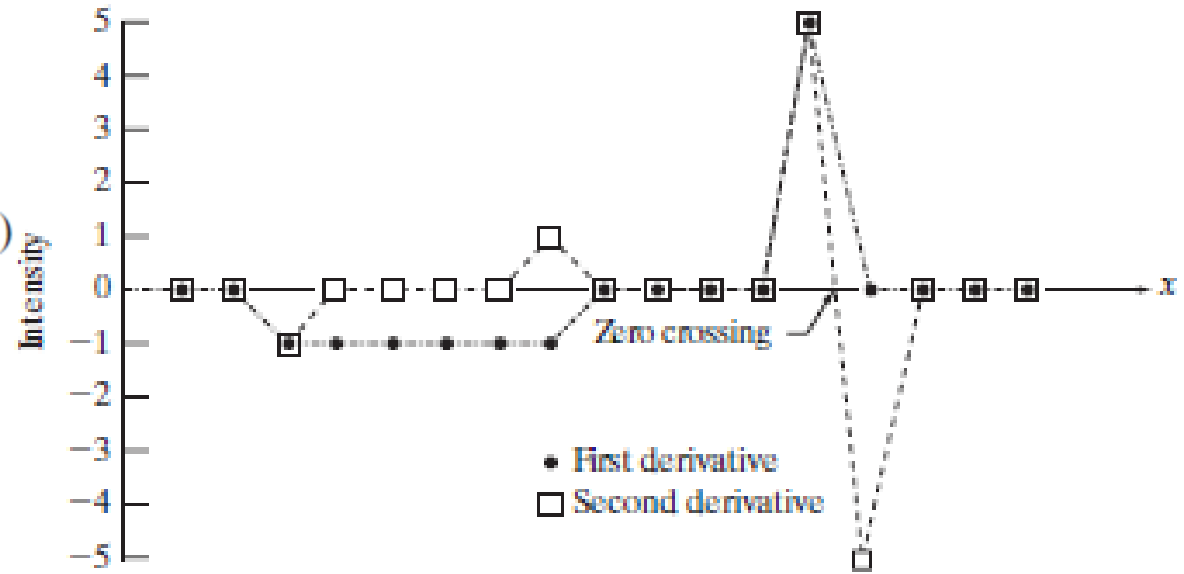
$$\frac{\partial^2 f}{\partial x^2} = f(x + 1) + f(x - 1) - 2f(x)$$



Scan line	6	6	6	6	5	4	3	2	1	1	1	1	1	1	6	6	6	6	6	x
-----------	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

