

CSCI 420 Computer Graphics

Lecture 8

Shadows Hierarchical Models

Projections and Shadows
Hierarchical Models
[Angel Ch. 8]

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How is HW1 going?

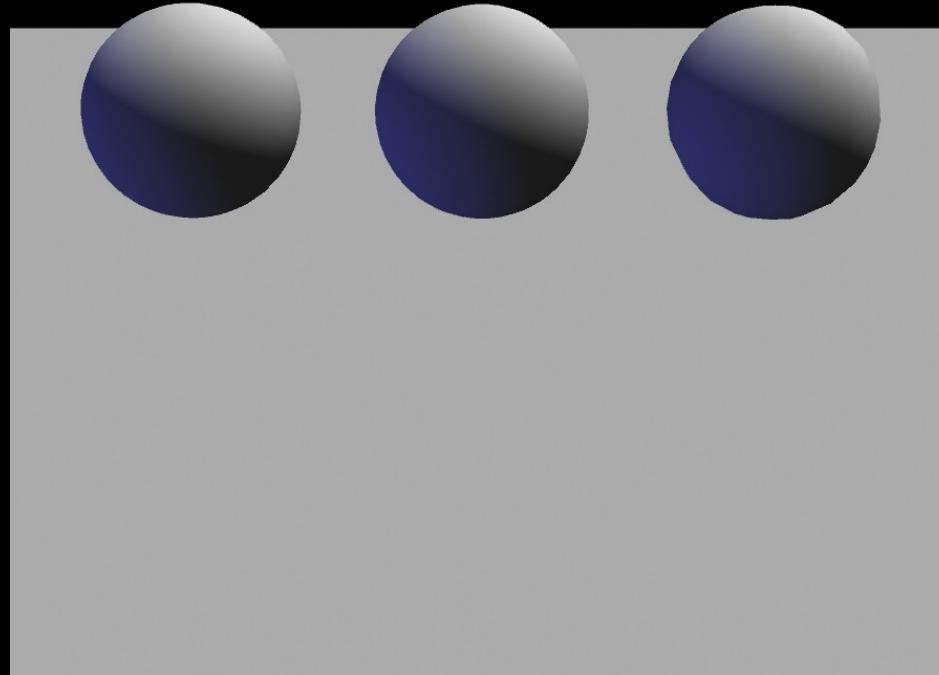
- After last class, you should all have started working on HW1.
- HW1 is due Oct 7.
- **If you have not compiled your starter code yet, please see me in the break!**
- Ask questions on Piazza.
- Use the office hours if you need individual help.
- Good luck!

Roadmap

- Last lecture: Shaders
- Today:
 - Shadows via projections
 - Hierarchical models
- Next: Polygonal Meshes, Curves and Surfaces
- Goal: background for Assignment 2
 - (specifically curves)

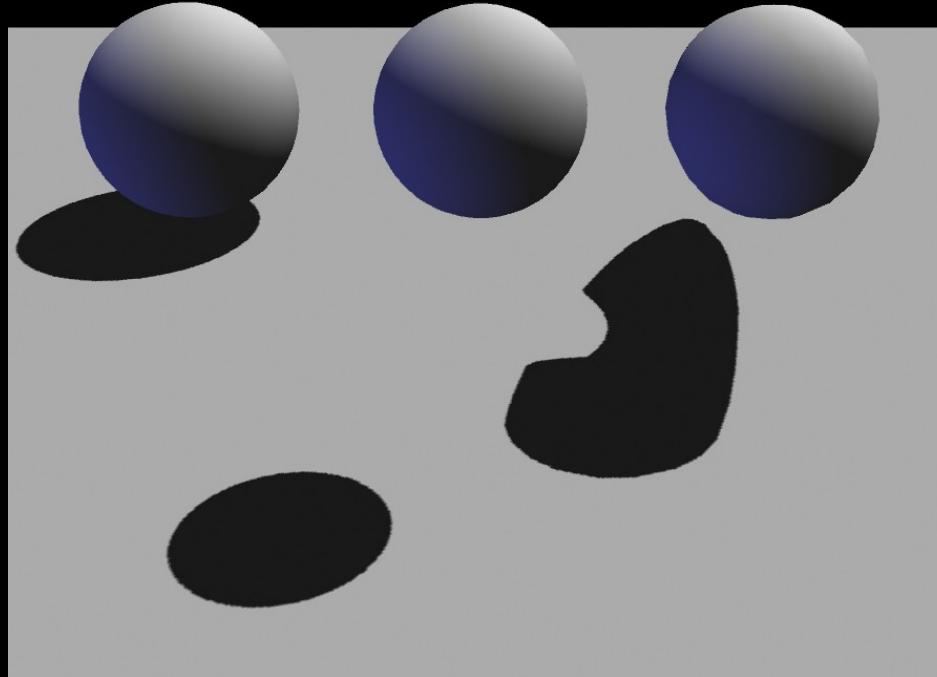
Importance of shadows

What is the difference between the 3 balls?

