Sung Jae Park

&(+82)10-5361-0240 **teri3**05@snu.ac.kr

Education

Seoul National University:

Mar. 2017 – Present

Department of Mechanical Engineering (Double Major in Mathematics), Accumulative GPA: 4.24/4.3

Gyeonggi Science Highschool for the Gifted:

Mar. 2014 – Feb. 2017

Research Interests

I am interested in robot learning for complex, long-horizon robot manipulation, and ultimately aim to develop a general-purpose robot. To achieve this, the specific topics I am interested in are:

- Learning a model with a human-level physical understanding
- Contact-rich dexterous manipulation
- Efficient RL Algorithms

Major Courseworks

- Dynamics / Control Theory
- Introduction to Deep Learning
- Mechatronics
- Numerical Optimization
- Thermodynamics / Heat Transfer
- Probabilistic Graphical Model
- Mathematical Analysis / Abstract Algebra
- Introduction to Robotics
- Mathematical Foundations of Deep Learning
- Data Structure
- •Fluid Mechanics
- Solid Mechanics / Mechanics and Design
- Introduction to Topology

Research Experiences

Dynamic Robotics Systems Lab Research Intern |

Jul. 2021 – Aug. 2021, Jan. 2022 – June. 2022

Advisor: Jaeheung Park from Seoul National University

- Developed vision-based peg-in-hole algorithm for dual robot arm with hole detection using hand-eye camera and YOLO
- Developed motion planning algorithm under constraint with Block Neural Autoregressive Flow for Panda Franka robot arm.

SNU Robotics Lab Undergraduate Thesis Research Intern |

Mar. 2022 – Dec. 2022

Advisor: Frank C. Park from Seoul National University

• Developed cross-embodiment RL with object-centric planning.

Cognitive Learning for Vision and Robotics Lab Research Intern | Jul. 2022 – Present Advisor: Joseph J. Lim from Korea Advanced Institute of Science and Technology (KAIST)

• Developing an efficient reinforcement learning algorithm based on task-oriented state criticalness.

Honors and Awards

Silver Prize (Math/Computation Field), Samsung Humantech Paper Award
Gangwon Future Highflier Scholarship

Jan. 2018 – Present

International Design Contest Robocon 2018 2nd place Full-funded scholarship for academic excellence Presidential Science Scholarship Aug. 2018 Mar. 2018 – Dec. 2019, Mar.2021 Mar. 2021 – Present

Skills

Language: C++, Python, Java

Libraries/Frameworks: Pytorch, ROS, YOLO, SMACH

Modeling: SolidWorks

Teaching Experience

Undergraduate Tutoring | Physics 1,2 Mar. 2018 – Dec. 2018, Mar. 2021 – Dec. 2021

Undergraduate Tutoring | Linear Algebra 1 Mar. 2021 – Jun.2021

Teaching Assistant | Introduction to Robotics Mar. 2022 – Jun. 2022

English Proficiency

GRE: Verbal Reasoning 160/170, Quantitative Reasoning 170/170, Analytical Writing 4.0/6.0

TOEFL: 112/120 (Reading 29/30, Listening 30/30, Speaking 26/30, Writing 27/30)