1st derivative 0 0 -1 -1 -1 -1 -1 0 0 0 0 0 0 5 0 0 0 0

2nd derivative 0 0 -1 0 0 0 0 1 0 0 0 0 0 5 -5 0 0 0



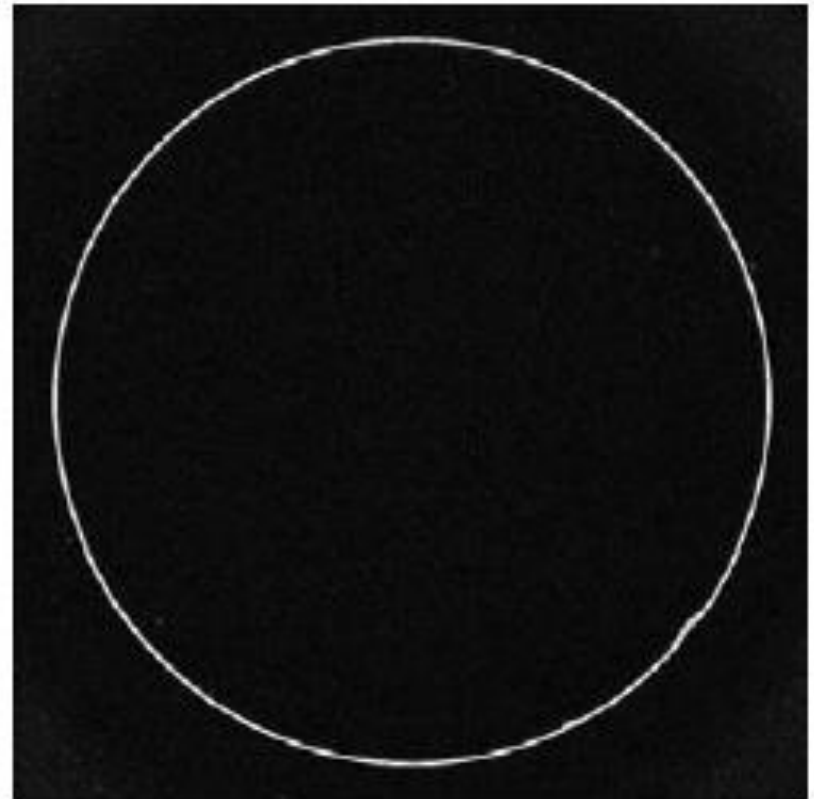
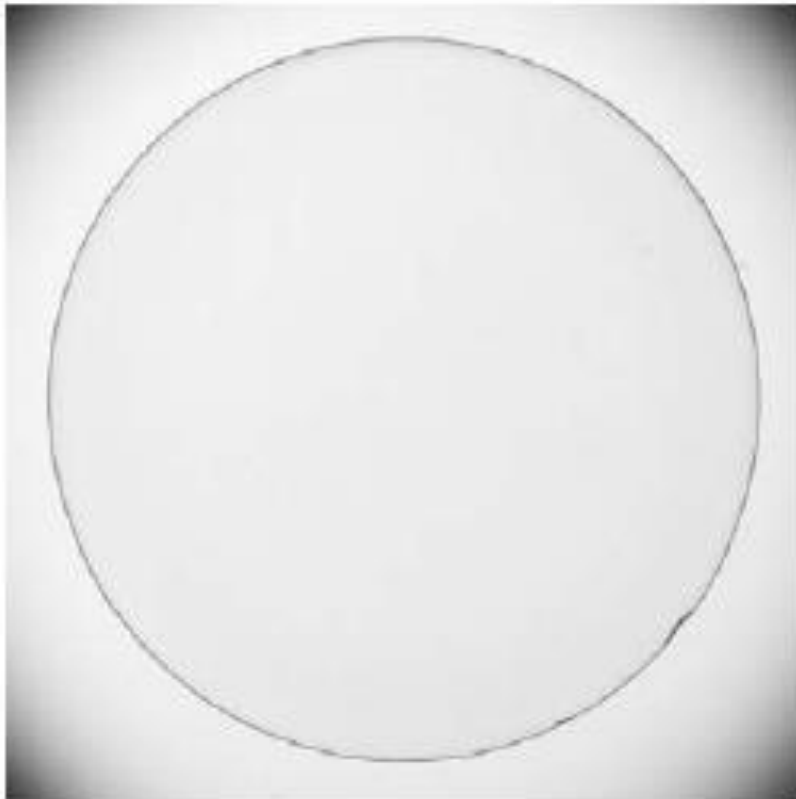
Sobel operators for directional edges

$$g_x = \frac{\partial f}{\partial x} = (z_7 + 2z_8 + z_9) - (z_1 + 2z_2 + z_3)$$

$$g_y = \frac{\partial f}{\partial y} = (z_3 + 2z_6 + z_9) - (z_1 + 2z_4 + z_7)$$

-1	-2	-1	-1	0	1
0	0	0	-2	0	2
1	2	1	-1	0	1

Original and Sobel gradient



Laplacian as an isotropic second derivative

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$$\nabla^2 f(x, y) = f(x + 1, y) + f(x - 1, y) + f(x, y + 1) + f(x, y - 1) - 4f(x, y) \quad (3.6-6)$$