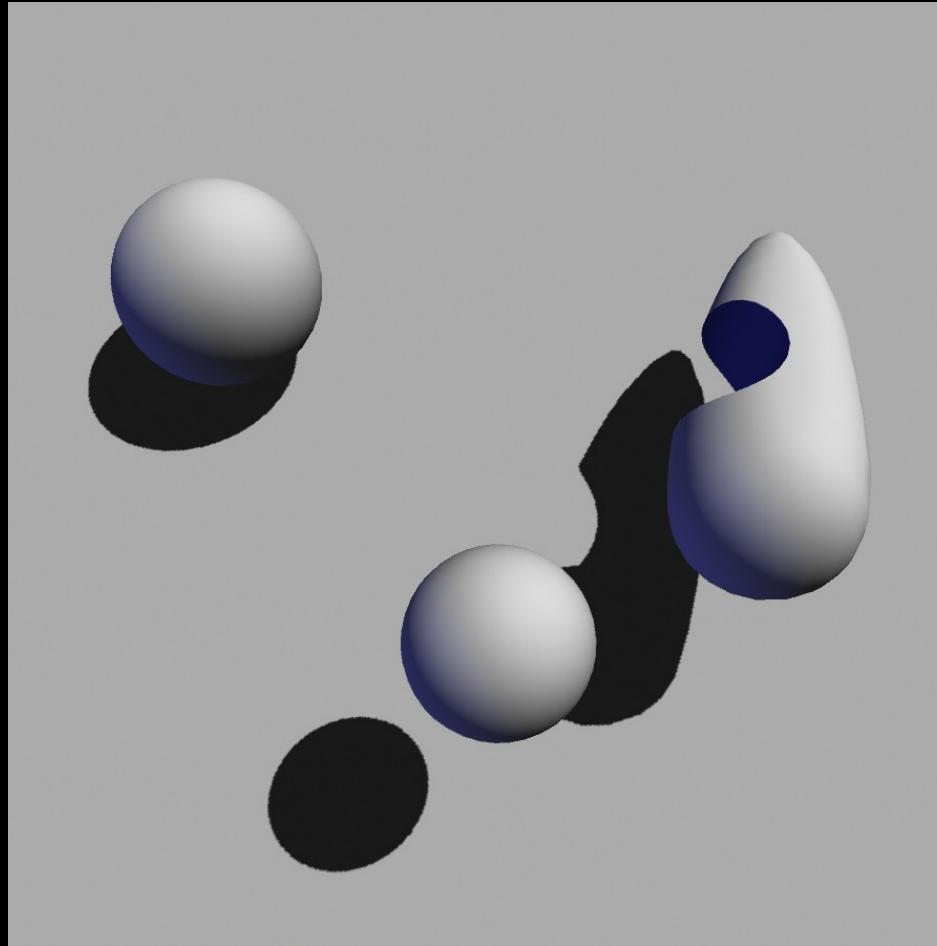


Source: UNC

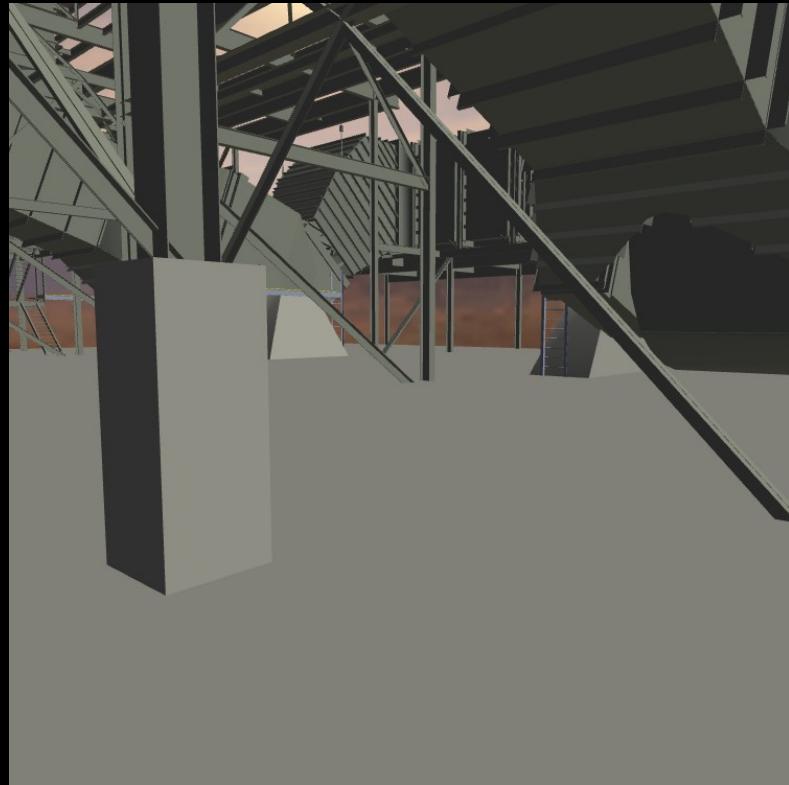
Importance of Shadows



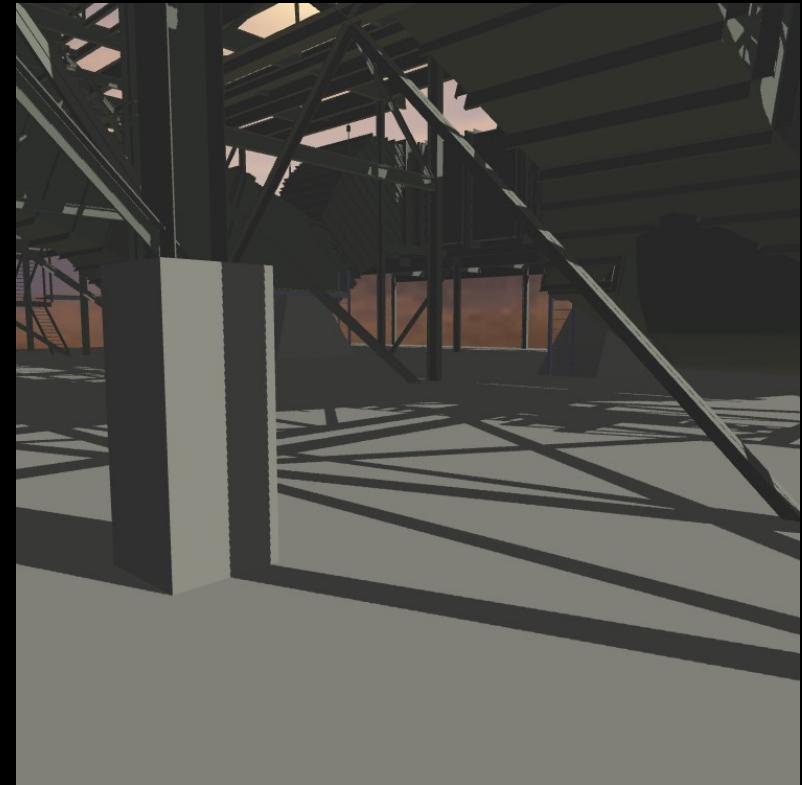
Importance of Shadows



Importance of Shadows



Without shadows



With shadows

Source: UNC

Utility of Shadows

- **Main limitation:**
 - Our screen is 2D while the real world is 3D.
- We have lots of ways to *fake* three-dimensionality.
 - Depth
 - Perspective
- Create the illusion of 3D on a 2D screen.
- Shadows are an important tool in this toolkit.

