Getting Started with MangoPi Board

The following are the steps to be followed to set up the RISCV64 MangoPi board. You need a microSD card for loading the boot images and USB-UART bridge device for connecting it to Host Computer's Serial Terminal Application.

Prepare the Repo

Get the latest repo with all the latest BSP: <u>https://github.com/RT-Thread/rt-thread</u> this is the repo I used. (My case I have saved the repo at the location: /rtsmart/rtthread-smart/userapps)

Also update the toolchain to latest using the command from the tools folder. :-/rtsmart/rtthread-smart/tools\$ python3 get_toolchain.py riscv64

Also make sure that the environment is set correctly. *source ./smart-env.sh riscv64* must be executed at the correct folder.

Build the BSP

Build the BSP for the board: Now build the right BSP for your allwinner board. Navigate to the folder , in my case rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s

/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s\$ scons --menuconfig



Figure 1: Menuconfig Save



Figure 2:Menuconfig Exit

Execute scons after that,

~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s\$ scons

.....

scons: done building targets.

Check for and sd.bin file which gets generated. This is the image we are going to store in the SDCard and boot the mangopi board

Preparing SD Card

Connect the SD Card to your system. Find out the entry corresponding to your SD Card from /dev folder. For me the name was sdb.

Format the sdb disk using fdisk command.

:~\$ sudo fdisk /dev/sdb Welcome to fdisk (util-linux 2.34). Changes will remain in memory only, until you decide to write them. Be careful before using the write command. Command (m for help): o Created a new DOS disklabel with disk identifier 0xbf06dddf. Command (m for help): n Partition type p primary (0 primary, 0 extended, 4 free) e extended (container for logical partitions) Select (default p): p Partition number (1-4, default 1): 1 First sector (2048-125542399, default 2048): 16384 Last sector, +/-sectors or +/-size{K,M,G,T,P} (16384-125542399, default 125542399): Created a new partition 1 of type 'Linux' and of size 59,9 GiB. Partition #1 contains a vfat signature. Do you want to remove the signature? [Y]es/[N]o: Yes The signature will be removed by a write command. Command (m for help): q

You can use gparted command to cross verify the partition.



Figure 3 Gparted showing the SDCard Partition

Now flash the <u>sd.bin</u> and boot image, <u>boot0_sdcard_sun20iw1p1_d1s.bin</u> onto the SDCard. Use the following two commands from the right folder. sudo dd if=boot0_sdcard_sun20iw1p1_d1s.bin of=/dev/sdb bs=1024 seek=8 sudo dd if=sd.bin of=/dev/sdb bs=1024 seek=56

Command logs are followed.

```
hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s/tools$ sudo dd

if=boot0_sdcard_sun20iw1p1_d1s.bin of=/dev/sdb bs=1024 seek=8

48+0 records in

48+0 records out

49152 bytes (49 kB, 48 KiB) copied, 0,0181441 s, 2,7 MB/s

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s/tools$

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s/tools$

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s/tools$

cd ...

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s/tools$ cd ...

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s$ sudo dd

if=sd.bin of=/dev/sdb bs=1024 seek=56

772+0 records in

772+0 records out

790528 bytes (791 kB, 772 KiB) copied, 0,152477 s, 5,2 MB/s

hima @himapc:~/rtsmart/rtthread-smart/userapps/rt-thread/bsp/allwinner/d1s$
```

SD Card is now ready.

Setting Up the Hardware

Plug the already prepared SD Card on to the Mangopi Board, on the microSD Card slot.



Figure 4:Micro-SD Card Installation

Also connect a UART-USB Bridge, so that you can check the UART Commands from your PC. I am using the CP2102 USB to TTL interface board as UART-USB Bridge. Connect RX and TX of the bridge to TX and RX of MangoPi board respectively.

 $\begin{array}{ll} \mathsf{RX} \; (\mathsf{CP2102}) \; \rightarrow \mathsf{TX} \; (\mathsf{P3.7}) \; \mathsf{MangoPi} \\ \mathsf{TX} \; (\mathsf{CP2102}) \; \rightarrow \mathsf{RX} (\mathsf{P3.8}) \; \mathsf{MangoPi} \end{array}$



Figure 5:UART RX-TX Connection

Now Open any Terminal Application and connect to you UART Device. Make sure that the Baud Rate is configured as <u>500000</u>. The board boots up, when it is reset.



Figure 6: Boot logs on the Serial Terminal