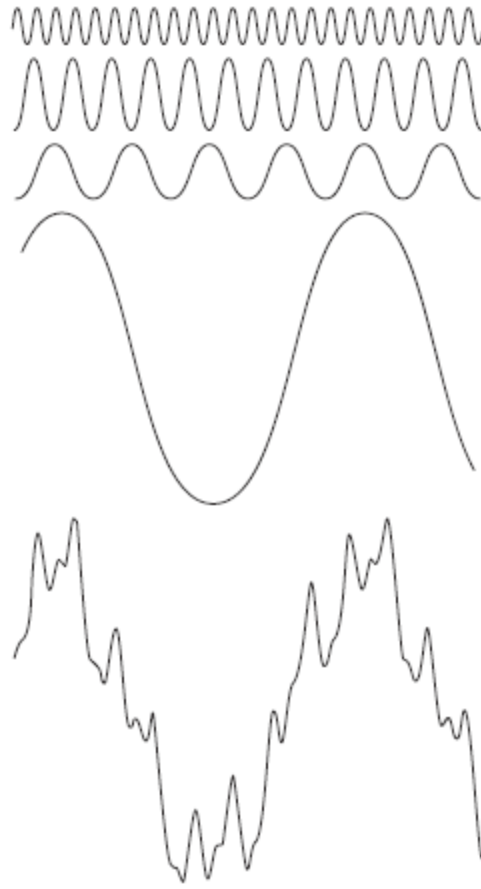


# EE610 – Image Processing

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asethi, 7483

# Periodic signal of arbitrary shape can be constructed by summing up sinusoids



# Revision of complex numbers

- Real and imaginary
- Complex conjugate
- Euler's formula for  $e^{j\theta}$
- Magnitude and phase

# Revision of Fourier series

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{j\frac{2\pi n}{T}t}$$

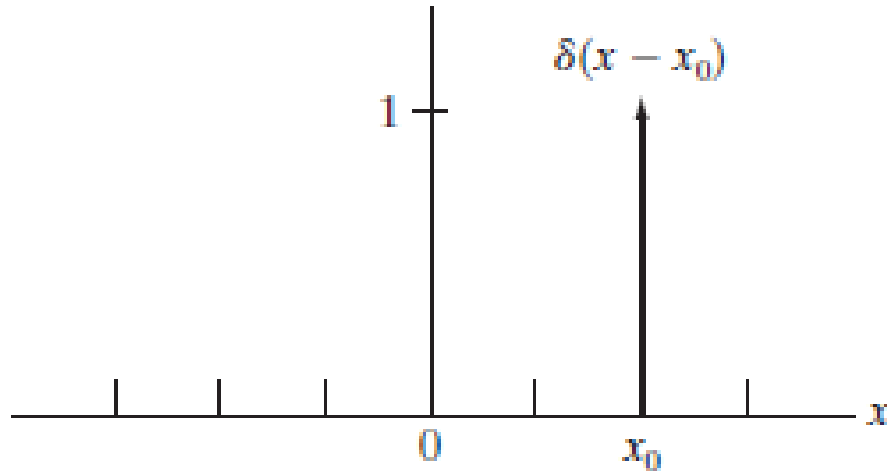
$$c_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-j\frac{2\pi n}{T}t} dt \quad \text{for } n = 0, \pm 1, \pm 2, \dots$$

# Fourier transform pair

$$F(\mu) = \int_{-\infty}^{\infty} f(t) e^{-j2\pi\mu t} dt$$

$$f(t) = \int_{-\infty}^{\infty} F(\mu) e^{j2\pi\mu t} d\mu$$

# Impulse and shifted impulse



- Definition of an impulse function
- Sifting property of impulse and shifted impulse
- Same in discrete domain

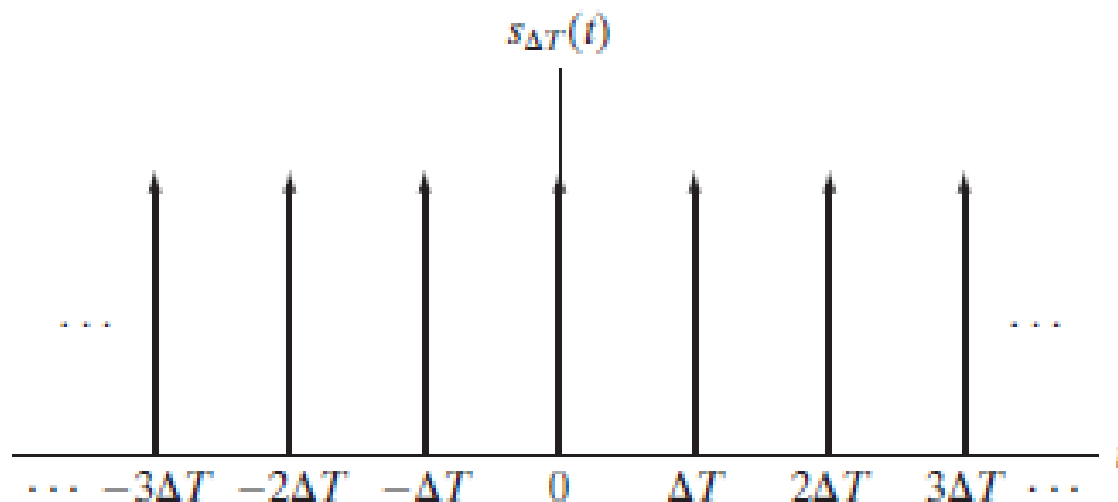
# Fourier transform of Dirac delta

$$\begin{aligned}F(\mu) &= \int_{-\infty}^{\infty} \delta(t) e^{-j2\pi\mu t} dt \\&= \int_{-\infty}^{\infty} e^{-j2\pi\mu t} \delta(t) dt \\&= e^{-j2\pi\mu 0} = e^0 \\&= 1\end{aligned}$$

$$\begin{aligned}F(\mu) &= \int_{-\infty}^{\infty} \delta(t - t_0) e^{-j2\pi\mu t} dt \\&= \int_{-\infty}^{\infty} e^{-j2\pi\mu t} \delta(t - t_0) dt \\&= e^{-j2\pi\mu t_0} \\&= \cos(2\pi\mu t_0) - j\sin(2\pi\mu t_0)\end{aligned}$$

$$e^{-j2\pi\mu t_0};$$

# Impulse train



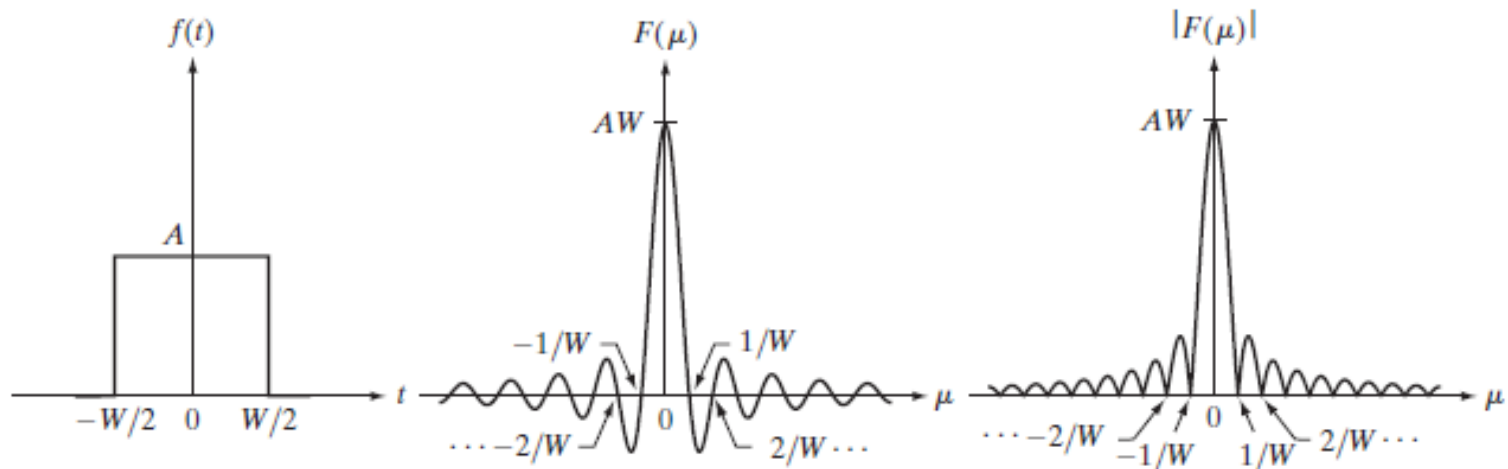
$$s_{\Delta T}(t) = \sum_{n=-\infty}^{\infty} \delta(t - n\Delta T)$$



# Fourier transform of an impulse train

$$\begin{aligned} S(\mu) &= \mathfrak{F}\{s_{\Delta T}(t)\} \\ &= \mathfrak{F}\left\{\frac{1}{\Delta T} \sum_{n=-\infty}^{\infty} e^{j\frac{2\pi n}{\Delta T}t}\right\} \\ &= \frac{1}{\Delta T} \mathfrak{F}\left\{\sum_{n=-\infty}^{\infty} e^{j\frac{2\pi n}{\Delta T}t}\right\} \\ &= \frac{1}{\Delta T} \sum_{n=-\infty}^{\infty} \delta\left(\mu - \frac{n}{\Delta T}\right) \end{aligned}$$

# Fourier transform of a box function



$$\begin{aligned}
 F(\mu) &= \int_{-\infty}^{\infty} f(t) e^{-j2\pi\mu t} dt = \int_{-W/2}^{W/2} A e^{-j2\pi\mu t} dt \\
 &= \frac{-A}{j2\pi\mu} \left[ e^{-j2\pi\mu t} \right]_{-W/2}^{W/2} = \frac{-A}{j2\pi\mu} \left[ e^{-j\pi\mu W} - e^{j\pi\mu W} \right] \\
 &= \frac{A}{j2\pi\mu} \left[ e^{j\pi\mu W} - e^{-j\pi\mu W} \right] \\
 &= AW \frac{\sin(\pi\mu W)}{(\pi\mu W)}
 \end{aligned}$$

$$\text{sinc}(m) = \frac{\sin(\pi m)}{(\pi m)}$$

# Convolution and multiplication

$$f(t) \star h(t) = \int_{-\infty}^{\infty} f(\tau) h(t - \tau) d\tau$$

$$\mathfrak{S}\{f(t) \star h(t)\} = \int_{-\infty}^{\infty} \left[ \int_{-\infty}^{\infty} f(\tau) h(t - \tau) d\tau \right] e^{-j2\pi\mu t} dt$$

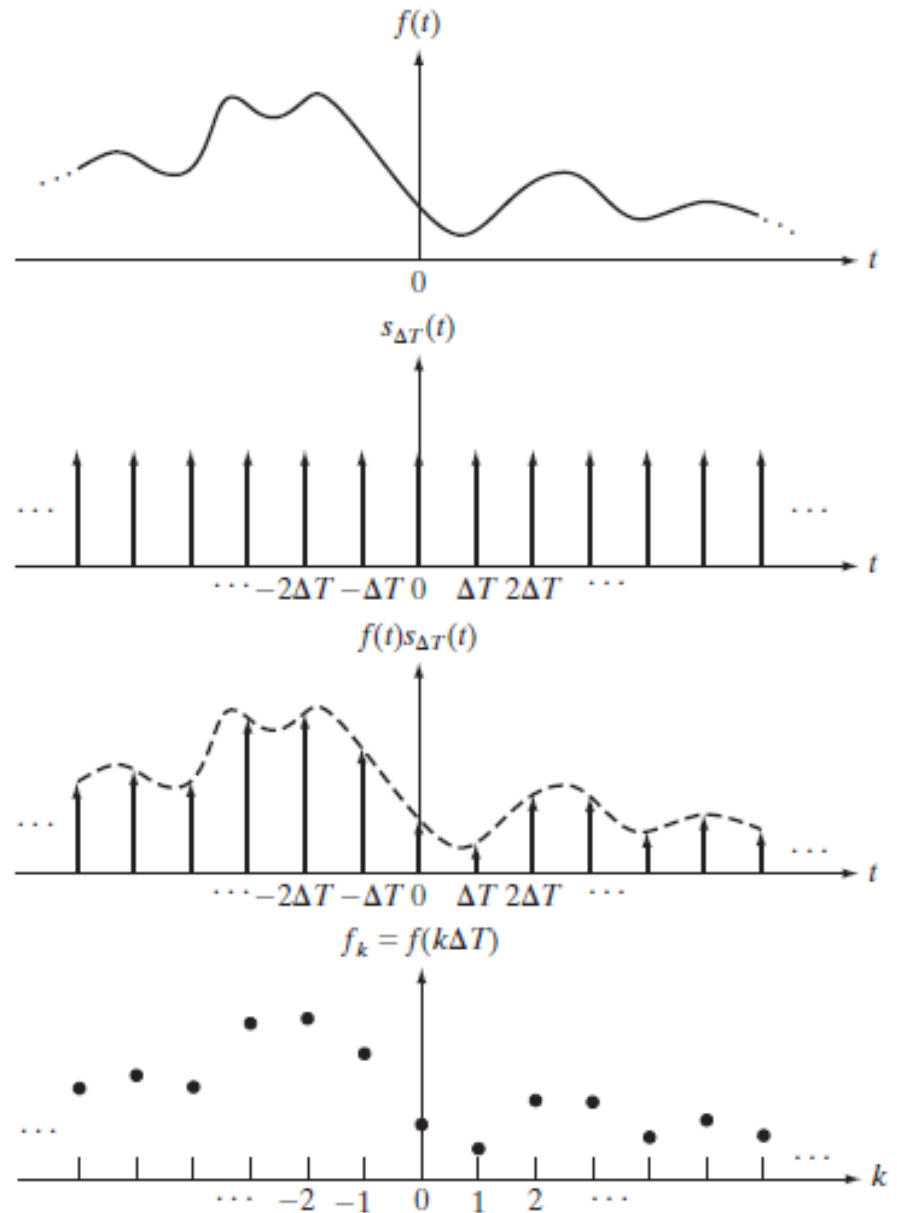
$$= \int_{-\infty}^{\infty} f(\tau) \left[ \int_{-\infty}^{\infty} h(t - \tau) e^{-j2\pi\mu t} dt \right] d\tau$$

$$\mathfrak{S}\{f(t) \star h(t)\} = \int_{-\infty}^{\infty} f(\tau) [H(\mu) e^{-j2\pi\mu\tau}] d\tau$$

$$= H(\mu) \int_{-\infty}^{\infty} f(\tau) e^{-j2\pi\mu\tau} d\tau$$

$$= H(\mu) F(\mu)$$

# Sampling of a function



# Frequency spectrum of sampled function

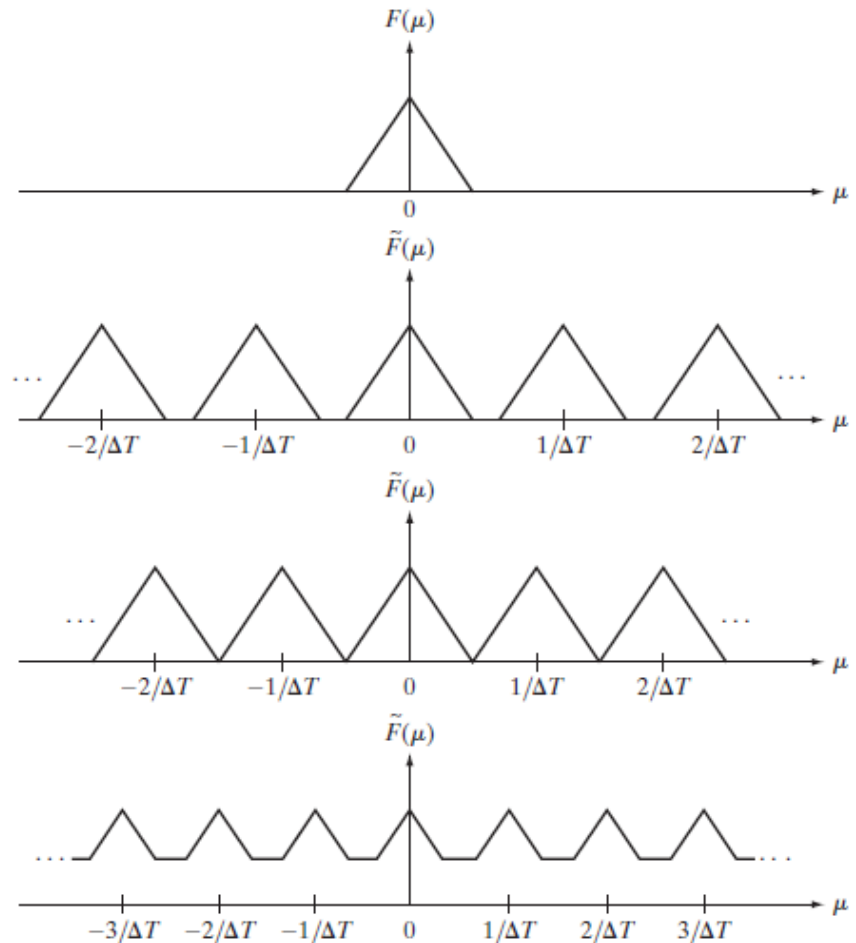
$$\tilde{F}(\mu) = F(\mu) \star S(\mu)$$

$$= \int_{-\infty}^{\infty} F(\tau) S(\mu - \tau) d\tau$$

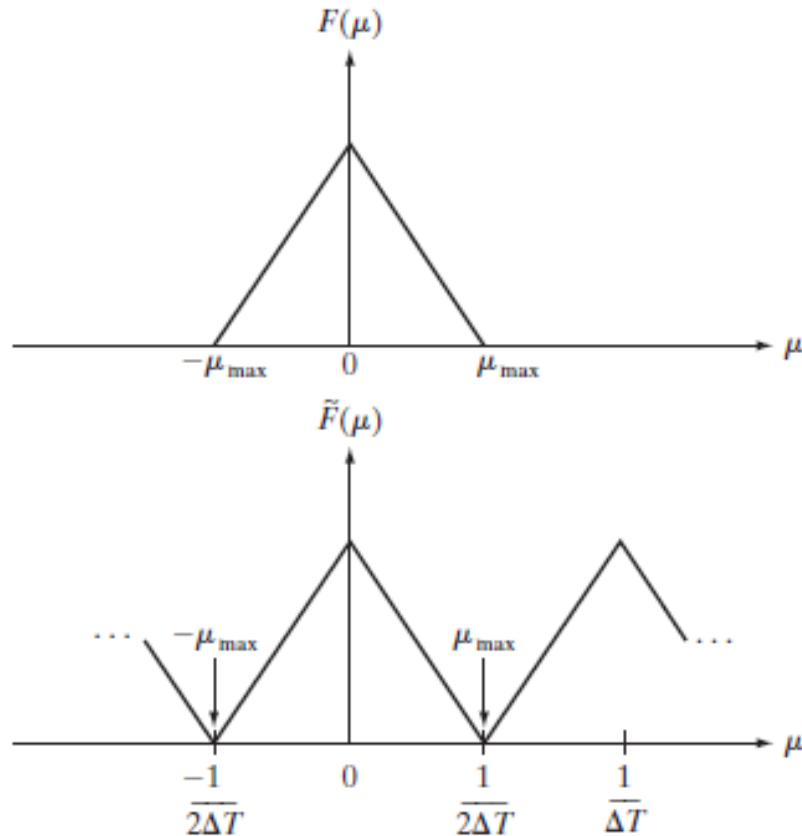
$$= \frac{1}{\Delta T} \int_{-\infty}^{\infty} F(\tau) \sum_{n=-\infty}^{\infty} \delta\left(\mu - \tau - \frac{n}{\Delta T}\right) d\tau$$

$$= \frac{1}{\Delta T} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} F(\tau) \delta\left(\mu - \tau - \frac{n}{\Delta T}\right) d\tau$$

$$= \frac{1}{\Delta T} \sum_{n=-\infty}^{\infty} F\left(\mu - \frac{n}{\Delta T}\right)$$

