

PA2 Problem 1

In [1]:

```
from google.colab import drive
drive.mount('/content/drive')
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

In [2]:

```
# import os
# os.chdir('/content/drive/MyDrive/2_pose_estimation')
# !python main.py
```

In [3]:

```
import os
import sys
sys.path.append(os.path.abspath('/content/drive/MyDrive/2_pose_estimation'))

from model import *
import torch
import numpy as np
import torchvision
import tqdm
from torch.utils.data import Dataset
from torch.utils.data import DataLoader
import cv2
import math
import torch.nn as nn
import torch.optim as optim

from glob import glob
import pandas
import matplotlib.pyplot as plt

device = 'cuda:0'
num_joints = 21
```

In [4]:

```
class Dataset(Dataset):
    def __init__(self, method=None):
        self.root = '/content/drive/MyDrive/2_pose_estimation/dataset/'
        self.x_data = []
        self.y_data = []
        if method == 'train':
            self.root = self.root + 'train/'
            self.img_path = sorted(glob(self.root + 'rgb/*.jpg'))

        elif method == 'test':
            self.root = self.root + 'test/'
            self.img_path = sorted(glob(self.root + 'rgb/*.jpg'))

        for i in tqdm.tqdm(range(len(self.img_path))):
            img = cv2.imread(self.img_path[i], cv2.IMREAD_COLOR)
            b, g, r = cv2.split(img)
            img = cv2.merge([r, g, b])
            self.x_data.append(img)

            num = self.img_path[i].split('.')[0].split('/')[ -1]
            img_pkl = self.root + 'meta/' + str(num) + '.pkl'
            pkl = pandas.read_pickle(img_pkl)
            coords_2d = pkl['coords_2d']
```

```

        self.y_data.append(coords_2d)

def __len__(self):
    return len(self.img_path)

def __getitem__(self, idx):
    transform1 = torchvision.transforms.ToTensor()
    new_x_data = transform1(self.x_data[idx])

    return new_x_data, self.y_data[idx]

```

In [5]:

```

class Tester(object):
    def __init__(self, batch_size):
        self.batch_size = batch_size
        self._build_model()

        self.root = '/content/drive/MyDrive/2_pose_estimation/dataset/'

        # Load of pretrained_weight file
        weight_PATH = '/content/drive/MyDrive/2_pose_estimation/dataset/pretrained_weight
.pth'

        self.poseNet.load_state_dict(torch.load(weight_PATH))

        print("Testing...")

    def _build_model(self):
        # 2d pose estimator
        poseNet = CPM2DPose()
        self.poseNet = poseNet.to(device)

        print('Finish build model.')

    def heatmap2skeleton(self, heatmapsPoseNet):
        skeletons = np.zeros((heatmapsPoseNet.shape[0], heatmapsPoseNet.shape[1], 2))
        for m in range(heatmapsPoseNet.shape[0]):
            for i in range(heatmapsPoseNet.shape[1]):
                u, v = np.unravel_index(np.argmax(heatmapsPoseNet[m][i]), (32, 32))
                skeletons[m, i, 0] = u * 8
                skeletons[m, i, 1] = v * 8
        return skeletons

    @staticmethod
    def plot_hand(coords_hw, axis, color_fixed=None, linewidth='1'):
        colors = np.array([[0., 0., 1.],
                           [0., 0., 1.],
                           [0., 0., 1.],
                           [0., 0., 1.],
                           [1., 0., 1.],
                           [1., 0., 1.],
                           [1., 0., 1.],
                           [1., 0., 1.],
                           [1., 0., 0.],
                           [1., 0., 0.],
                           [1., 0., 0.],
                           [1., 0., 0.],
                           [0., 1., 0.],
                           [0., 1., 0.],
                           [0., 1., 0.],
                           [0., 1., 0.],
                           [1., 0.5, 0.],
                           [1., 0.5, 0.],
                           [1., 0.5, 0.],
                           [1., 0.5, 0.]])
        bones = [((1, 0), colors[0, :]),
                  ((2, 1), colors[1, :]),
                  ((3, 2), colors[2, :]),
                  ((4, 3), colors[3, :]),
                  ((0, 5), colors[4, :]),
                  ((5, 6), colors[5, :]),

```