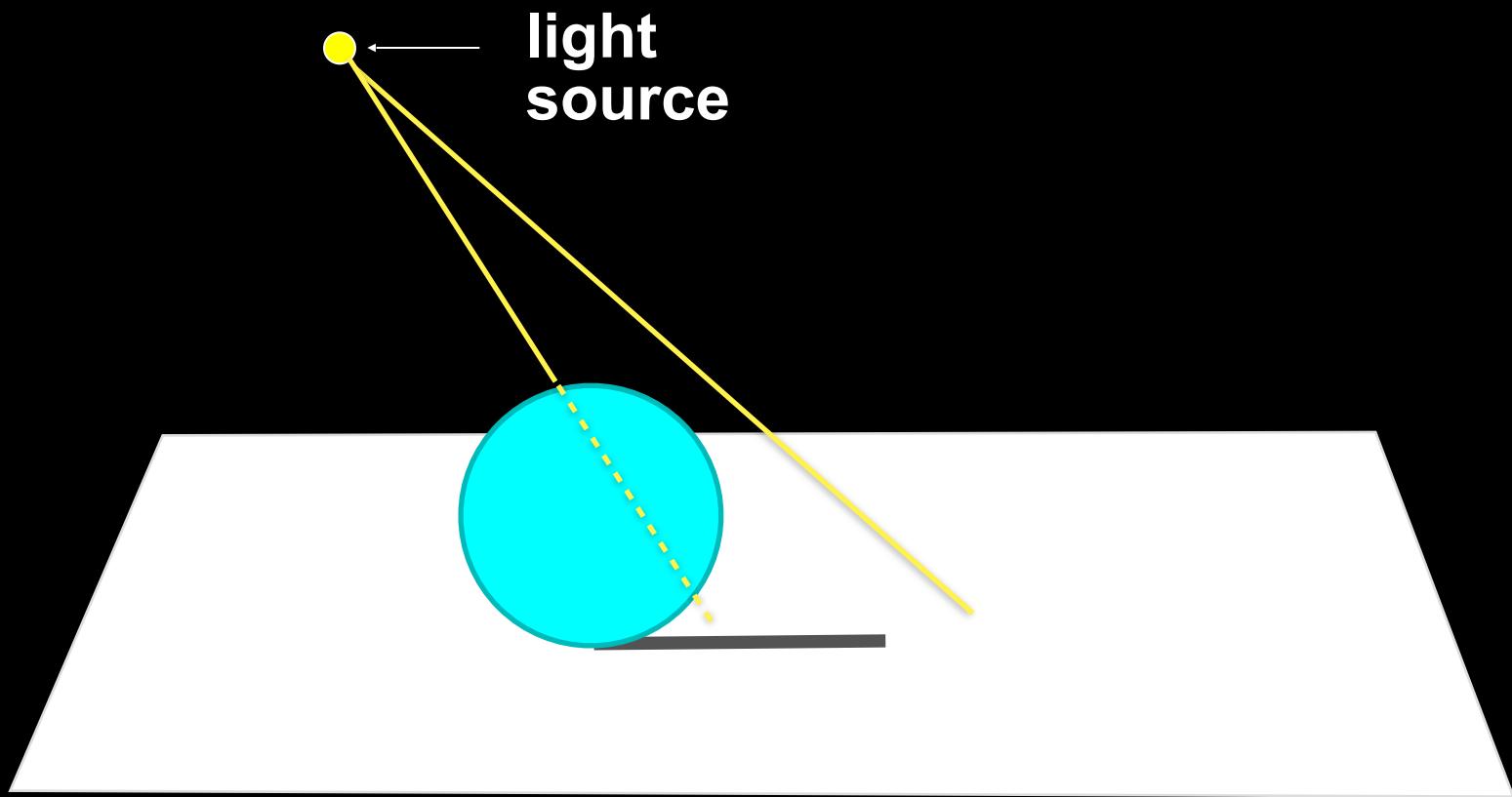
Doom III



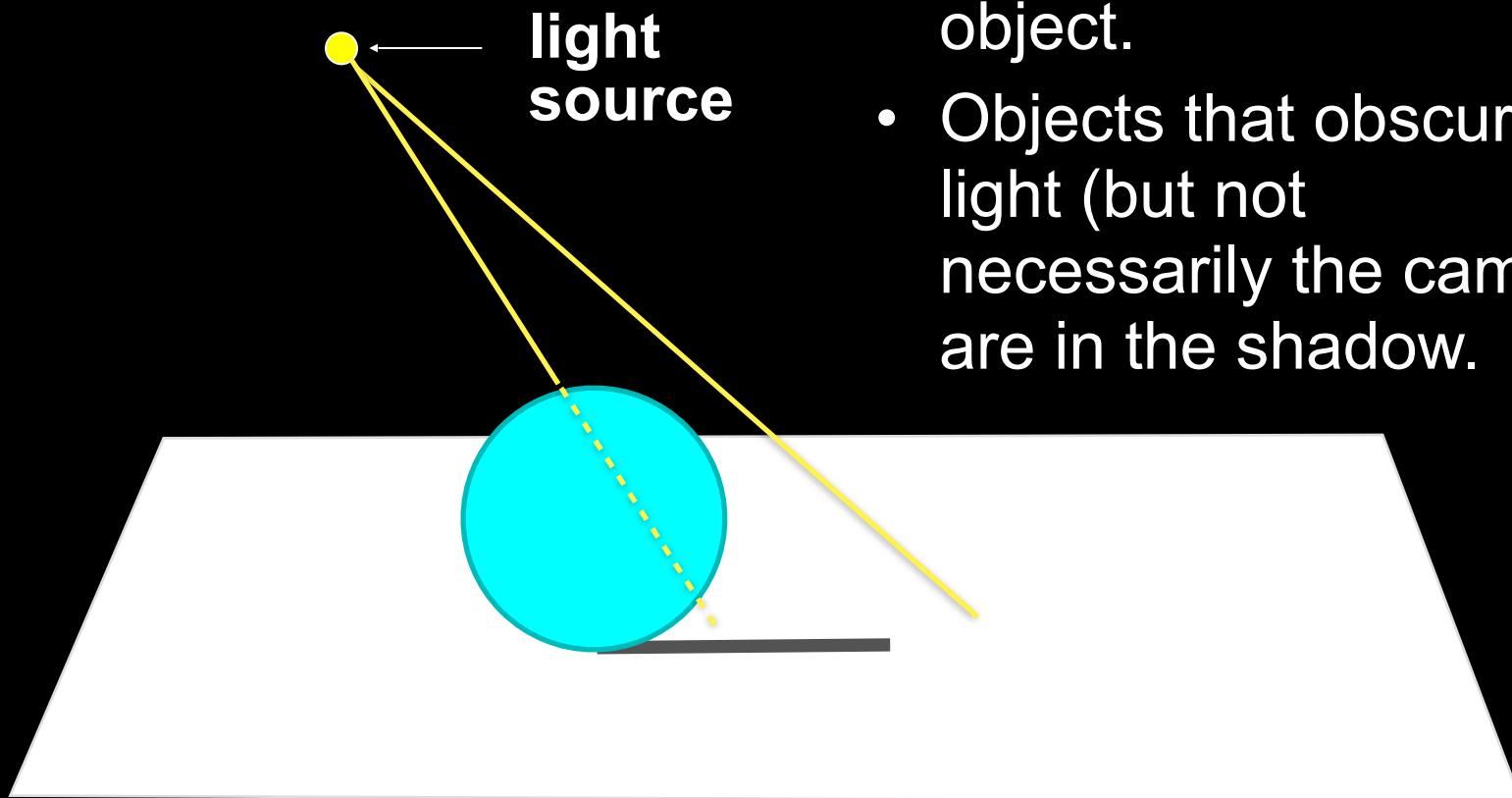
Reported to
spend 50% of
time rendering
shadows!

Source: Wikipedia

How are Shadows Defined?

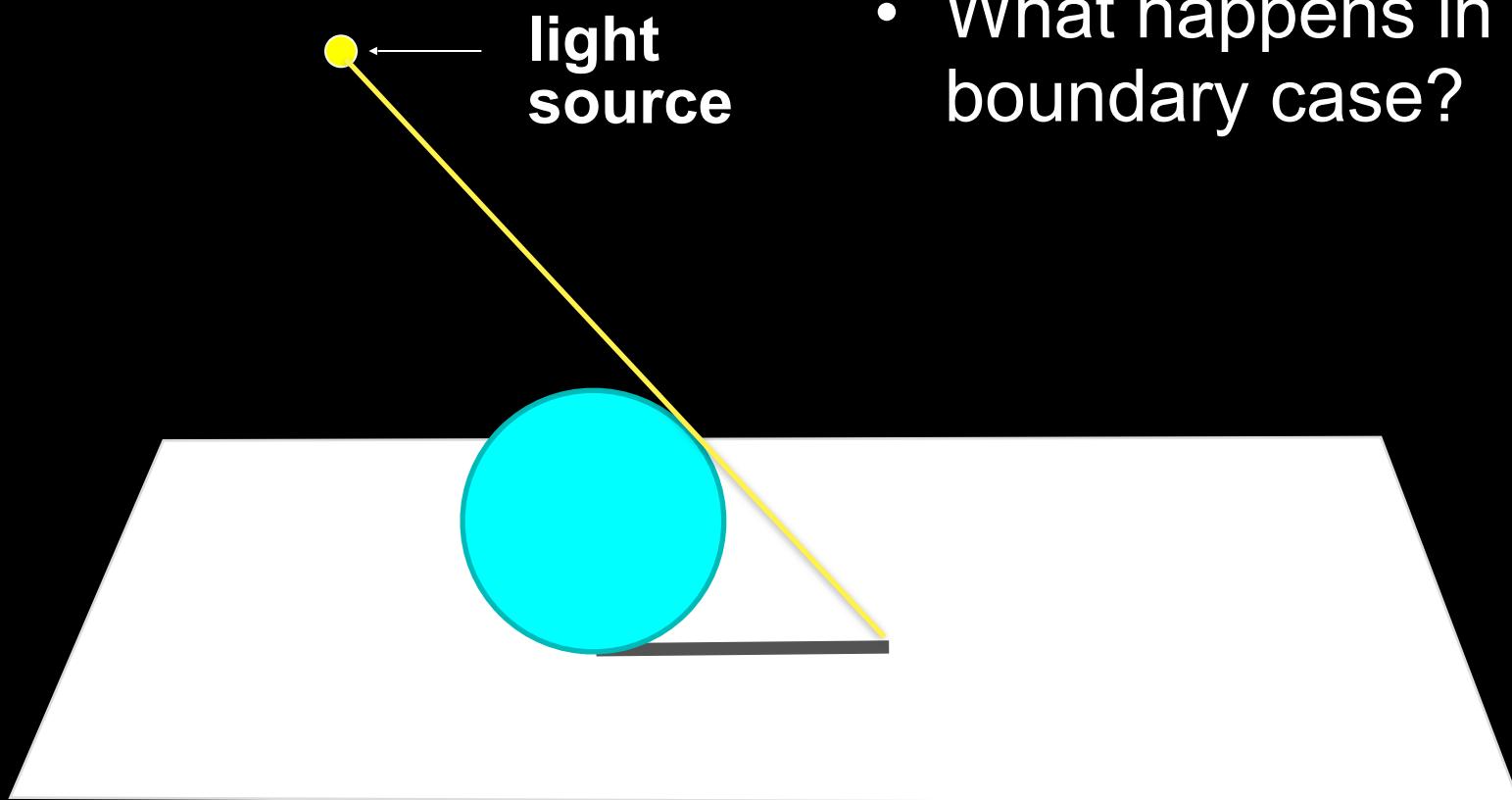


How are Shadows Defined?