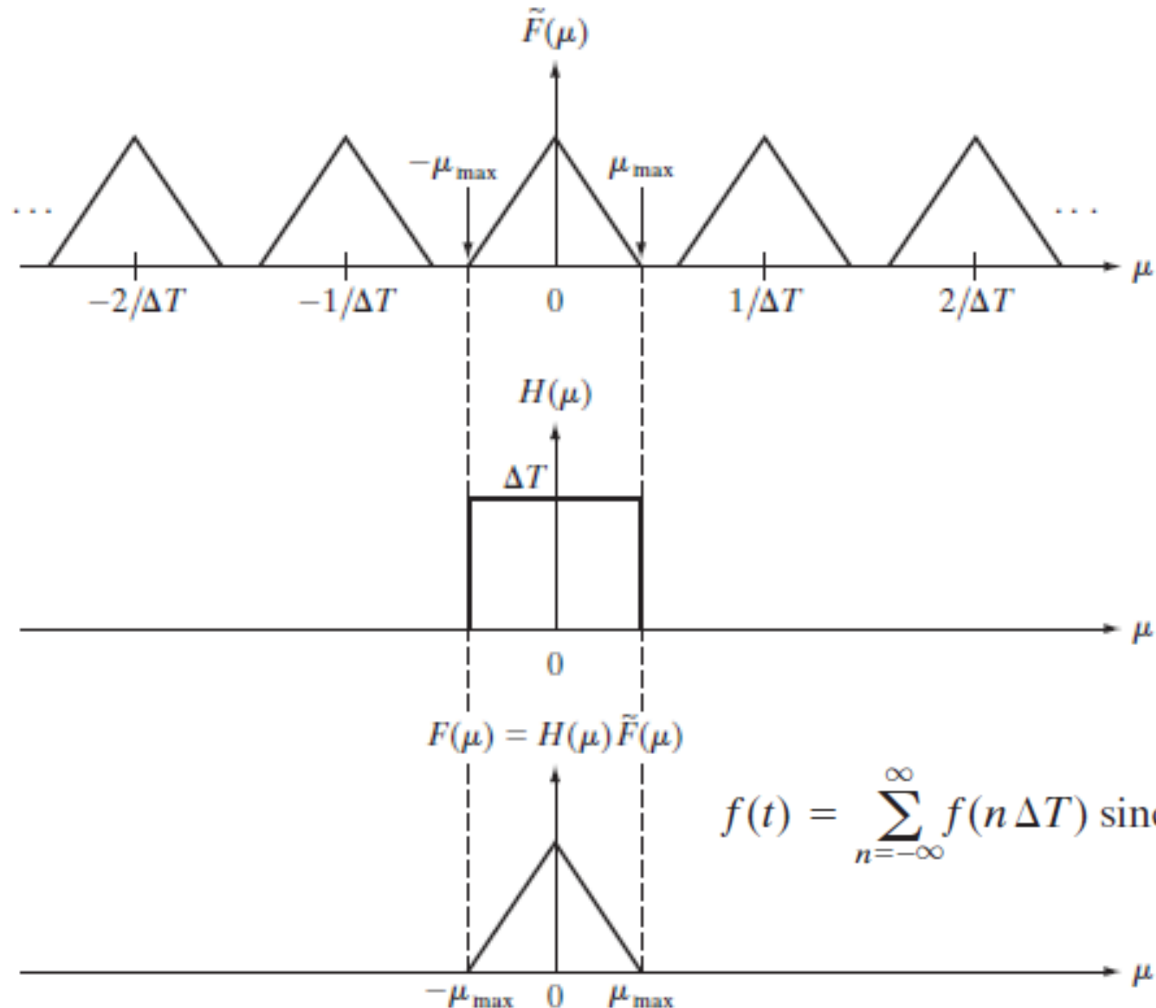


# Nyquist criterion

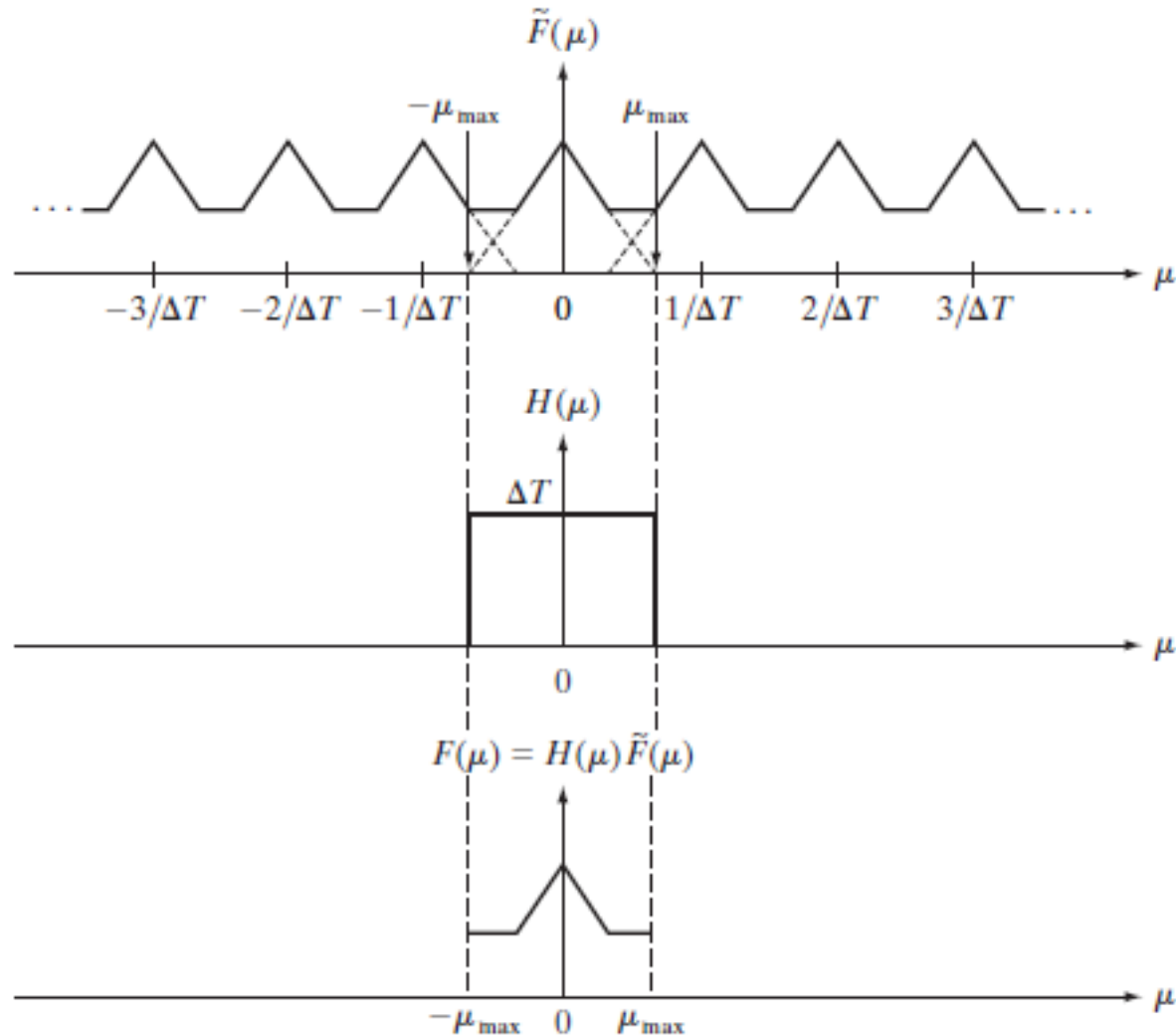


$$\frac{1}{\Delta T} > 2\mu_{\max}$$

# Convolving samples with a sinc function for interpolation

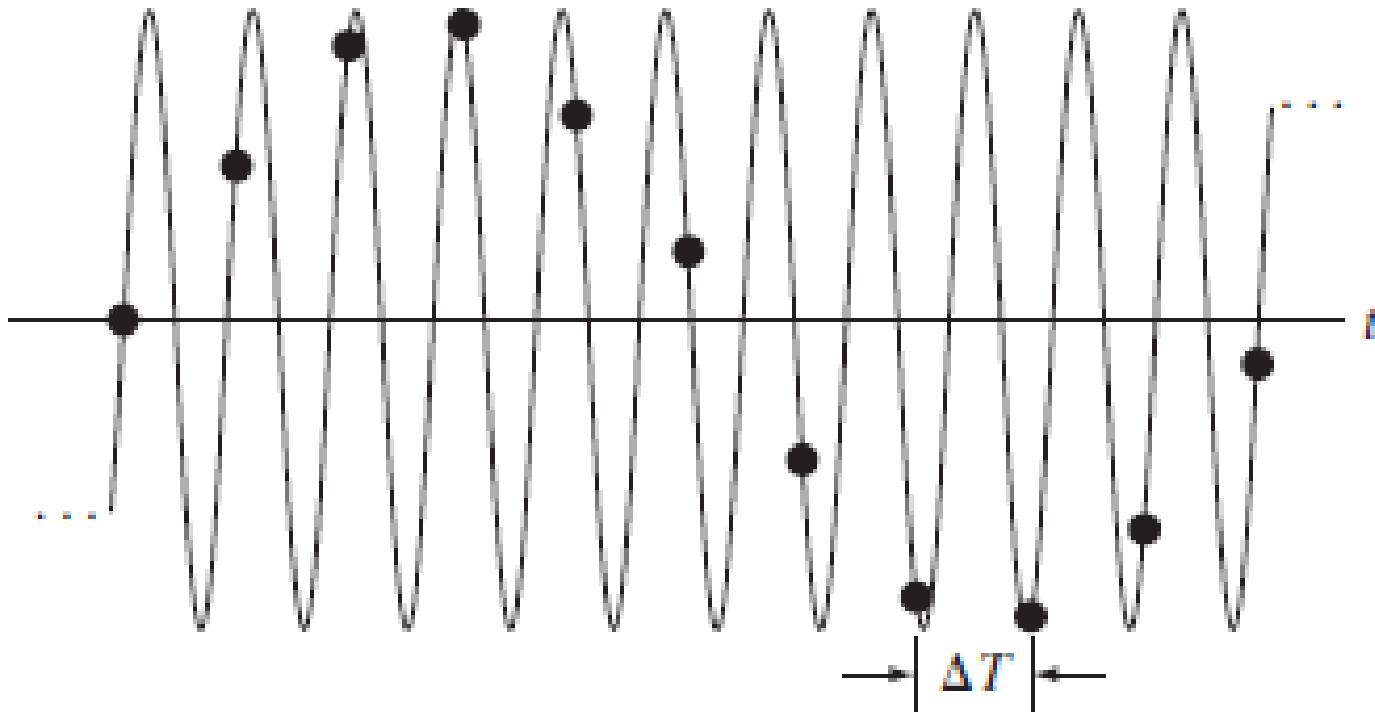


# Aliasing is a consequence of violating Nyquist limit during interpolation

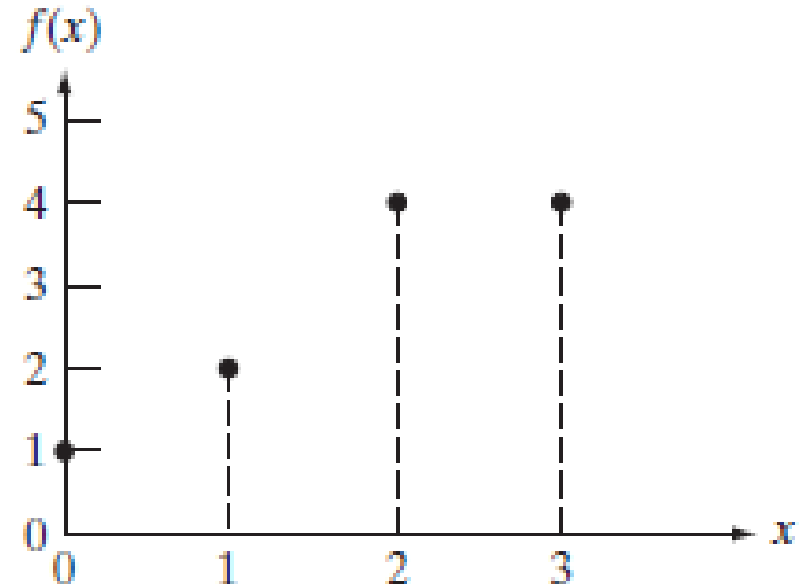
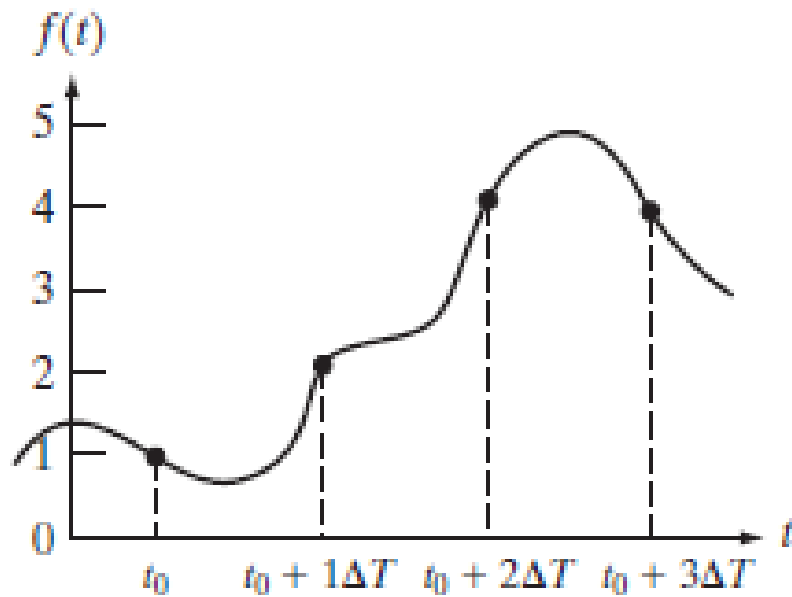




# Aliasing in spatial (time) domain



# Making space (or time) discrete



# Discrete Fourier Transform

$$\begin{aligned}\tilde{F}(\mu) &= \int_{-\infty}^{\infty} \tilde{f}(t) e^{-j2\pi\mu t} dt \\&= \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} f(t) \delta(t - n\Delta T) e^{-j2\pi\mu t} dt \\&= \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} f(t) \delta(t - n\Delta T) e^{-j2\pi\mu t} dt \\&= \sum_{n=-\infty}^{\infty} f_n e^{-j2\pi\mu n\Delta T}\end{aligned}$$

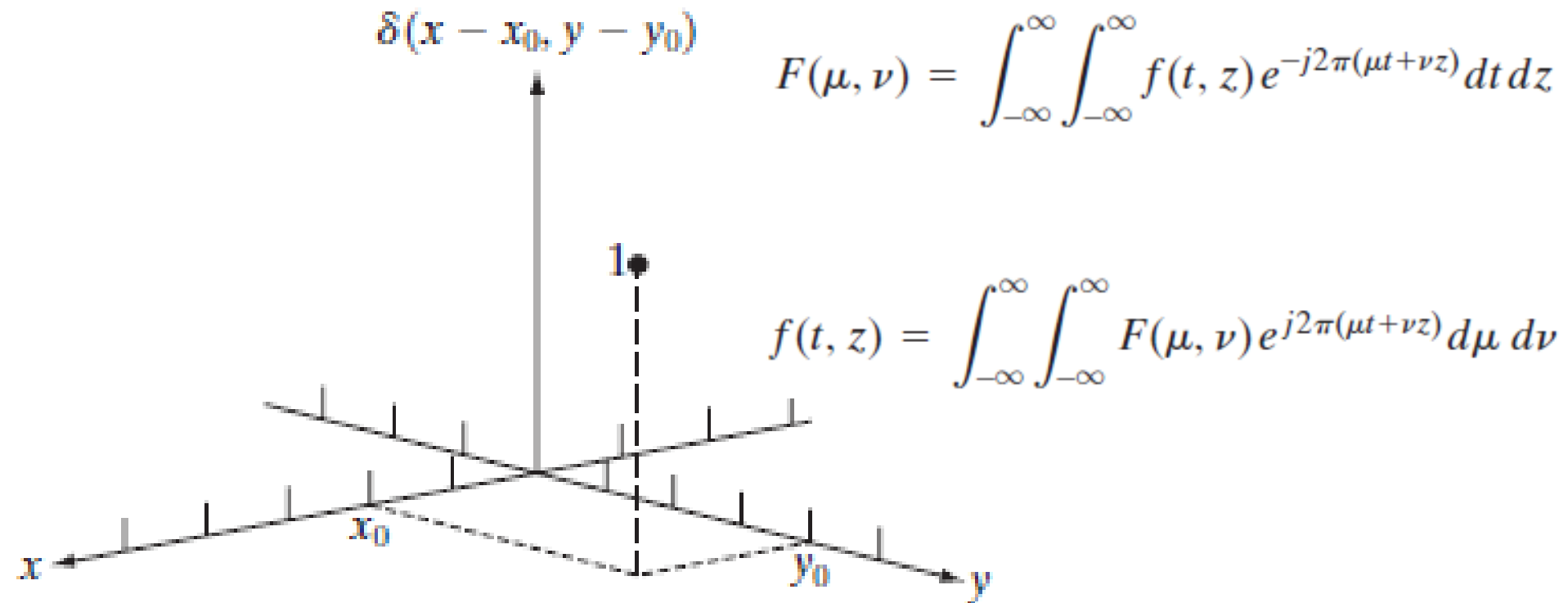
$$\mu = \frac{m}{M\Delta T}$$

$$F_m = \sum_{n=0}^{M-1} f_n e^{-j2\pi mn/M}$$

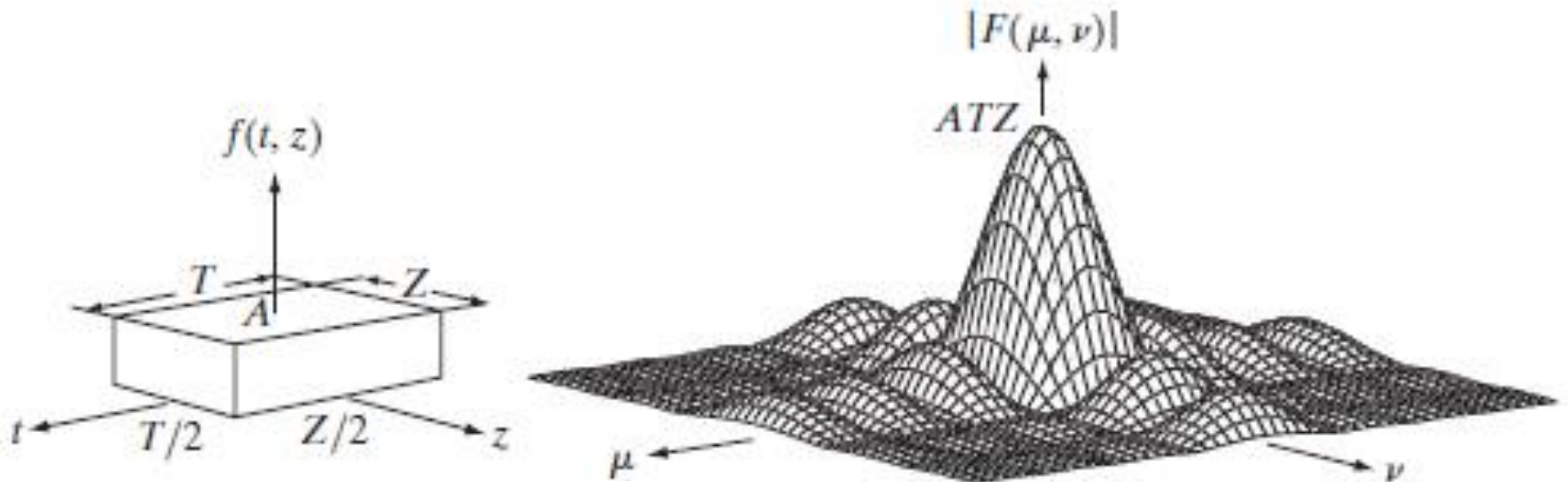
$$f_n = \frac{1}{M} \sum_{m=0}^{M-1} F_m e^{j2\pi mn/M}$$

$$f(x) \star h(x) = \sum_{m=0}^{M-1} f(m)h(x - m)$$

# Extension to two variables



# Box and Sinc in 2-D

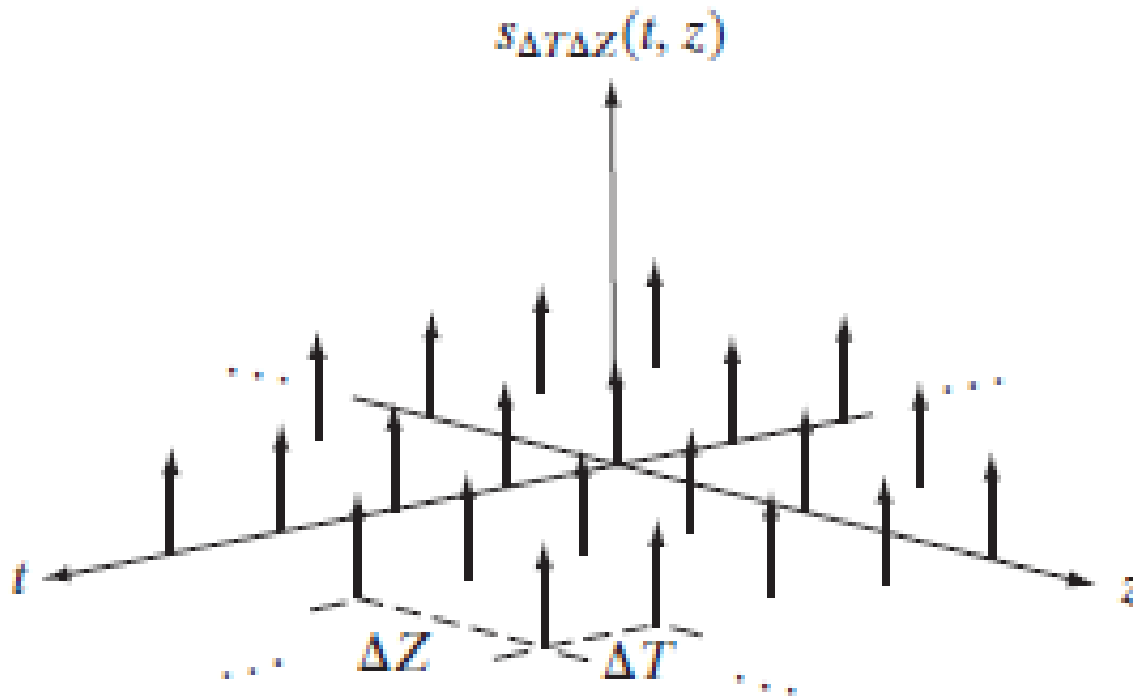


$$F(\mu, \nu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t, z) e^{-j2\pi(\mu t + \nu z)} dt dz$$

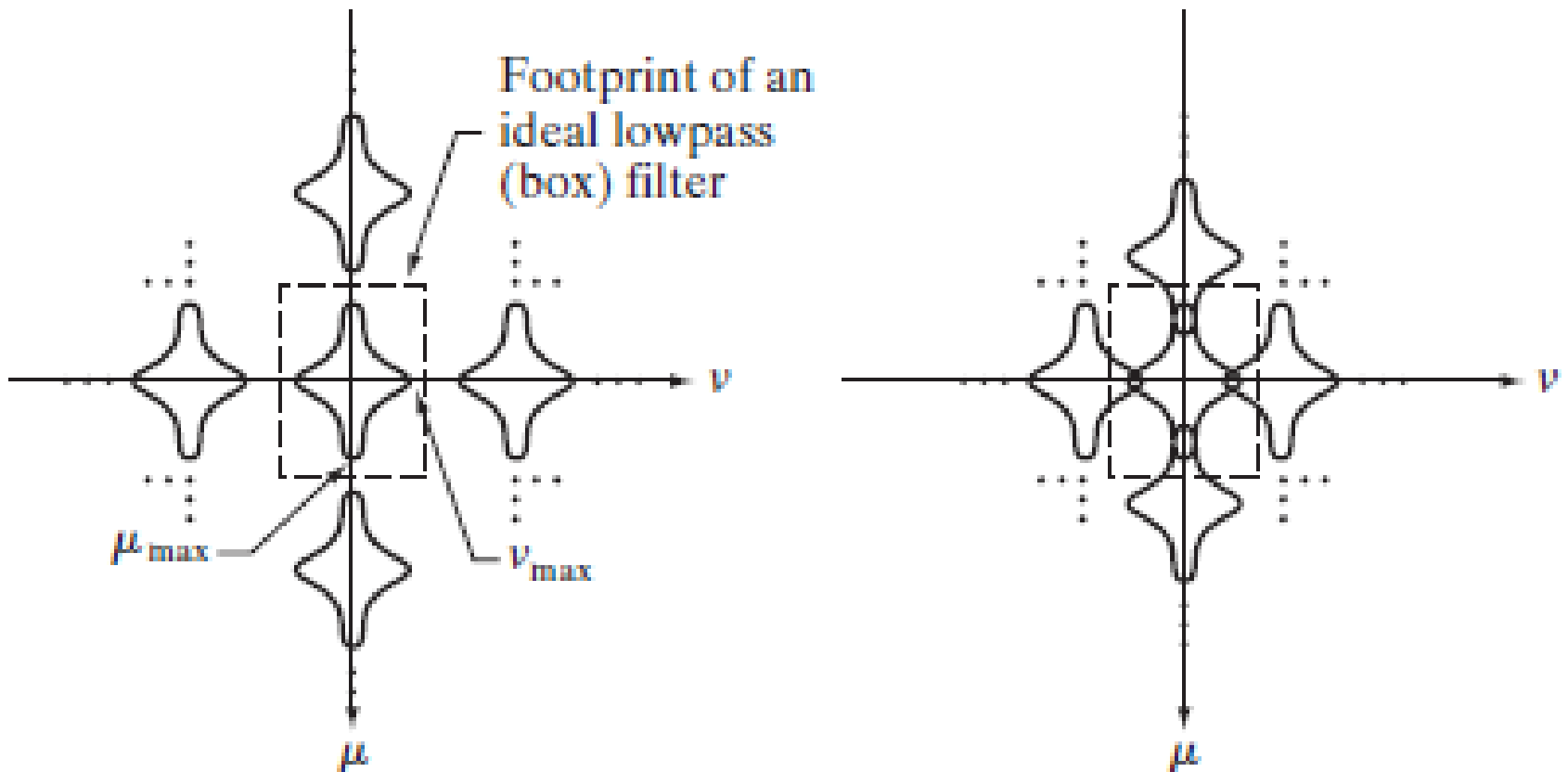
$$= \int_{-T/2}^{T/2} \int_{-Z/2}^{Z/2} A e^{-j2\pi(\mu t + \nu z)} dt dz$$

$$= ATZ \left[ \frac{\sin(\pi\mu T)}{(\pi\mu T)} \right] \left[ \frac{\sin(\pi\nu Z)}{(\pi\nu Z)} \right]$$