```

        ((6, 7), colors[6, :]),
        ((7, 8), colors[7, :]),
        ((0, 9), colors[8, :]),
        ((9, 10), colors[9, :]),
        ((10, 11), colors[10, :]),
        ((11, 12), colors[11, :]),
        ((0, 13), colors[12, :]),
        ((13, 14), colors[13, :]),
        ((14, 15), colors[14, :]),
        ((15, 16), colors[15, :]),
        ((0, 17), colors[16, :]),
        ((17, 18), colors[17, :]),
        ((18, 19), colors[18, :]),
        ((19, 20), colors[19, :]))
    for connection, color in bones:
        coord1 = coords_hw[connection[0], :]
        coord2 = coords_hw[connection[1], :]
        coords = np.stack([coord1, coord2])
        if color_fixed is None:
            axis.plot(coords[:, 1], coords[:, 0], color=color, linewidth=linewidth)
        else:
            axis.plot(coords[:, 1], coords[:, 0], color_fixed, linewidth=linewidth)

# test '106.png' image, origin code
def test106(self):
    path = self.root + 'test/rgb/106.jpg'
    pkl_path = self.root + 'test/meta/106.pkl'
    print(path)
    print(pkl_path)
    img = cv2.imread(path, cv2.IMREAD_COLOR)
    b, g, r = cv2.split(img)
    img = cv2.merge([r, g, b])
    transform1 = torchvision.transforms.ToTensor()
    x_data = transform1(img)
    pkl = pandas.read_pickle(pkl_path)
    y_test = pkl['coords_2d']

    self.poseNet.eval()

    print("Testing 106.jpg heatmap")

    print(x_data.size())

    heatmapsPoseNet = self.poseNet(x_data.unsqueeze(0).cuda()).cpu().detach().numpy()
)
    heatmap = np.transpose(heatmapsPoseNet[0], (1, 2, 0))

    plt.rcParams['figure.figsize'] = [12, 5]
    for i in range(num_joints):
        ax = plt.subplot(3, 7, i + 1)
        ax.imshow(heatmap[:, :, i])
    plt.savefig(self.root + 'heatmap.png')
    plt.show()

    print("Testing 106.jpg heatmap")

    ax = plt.subplot(1, 1, 1)
    ax.imshow(img)
    pred = self.heatmap2skeleton(heatmapsPoseNet)[0]
    self.plot_hand(pred, ax)
    error = self.calc_error(y_test, pred)
    print(f"Error is {error}")
    plt.savefig(self.root + 'results.png')
    plt.show()

# test all images
def test(self):
    totalError = 0
    for i in range(500):
        img_path = self.root + 'test/rgb/%d.jpg' % (i)
        pkl_path = self.root + 'test/meta/%d.pkl' % (i)
        print(img_path)

```

```

img = cv2.imread(img_path, cv2.IMREAD_COLOR)
b, g, r = cv2.split(img)
img = cv2.merge([r, g, b])
transform1 = torchvision.transforms.ToTensor()
x_data = transform1(img)
pkl = pandas.read_pickle(pkl_path)
y_test = pkl['coords_2d']

self.poseNet.eval()

heatmapsPoseNet = self.poseNet(x_data.unsqueeze(0).cuda()).cpu().detach().numpy()

heatmap = np.transpose(heatmapsPoseNet[0], (1, 2, 0))

pred = self.heatmap2skeleton(heatmapsPoseNet)[0]
error = self.calc_error(y_test, pred)
print(f"Testing {i}-th image's error is {error}")
totalError += error

print(f"Total Error is {totalError/500}")

# Probl - 3)
def calc_error(self, gt, pred):
    k = 21 # num of keypoints
    err = 0
    for i in range(k):
        err += math.sqrt(math.pow((gt[i][0] - pred[i][0]),2) + math.pow((gt[i][1] - pred[i][1]),2)) # calculate Loss

    err = err/k # Loss average of keypoints
    return err

```

In [6]:

