CS310 Operating Systems

Lecture 27: Thread Scheduling, Linux Scheduling

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Acknowledgements!

- Contents of this class presentation has been taken from various sources. Thanks are due to the original content creators:
 - Book: Linux System Programming, Robert Love
 - CS162, Operating System and Systems Programming, University of California, Berkeley
 - Book: Modern Operating System, Andrew Tanenbaum

Reading

- Book: Linux Kernel Development, Robert Love
 - Chapter 4 Process Scheduling
- Book: Advanced Unix Programming, by Mark J Rochkind

Previous Classes

First-Come, First-Served (FCFS) Scheduling

- First-Come, First-Served (FCFS)
 - Also First In First Out (FIFO) or Run until done
 - In early systems, FCFS meant one program scheduled until done (including I/O)
 - Now, means keep CPU until thread blocks



- Simple Algorithm, Easy to implement (+)
- FCFS Scheme: Potentially bad for short jobs!
 - Depends on submit order
 - If you are first in line at supermarket with milk, you don't care who is behind you, on the other hand...
 - Convoy effect: short process stuck behind long process (-)

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Shortest Job First (SJF)

- Non-preemptive
- Run whatever job has least amount of computation to do
- Provably optimal
- Need to know run times in advance

Shortest Remaining Time First (SRTF)

- Preemptive version of SJF
- If job arrives and has a shorter time to completion than the remaining time on the current job, immediately preempt CPU
- Sometimes called Shortest Remaining Time to Completion First (SRTCF)
- Both SJF and SRTF:
 - These can be applied to whole program or current CPU burst
 - Idea is to get short jobs out of the system
 - Big effect on short jobs, only small effect on long ones
 - Result is better average response time

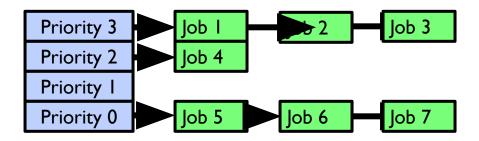
Round Robin (RR) Scheduling



- Uses Preemption!
- Each process gets a small unit of CPU time (time quantum), usually 10-100 milliseconds
- After quantum expires, the process is preempted and added to the end of the ready queue
- n processes in ready queue and time quantum is q
 - Each process gets 1/n of the CPU time
 - In chunks of at most q time units
 - No process waits more than (n-1)q time units

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Multilevel Queue Scheduling – Strict Priority



Execution Plan

- Always execute highest-priority runnable jobs to completion
- Each queue can be processed in RR with some time-quantum
- A priority is assigned statically to each process, and a process remains in the same queue for the duration of the run time

Problems

- Starvation
 - Lower priority jobs don't get to run because higher priority jobs
- Deadlock: Priority Inversion
 - Happens when low priority task holds a lock needed by high-priority task

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Example of Multilevel Feedback Queue

Priority	Time Slice (ms)	Round Robin Queues
1	10	New or I/O Bound Task
2	20	Time Slice Expiration
3	40	•
4	80	•

Ref: Book: Anderson and Dahlin

Lottery Scheduling

- Proportional share scheduling
 - Give each job some number of lottery tickets
 - On each time slice, randomly pick a winning ticket
 - On average, CPU time is proportional to number of tickets given to each job
- How to assign tickets? Users can define policy
 - To approximate SRTF, short running jobs get more, long running jobs get fewer
 - To avoid starvation, every job gets at least one ticket (everyone makes progress)
- Advantage over strict priority scheduling: behaves gracefully as load changes
 - Adding or deleting a job affects all jobs proportionally, independent of how many tickets each job possesses

Use Randomness

Requires a good random number generator



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Scheduling Summary

- FCFS is simple and it minimizes overhead
- If tasks are variable in size, FCFS can have very poor average response time
- FCFS suffers from convoy effect
- SJF is optimal in terms of average response time
- If tasks are variable in size, Round Robin approximates SJF
- If tasks are equal in size, Round Robin will have very poor average response time
- Round Robin avoid starvation
- MFQ scheduler can achieve a balance between responsiveness, low overhad and fairness

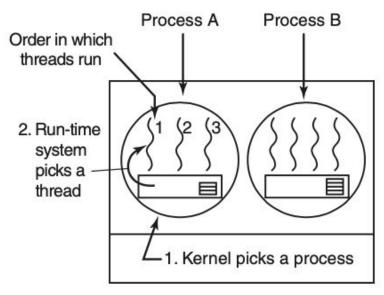
Thread - Scheduling

So, Does the OS Schedule Processes or Threads?