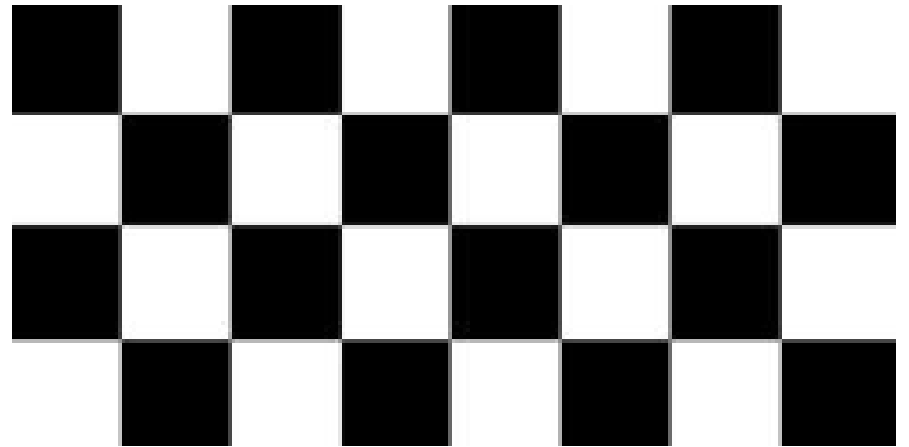
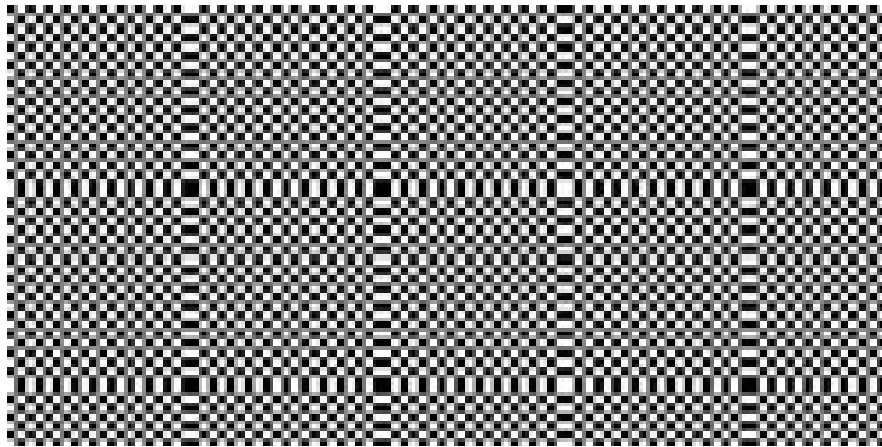
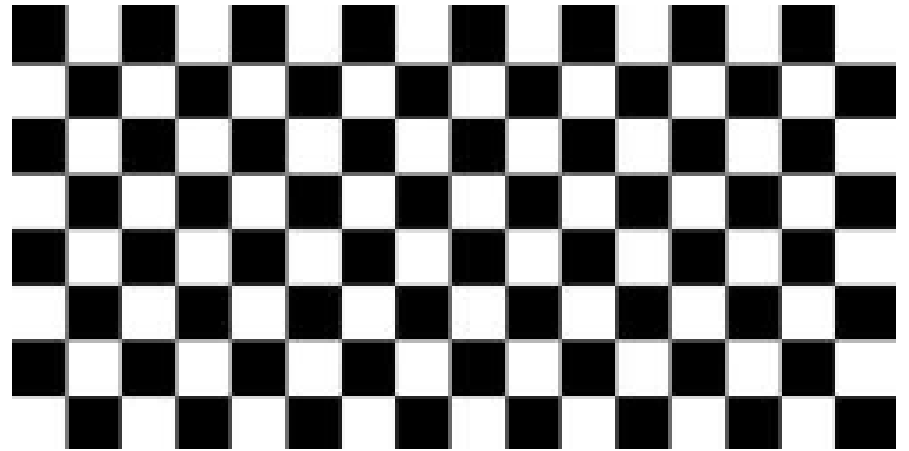
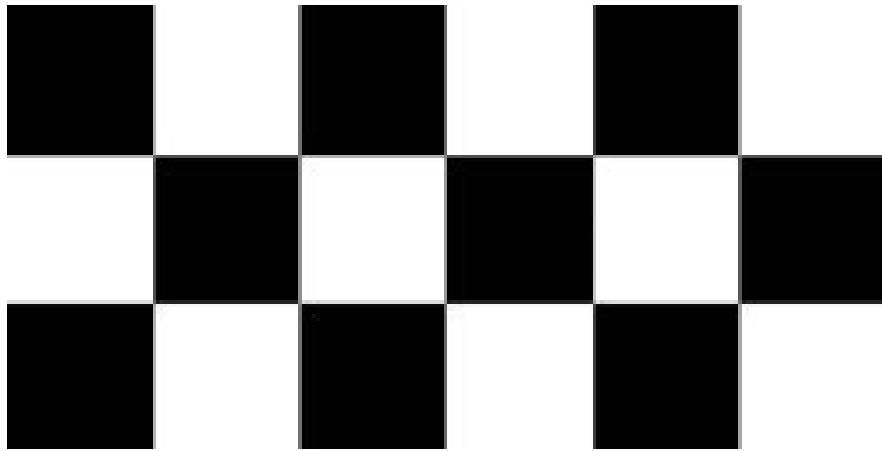
# Impulse train in 2-D



# Aliasing in 2-D



# Spatial examples of aliasing

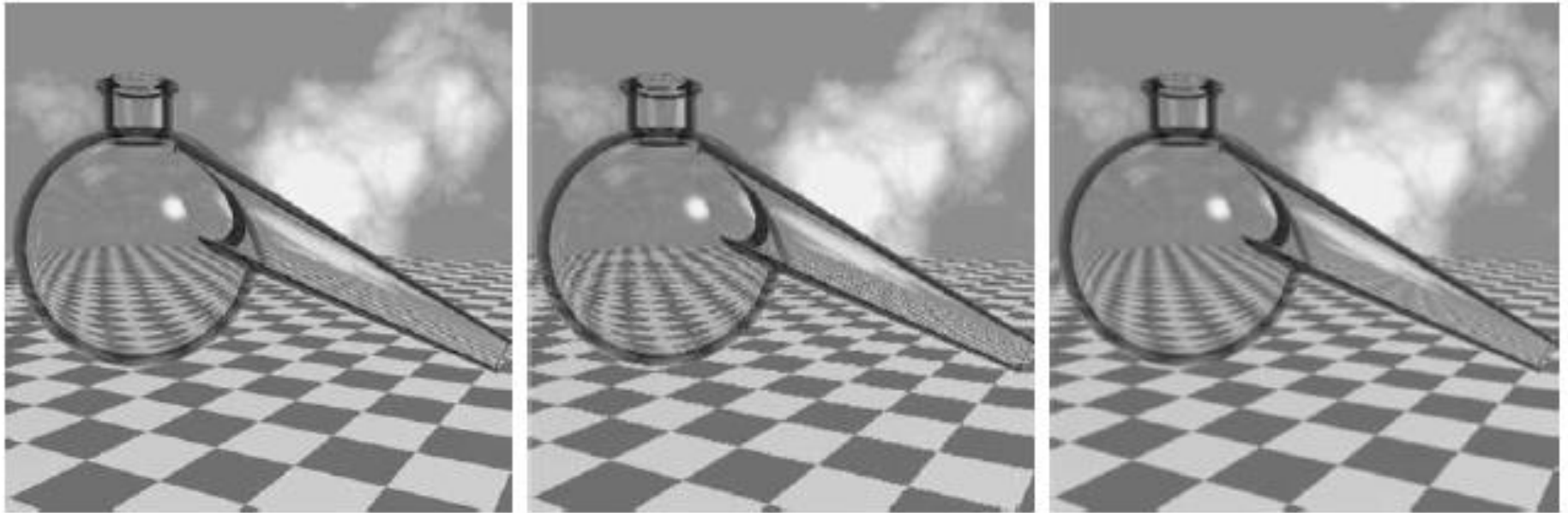




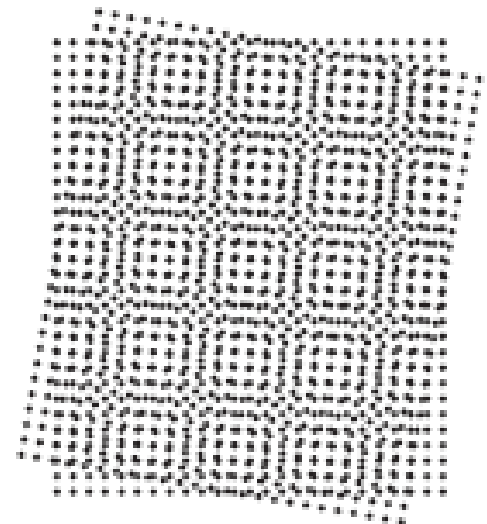
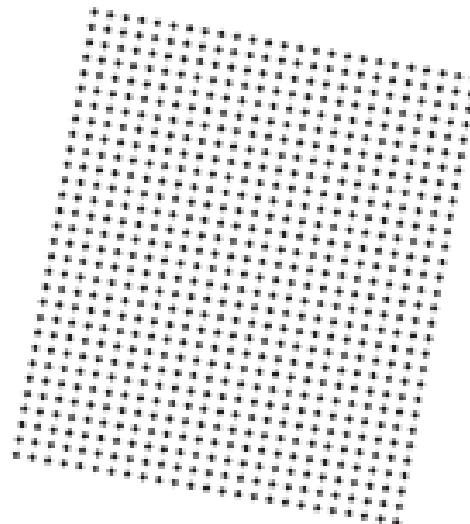
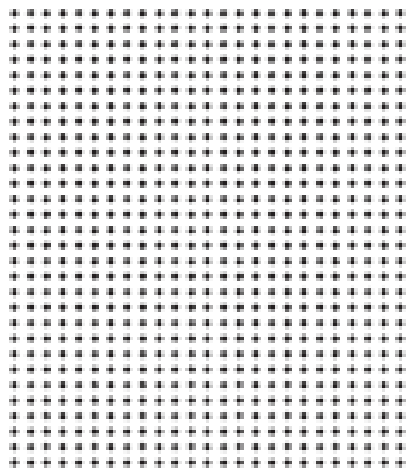
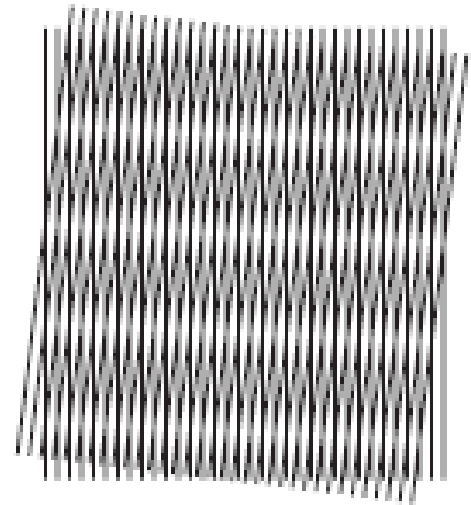
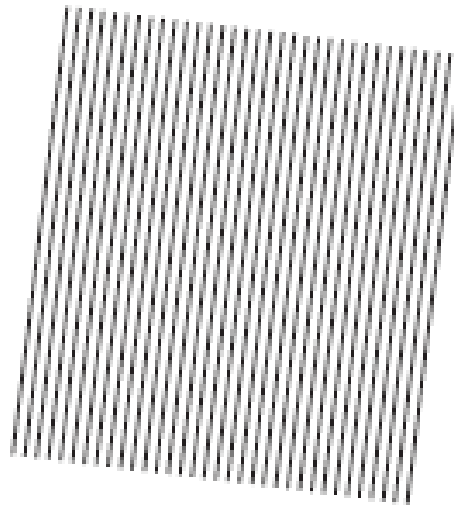
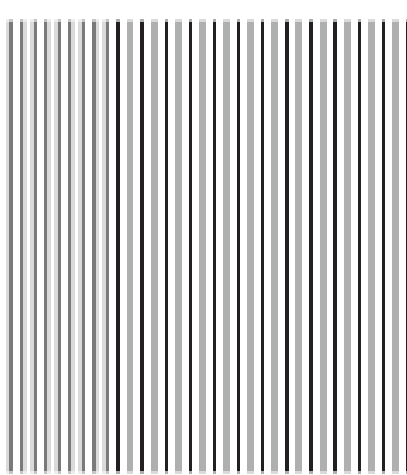
# Aliasing due to reduction of image resolution and anti-aliasing using smoothing



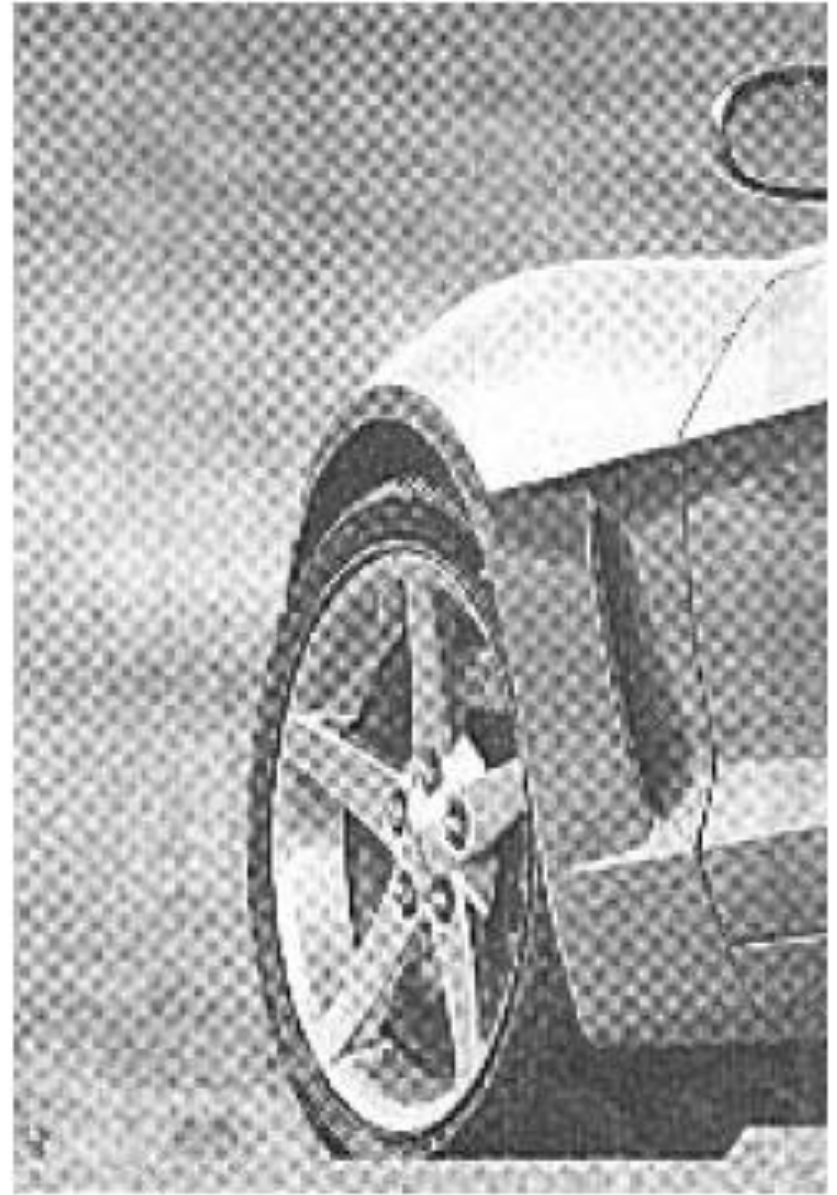
# Jaggies due to aliasing, and anti-aliasing using smoothing



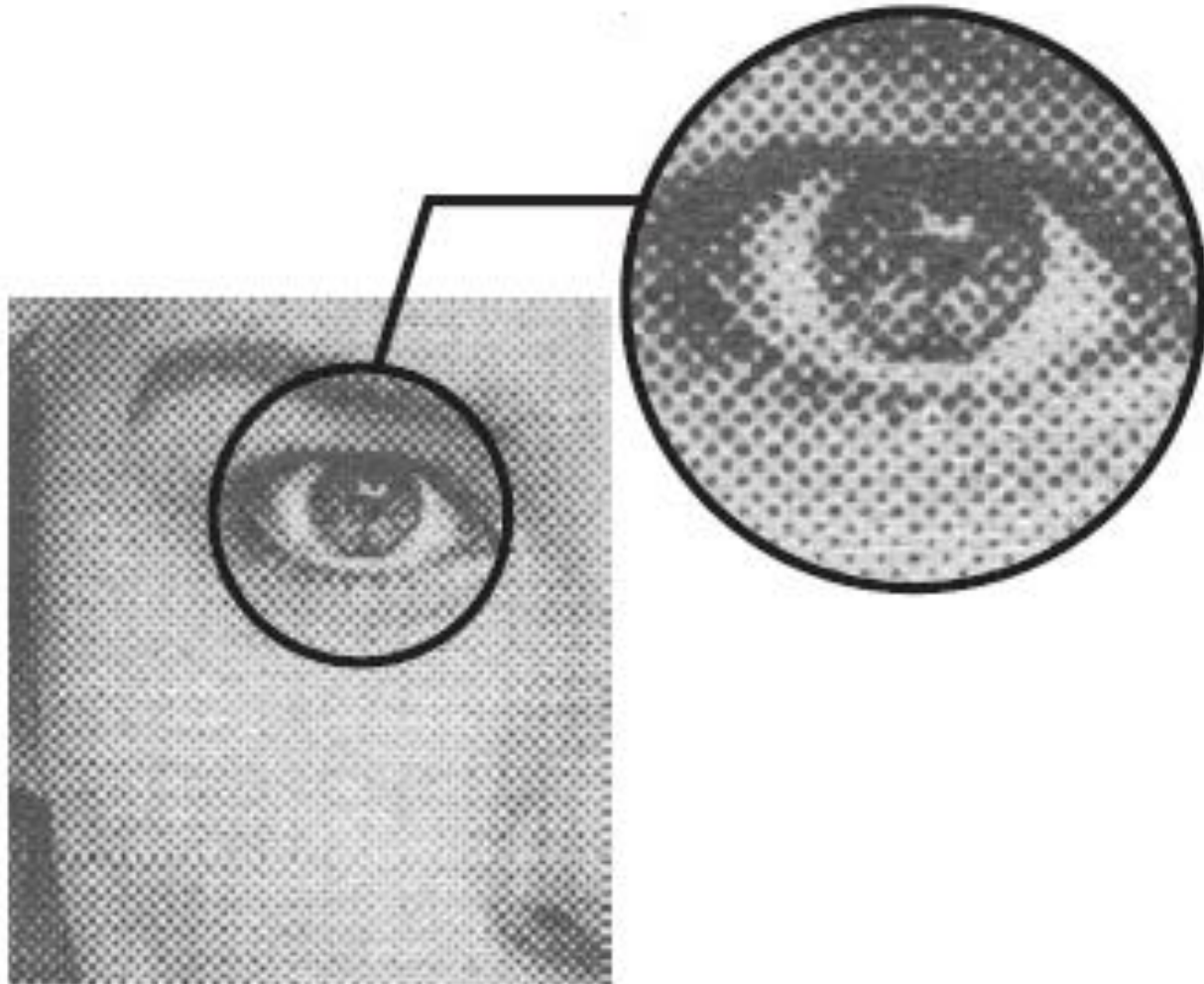
# Moiré effect



Oriented dots  
and Cartesian  
grid create Moiré  
patterns



# Close up of newspaper printing



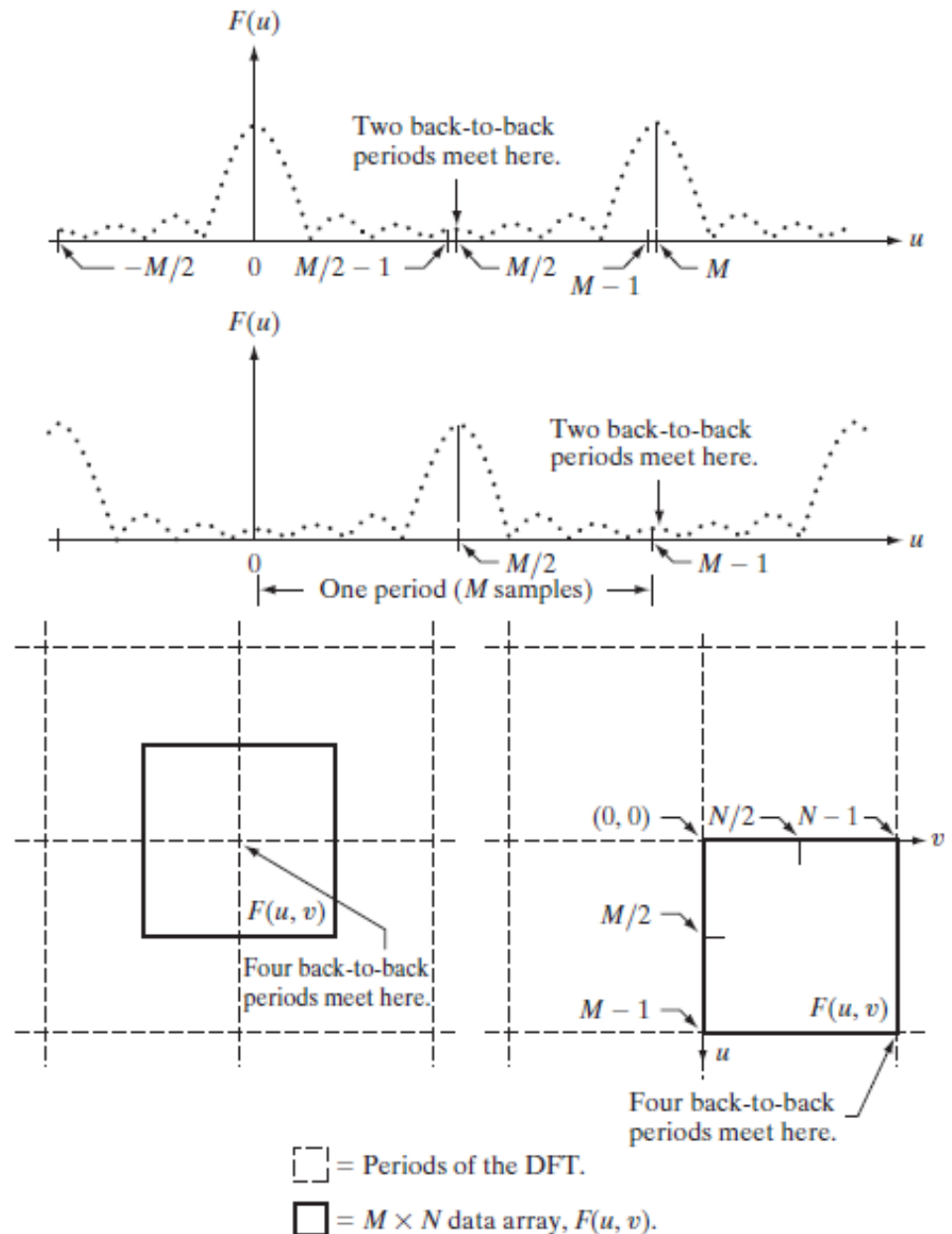
Source: Digital Image Processing, Gonzalez and Woods, Prentice Hall

# DFT in 2-D

$$F(u, v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(ux/M + vy/N)}$$

$$f(x, y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M + vy/N)}$$

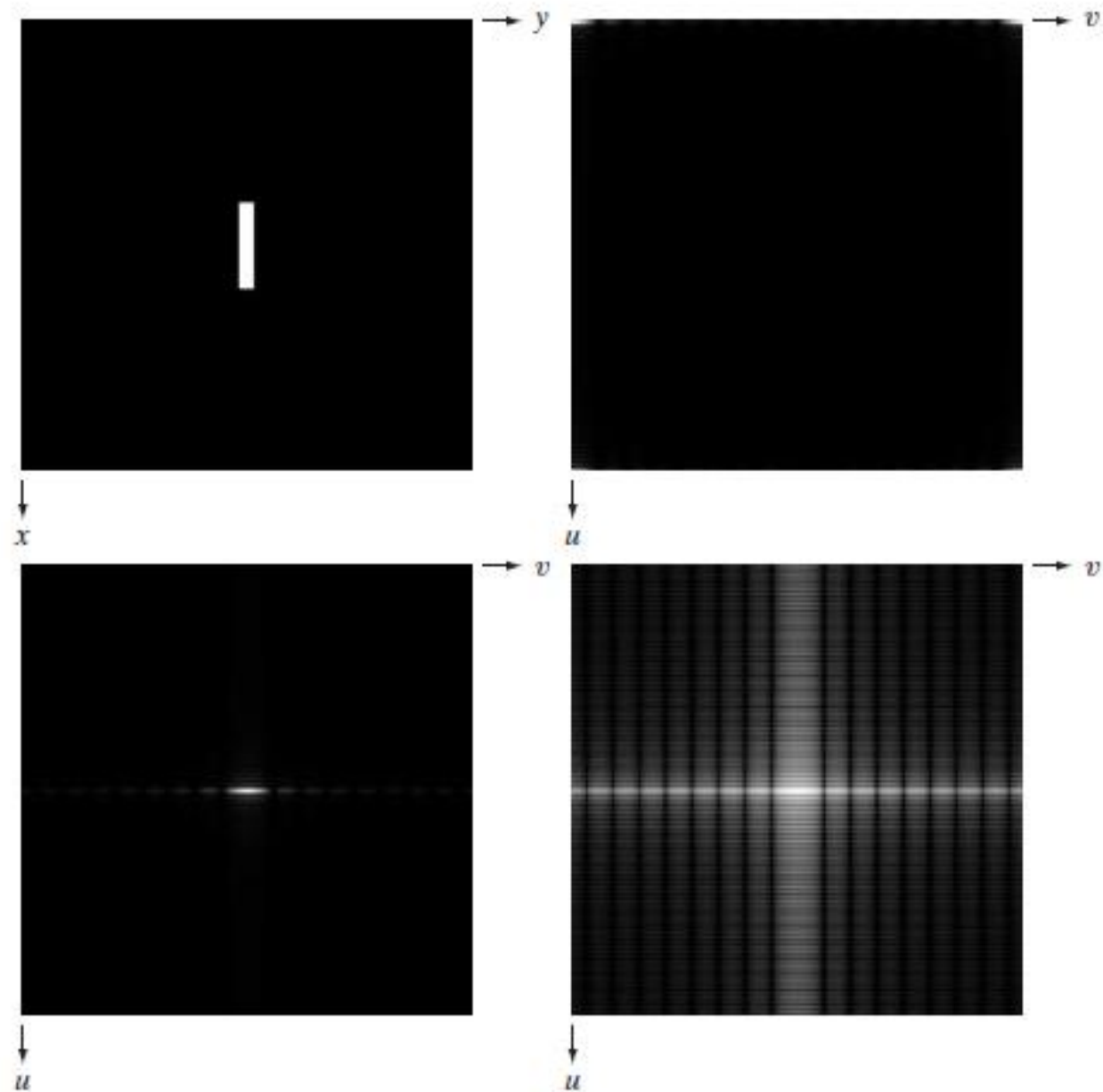
# Representation of DFT



Spatial Domain <sup>†</sup>		Frequency Domain <sup>†</sup>
1)	$f(x, y)$ real	$\Leftrightarrow F^*(u, v) = F(-u, -v)$
2)	$f(x, y)$ imaginary	$\Leftrightarrow F^*(-u, -v) = -F(u, v)$
3)	$f(x, y)$ real	$\Leftrightarrow R(u, v)$ even; $I(u, v)$ odd
4)	$f(x, y)$ imaginary	$\Leftrightarrow R(u, v)$ odd; $I(u, v)$ even
5)	$f(-x, -y)$ real	$\Leftrightarrow F^*(u, v)$ complex
6)	$f(-x, -y)$ complex	$\Leftrightarrow F(-u, -v)$ complex
7)	$f^*(x, y)$ complex	$\Leftrightarrow F^*(-u - v)$ complex
8)	$f(x, y)$ real and even	$\Leftrightarrow F(u, v)$ real and even
9)	$f(x, y)$ real and odd	$\Leftrightarrow F(u, v)$ imaginary and odd
10)	$f(x, y)$ imaginary and even	$\Leftrightarrow F(u, v)$ imaginary and even
11)	$f(x, y)$ imaginary and odd	$\Leftrightarrow F(u, v)$ real and odd
12)	$f(x, y)$ complex and even	$\Leftrightarrow F(u, v)$ complex and even
13)	$f(x, y)$ complex and odd	$\Leftrightarrow F(u, v)$ complex and odd



