# Hierarchical Clustering

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**DSAA 5002** 

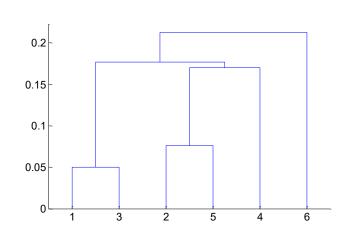
The Hong Kong of Science and Technology (Guangzhou)

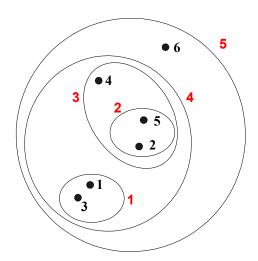
2025 Fall

Sep 29

### **Hierarchical Clustering**

- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
  - A tree like diagram that records the sequences of merges or splits





## Strengths of Hierarchical Clustering

- Do not have to assume any particular number of clusters
  - Any desired number of clusters can be obtained by 'cutting' the dendogram at the proper level

- They may correspond to meaningful taxonomies
  - Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ···)

### **Hierarchical Clustering**

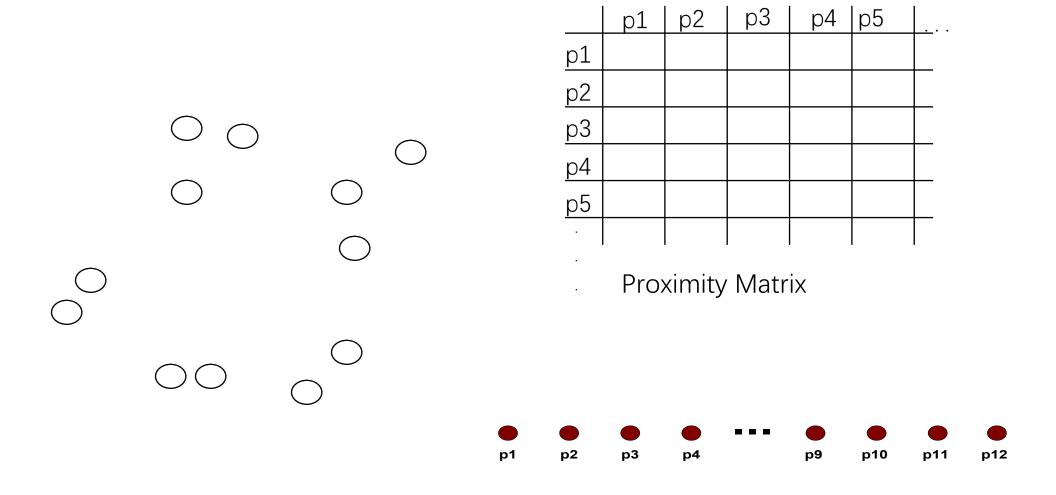
- Two main types of hierarchical clustering
  - Agglomerative: "bottom up"
    - Start with the points as individual clusters
    - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
  - Divisive: "top down"
    - Start with one, all-inclusive cluster
    - At each step, split a cluster until each cluster contains a point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
  - Merge or split one cluster at a time

## **Agglomerative Clustering Algorithm**

- More popular hierarchical clustering technique
- Basic algorithm is straightforward
  - 1. Compute the proximity matrix
  - 2. Let each data point be a cluster
  - 3. Repeat
  - 4. Merge the two closest clusters
  - 5. Update the proximity matrix
  - **6.** Until only a single cluster remains
- Key operation is the computation of the proximity of two clusters
  - Different approaches to defining the distance between clusters distinguish the different algorithms

