

EE368 Robotic Motion and Control

Spring 2024

Project: Pick-and-Place

Date: 3.30 18:00

The task involves picking up an object from one location and placing it in another location. You will use a Kinova Gen3 Lite to complete this task.

Task:

Write a program that instructs the robotic arm to

1. move to the pick-up location.
2. pick up the object.
3. move to the place location.
4. place the object.
5. pick and place should be in different pose.

Submission:

Demonstrate your program to the teaching assistant.