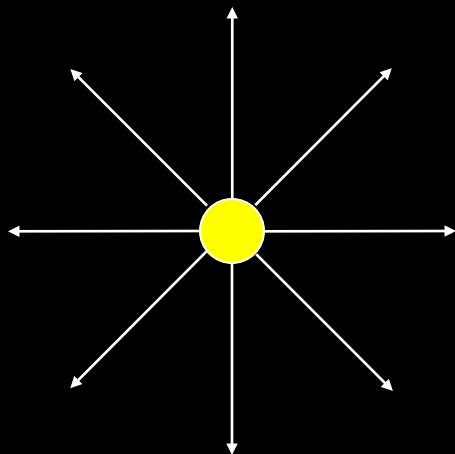
- A light source illuminates every object.
- Objects that obscure a light (but not necessarily the camera) are in the shadow.

How are Shadows Defined?

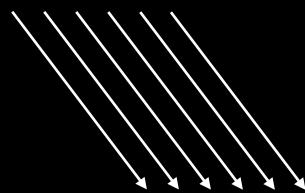


- What happens in this boundary case?

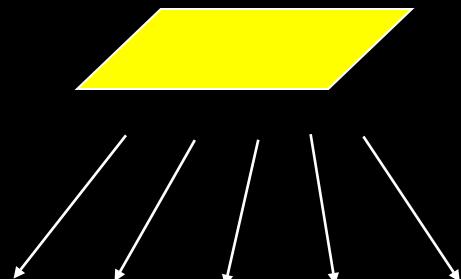
Light sources



point
light source



directional
light source

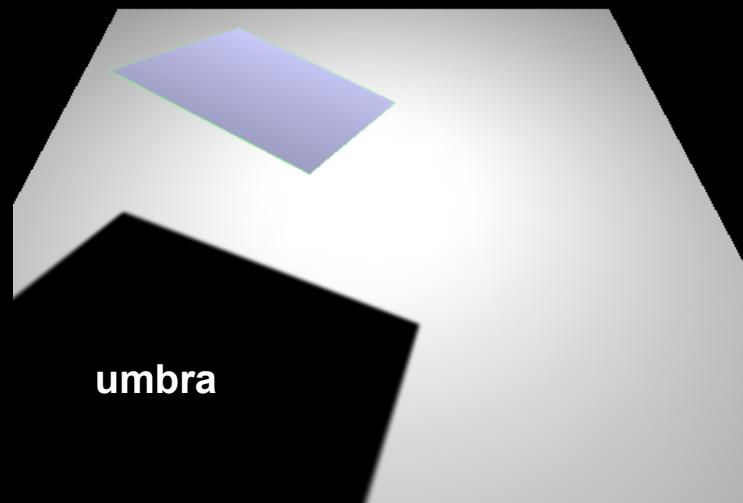


area
light source

Hard and soft shadows

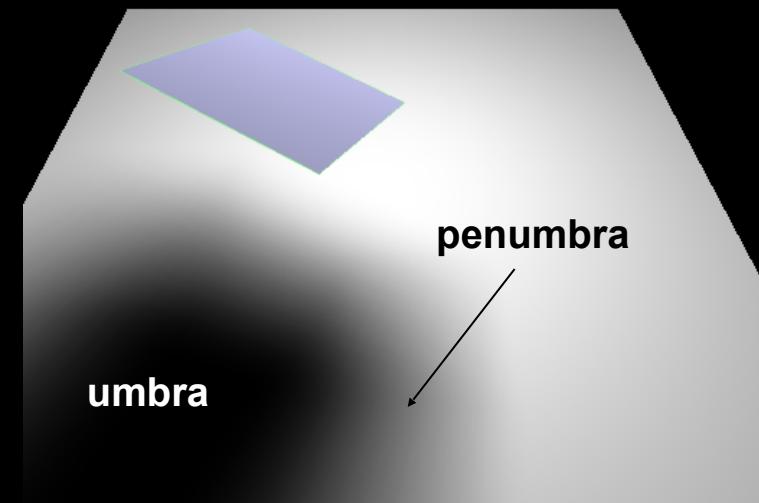


point
light



Hard shadow

area
light



Soft shadow

Source: UNC

Hard and soft shadows

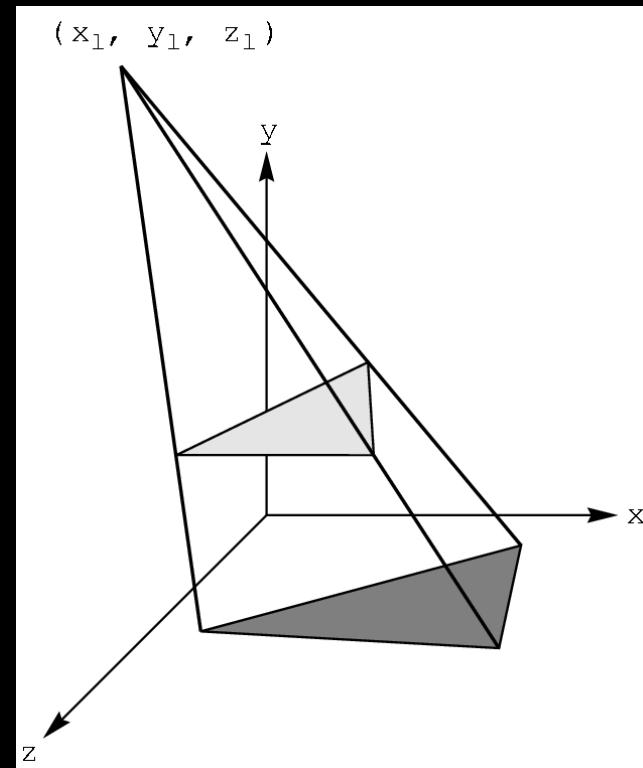
Blender demo

Shadow Algorithms

- With visibility tests
 - Accurate yet expensive
 - Example: ray casting or ray tracing
 - physical ideal
 - Example: 2-pass z-buffer
[Foley, Computer Graphics: Principles and Practice, Ch. 16.4.4]
- Without visibility tests (“fake” shadows)
 - Approximate and inexpensive
 - Using a model-view matrix “trick”

Projection-based Shadows

- Assume light source at $[x_l \ y_l \ z_l]^T$
- Assume shadow on plane $y = 0$
- Construct a modelview matrix to flatten the geometry onto the shadow plane



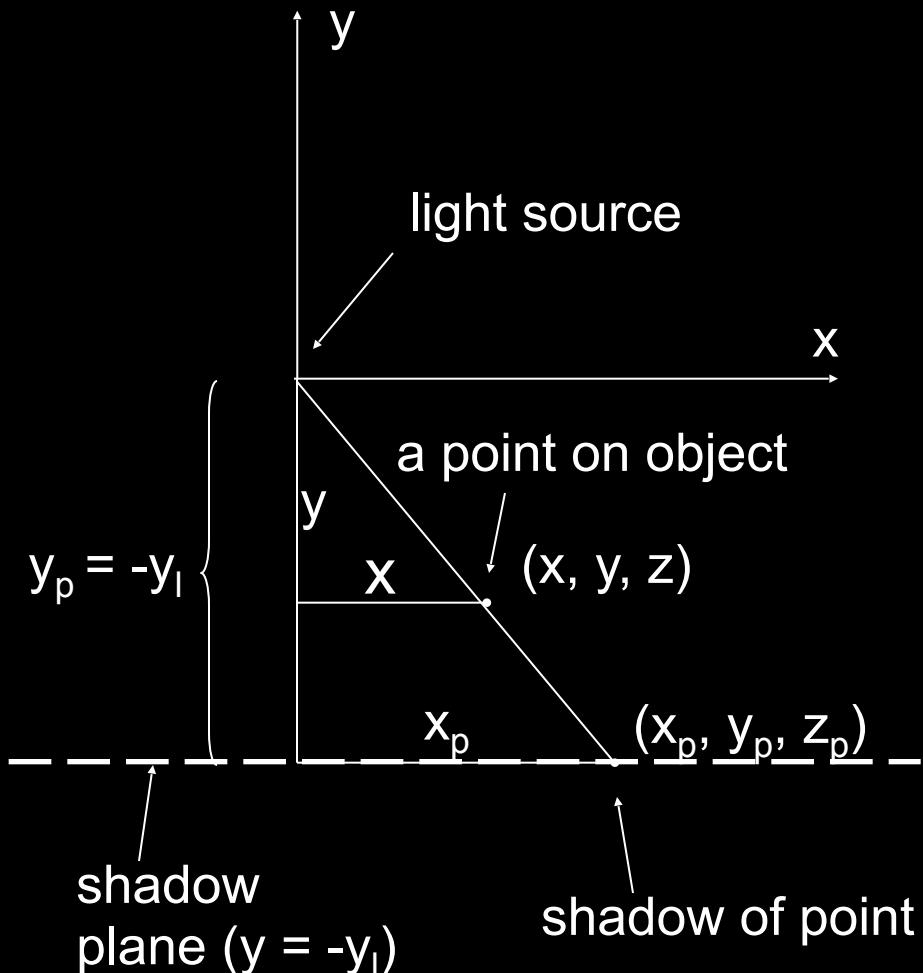
Shadow Projection Strategy

- Move light source to origin
- Apply appropriate projection matrix
- Move light source back
- Instance of general strategy: compose complex transformation from simpler ones!