DFT of a  
bar:  
Original,  
DFT not  
centered,  
centered,  
log Xform

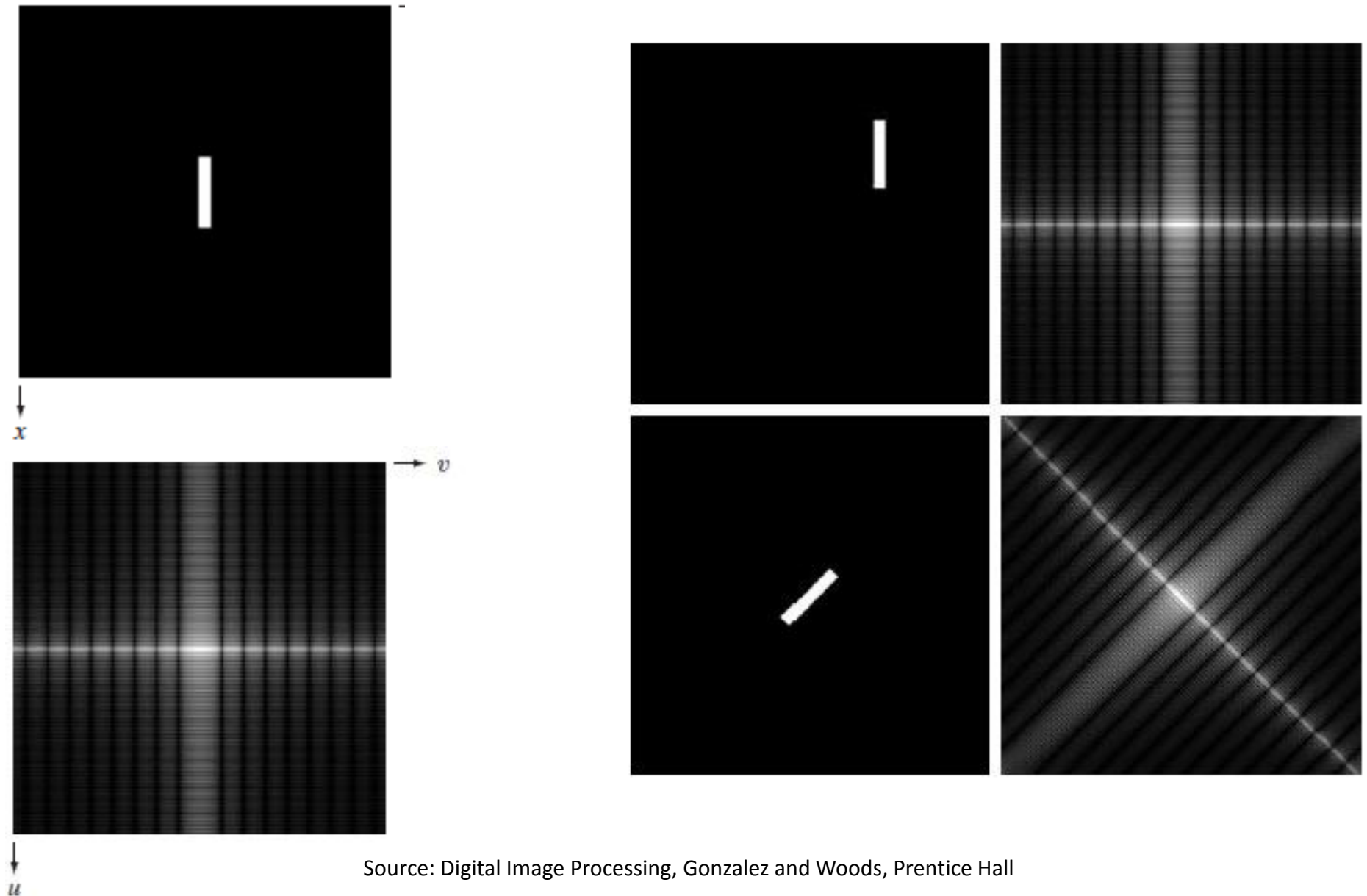


# Rotation and phase shift

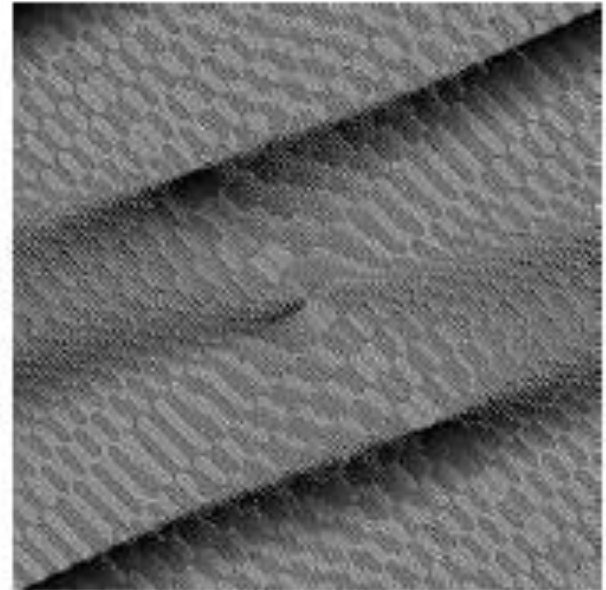
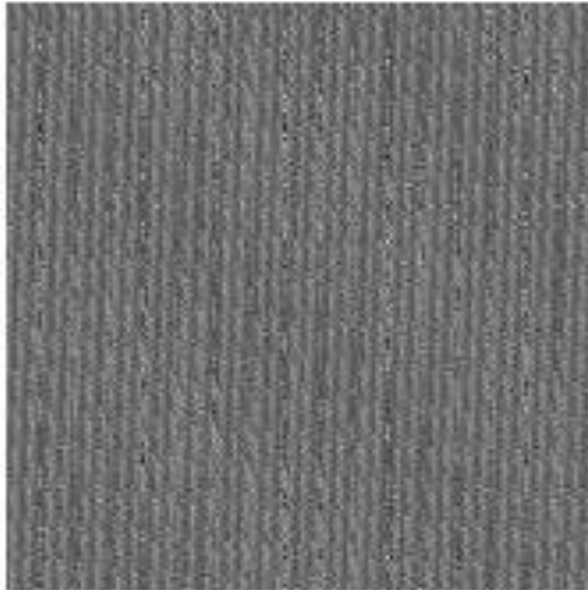
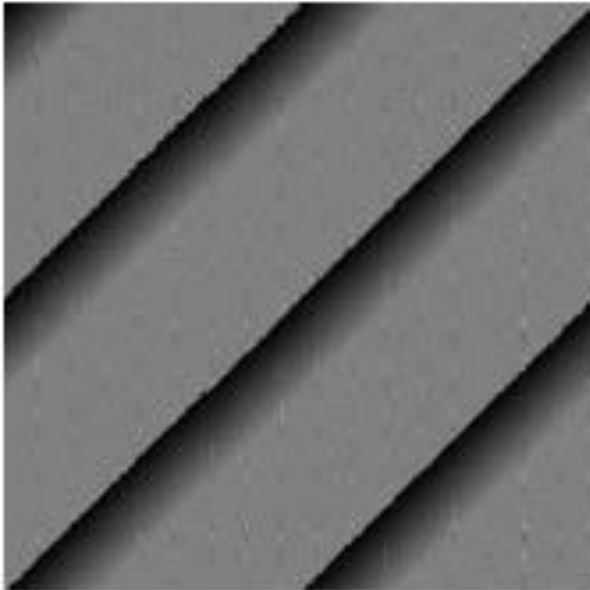
$$f(x, y) e^{j2\pi(u_0 x/M + v_0 y/N)} \Leftrightarrow F(u - u_0, v - v_0)$$

$$f(x - x_0, y - y_0) \Leftrightarrow F(u, v) e^{-j2\pi(x_0 u/M + y_0 v/N)}$$

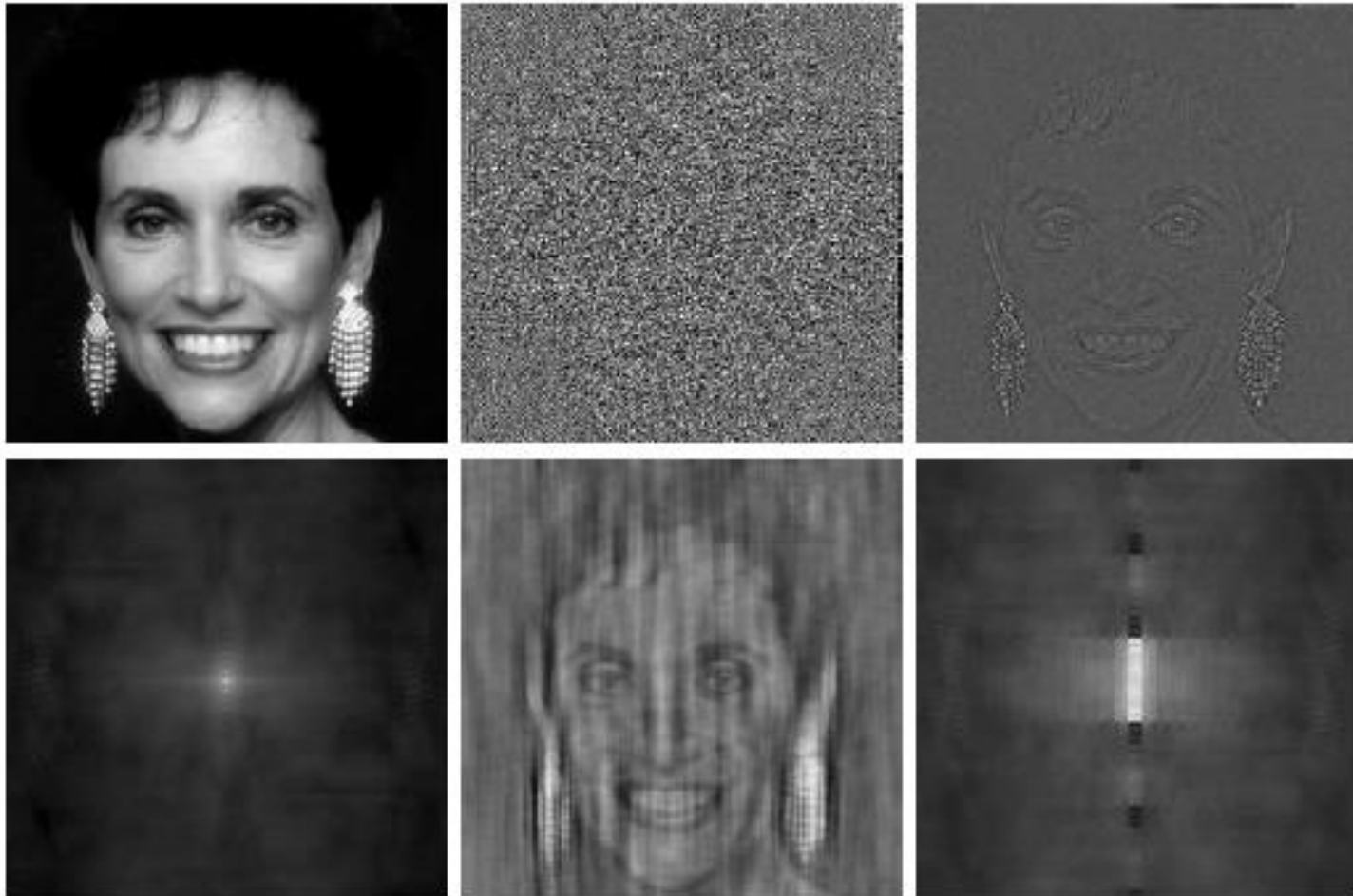
# Visualizing rotation and translation



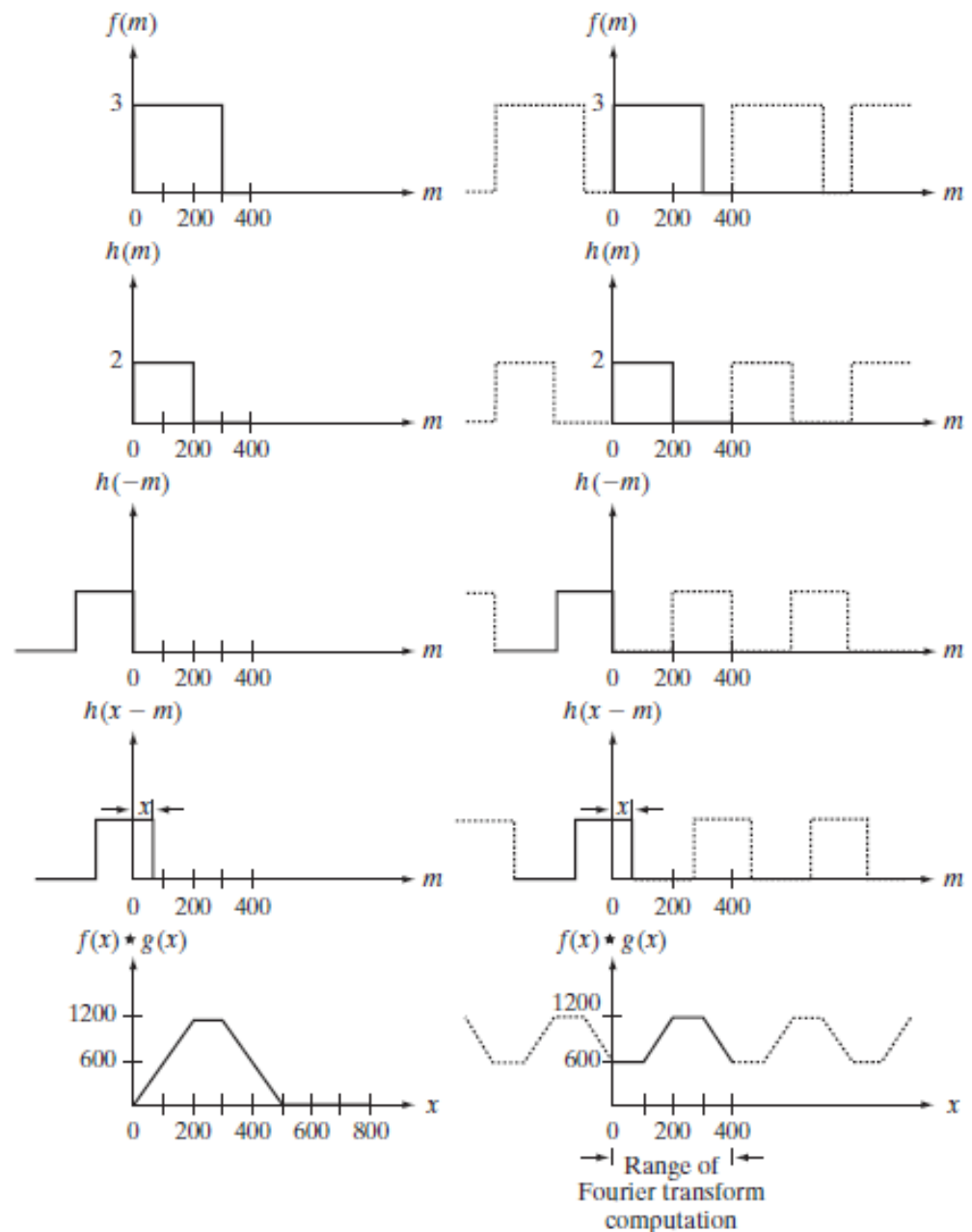
# Phase of original bar, translated, rotated



Importance of phase: Original, phase,  
reconstruction based on: phase, magnitude,  
some other image's magnitude, some other  
image's phase



# Implicit periodicity leads to wraparound



Name	Expression(s)
1) Discrete Fourier transform (DFT) of $f(x, y)$	$F(u, v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(ux/M + vy/N)}$
2) Inverse discrete Fourier transform (IDFT) of $F(u, v)$	$f(x, y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M + vy/N)}$
3) Polar representation	$F(u, v) =  F(u, v)  e^{j\phi(u, v)}$
4) Spectrum	$ F(u, v)  = [R^2(u, v) + I^2(u, v)]^{1/2}$ $R = \text{Real}(F); \quad I = \text{Imag}(F)$
5) Phase angle	$\phi(u, v) = \tan^{-1} \left[ \frac{I(u, v)}{R(u, v)} \right]$
6) Power spectrum	$P(u, v) =  F(u, v) ^2$
7) Average value	$\bar{f}(x, y) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) = \frac{1}{MN} F(0, 0)$

(Continued)

Name	Expression(s)
8) Periodicity ( $k_1$ and $k_2$ are integers)	$F(u, v) = F(u + k_1M, v) = F(u, v + k_2N)$ $= F(u + k_1M, v + k_2N)$ $f(x, y) = f(x + k_1M, y) = f(x, y + k_2N)$ $= f(x + k_1M, y + k_2N)$
9) Convolution	$f(x, y) \star h(x, y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} f(m, n)h(x - m, y - n)$
10) Correlation	$f(x, y) \star h(x, y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} f^*(m, n)h(x + m, y + n)$
11) Separability	The 2-D DFT can be computed by computing 1-D DFT transforms along the rows (columns) of the image, followed by 1-D transforms along the columns (rows) of the result. See Section 4.11.1.
12) Obtaining the inverse Fourier transform using a forward transform algorithm.	$MNf^*(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F^*(u, v)e^{-j2\pi(ux/M+vy/N)}$ <p>This equation indicates that inputting <math>F^*(u, v)</math> into an algorithm that computes the forward transform (right side of above equation) yields <math>MNf^*(x, y)</math>. Taking the complex conjugate and dividing by <math>MN</math> gives the desired inverse. See Section 4.11.2.</p>

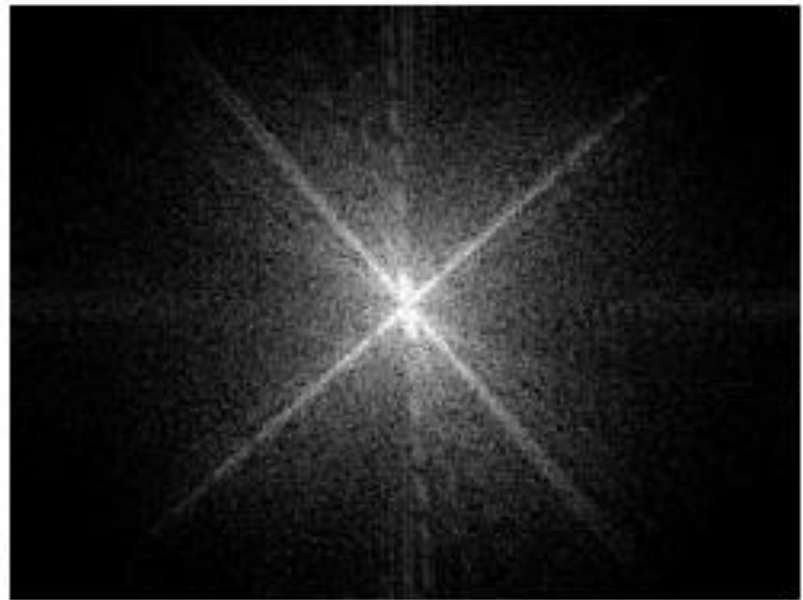
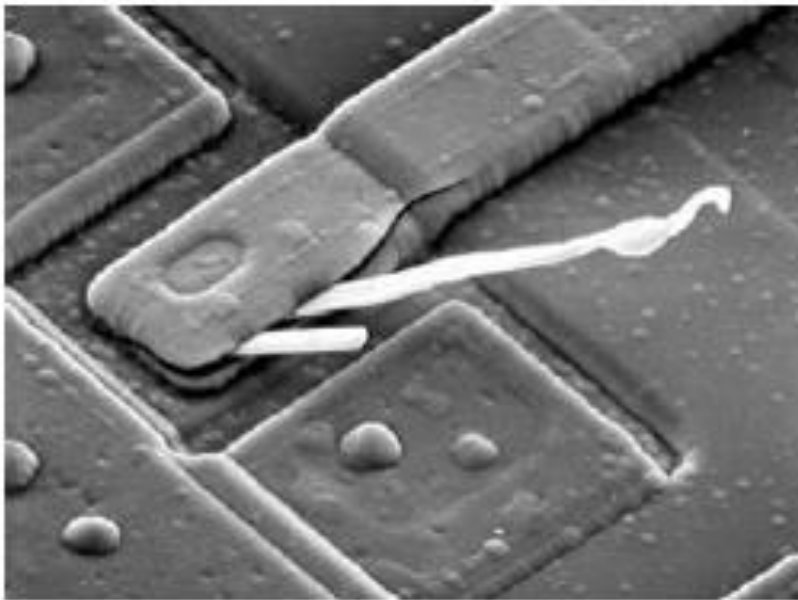


Name	DFT Pairs
1) Symmetry properties	See Table 4.1
2) Linearity	$af_1(x, y) + bf_2(x, y) \Leftrightarrow aF_1(u, v) + bF_2(u, v)$
3) Translation (general)	$f(x, y)e^{j2\pi(u_0x/M+v_0y/N)} \Leftrightarrow F(u - u_0, v - v_0)$ $f(x - x_0, y - y_0) \Leftrightarrow F(u, v)e^{-j2\pi(ux_0/M+vy_0/N)}$
4) Translation to center of the frequency rectangle, $(M/2, N/2)$	$f(x, y)(-1)^{x+y} \Leftrightarrow F(u - M/2, v - N/2)$ $f(x - M/2, y - N/2) \Leftrightarrow F(u, v)(-1)^{u+v}$
5) Rotation	$f(r, \theta + \theta_0) \Leftrightarrow F(\omega, \varphi + \theta_0)$ $x = r \cos \theta \quad y = r \sin \theta \quad u = \omega \cos \varphi \quad v = \omega \sin \varphi$
6) Convolution theorem <sup>†</sup>	$f(x, y) \star h(x, y) \Leftrightarrow F(u, v)H(u, v)$ $f(x, y)h(x, y) \Leftrightarrow F(u, v) \star H(u, v)$