- Switching threads vs. switching processes incurs different costs:
 - Switch threads: Save/restore registers
 - Switch processes: Change active address space too!
 - Expensive
 - Disrupts caching
- A system have have many processes and many threads running
- Recall User level threads vs Kernel level threads
 - Scheduling for both differs

User level thread Scheduling

- Kernel is not aware of existence of threads
- Kernel picks up a process, say A, and giving it a control for the quantum
 - Runtime system (Thread scheduler) inside A decides which thread to run, say A1
 - As there are no clock interrupts used within Runtime System, A1 will continue to run unless it has do to I/O or process scheduler context switches it
 - When A is resumed back, A1 again starts running
 - If A1 finishes within the quantum, runtime scheduler will schedule A2 ..and so on



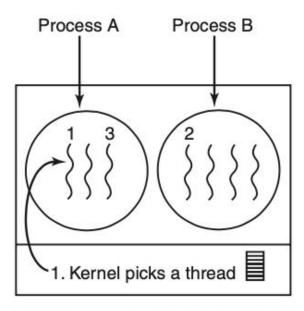
Possible: A1, A2, A3, A1, A2, A3 Not possible: A1, B1, A2, B2, A3, B3

Runtime scheduler can run any scheduling algorithm: example: RR

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Kernel level thread Scheduling

- Kernel picks up a particular thread to run
- It doesn't take into account which process the thread belongs to
 - However it can take into account if it wants to
- Doing thread scheduling at Kernel level requires full context switch
 - Changing memory map
 - Cache data management
- Slower than that in User level switching
- If a thread blocks on I/O, entire process is not blocked
 - Kernel can switch to another thread in the same process



Possible: A1, A2, A3, A1, A2, A3 Also possible: A1, B1, A2, B2, A3, B3

Runtime scheduler can run any scheduling algorithm: example: RR

Book: Tenenbaum's Book on Modern OS 16

Linux – Completely Fair Scheduler (CFS)

Linux Scheduler Overview

- Scheduling policy attempts to satisfy conflicting goals
 - Fast process response time
 - Maximal system utilization (throughput)
- Aims to provide good interactive responses
 - ☐ favors I/O bound processes over processor bound processes
 - Done in creative manner doesn't neglect processor-bound processes
- Reasonably good for Real-time applications
 - So, there must be something to handle real-time processes
- Priority based Scheduling
 - So, there must be some way to define priority of a process
- Preemptive Scheduling
- Thread based Scheduling Linux treats a process (without threads inside) as a single thread Kernel level threads
- Two states that are of interest in scheduling: blocked and runnable

Priority Based Scheduling

- CFS was introduced in Linux 2.6.23 in 2207
 - For Normal processes .. Named as SCHED_NORMAL
 - Can be configured for batch workloads: SCHED_BATCH
- Rank processes based on their worth and need for processor time
 - User and the system can set a process's priority
- Real-Time processes have higher priorities than those of all normal processes
- The Linux kernel implements two separate priority ranges
 - Nice value
 - Real time priority