$$T = \begin{bmatrix} 1 & 0 & 0 & -x_l \\ 0 & 1 & 0 & -y_l \\ 0 & 0 & 1 & -z_l \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Derive Equation

- Now, light source at origin



$$\frac{x_p}{y_p} = \frac{x}{y} \quad (\text{see picture})$$
$$y_p = -y_l \quad (\text{move light})$$
$$x_p = \frac{x}{y} y_p = -\frac{x}{y} y_l$$
$$z_p = \frac{z}{y} y_p = -\frac{z}{y} y_l$$

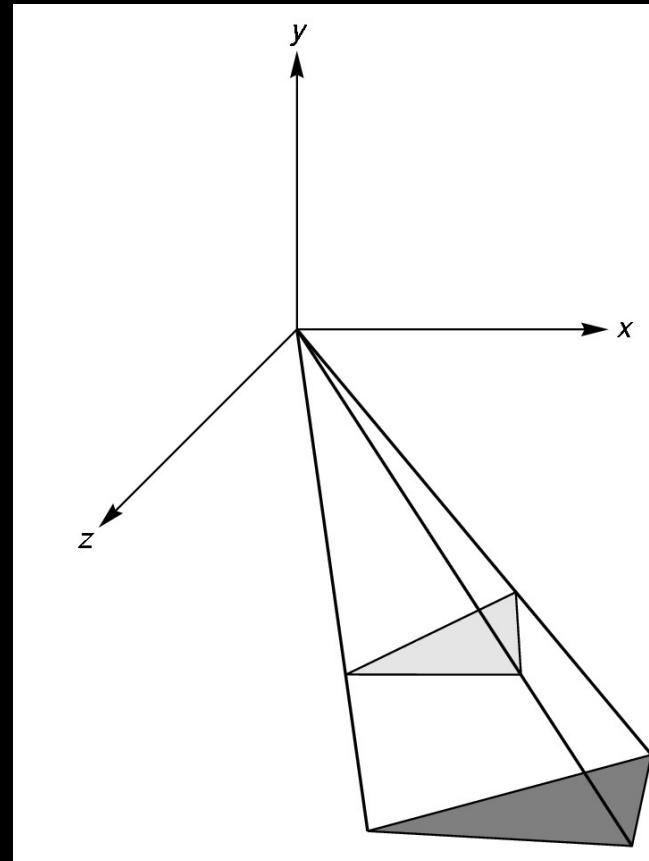
Light Source at Origin

- After translation, solve

$$M \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = w \begin{bmatrix} -\frac{xy_l}{y} \\ -y_l \\ -\frac{zy_l}{y} \\ 1 \end{bmatrix}$$

- w can be chosen freely
- Use $w = -y / y_l$

$$M \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \\ -\frac{y}{y_l} \end{bmatrix}$$



Shadow Projection Matrix

- Solution of previous equation

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -\frac{1}{y_l} & 0 & 0 \end{bmatrix}$$

- Total shadow projection matrix

$$S = T^{-1}MT = \dots$$

Implementation

- Recall column-major form

```
GLfloat m[16] =  
{1.0, 0.0, 0.0, 0.0,  
 0.0, 1.0, 0.0, -1.0 / yl,  
 0.0, 0.0, 1.0, 0.0,  
 0.0, 0.0, 0.0, 0.0};
```

- yl is light source height
- Assume `drawPolygon();` draws object

Saving the ModelView Matrix State

- Assume xl, yl, zl hold light coordinates
- Core OpenGL code (compatibility code is similar)

```
openGLMatrixMatrixMode(OpenGLMatrix::ModelView);
// here, set the model view matrix, in the usual way
// ...

drawPolygon();      // draw normally
openGLMatrixPushMatrix();    // save current matrix
openGLMatrix.Translate(xl, yl, zl);    // translate
back
openGLMatrix.MultMatrix(m);        // project
openGLMatrix.Translate(-xl, -yl, -zl); // move light to
origin

float ms[16];
openGLMatrix.GetMatrix(ms); // read the shadow matrix
```

Saving the ModelView Matrix State (cont.)

```
// upload the shadow matrix to the GPU
pipelineProgram->SetUniformVariableMatrix4fv(
    "modelViewMatrix", GL_FALSE, ms);

drawPolygon(); // draw polygon again for shadow

// restore original modelview matrix
openGLMatrix.PopMatrix();
openGLMatrix.GetMatrix(ms);
pipelineProgram->SetUniformVariableMatrix4fv(
    "modelViewMatrix", GL_FALSE, ms);

// continue rendering more objects, as usual ...
```

The Matrix and Attribute Stacks

- Mechanism to save and restore state
 - `{OpenGLMatrix::, gl}PushMatrix();`
 - `{OpenGLMatrix::, gl}PopMatrix();`
 - Remember how stacks work?
- Apply to current matrix
- In compatibility profile, can also save current attribute values
 - Examples: color, lighting
 - `glPushAttrib(GLbitfield mask);`
 - `glPopAttrib();`
 - Mask determines which attributes are saved
 - This feature has been removed in the core profile

Drawing on a Surface

- Shimmering (“z-buffer fighting”) when drawing shadow on surface
- Due to limited precision of depth buffer
- Solution: slightly displace either the surface or the shadow
(`glPolygonOffset` in OpenGL)



z-buffer
fighting



no z-buffer
fighting

Drawing on a Surface

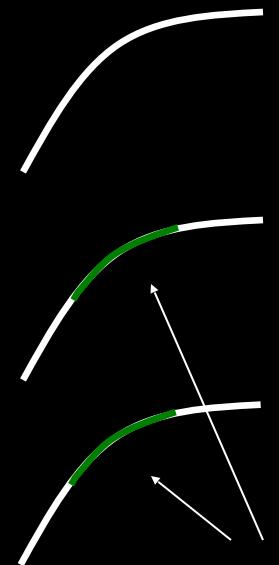
Or use general technique

1. Set depth buffer to read-only,
draw surface
2. Set depth buffer to read-write,
draw shadow
3. Set color buffer to read-only,
draw surface again
4. Set color buffer to read-write