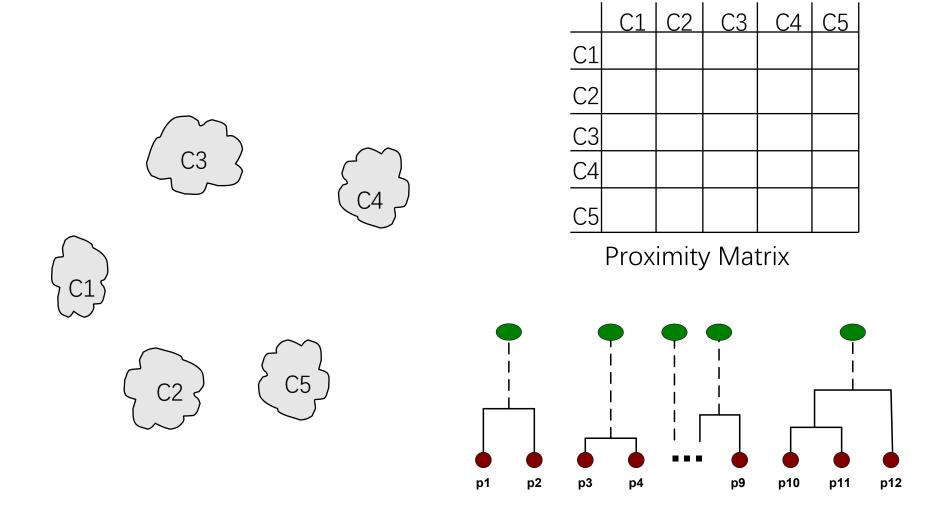
## **Starting Situation**

Start with clusters of individual points and a proximity matrix



#### **Intermediate Situation**

After some merging steps, we have some clusters

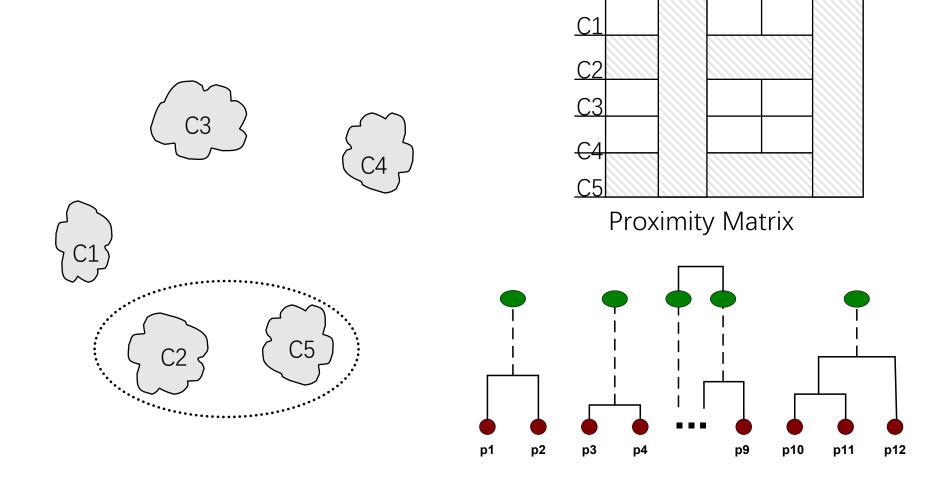


#### **Intermediate Situation**

We want to merge the two closest clusters (C2 and C5) and update the proximity

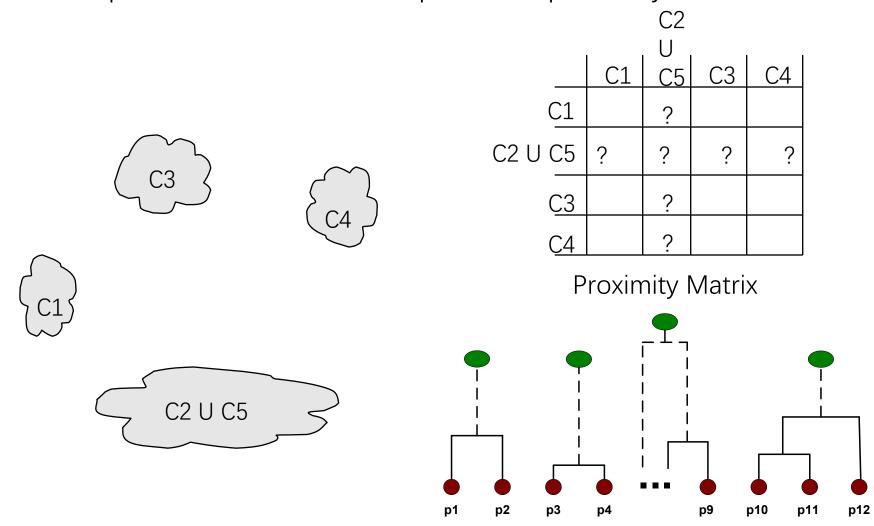
C4 C5

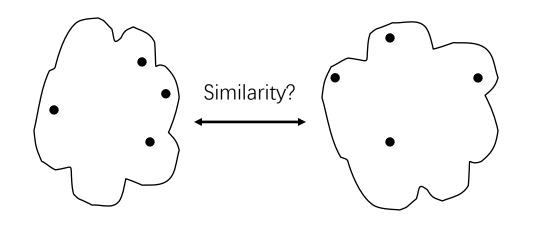
matrix.