Real Time Priority

- Range from 0 to 99, inclusive
- Opposite from nice values, higher real-time priority values correspond to a greater priority
- All real-time processes are at a higher priority than normal processes
- The real-time priority and nice value are in disjoint value spaces

ps -eo state,uid,pid,ppid,rtprio,time,comm

	LITE	DID	DDT	DIDDIO	TTME	COMMAND
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2	0	1 2		-	00:00:00	
2	0	3		_		ksoftirgd/0
2	0	5		5		kworker/0:0H
2	0	7	1	_		rcu_sched
2	0	8	1	-	00:00:13	
2	0	9		99		migration/0
2	0	10	1	99	00:00:00	watchdog/0
2	0	11		99		watchdog/1
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S	0	417	- 7	50	00:00:15	irq/51-DELL0767
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S	0	637	7	1	00:00:00	comp 1.0.5
S	0	638	7	1	00:00:00	comp 1.0.6
S	0	639	1	1	00:00:00	comp 1.0.7
s	0	640	7	1	00:00:00	sdma0
S	0	641	3	1	00:00:00	sdma1
S	102	808			00:00:02	dbus-daemon
J	IVE	000	-		00.00.02	COCO GOCHOII

Nice Value

- A number from -20 to +19 with a default of 0
- Larger nice values correspond to a lower priority
 - you are being "nice" to the other processes on the system
- Processes with a lower nice value (higher priority) receive a larger proportion of the system's processor compared to processes with a higher nice value (lower priority)
- Nice values are the standard priority range used in all Unix systems
 - Different Unix systems apply them in different way based on the individual scheduling algorithm
 - Mac OS X, the nice value is a control over the absolute timeslice allotted to a process;
 - In Linux, it is a control over the *proportion* of timeslice

ps -el

[(base) Ravis-MacBook-Pro-2:~ ravi itta; ps -el											
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0	149	1	4004	0	0	1306048	612 -	Ss	0 ??		/sbin/taunchu /usr/sbin/syslogd
0	150	1	4004	0 3		1336300	3384 -	Ss	0 ??		/usr/libexec/UserEventAgent (System)
0	153	1	4004	0 2	0	1280516	392 -	Ss	0 ??		/System/Library/PrivateFrameworks/Uninstall.framework/Resourc
0	154	1	4004	0 4	0	1853492	1860 -	Ss	0 ??		/usr/libexec/kextd
0	155		1004004	0 5	0	5483084	2436 -		0 ??		/System/Library/Frameworks/CoreServices.framework/Versions/A/
0	157	1	4004	0 2		1283024	2436 - 64 -	Ss	0 ??		/System/tibrary/riameworks/coreservices.riamework/versions/A/ /Library/Frameworks/OVPNHelper.framework/Versions/Current/usr
9	158	1	4004	0 2	0	1337344	900 -	Ss Ss	0 ??		/System/Library/PrivateFrameworks/MediaRemote.framework/Suppo
0	161	1	4004	0 2		1290712	68 -	Ss	0 ??		/Library/Frameworks/OpenVPNConnect.framework/Versions/Current
0	162	1	4004	0 2	0	1356092	19856 -		0 ??		/usr/sbin/systemstatsdaemon
0	163	1	4004 400c			1342128	4112 -	Ss	0 ??		/usr/libexec/configd
0	165	1	4004	0 3 0 3	0	1335032	3620 -	Ss Ss	0 ??		/System/Library/CoreServices/powerd.bundle/powerd
0	170	1	4004	0 3	0	1402740	7788 -	Ss	0 ??		/system/Library/coreservices/powerd.bundte/powerd /usr/libexec/logd
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0	214		40004004	0 3 0 6	0	1340320	5532 -	Ss	0 ??		/usr/sbin/bluetoothd
261	215	1	4004	0 6	0	1337444	3948 -	Ss	0 ??		/usr/libexec/hidd
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0	225	1	4004	0	0	1305896	2604 -	Ss	0 ??		/usr/sbin/cfprefsd daemon
0	226	1	4004	0 3 0 6		1379508	11932 -	Ss	0 ??		/usr/libexec/syspolicyd
501	228		80004104			1396456	18332 -	Ss	0 ??		/System/Library/CoreServices/loginwindow.app/Contents/MacOS/l
0	230	1	4004	0	0	1337684	3504 -	Ss	0 ??		/System/Library/Frameworks/Security.framework/Versions/A/XPCS
263	275	1	4004	0 3		1340620	5684 -	Ss	0 ??		/System/Library/PrivateFrameworks/CoreAnalytics.framework/Sup
0	278	1	4004	0	0	1344108	5588 -	Ss	0 ??		/usr/libexec/trustd
9	279	1	4004	0 3 0 6		1374912		Ss	0 ??		/usr/libexec/airportd
202 0	280 281	1 1	4004 4004	0 6 0	0	1344296 1342944	2372 - 6316 -	Ss Ss	0 ?? 0 ??		/usr/sbin/coreaudiod
V	201	1	4004	V	Ø	1342944	0210 -	35	Ø ??	0:39.09	/usr/libexec/lsd runAsRoot