depth buffer



color buffer



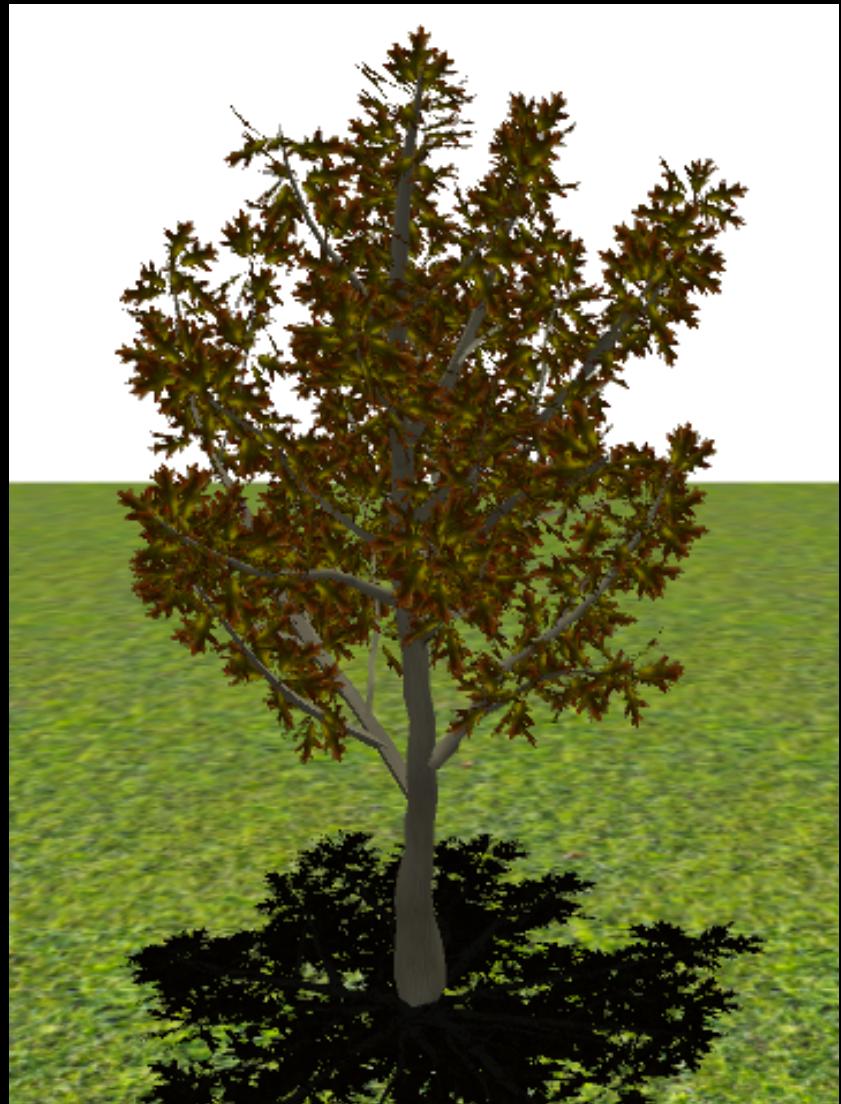
shadow
on surface

Outline

- Projections and Shadows
- Hierarchical Models

Hierarchical Models

- Many graphical objects are structured
- Exploit structure for
 - Efficient rendering
 - Example: tree leaves
 - Concise specification of model parameters
 - Example: joint angles
 - Physical realism
- Structure often naturally hierarchical



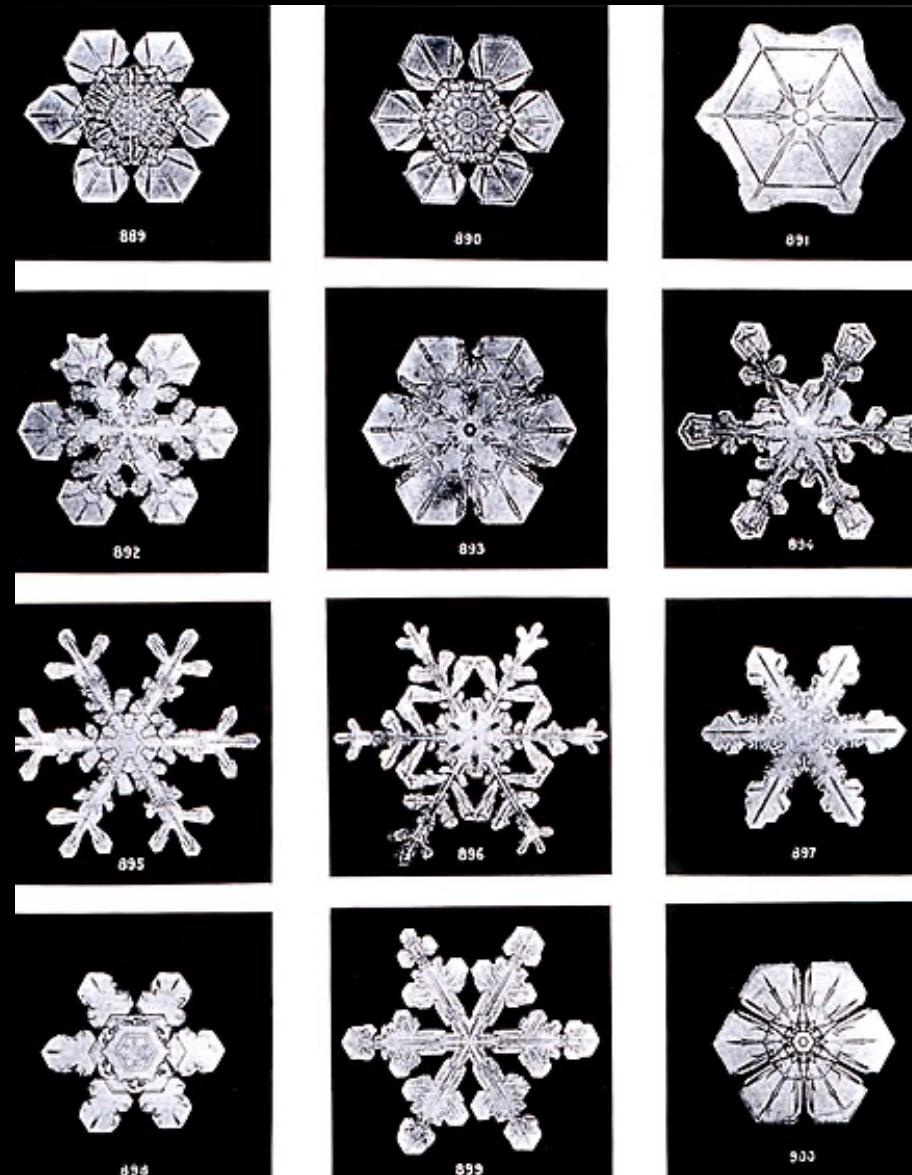
Hierarchical Models

- Crowds of background characters



Hierarchical Models

- Snowflakes



[https://commons.wikimedia.org/wiki/
File:SnowflakesWilsonBentley.jpg](https://commons.wikimedia.org/wiki/File:SnowflakesWilsonBentley.jpg)

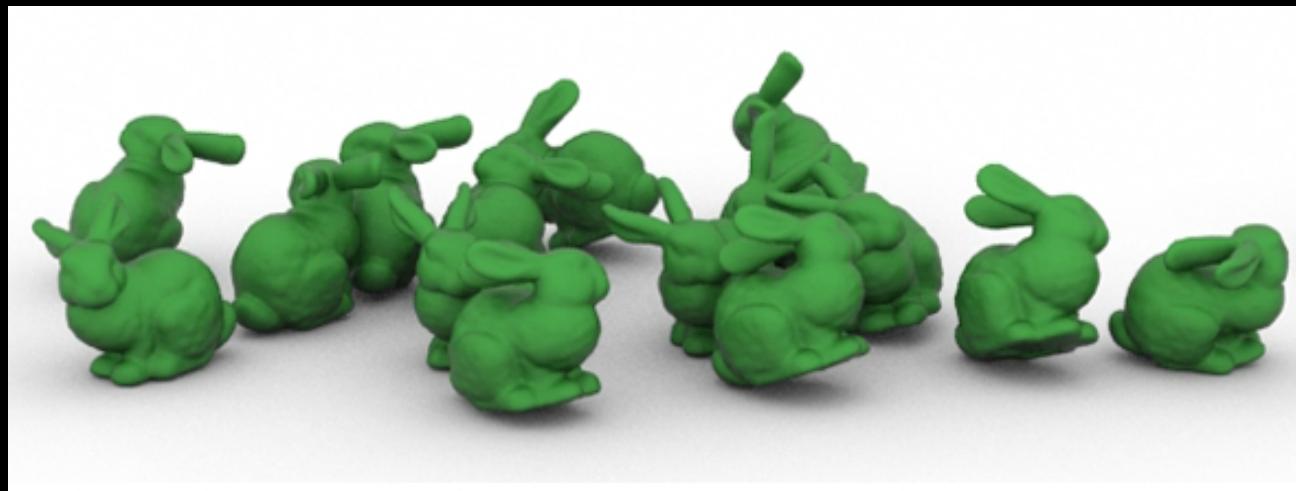
Instance Transformation

- Often we need several instances of an object
 - Wheels of a car
 - Arms or legs of a figure
 - Chess pieces