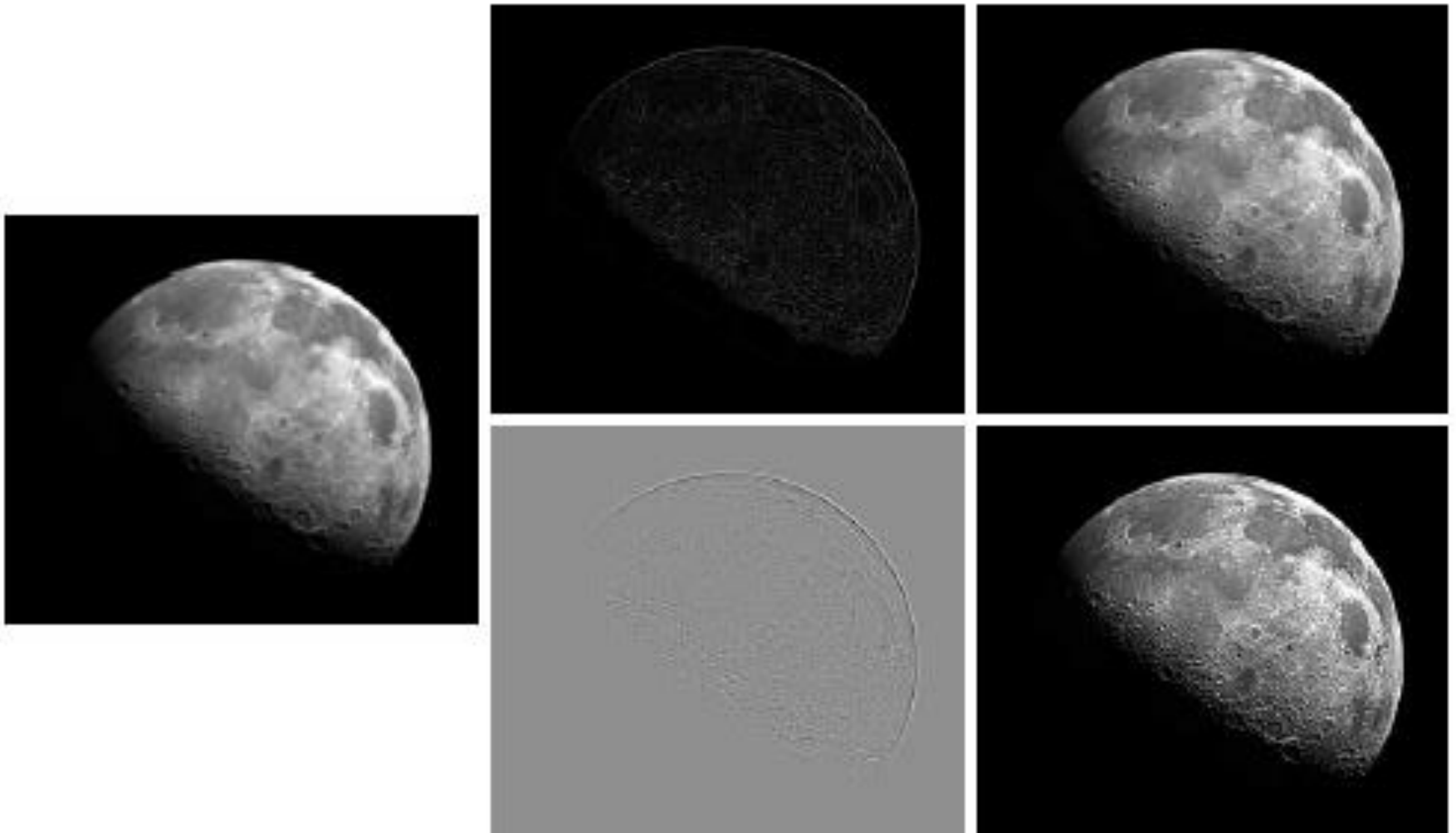
0	1	0	1	1	1
1	-4	1	1	-8	1
0	1	0	1	1	1

Practical implementation of Laplacian

0	-1	0	-1	-1	-1
-1	4	-1	-1	8	-1
0	-1	0	-1	-1	-1

$$g(x, y) = f(x, y) + c \left[\nabla^2 f(x, y) \right]$$