```

def main():
    epochs = 60
    batchSize = 16
    learningRate = 1e-5

    # trainer = Trainer(epochs, batchSize, learningRate)
    # trainer.train()

    tester = Tester(batchSize)
    # Probl - 1) & 2)
    tester.test106()
    # Probl - 4)
    tester.test()

```

In [7]:

```

if __name__ == '__main__':
    main()

```

Finish build model.

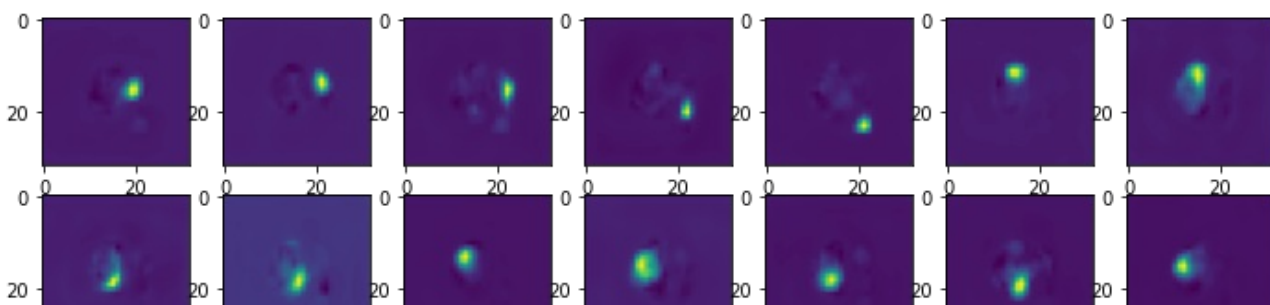
Testing...

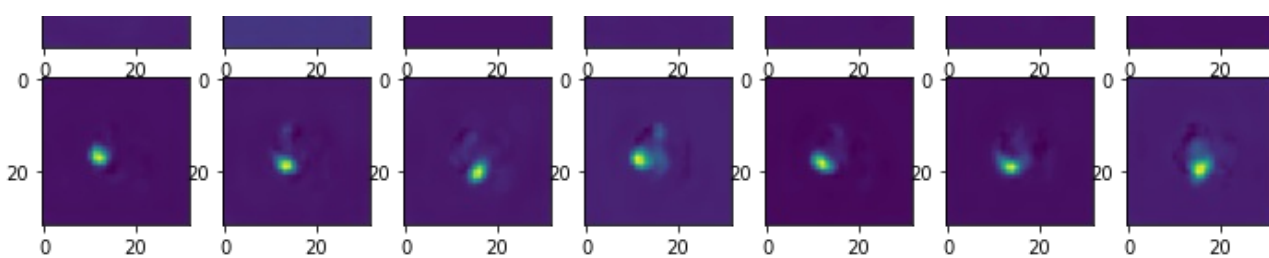
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/106.jpg

/content/drive/MyDrive/2_pose_estimation/dataset/test/meta/106.pkl

Testing 106.jpg heatmap

torch.Size([3, 256, 256])





Testing 106.jpg heatmap

Error is 11.913604723320782



/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/0.jpg

Testing 0-th image's error is 57.66479025779912

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/1.jpg

Testing 1-th image's error is 10.878121586641532

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/2.jpg

Testing 2-th image's error is 21.998594504762927

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/3.jpg

Testing 3-th image's error is 42.90298992041422

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/4.jpg

Testing 4-th image's error is 24.60365074156147

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/5.jpg

Testing 5-th image's error is 8.859807612912068

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/6.jpg

Testing 6-th image's error is 9.376239102893528

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/7.jpg

Testing 7-th image's error is 17.242627566389803

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/8.jpg

Testing 8-th image's error is 11.109252545202887

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/9.jpg

Testing 9-th image's error is 14.265853417969332

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/10.jpg

Testing 10-th image's error is 31.195565236688193

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/11.jpg

Testing 11-th image's error is 16.45780807764936

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/12.jpg

Testing 12-th image's error is 37.536740487868485

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/13.jpg

Testing 13-th image's error is 51.03928416461971

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/14.jpg

Testing 14-th image's error is 23.495382011013923

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/15.jpg

Testing 15-th image's error is 14.661141059359482

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/16.jpg

Testing 16-th image's error is 21.837973939230512

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/17.jpg

Testing 17-th image's error is 35.686825397423085

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/18.jpg

Testing 18-th image's error is 9.707463754127605

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/19.jpg

Testing 19-th image's error is 19.396134140739026

/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/20.jpg

Testing 20-th image's error is 17.88031904986894
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/21.jpg
Testing 21-th image's error is 15.236939240129654
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/22.jpg
Testing 22-th image's error is 33.474850285390986
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/23.jpg
Testing 23-th image's error is 20.058233874408423
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/24.jpg
Testing 24-th image's error is 38.08383598013794
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Testing 25-th image's error is 49.15279473348567
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Testing 26-th image's error is 17.83000011819201
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Testing 27-th image's error is 38.07067324813305
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Testing 28-th image's error is 47.446253588910906
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Testing 29-th image's error is 27.29204017618509
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Testing 30-th image's error is 28.437856559829623
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/31.jpg
Testing 31-th image's error is 22.282793631910877
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Testing 32-th image's error is 23.590027092885204
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/33.jpg
Testing 33-th image's error is 40.94975439697934
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Testing 34-th image's error is 28.580485843549155
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Testing 35-th image's error is 12.823465231605073