(Continued)

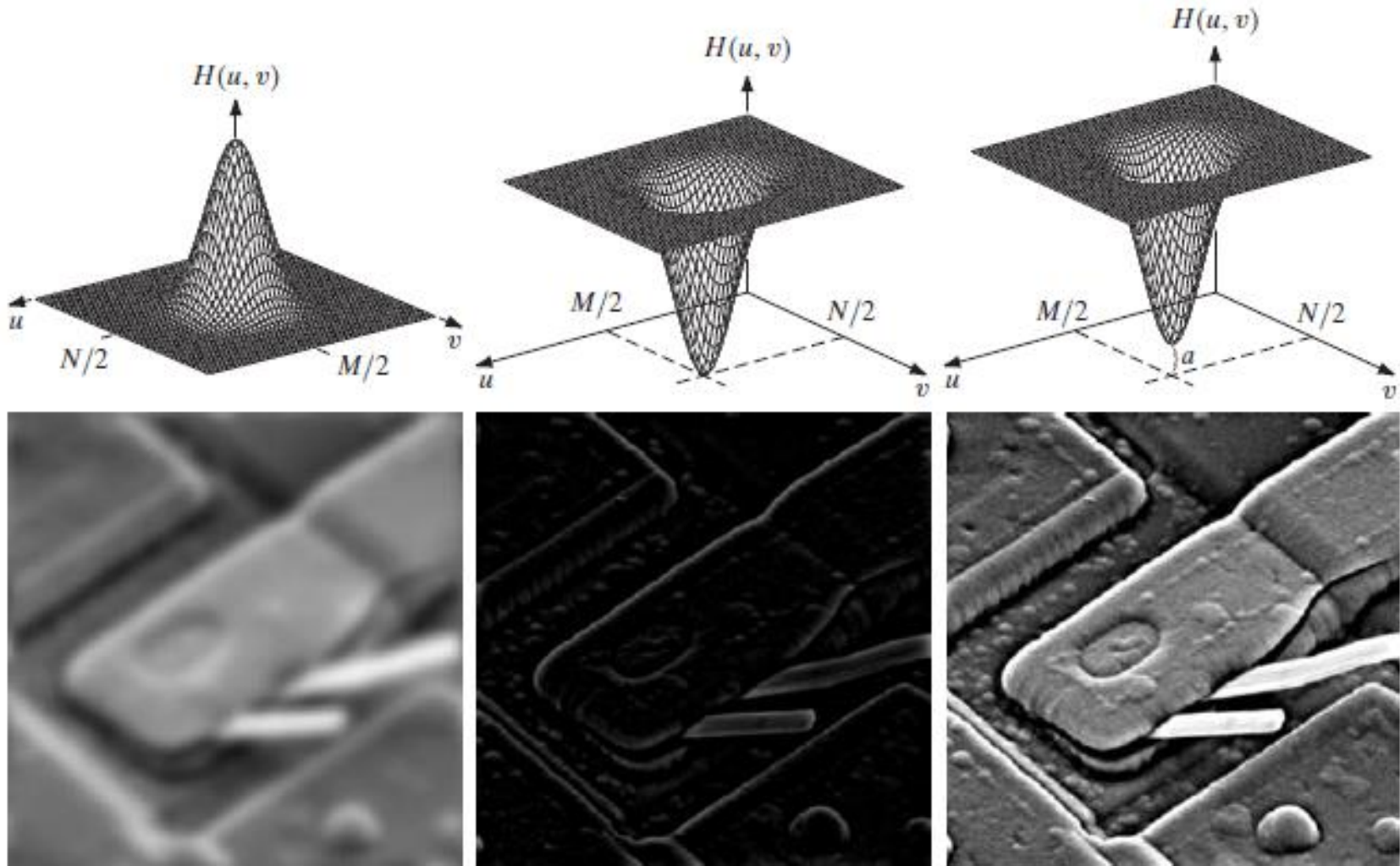
Name	DFT Pairs
7) Correlation theorem <sup>†</sup>	$f(x, y) \star h(x, y) \Leftrightarrow F^*(u, v) H(u, v)$ $f^*(x, y) h(x, y) \Leftrightarrow F(u, v) \star H(u, v)$
8) Discrete unit impulse	$\delta(x, y) \Leftrightarrow 1$
9) Rectangle	$\text{rect}[a, b] \Leftrightarrow ab \frac{\sin(\pi ua)}{(\pi ua)} \frac{\sin(\pi vb)}{(\pi vb)} e^{-j\pi(ua+vb)}$
10) Sine	$\sin(2\pi u_0 x + 2\pi v_0 y) \Leftrightarrow$ $j \frac{1}{2} [\delta(u + Mu_0, v + Nv_0) - \delta(u - Mu_0, v - Nv_0)]$
11) Cosine	$\cos(2\pi u_0 x + 2\pi v_0 y) \Leftrightarrow$ $\frac{1}{2} [\delta(u + Mu_0, v + Nv_0) + \delta(u - Mu_0, v - Nv_0)]$
<p>The following Fourier transform pairs are derivable only for continuous variables, denoted as before by <math>t</math> and <math>z</math> for spatial variables and by <math>\mu</math> and <math>\nu</math> for frequency variables. These results can be used for DFT work by sampling the continuous forms.</p>	
12) Differentiation (The expressions on the right assume that $f(\pm\infty, \pm\infty) = 0$ .)	$\left(\frac{\partial}{\partial t}\right)^m \left(\frac{\partial}{\partial z}\right)^n f(t, z) \Leftrightarrow (j2\pi\mu)^m (j2\pi\nu)^n F(\mu, \nu)$ $\frac{\partial^m f(t, z)}{\partial t^m} \Leftrightarrow (j2\pi\mu)^m F(\mu, \nu); \frac{\partial^n f(t, z)}{\partial z^n} \Leftrightarrow (j2\pi\nu)^n F(\mu, \nu)$
13) Gaussian	$A 2\pi\sigma^2 e^{-2\pi^2\sigma^2(t^2+z^2)} \Leftrightarrow A e^{-(\mu^2+\nu^2)/2\sigma^2} \quad (A \text{ is a constant})$

<sup>†</sup>Assumes that the functions have been extended by zero padding. Convolution and correlation are associative, commutative, and distributive.

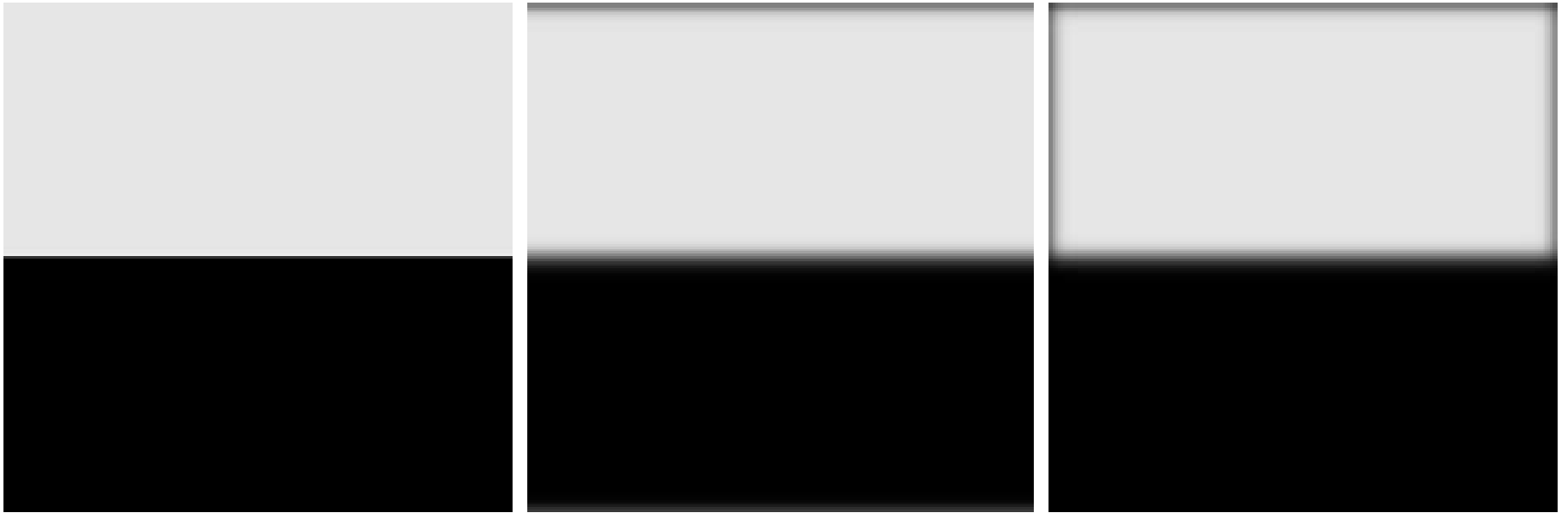


# Filtering in frequency domain

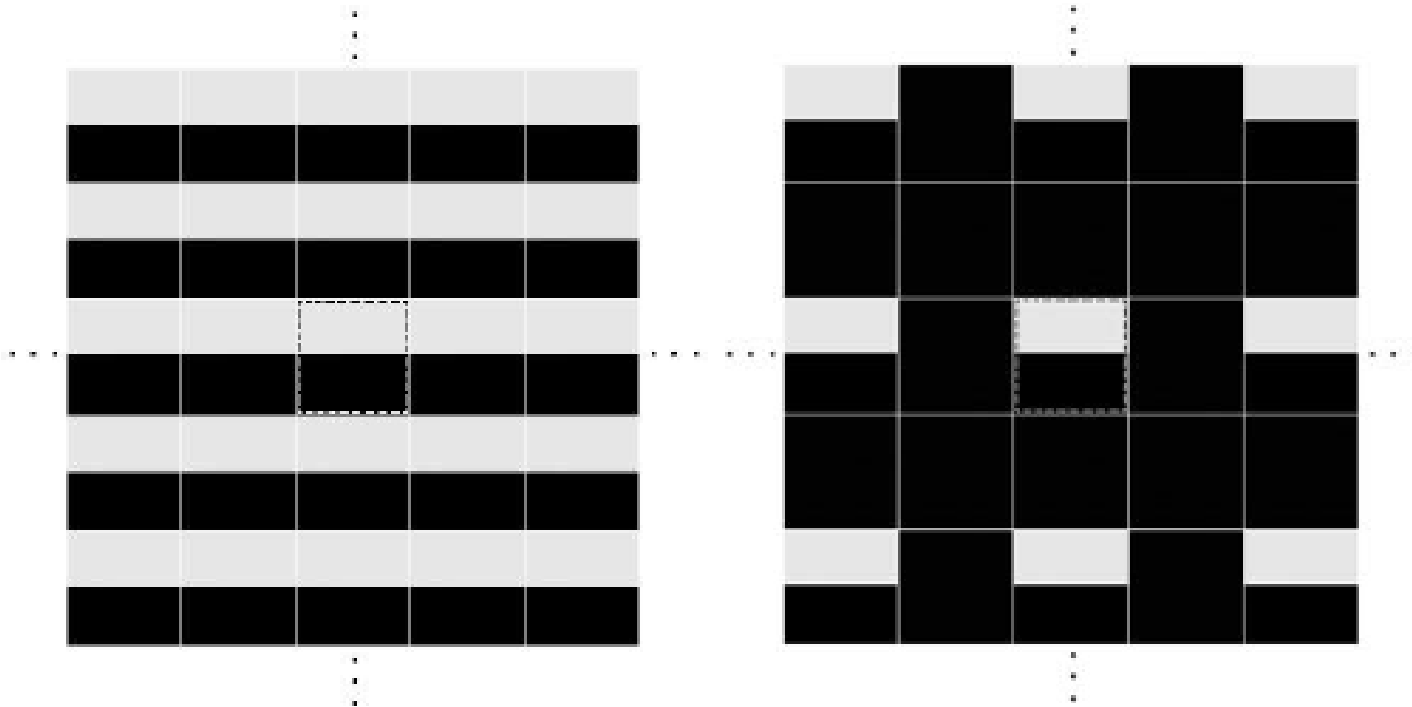
$$g(x, y) = \mathcal{F}^{-1}[H(u, v)F(u, v)]$$



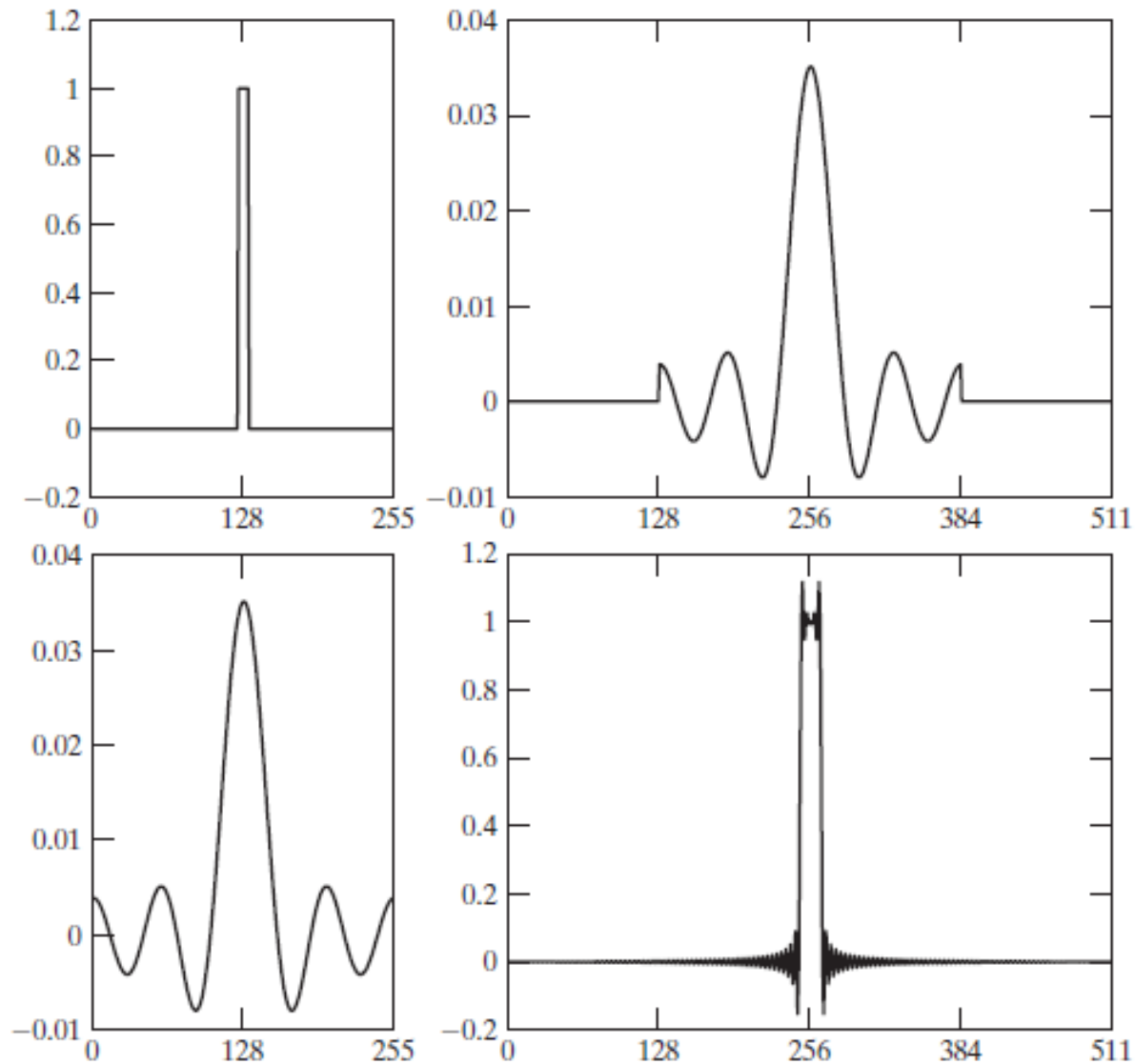
# Effect of wraparound and zero padding



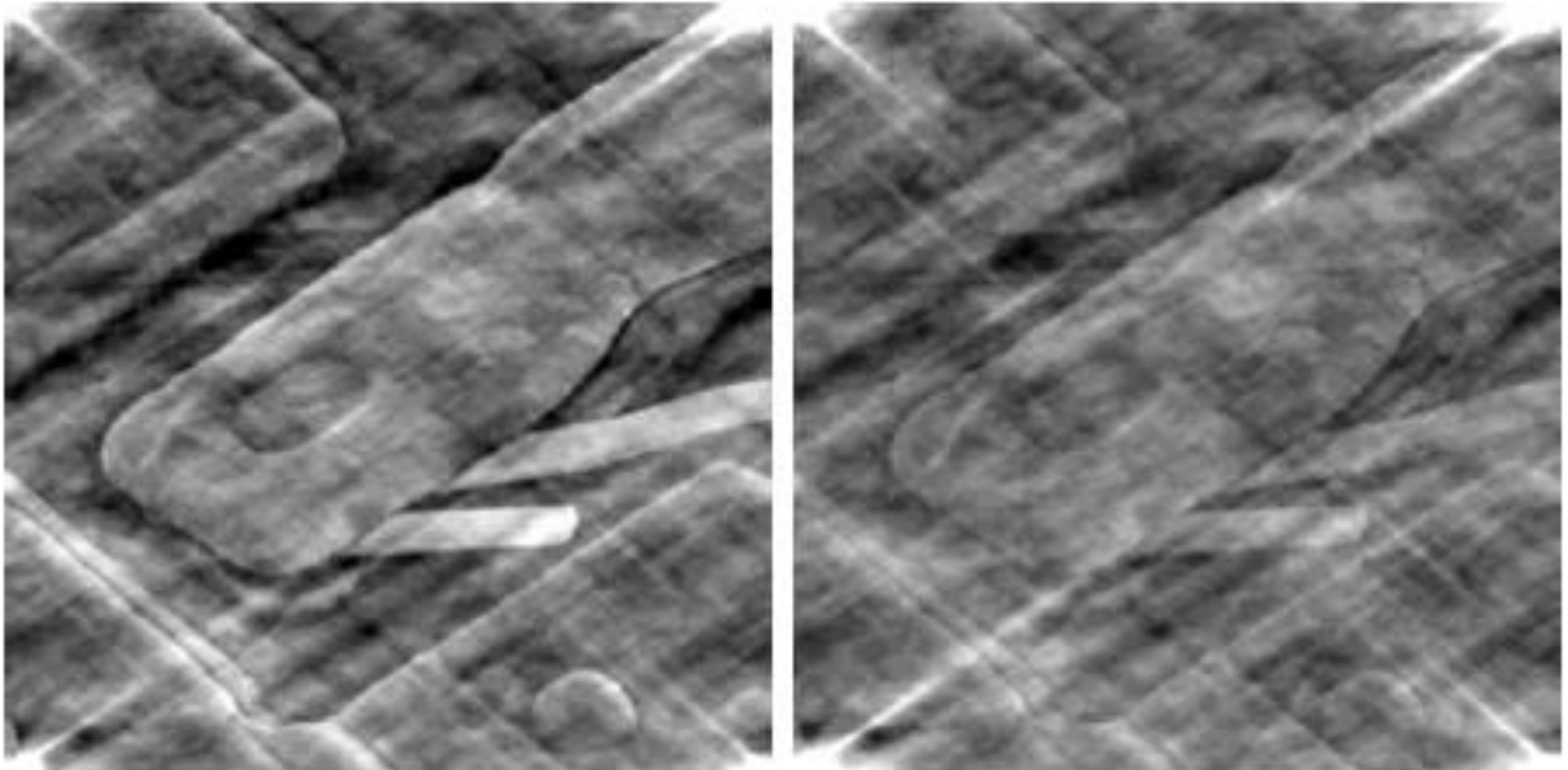
# Implicit periodicity without and with zero padding



One cannot  
work with  
ideal  
frequency  
cut-offs and  
avoiding  
wraparound  
errors



# Importance of phase – Multiplying phase with 0.5 and 0.25; and zero phase shift filters



$$g(x, y) = \mathfrak{F}^{-1} \left[ H(u, v) R(u, v) + j H(u, v) I(u, v) \right]$$



# Summary of frequency filtering

1. Given an input image  $f(x, y)$  of size  $M \times N$ , obtain the padding parameters  $P$  and  $Q$  from Eqs. (4.6-31) and (4.6-32). Typically, we select  $P = 2M$  and  $Q = 2N$ .
2. Form a padded image,  $f_p(x, y)$ , of size  $P \times Q$  by appending the necessary number of zeros to  $f(x, y)$ .
3. Multiply  $f_p(x, y)$  by  $(-1)^{x+y}$  to center its transform.
4. Compute the DFT,  $F(u, v)$ , of the image from step 3.
5. Generate a real, symmetric filter function,  $H(u, v)$ , of size  $P \times Q$  with center at coordinates  $(P/2, Q/2)$ .<sup>†</sup> Form the product  $G(u, v) = H(u, v)F(u, v)$  using array multiplication; that is,  $G(i, k) = H(i, k)F(i, k)$ .
6. Obtain the processed image:

$$g_p(x, y) = \left\{ \text{real} \left[ \mathfrak{F}^{-1} [G(u, v)] \right] \right\} (-1)^{x+y}$$

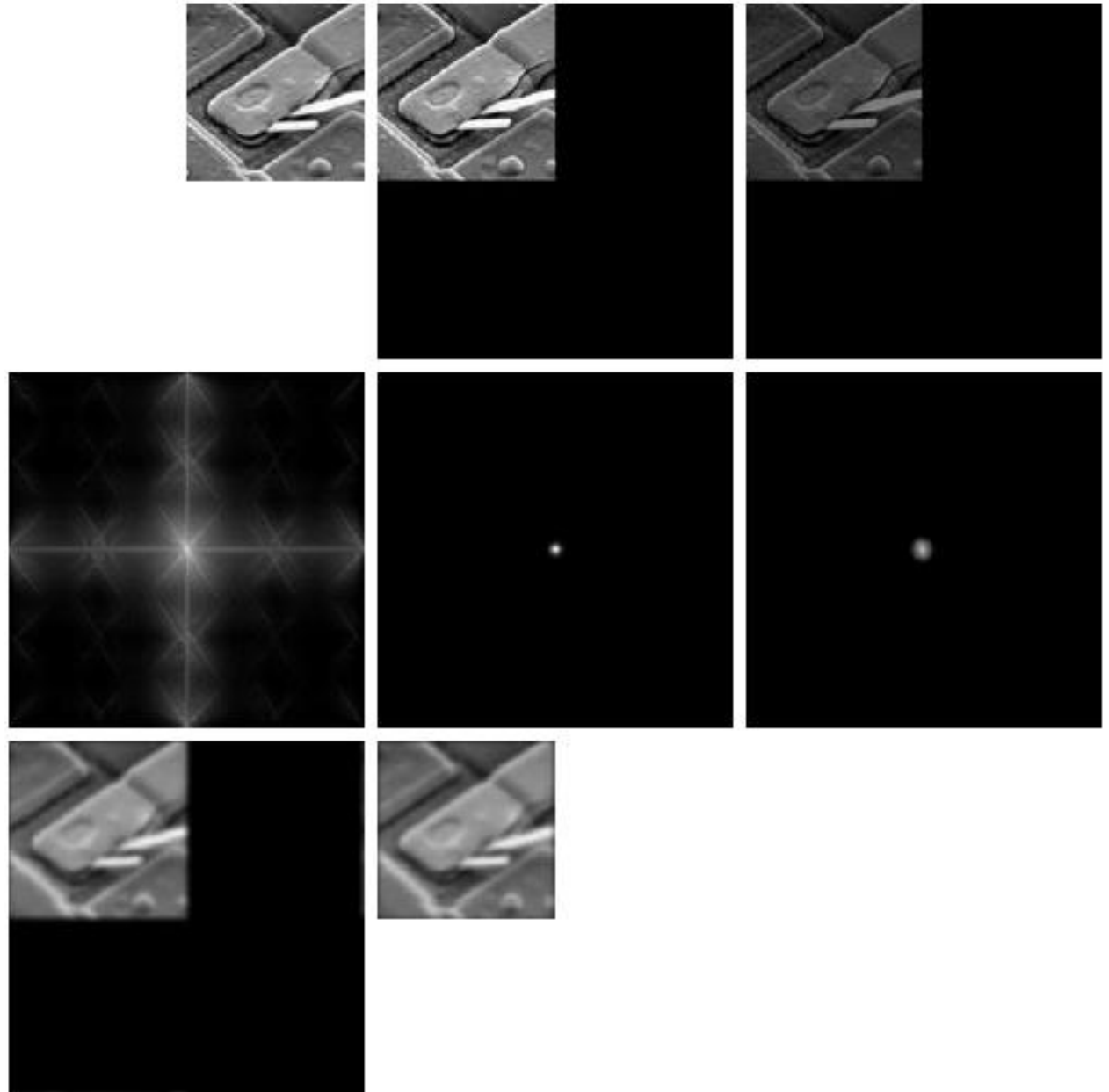
where the real part is selected in order to ignore parasitic complex components resulting from computational inaccuracies, and the subscript  $p$  indicates that we are dealing with padded arrays.