## **After Merging**

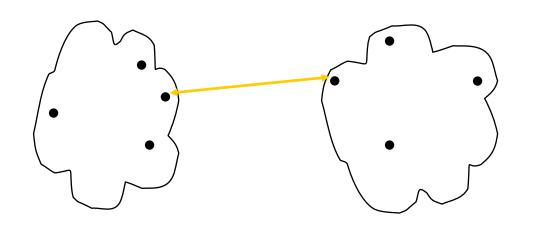
The question is "How do we update the proximity matrix?"





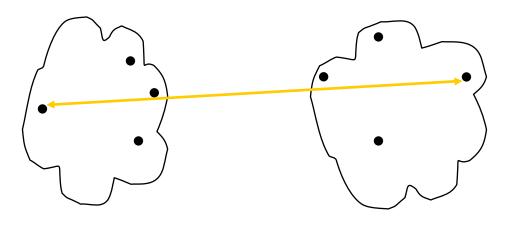
|                        | p1 | p2 | р3 | р4 | р5 | <u>.</u> |
|------------------------|----|----|----|----|----|----------|
| <u>p1</u>              |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |
| <u>p2</u><br><u>p3</u> |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |
| <u>p4</u><br><u>p5</u> |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |

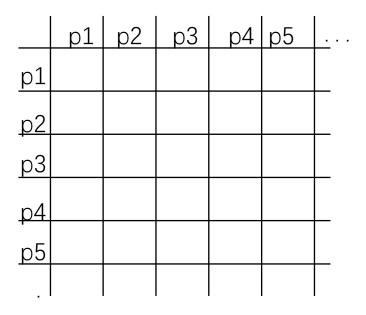
- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error



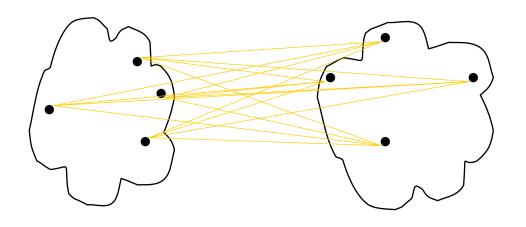
|                        | p1 | p2 | р3 | p4 | р5 | <u> </u> |
|------------------------|----|----|----|----|----|----------|
| p1                     |    |    |    |    |    |          |
| <u>p2</u>              |    |    |    |    |    |          |
| <u>p2</u><br><u>p3</u> |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |
| <u>р4</u><br><u>р5</u> |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |

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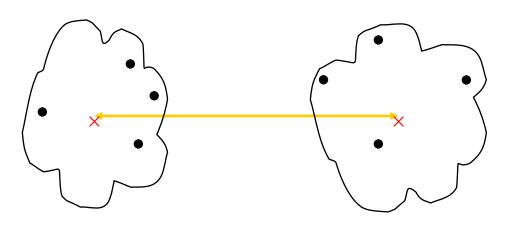


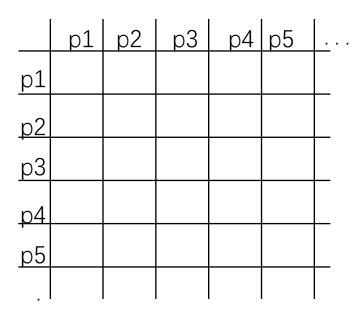
- MIN
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|                        | p1 | p2 | р3 | p4 | p5 | <u> </u> |
|------------------------|----|----|----|----|----|----------|
| <u>р1</u>              |    |    |    |    |    |          |
| <u>p2</u>              |    |    |    |    |    |          |
| <u>p2</u><br><u>p3</u> |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |
| <u>р4</u><br>р5        |    |    |    |    |    |          |
|                        |    |    |    |    |    |          |

- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
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- MIN
- MAX
- Group Average

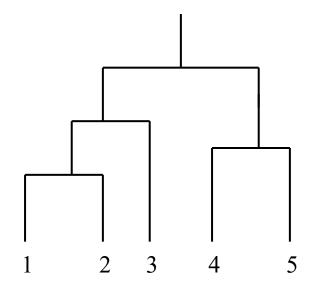
function

- Distance Between Centroids
- Other methods driven by an objective
  - Ward's Method uses squared error