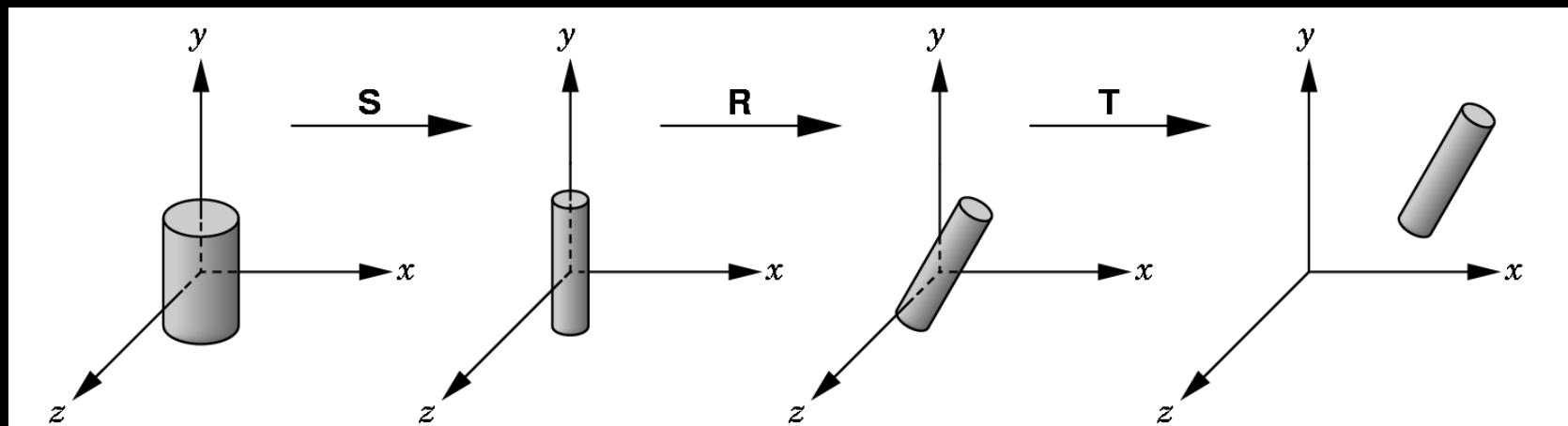
Instance Transformation

- Instances can be shared across space or time
- Write a function that renders the object in “standard” configuration
- Apply transformations to different instances
- Typical order: scaling, rotation, translation



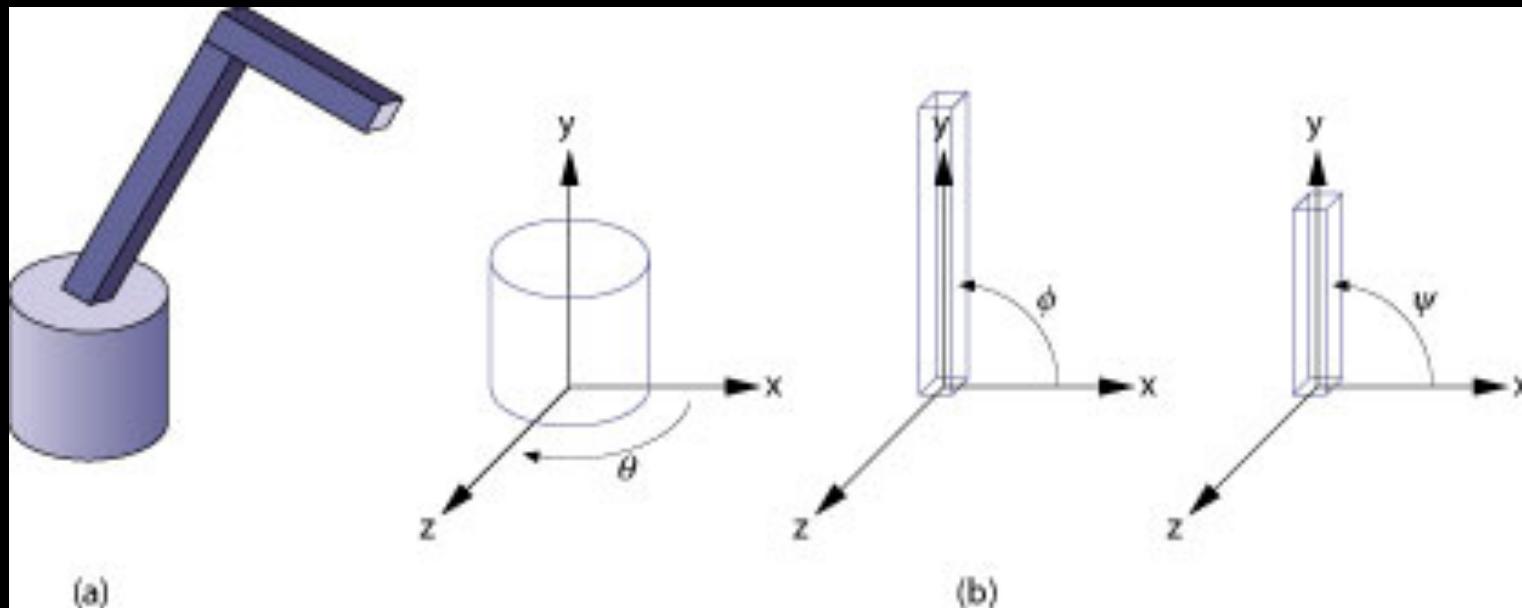
Sample Instance Transformation

```
openGLMatrixMatrixMode(OpenGLMatrix::ModelView);  
openGLMatrixLoadIdentity();  
openGLMatrix.Translate(...);  
openGLMatrix.Rotate(...);  
openGLMatrix.Scale(...);  
// ... upload modelview matrix to GPU, as usual ...  
renderCylinder(...);
```



Drawing a Compound Object

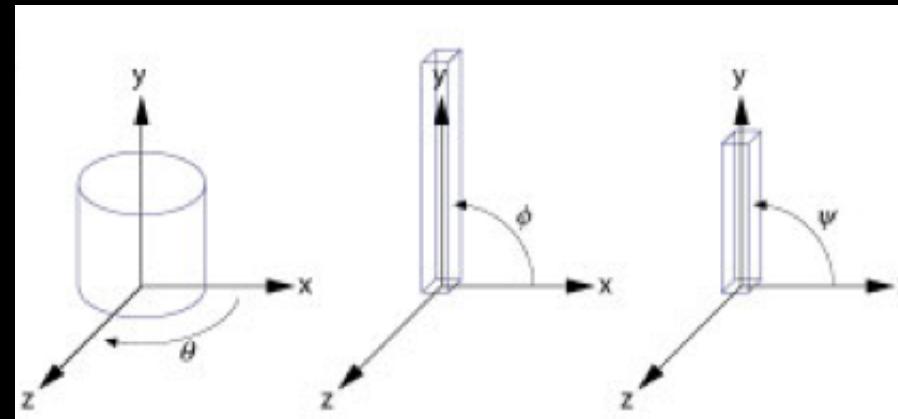
- Example: simple “robot arm”