7. Obtain the final processed result,  $g(x, y)$ , by extracting the  $M \times N$  region from the top, left quadrant of  $g_p(x, y)$ .

# Example

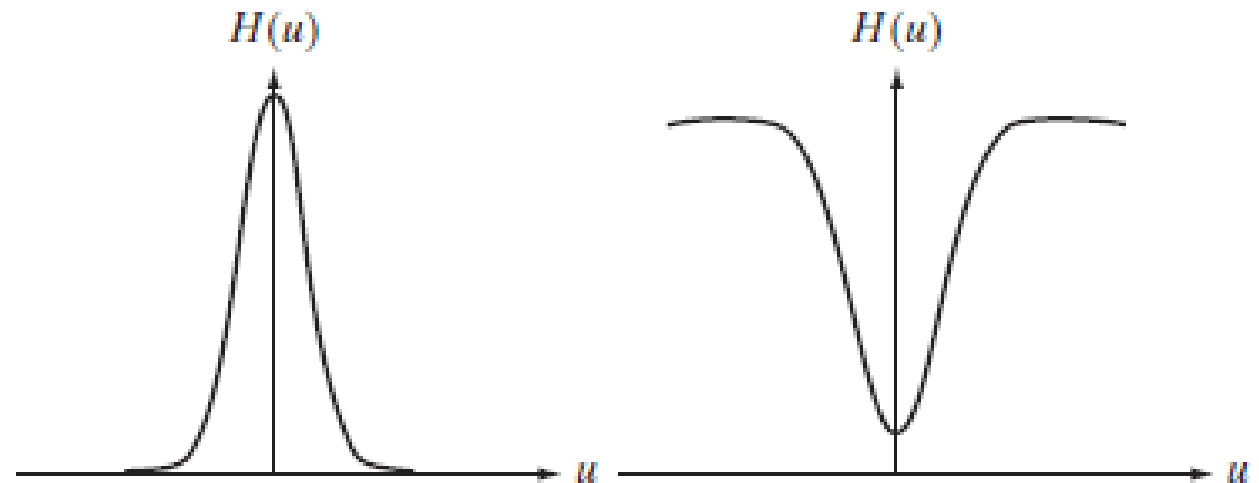
**FIGURE 4.36**

- (a) An  $M \times N$  image,  $f$ .
- (b) Padded image,  $f_p$  of size  $P \times Q$ .
- (c) Result of multiplying  $f_p$  by  $(-1)^{x+y}$ .
- (d) Spectrum of  $F_p$ .
- (e) Centered Gaussian lowpass filter,  $H$ , of size  $P \times Q$ .
- (f) Spectrum of the product  $HF_p$ .
- (g)  $g_p$ , the product of  $(-1)^{x+y}$  and the real part of the IDFT of  $HF_p$ .
- (h) Final result,  $g$ , obtained by cropping the first  $M$  rows and  $N$  columns of  $g_p$ .

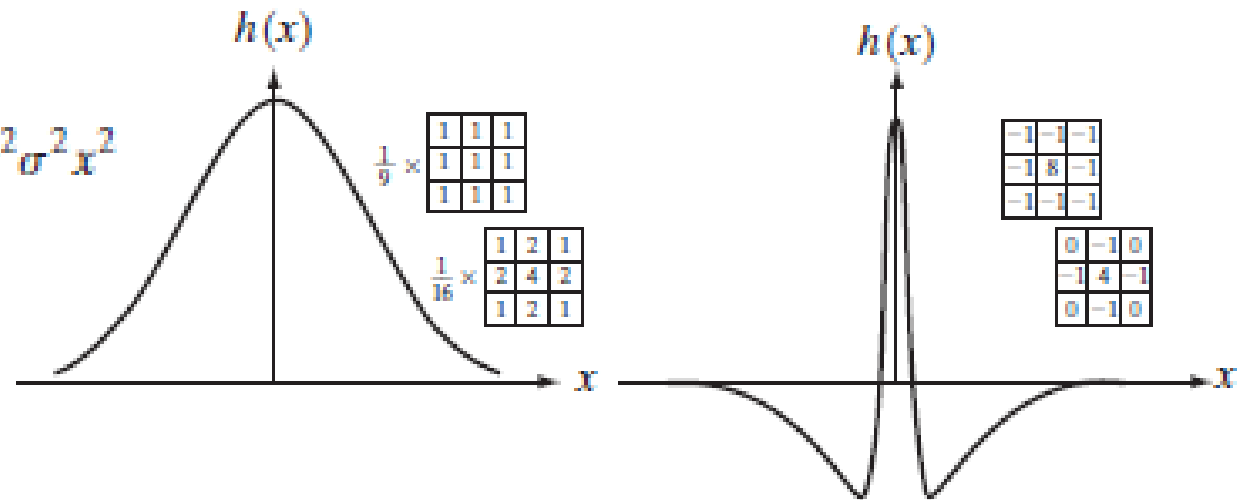


# Filtering using Gaussian filters

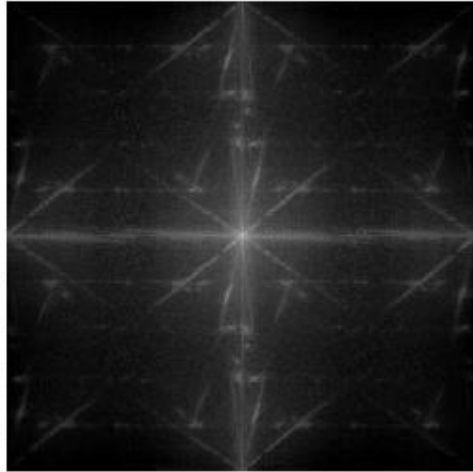
$$H(u) = A e^{-u^2/2\sigma^2}$$



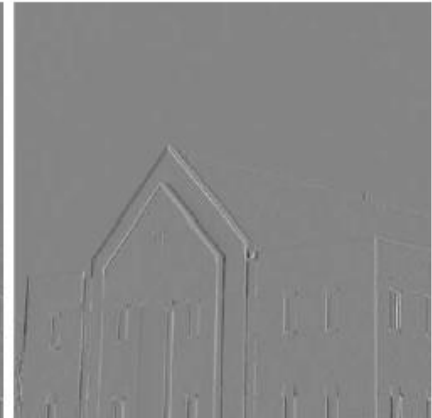
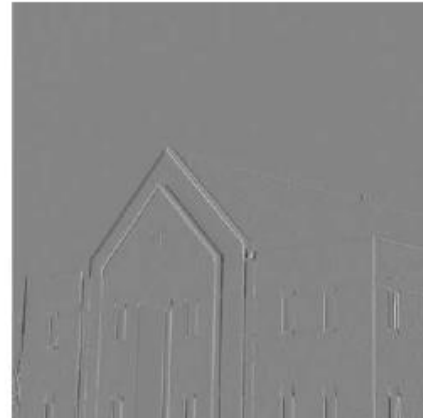
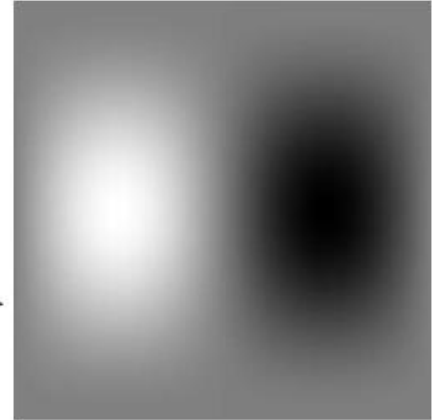
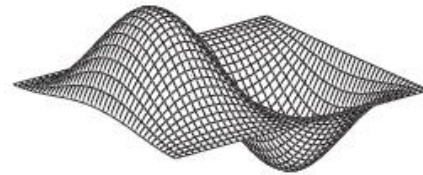
$$h(x) = \sqrt{2\pi}\sigma A e^{-2\pi^2\sigma^2 x^2}$$



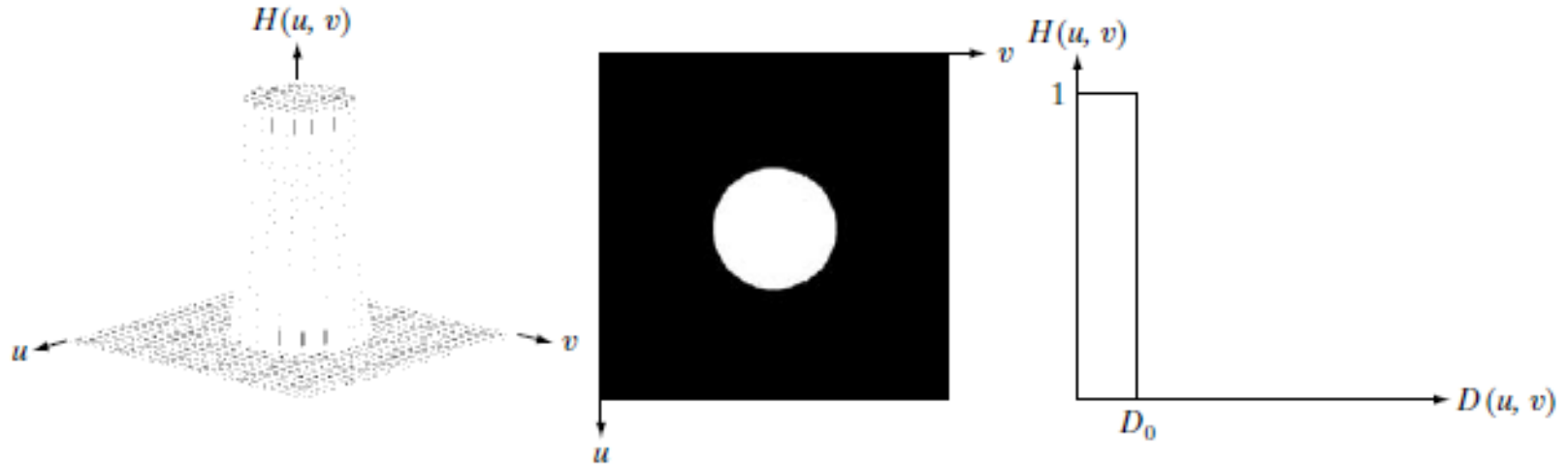
# Equivalence of spatial and frequency filtering



-1	0	1
-2	0	2
-1	0	1

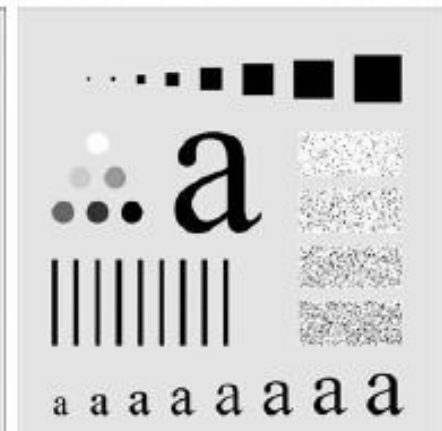
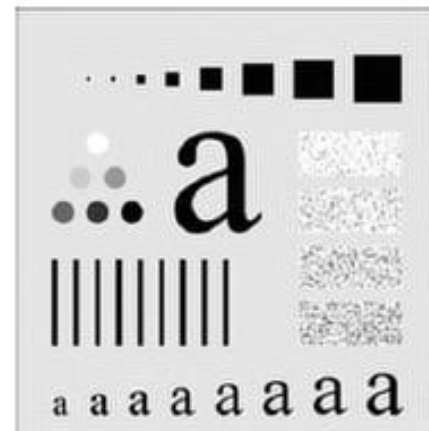
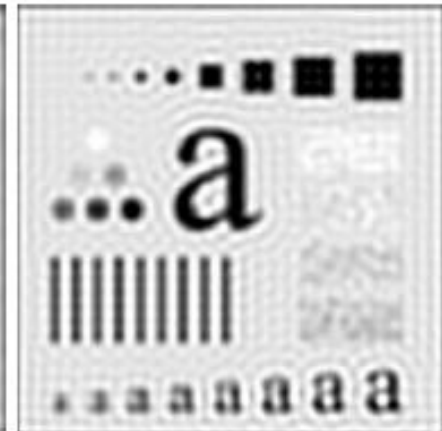
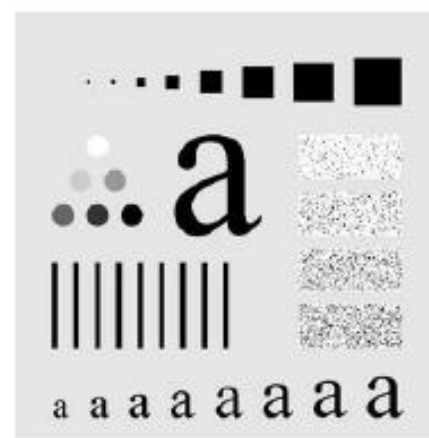
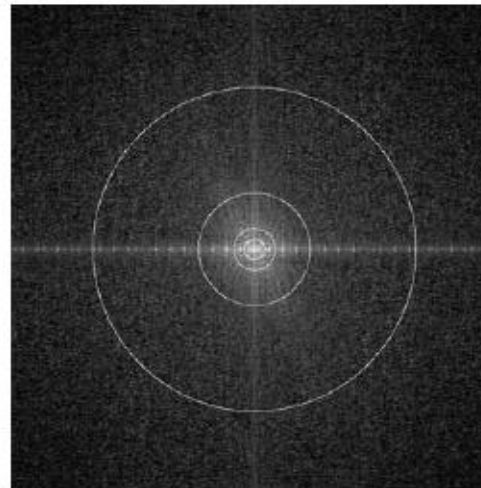
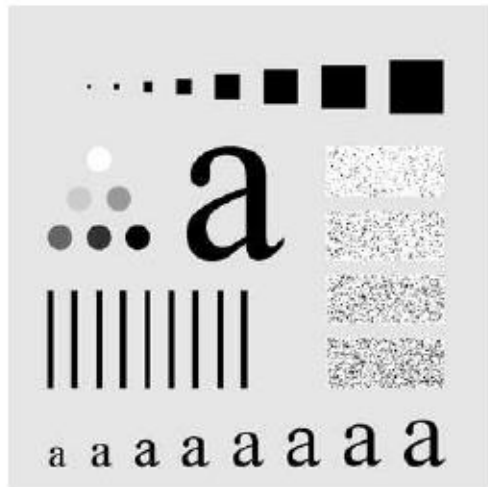


# An ideal low pass filter

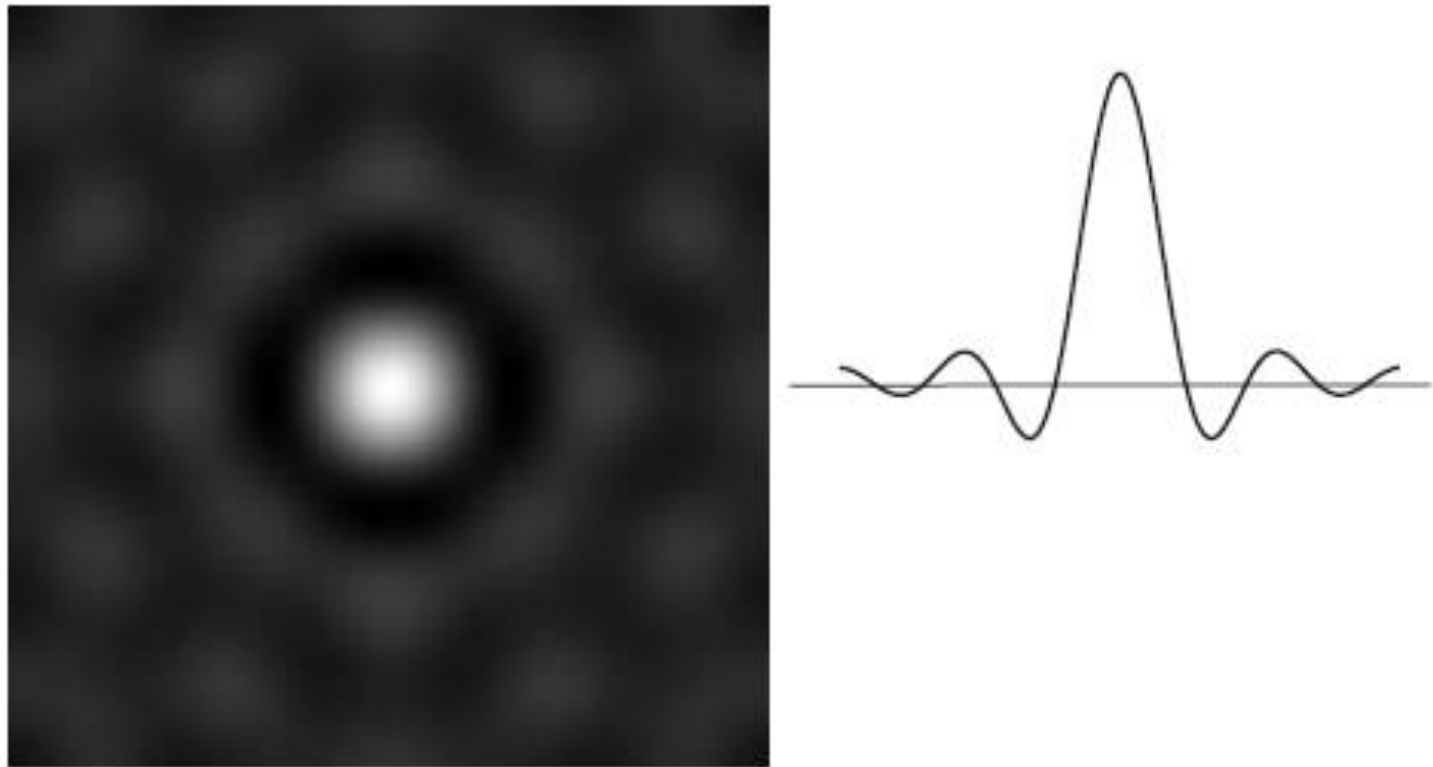


$$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases} \quad D(u, v) = \left[ (u - P/2)^2 + (v - Q/2)^2 \right]^{1/2}$$