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Testing 36-th image's error is 22.596865287710663
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/37.jpg
Testing 37-th image's error is 7.622680815919042
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/38.jpg
Testing 38-th image's error is 29.93984370107794
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/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/92.jpg

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Testing 97-th image's error is 23.08107074434513
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/98.jpg
Testing 98-th image's error is 12.833098402632531
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/99.jpg
Testing 99-th image's error is 11.93817328047916
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Testing 100-th image's error is 38.85726645408579
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Testing 101-th image's error is 60.32938689954893
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Testing 102-th image's error is 31.715437137838215
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Testing 103-th image's error is 11.97803948280676
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Testing 104-th image's error is 34.14524891960037
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/105.jpg
Testing 105-th image's error is 44.28574814725533
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/106.jpg
Testing 106-th image's error is 11.913604723320782
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/107.jpg
Testing 107-th image's error is 51.5213770074065
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/108.jpg
Testing 108-th image's error is 14.695662957264377
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/109.jpg
Testing 109-th image's error is 39.04141001187313
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/110.jpg
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/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/477.jpg
Testing 477-th image's error is 14.885512911595614
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/478.jpg
Testing 478-th image's error is 12.645748196976166
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/479.jpg
Testing 479-th image's error is 26.278373505808652
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/480.jpg
Testing 480-th image's error is 16.585615816300805
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/481.jpg
Testing 481-th image's error is 32.45800357676127
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/482.jpg
Testing 482-th image's error is 13.806562650736154
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/483.jpg
Testing 483-th image's error is 11.35747149699046
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/484.jpg
Testing 484-th image's error is 21.486829452143123
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/485.jpg
Testing 485-th image's error is 17.5641008512674
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/486.jpg
Testing 486-th image's error is 47.779975488954854
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/487.jpg
Testing 487-th image's error is 34.586874868151185
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/488.jpg

Testing 488-th image's error is 23.35343415609563
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/489.jpg
Testing 489-th image's error is 21.066705245441444
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/490.jpg
Testing 490-th image's error is 25.83557864500388
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/491.jpg
Testing 491-th image's error is 28.74209916696023
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/492.jpg
Testing 492-th image's error is 11.083623359032762
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/493.jpg
Testing 493-th image's error is 22.41207910653096
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/494.jpg
Testing 494-th image's error is 56.562314604481344
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/495.jpg
Testing 495-th image's error is 17.883711140984847
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/496.jpg
Testing 496-th image's error is 17.678014149215024
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/497.jpg
Testing 497-th image's error is 48.476006184075686
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/498.jpg
Testing 498-th image's error is 24.101821331360675
/content/drive/MyDrive/2_pose_estimation/dataset/test/rgb/499.jpg
Testing 499-th image's error is 39.94676871026735
Total Error is 27.091240426309717