

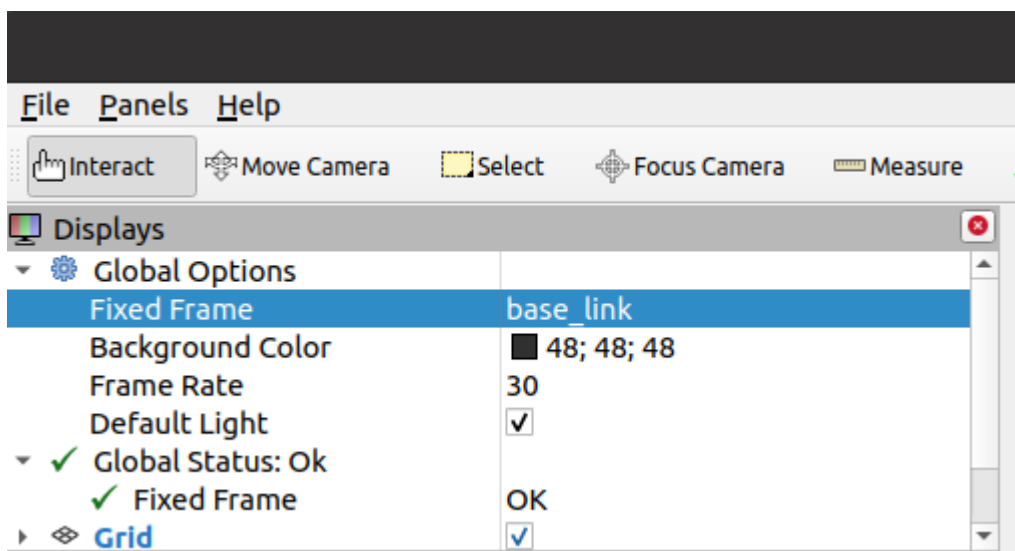
# Kinova ROS Package

官方教程 [https://github.com/Kinovarobotics/ros\\_kortex](https://github.com/Kinovarobotics/ros_kortex)

```
sudo rosdep init
rosdep update
sudo apt install git
sudo apt install python3 python3-pip
sudo python3 -m pip install conan==1.59.0
conan config set general.revisions_enabled=1
conan profile new default --detect > /dev/null
conan profile update settings.compiler.libcxx=libstdc++11 default
mkdir -p catkin_workspace/src
cd catkin_workspace/src
git clone https://github.com/Kinovarobotics/ros_kortex.git
cd ../
rosdep install --from-paths src --ignore-src -y
catkin_make
source devel/setup.bash
```

```
roslaunch kortex_gazebo spawn_kortex_robot.launch arm:="gen3_lite"
```

修改Fixed Frame



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