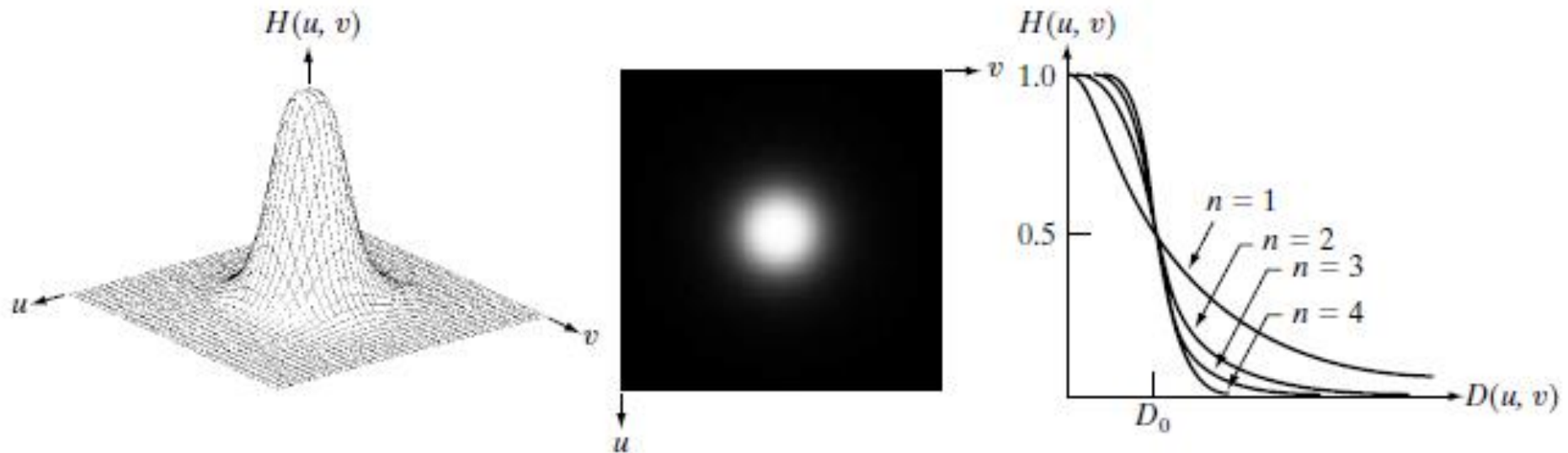
Results of  
ILPF; notice  
the ringing



# Spatial domain ILPF shows where ringing comes from



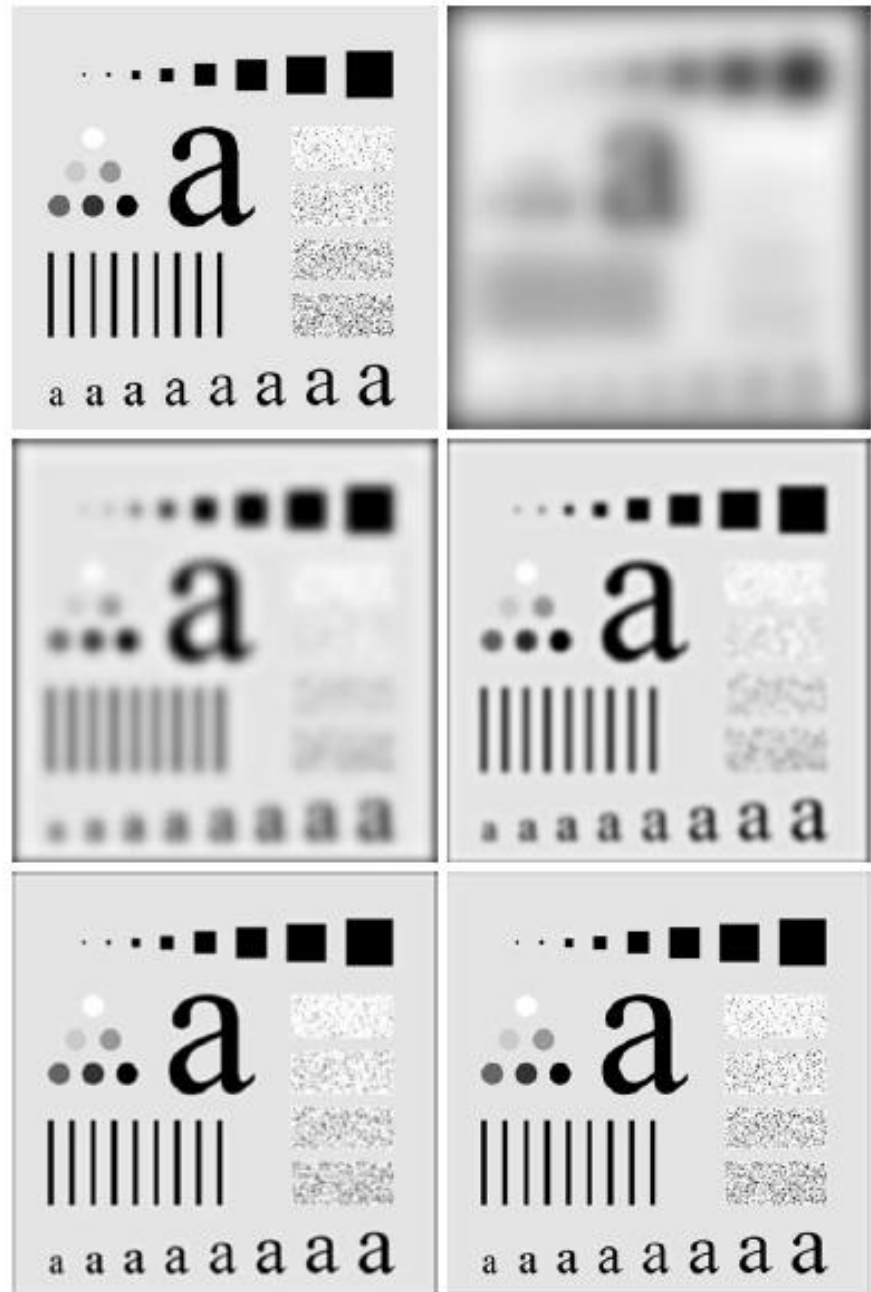
# Butterworth filters reduce ringing



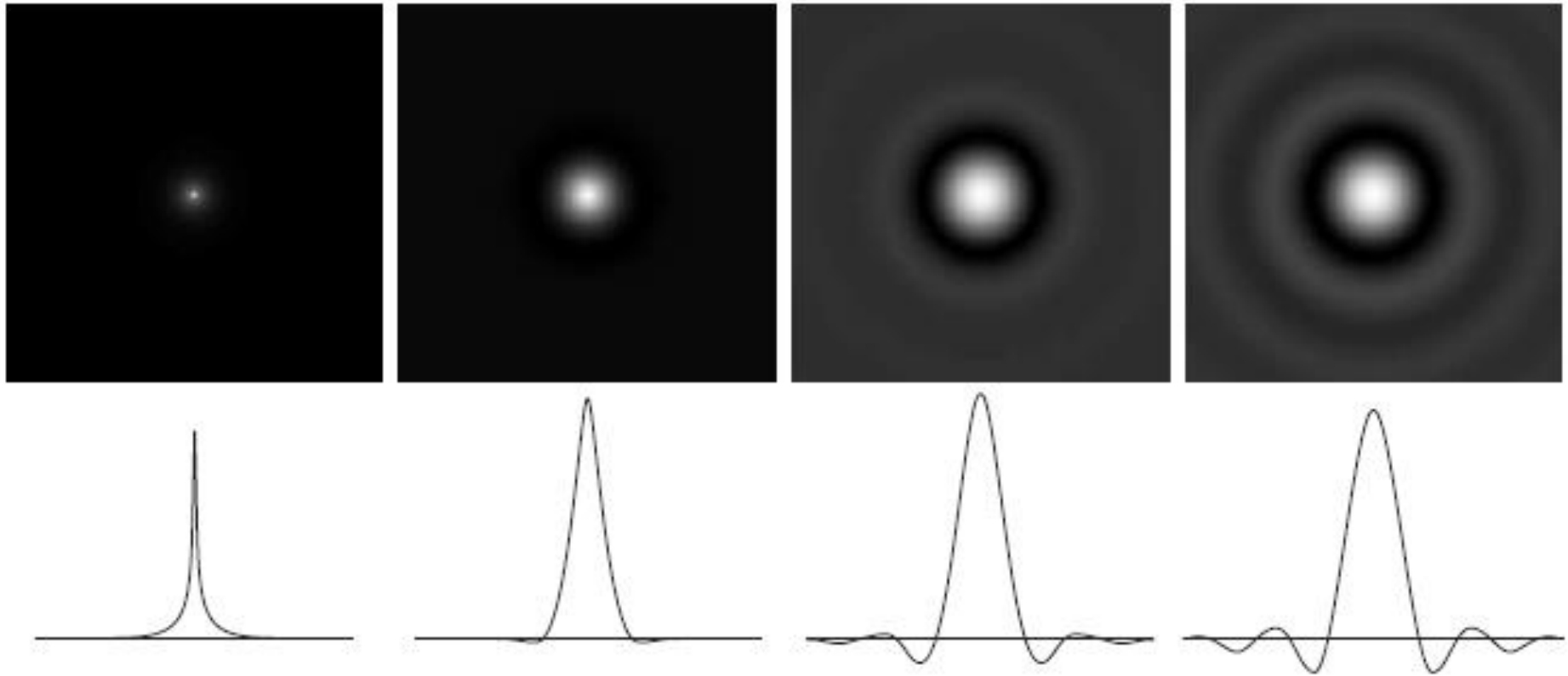
$$H(u, v) = \frac{1}{1 + [D(u, v)/D_0]^{2n}}$$



Ringings are imperceptible in Butterworth filters of order 2 of various  $D_0$

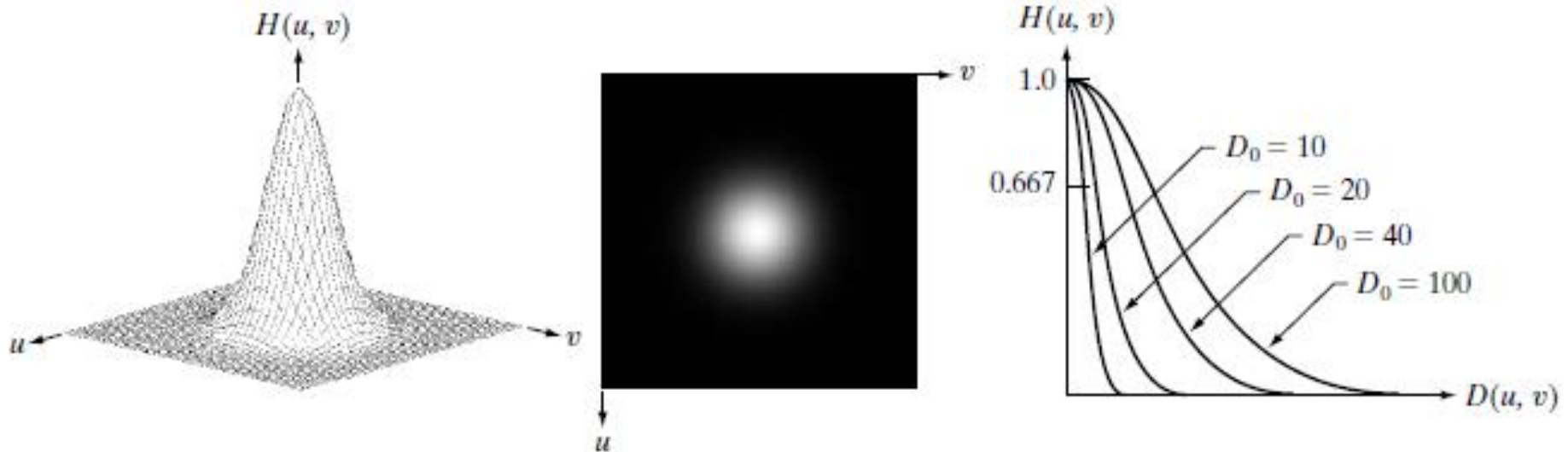


# Ringing increases in BLPFs with order (1, 2, 5, 20)

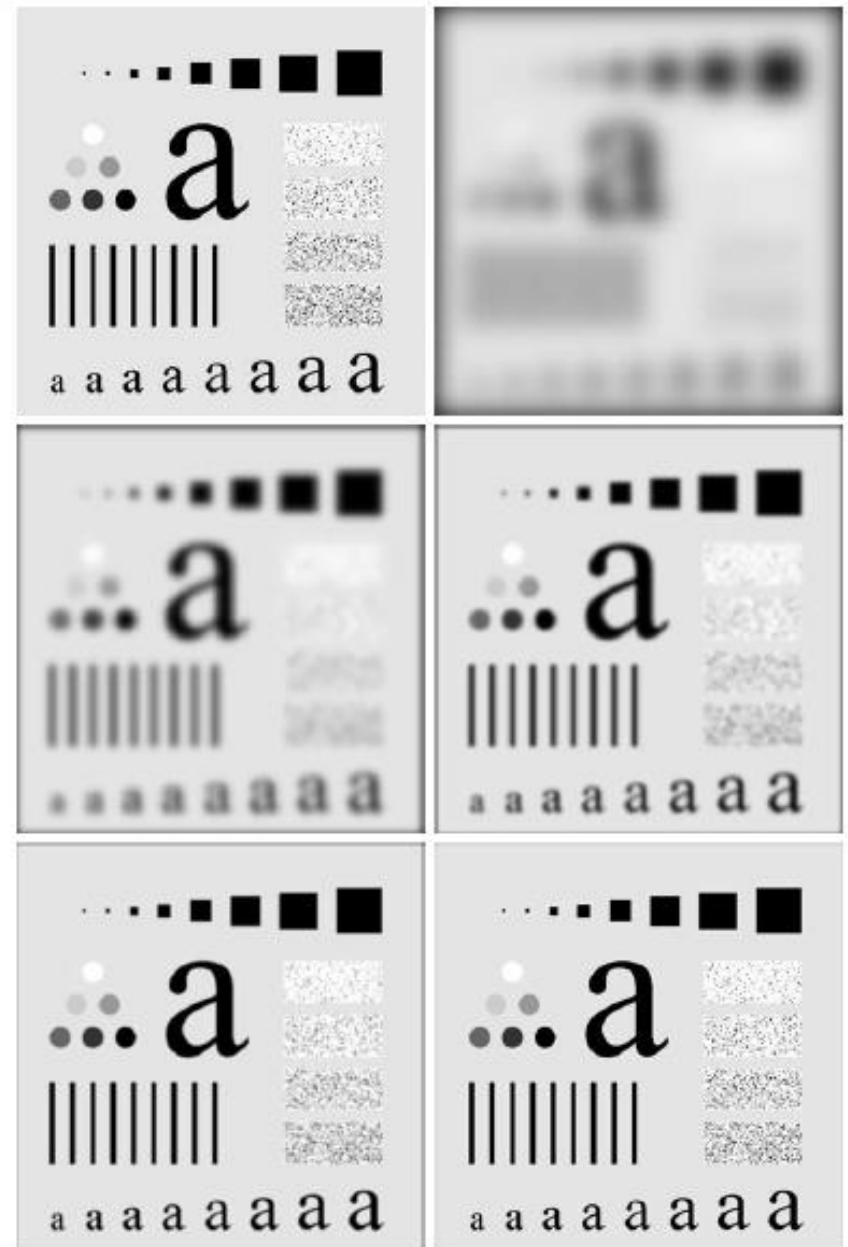


# Another option is GLPF

$$H(u, v) = e^{-D^2(u, v)/2D_0^2}$$



# Use of different cut-offs in GLPFs



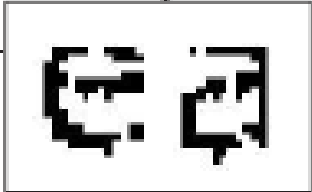
# Summary of the three LPFs

Lowpass filters.  $D_0$  is the cutoff frequency and  $n$  is the order of the Butterworth filter.

Ideal	Butterworth	Gaussian
$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$	$H(u, v) = \frac{1}{1 + [D(u, v)/D_0]^{2n}}$	$H(u, v) = e^{-D^2(u,v)/2D_0^2}$

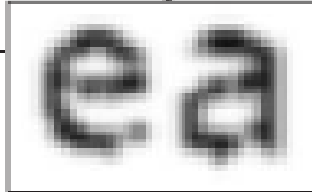
# Blurring with GLPF for continuity

Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



ea

Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



ea

# Anti-wrinkle cream or smoothening with GLPFs

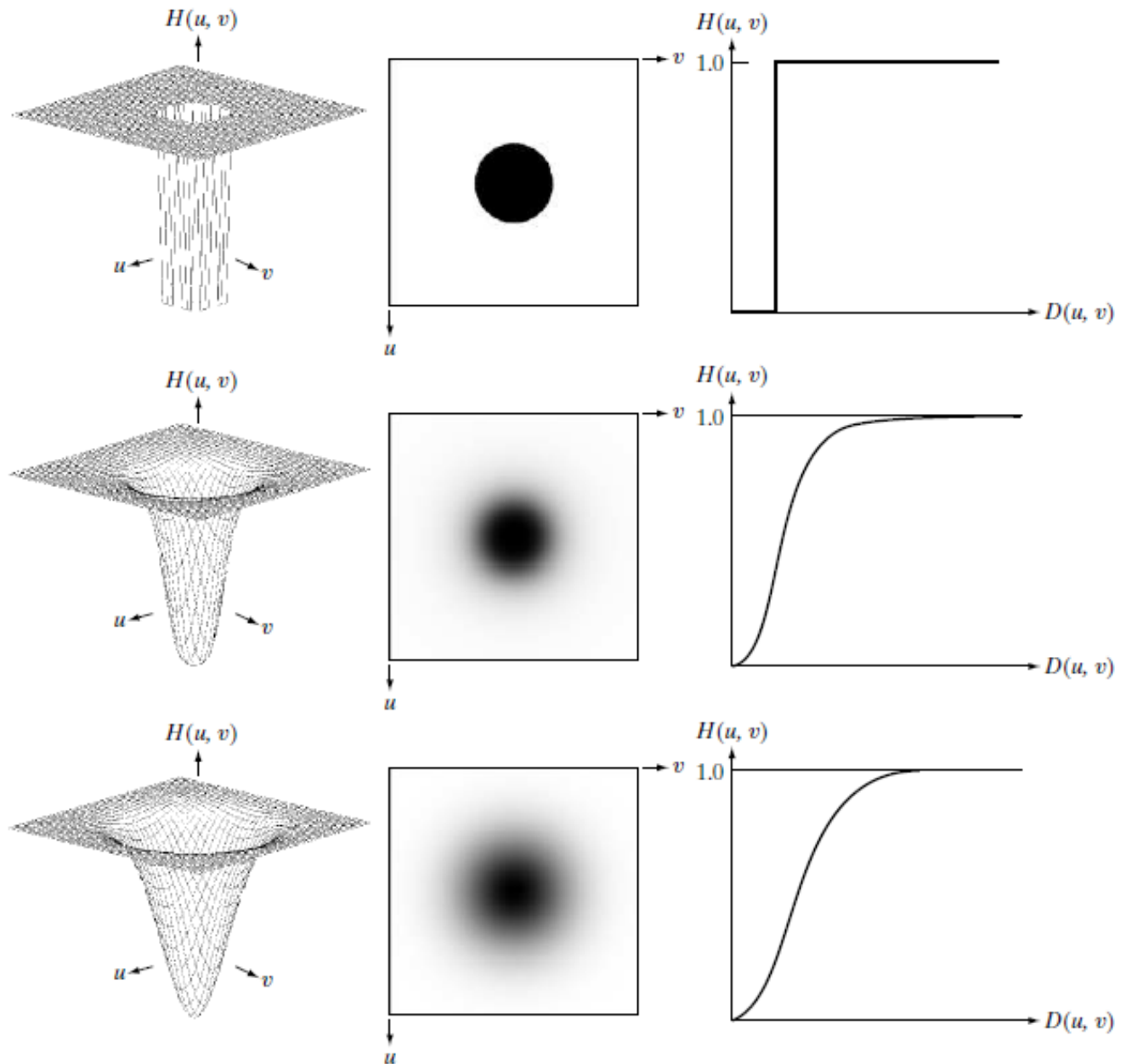


# Removal of scan lines using GLPF

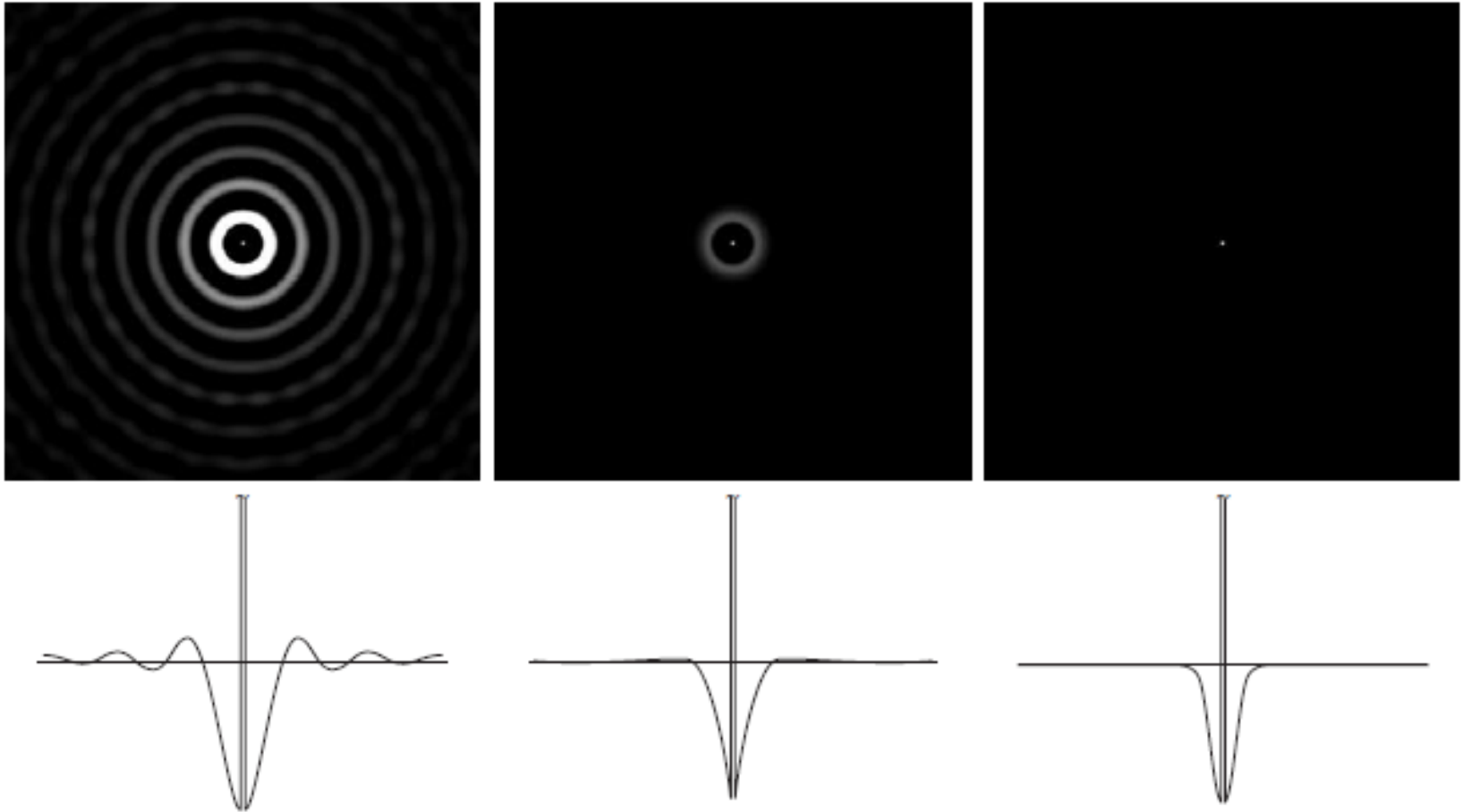




# High pass filters



# Ideal, Butterworth, and Gaussian HPFs in spatial domain



# IHPF with different radii







Highpass filters.  $D_0$  is the cutoff frequency and  $n$  is the order of the Butterworth filter.

Ideal	Butterworth	Gaussian
$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$	$H(u, v) = \frac{1}{1 + [D_0/D(u, v)]^{2n}}$	$H(u, v) = 1 - e^{-D^2(u,v)/2D_0^2}$

