
Algorithm 1: Transformation from Parameters to the Normal Form

Input: $m \in \mathbb{R}^2$, $C \in \mathbb{R}^{2 \times 2}$, where $C = C^\top$, $\sigma \in \mathbb{R}$

Output: $\alpha \in [0, \pi/2]$, $\kappa \in \mathbb{R}^{>1}$, $\sigma \in \mathbb{R}^+$

Rotate the coordinate system

$A \leftarrow [v_1 \ v_2]$ where $Cv_i = \lambda_i v_i$, $v_i = \frac{v_i}{\|v_i\|}$ \triangleright Eigendecomposition

$C \leftarrow A^\top C A$

$m \leftarrow A^\top m$

Rescale the coordinate system

$f_s \leftarrow \frac{1}{\sqrt{\det|C|}}$

$C \leftarrow f_s \cdot C$

$m \leftarrow f_s \cdot m$

Rescale to set $|m|$ to 1

$f_d \leftarrow \frac{1}{|m|}$

$m \leftarrow f_d \cdot m$

$\sigma \leftarrow f_d \cdot \sigma$

Flip and swap axis if necessary

if $m_{(1)} < 0$ **then**

$m \leftarrow \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \cdot m$

if $m_{(2)} < 0$ **then**

$m \leftarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot m$

if $C_{(1,1)} < 0$ **then**

$C \leftarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot C \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$m \leftarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot m \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

Aggregate return values

$\alpha \leftarrow \arccos(m_{(1)})$

$\kappa \leftarrow C_{(1,1)}$

return α, κ, σ