CFS

- No fixed timeslices
 - This is a major change from other OSs where time given to each processor remains fixed
- No explicit priorities
 - Does this mean priority of a process/thread changes over time?
- Amount of time for a given task is computed dynamically
 - As scheduling context changes

CFS - Algorithm

- CFS is designed to approximate perfect multitasking
 - Imagine as processor P, which is idealized in that it can executed multiple tasks simultaneously
 - If there are two tasks, both can run a the same time; each receiving 50% of processing power
- CFS scheduler has a target latency
 - Idealized as very small duration such that every runnable task gets at least one turn
 - Call it target latency: say 20 ms
 - If there are N tasks, each get 1/N slice of target latency
 - Example: If N = 4 each task get 5 ms
- Note that 1/N Slice: is not fixed as it depends on N
 - N keeps changing

CFS - Algorithm

- Each of these tasks (N) will contend for processor
- Now, traditional Nice value is used to weight the 1/N slice
- Low priority nice value : only a fraction of the 1/N slice is given to the task
- High priority nice value: proportionately greater fraction of the 1/N slice is given to a task
 - Nice values only modify 1/N slice
- To take care of overheads of switching, a minimum amount of time is fixed – where in a process must run before being preempted - called minimum granularity
 - Assume 4 ms
- If more number of processes are contending (say 20 processes), 1/N slice is much smaller than minimum granularity
 - No fairness

How does preemption occur?

- A task is preempted when it's period : weighted 1/N slice completes
- Which task is chosen to run now?
- Runnable task, say T2, which has the lowest virtual runtime (vruntime) among the tasks contending for the processor
 - vruntime (in nanosecond): records how long a task has run on the process
- Scheduler tracks the vruntime for all tasks
 - Runnable and blocked
- Lower a task's vruntime, more deserving the task is for the time on the processor
- vruntime = actual runtime normalized by the number of runnable processes

Rescheduling

- Rescheduling is required when the number of tasks , N, becomes such that
 - N > Target Latency / Minimum Granularity
- Now scheduler changes the Target latency to
 - N * minimum latency

Summary: Choosing the Right Scheduler

If You Care About:	Then Choose:			
CPU Throughput	FCF S			
Average Response Time	SRTF Approximation			
I/O Throughput	SRTF Approximation			
Fairness (CPU Time)	L <mark>inux CFS</mark>			
Fairness (Wait Time to Get CPU)	Round Robin			
Meeting Deadlines	Earliest Deadline First (EDF)			
Favoring Important Tasks	Priorit y			

Backup Slides

Choosing Time-slice

- The scheduler policy must dictate a default timeslice
 - Not easy to choose this number
- Too short timeslice

 Overhead of switching processes
- I/O bound processes don't need longer timeslice
- Linux's CFS scheduler, however, does not directly assign timeslices to processes
 - CFS assigns processes a proportion of the processor
 - the amount of processor time that a process receives is a function of the load of the system
 - This assigned proportion is further affected by each process's nice value
 - Acts as a weight, changing the proportion of the processor time each process receives

Time Slice

 The rule of thumb adopted by Linux is: choose a duration as long as possible, while keeping good system response time

- Which process to run?
 - Decision also depends on how much proportion of the processor the process has consumed
 - If it has consumed small proportion of the processor, it is run immediately