# HPF and thresholding

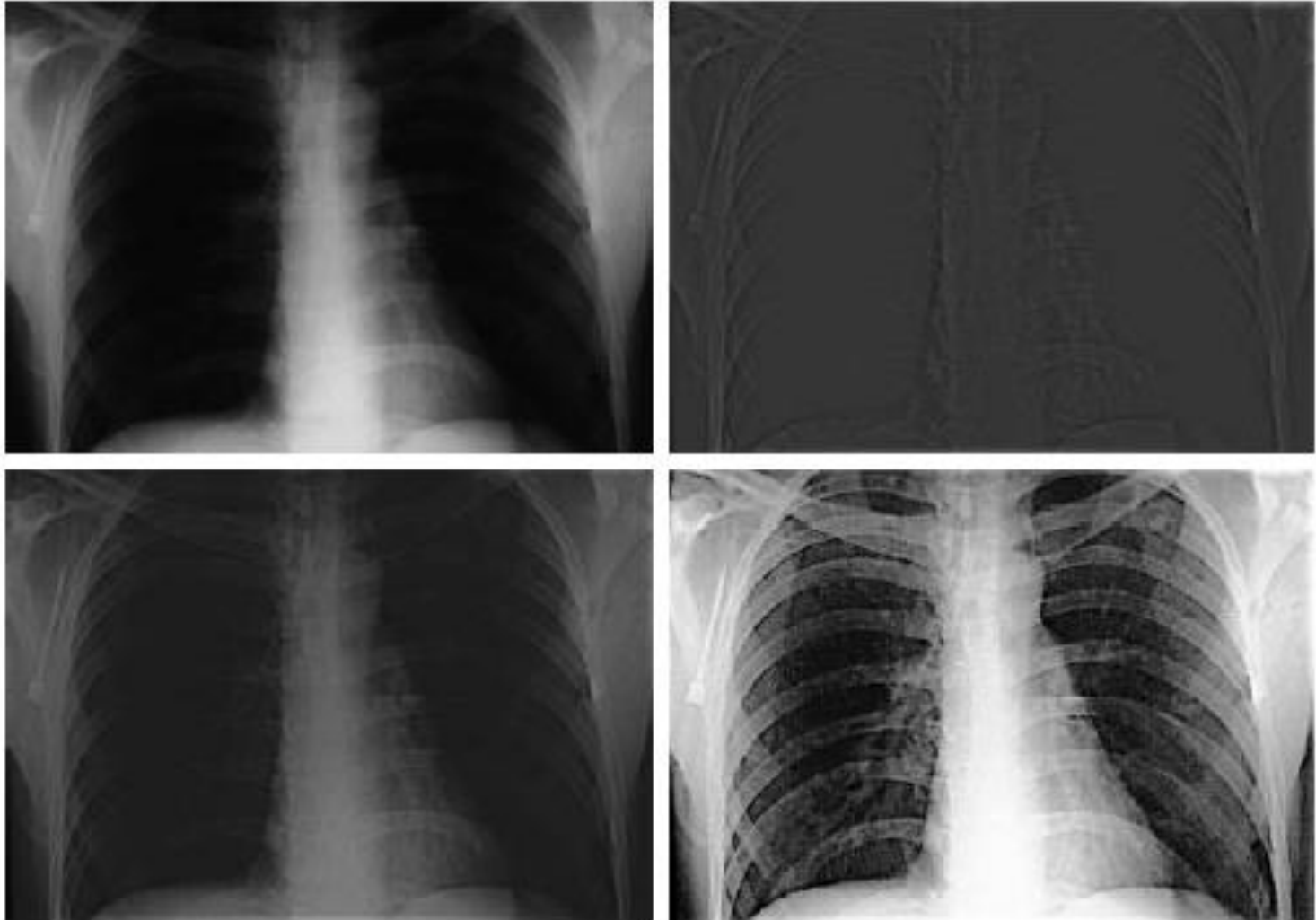


# Enhancement using Laplacian



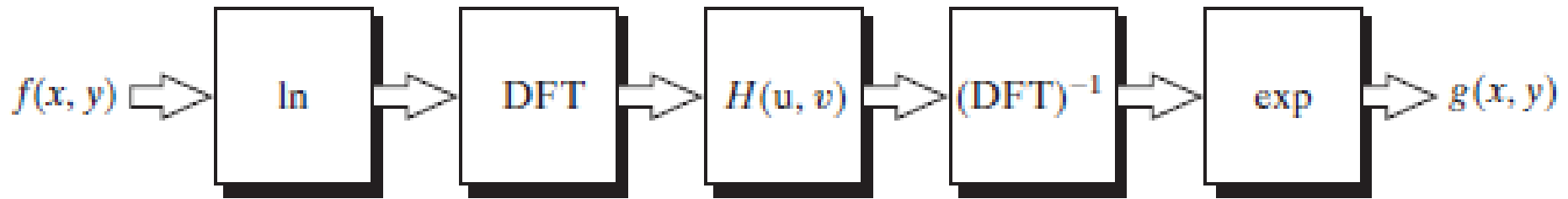


# Original, GHPF, Adding the two, equalizing histogram



Source: Digital Image Processing, Gonzalez and Woods, Prentice Hall

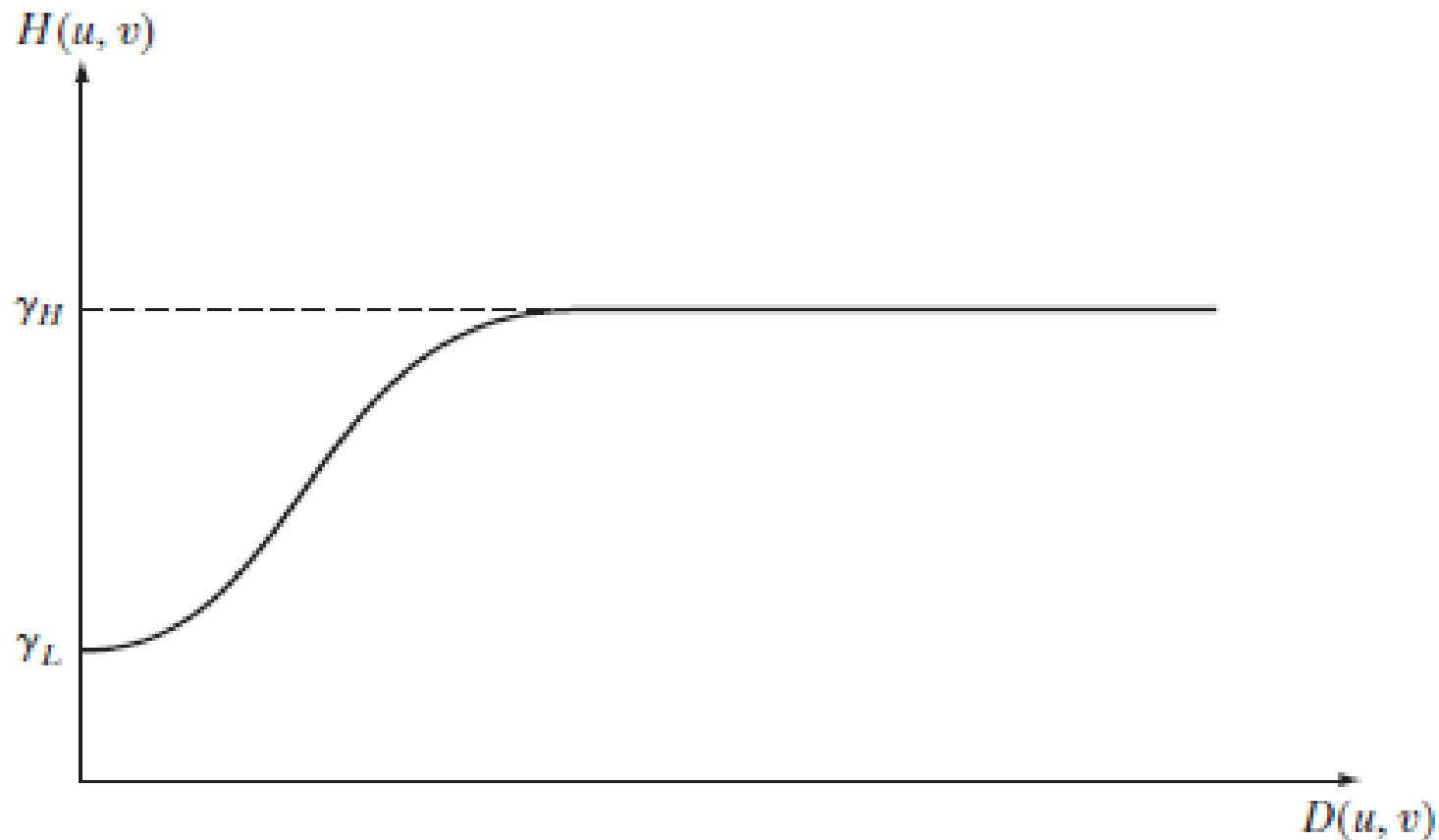
# Homomorphic filtering



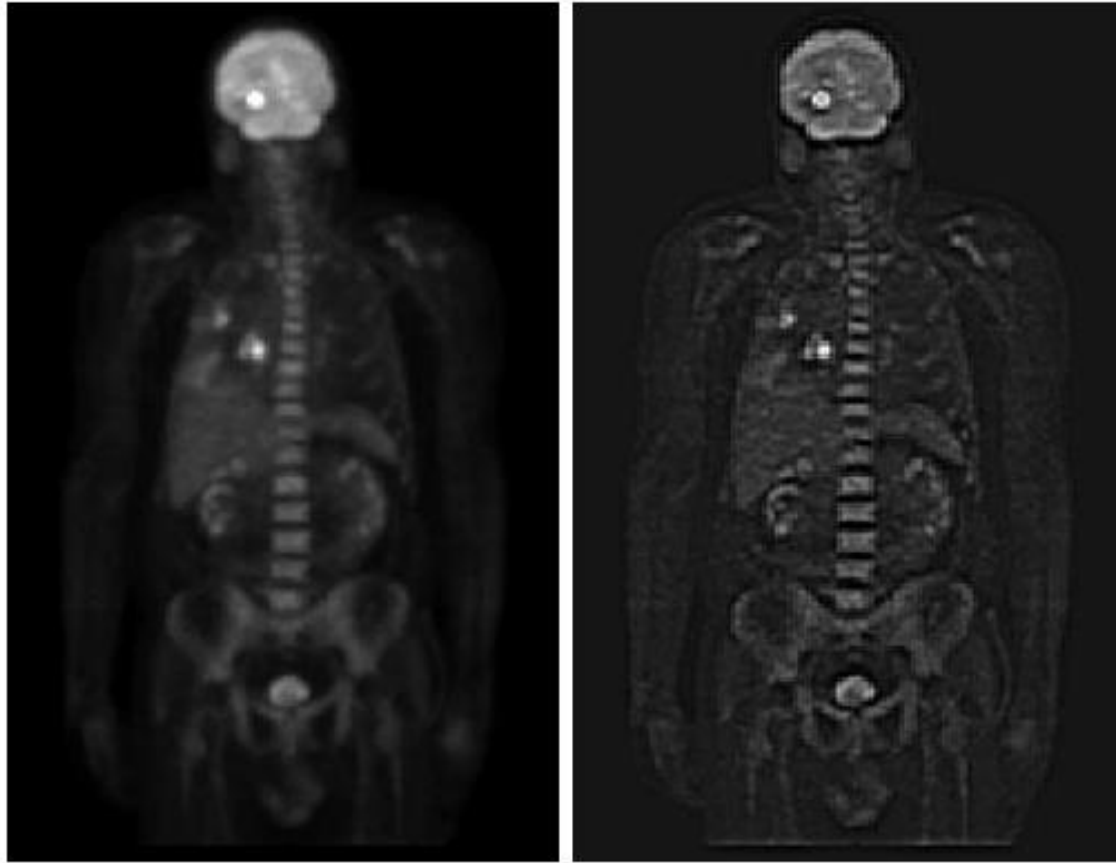
- Taking log of illumination  $\times$  reflectance
- Filter is precisely designed to affect illumination and reflectance separately, assuming low frequency illumination and high frequency reflectance

# Example radial cross section of a filter

$$H(u, v) = (\gamma_H - \gamma_L) \left[ 1 - e^{-c[D^2(u, v)/D_0^2]} \right] + \gamma_L \quad (4.9-29)$$



# Example enhancement of tumors in PET scan using homomorphic filtering

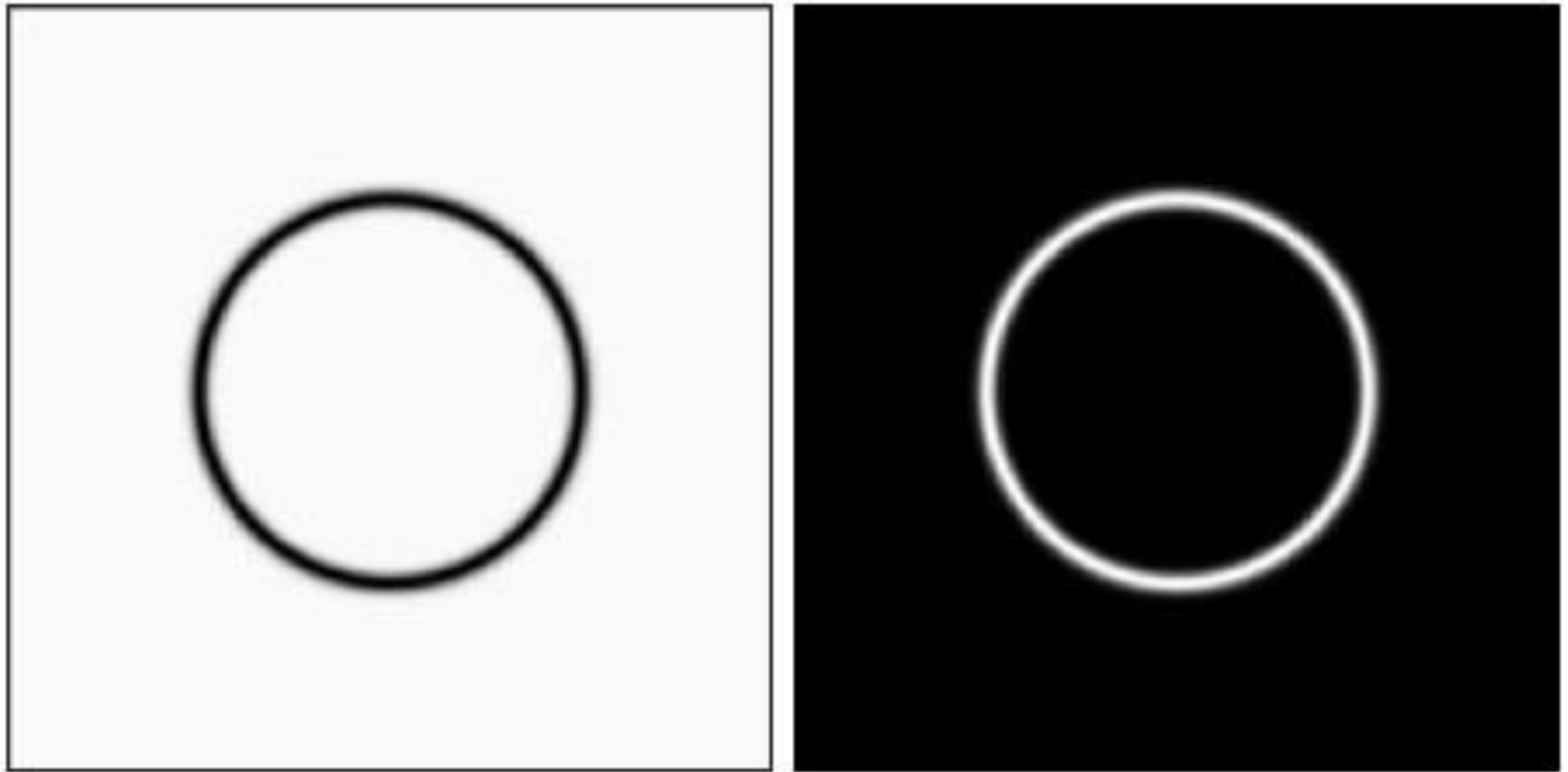


# Examples of band reject filters

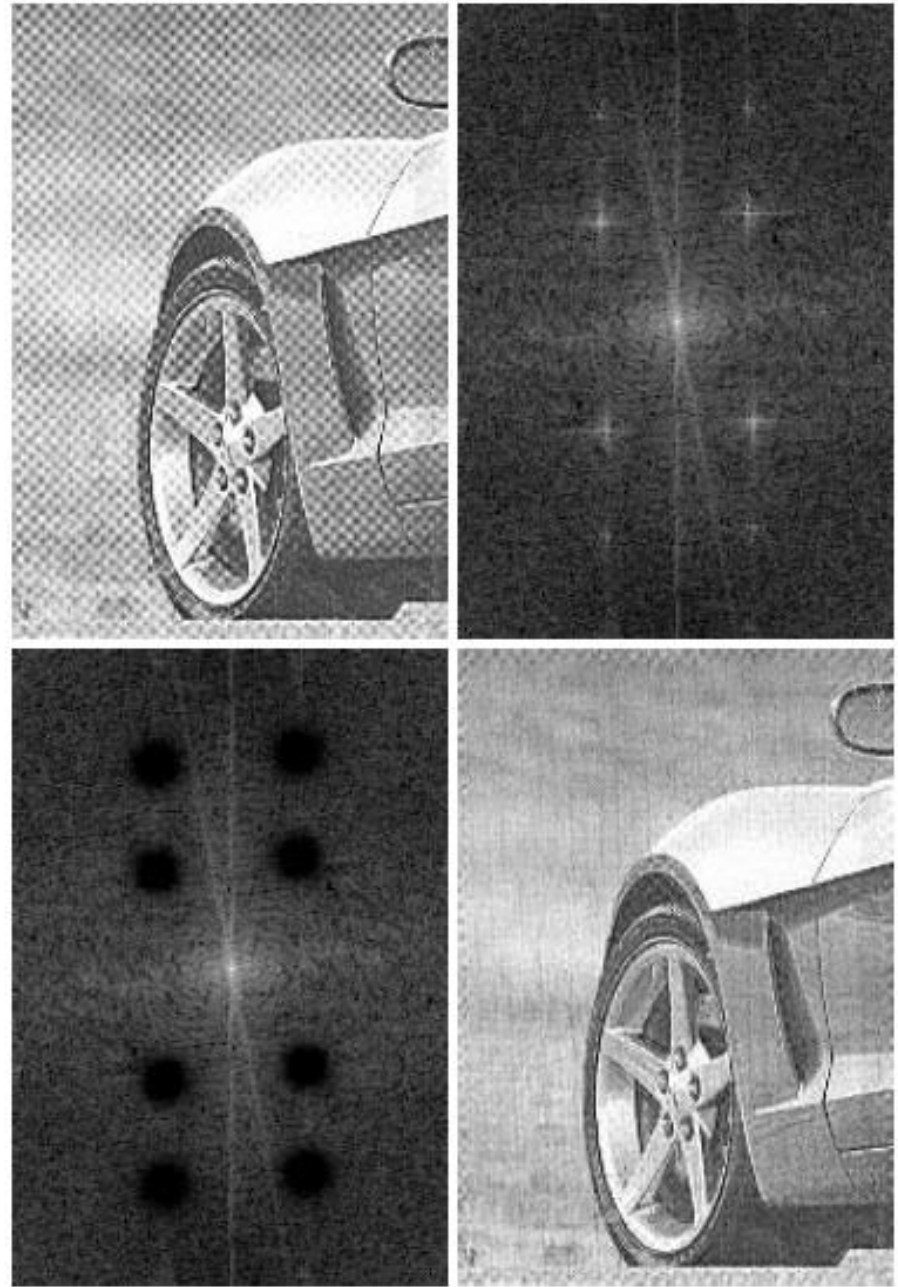
Ideal	Butterworth	Gaussian
$H(u, v) = \begin{cases} 0 & \text{if } D_0 - \frac{W}{2} \leq D \leq D_0 + \frac{W}{2} \\ 1 & \text{otherwise} \end{cases}$	$H(u, v) = \frac{1}{1 + \left[ \frac{DW}{D^2 - D_0^2} \right]^{2n}}$	$H(u, v) = 1 - e^{-\left[ \frac{D^2 - D_0^2}{DW} \right]^2}$

Similarly, bandpass filters can be defined

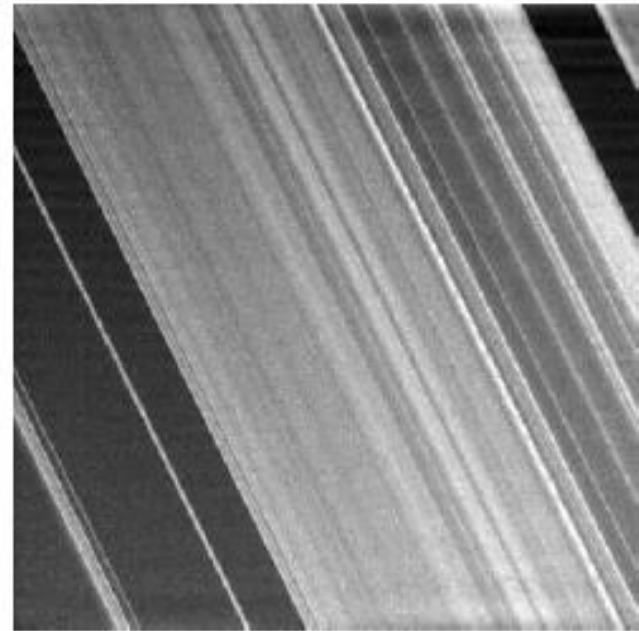
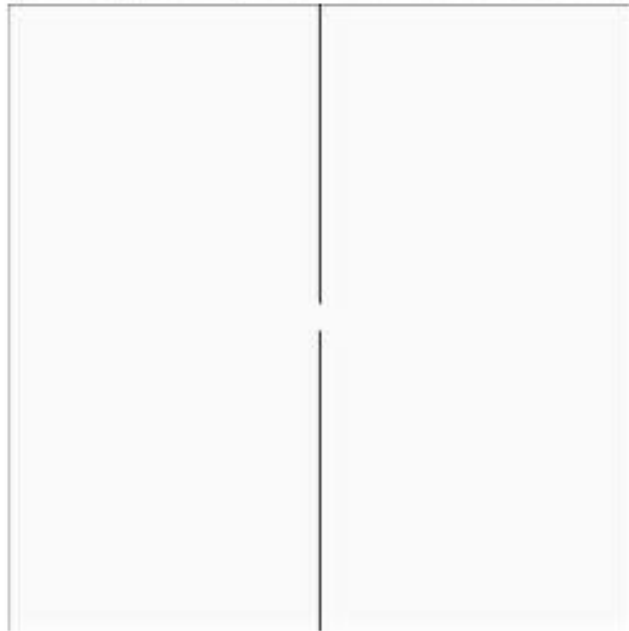
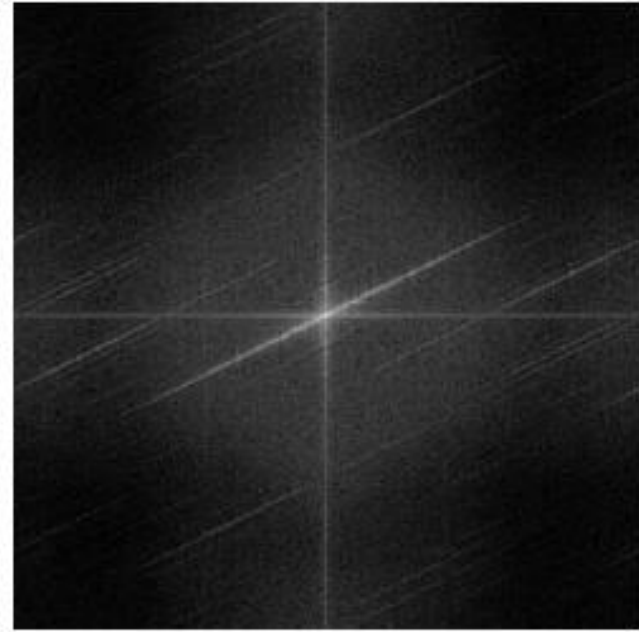
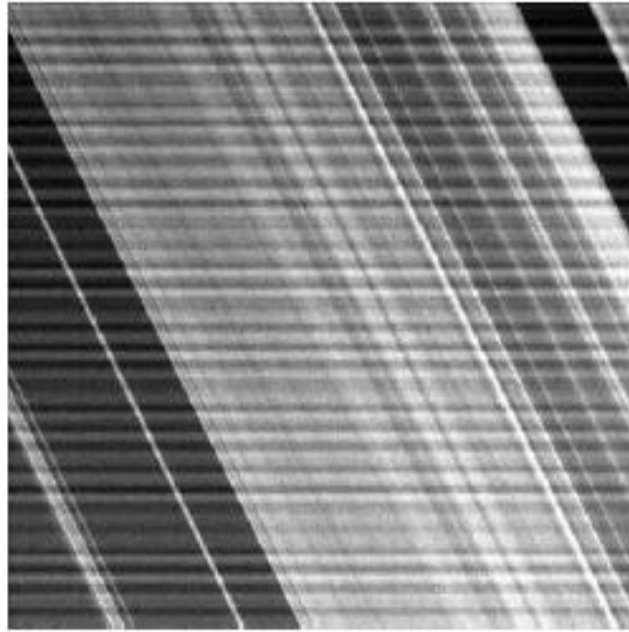
# Band reject vs. bandpass



Original, DFT  
Butterworth  
notch-reject  
multiplied,  
result

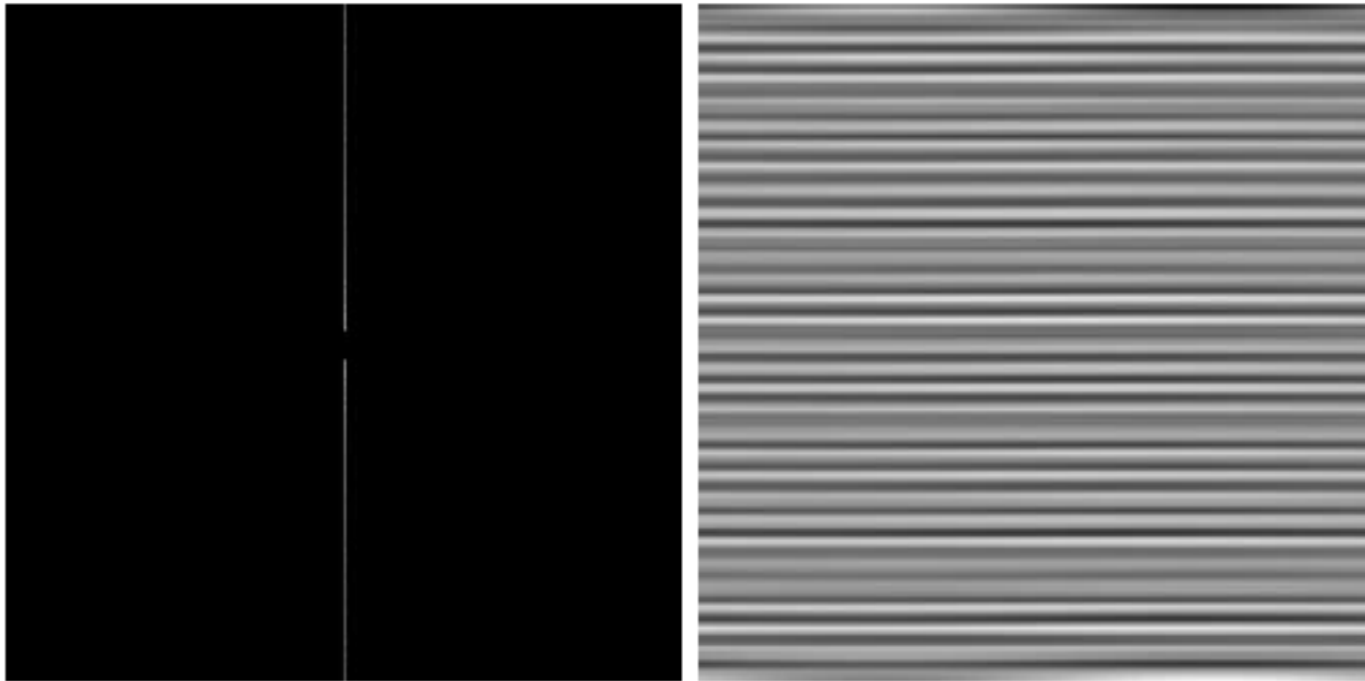


Saturn  
rings,  
DFT,  
Vertical  
notch-  
reject,  
result





# Notch-pass filter shows interference pattern



# Separability of 2-D DFT and IDFT

$$F(u, v) = \sum_{x=0}^{M-1} e^{-j2\pi ux/M} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi vy/N}$$

$$= \sum_{x=0}^{M-1} F(x, v) e^{-j2\pi ux/M}$$

$$m(n) = \frac{1}{2} M \log_2 M$$

$$a(n) = M \log_2 M$$

$$F(x, v) = \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi vy/N}$$

$$MNf^*(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F^*(u, v) e^{-j2\pi(ux/M + vy/N)}$$

# FFT algorithm for DFT

$$F(u) = \sum_{x=0}^{M-1} f(x) W_M^{ux} \quad M = 2^n$$

$$W_M = e^{-j2\pi/M} \quad M = 2K$$

$$\begin{aligned} F(u) &= \sum_{x=0}^{2K-1} f(x) W_{2K}^{ux} \\ &= \sum_{x=0}^{K-1} f(2x) W_{2K}^{u(2x)} + \sum_{x=0}^{K-1} f(2x+1) W_{2K}^{u(2x+1)} \end{aligned}$$

$$F(u) = \sum_{x=0}^{K-1} f(2x) W_K^{ux} + \sum_{x=0}^{K-1} f(2x+1) W_K^{ux} W_{2K}^u$$

$$F(u) = F_{\text{even}}(u) + F_{\text{odd}}(u) W_{2K}^u$$

# Savings of FFT over DFT $2^n/n$