Results of sharpening

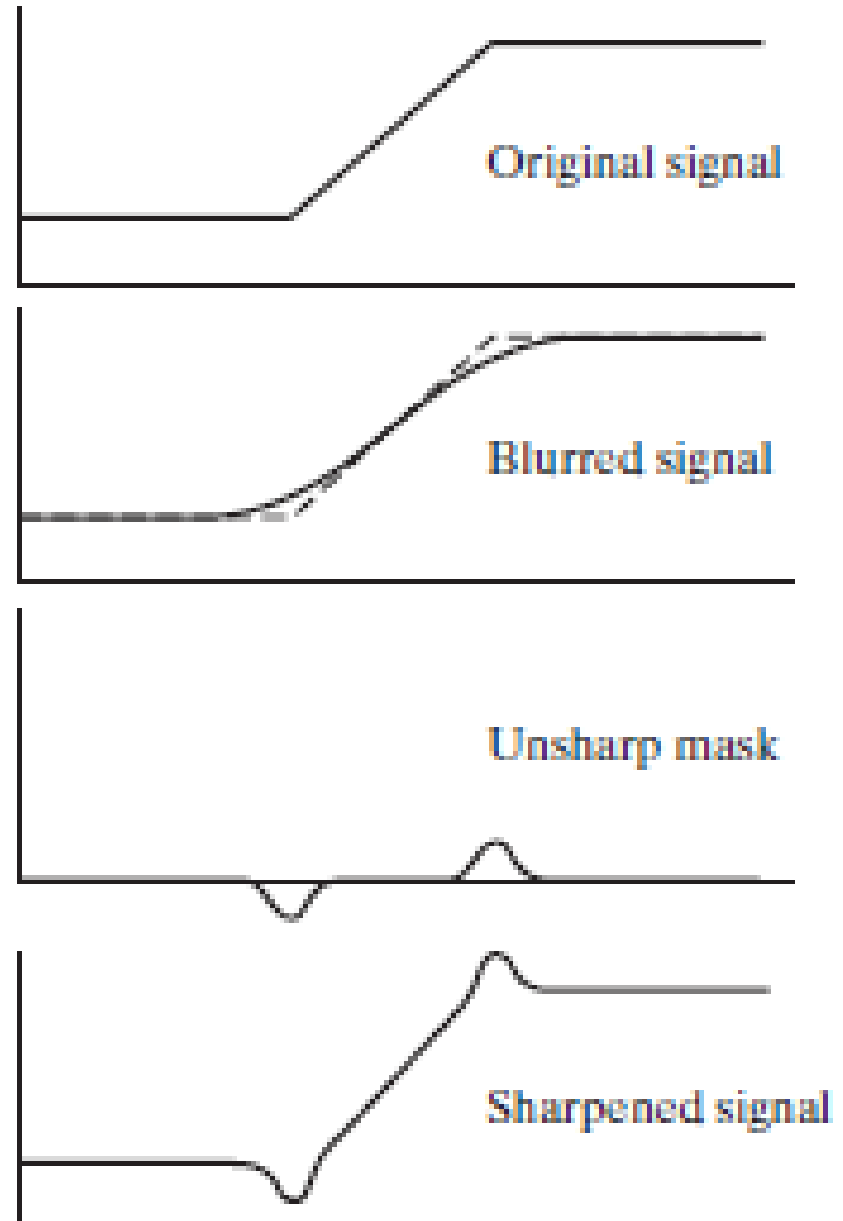


Unsharp masking

- Blur the original image.
- $mask = original - blurred$
- $output = original + mask$