Base rotation θ , arm angle ϕ , joint angle ψ

Hierarchical Objects and Animation

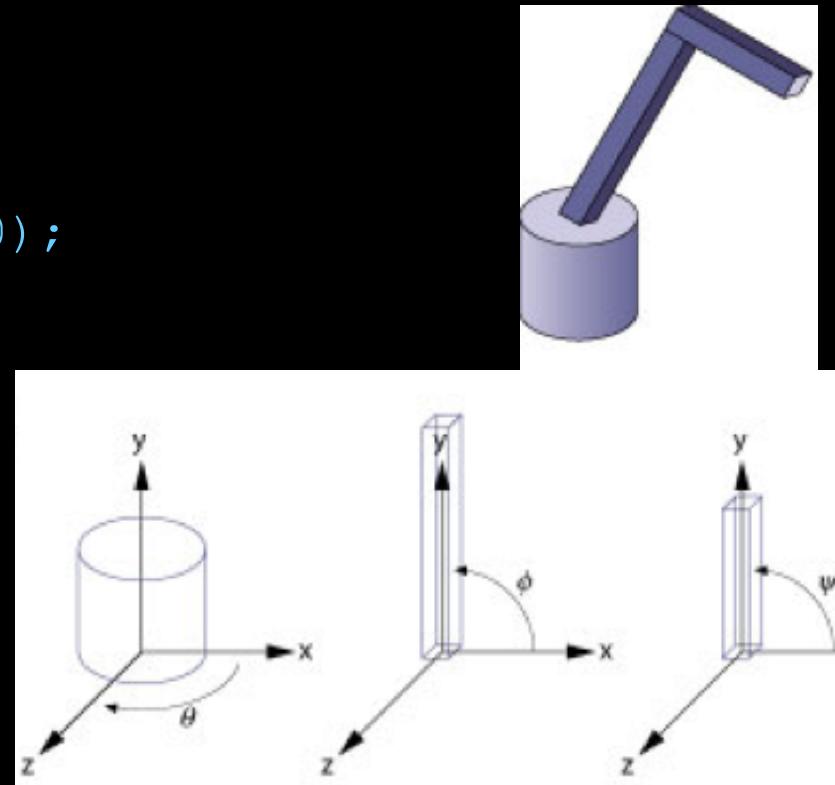
- Drawing functions are time-invariant and draw the object in a canonical position:
`drawBase(); drawLowerArm(); drawUpperArm();`
- Can be easily stored in a VBO
- Change parameters of model with time



Interleave Drawing & Transformation

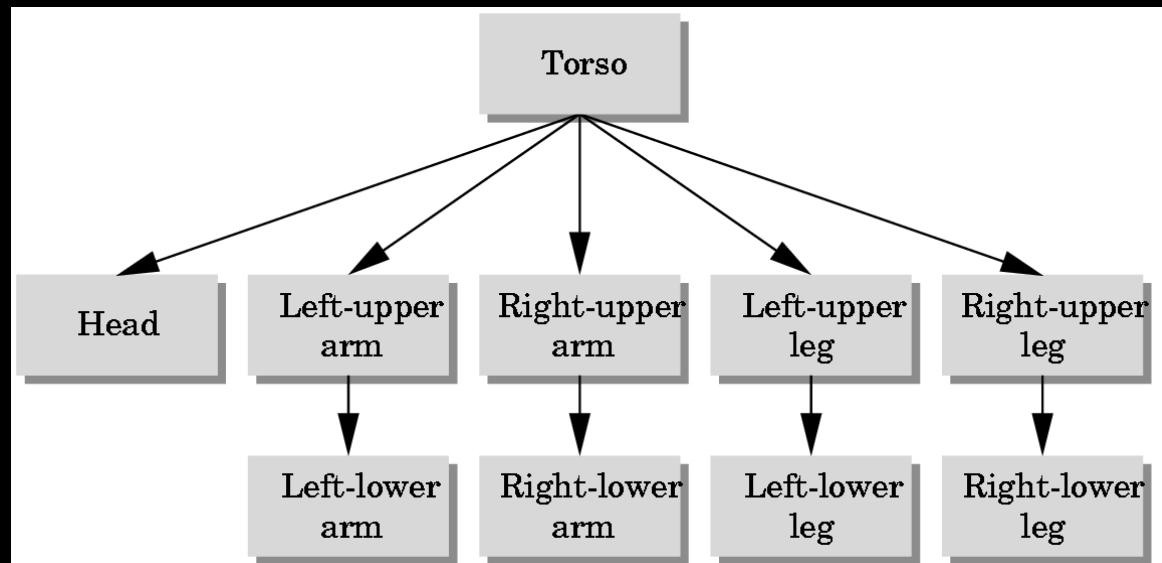
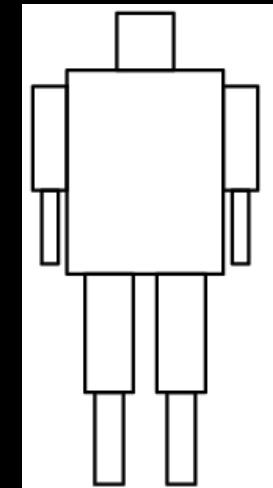
- $h1$ = height of base, $h2$ = length of lower arm
- This is pseudocode (must upload matrix to GPU)

```
void drawRobot(GLfloat theta,  
    GLfloat phi, GLfloat psi)  
{  
    Rotate(theta, 0.0, 1.0, 0.0);  
    drawBase();  
    Translate(0.0, h1, 0.0);  
    Rotate(phi, 0.0, 0.0, 1.0);  
    drawLowerArm();  
    Translate(0.0, h2, 0.0);  
    Rotate(psi, 0.0, 0.0, 1.0);  
    drawUpperArm();  
}
```



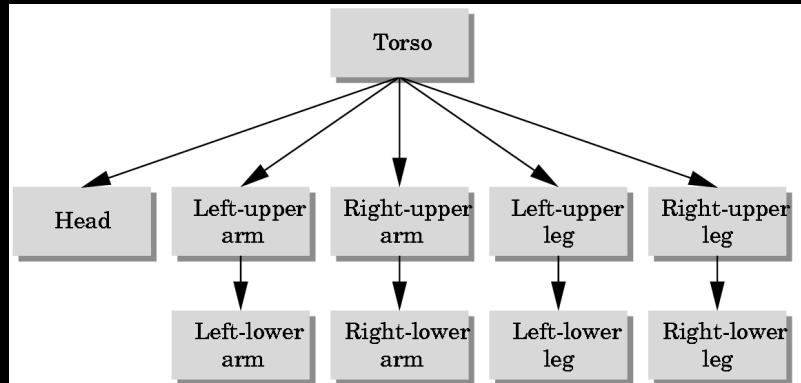
More Complex Objects

- Tree rather than linear structure
- Interleave along each branch
- Use push and pop to save state
 - (from our helper code)
 - why is a stack the right tool here?



Hierarchical Tree Traversal

- Order not necessarily fixed
(breadth-first, depth-first, etc.)
- Example:



```
void drawFigure()
{
    PushMatrix(); // save
    drawTorso();
    Translate(...); // move head
    Rotate(...); // rotate head
    drawHead();
    PopMatrix(); // restore
    PushMatrix();
```

```
    Translate(...);
    Rotate(...);
    drawLeftUpperArm();
    Translate(...)
    Rotate(...)
    drawLeftLowerArm();
    PopMatrix();
    ...
}
```

Using Tree Data Structures

- Can make tree form explicit in data structure

```
typedef struct treenode
{
    GLfloat m[16];
    void (*render) ( );
    struct treenode *sibling;
    struct treenode *child;
} treenode;
```

Initializing Tree Data Structure

- Initializing transformation matrix for node

```
treenode torso, head, ...;  
// in init function  
LoadIdentity();  
Rotate(...);  
GetMatrix(torso.m);
```

- Initializing pointers

```
torso.render = drawTorso;  
torso.sibling = NULL;  
torso.child = &head;
```

Generic Traversal: Recursion

```
void traverse (treenode *root)
{
    if (root == NULL)
        return;
    PushMatrix();
    MultMatrix(root->m);
    root->render();
    if (root->child != NULL)
        traverse(root->child);
    PopMatrix();
    if (root->sibling != NULL)
        traverse(root->sibling);
}
```

Advantages of hierarchical modeling

- Save memory on the GPU
 - Trade-off multiple render passes vs. memory constraints.
 - Allows offloading memory-intensive operations to loading screens.
- Even if hierarchical modeling is purely on CPU, it makes modeling much easier.
- Allows for easy control of complex shapes.
 - Will come in handy for animation later!

Exercise: Legos!

- Legos are the ultimate hierarchical modeling tool.
- Model simple lego bricks as cubes made from triangles
- Assemble, using instancing, Lego toys in your OpenGL world from HW1



Summary

- Projections and Shadows
- Hierarchical Models