$$g_{mask}(x, y) = f(x, y) - \bar{f}(x, y)$$

$$g(x, y) = f(x, y) + k * g_{mask}(x, y)$$



Sample
results of
unsharp
masking



DIP-XE



DIP-XE



DIP-XE

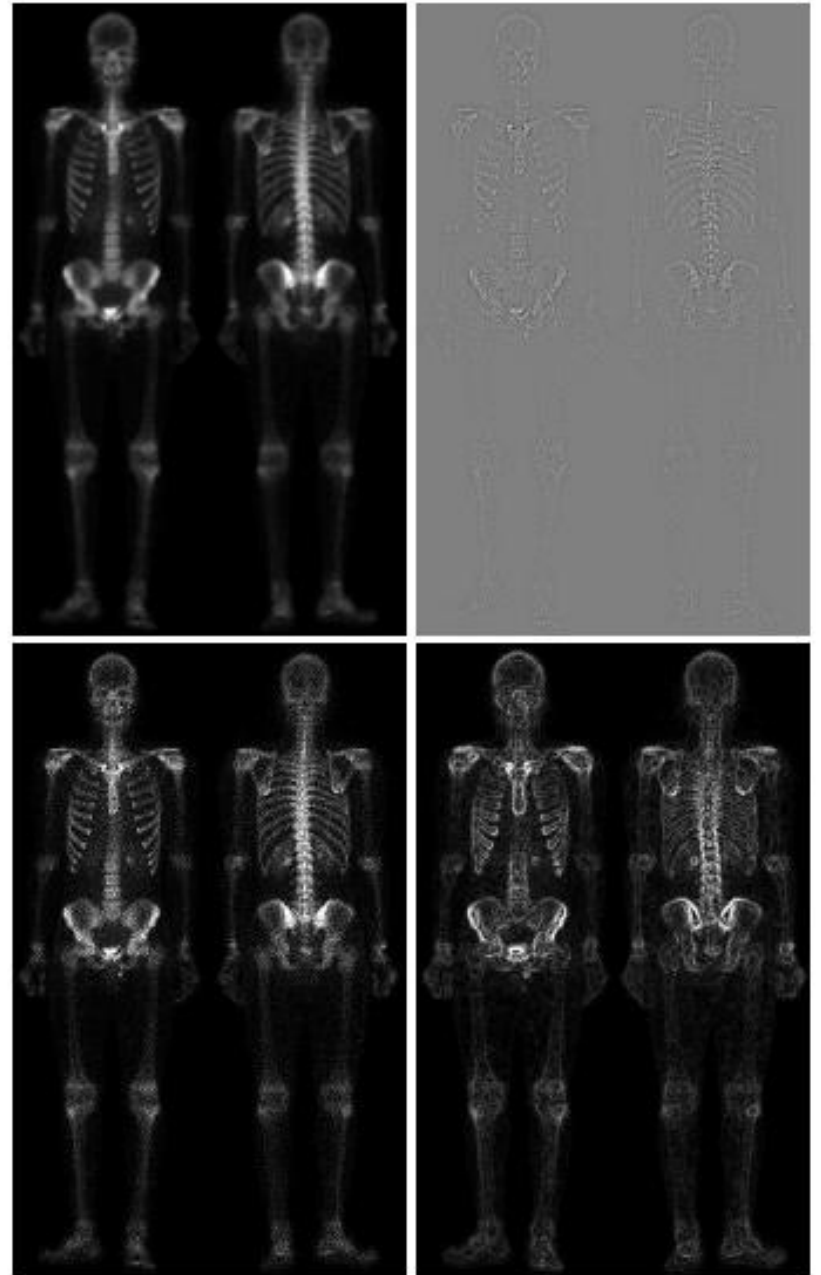


DIP-XE



DIP-XE

Original, Laplacian, Sharpened, Sobel gradient



Smoothened
Sobel, c^*e ,
a+f, power law
transformation