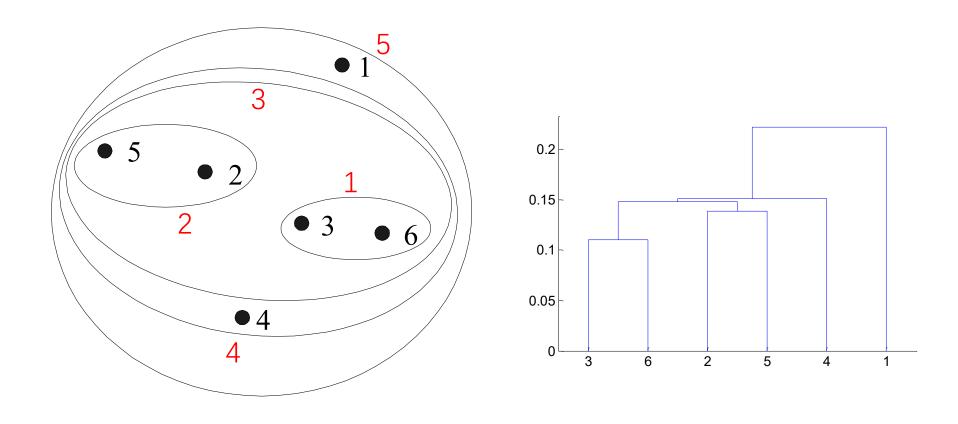
### Cluster Similarity: MIN or Single Link

- Similarity of two clusters is based on the two most similar (closest) points in the different clusters
  - Determined by one pair of points, i.e., by one link in the proximity graph.

|    | <b>I</b> 1                           | 12   | 13   | 14   | 15   |
|----|--------------------------------------|------|------|------|------|
| 11 | 1.00                                 | 0.90 | 0.10 | 0.65 | 0.20 |
| 12 | 0.90                                 | 1.00 | 0.70 | 0.60 | 0.50 |
| 13 | 0.10                                 | 0.70 | 1.00 | 0.40 | 0.30 |
| 14 | 0.65                                 | 0.60 | 0.40 | 1.00 | 0.80 |
| 15 | 1.00<br>0.90<br>0.10<br>0.65<br>0.20 | 0.50 | 0.30 | 0.80 | 1.00 |



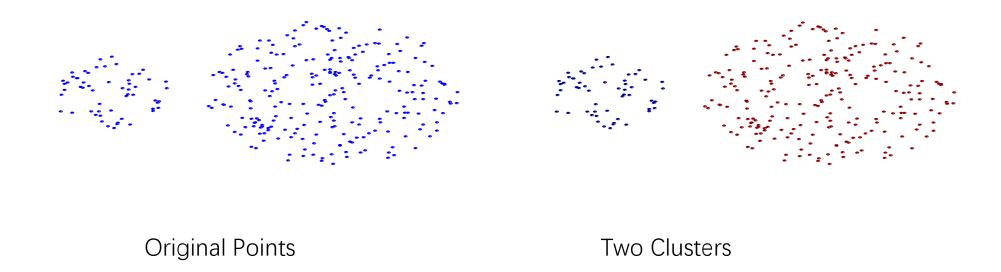
## **Hierarchical Clustering: MIN**



**Nested Clusters** 

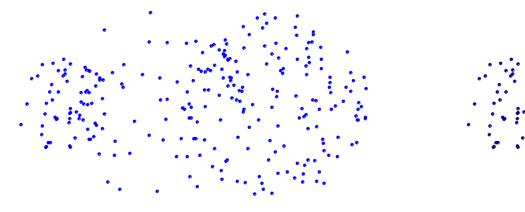
Dendrogram

## Strength of MIN



• Can handle non-elliptical shapes

## Limitations of MIN



**Original Points** 

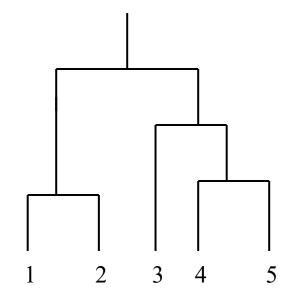
Two Clusters

• Sensitive to noise and outliers

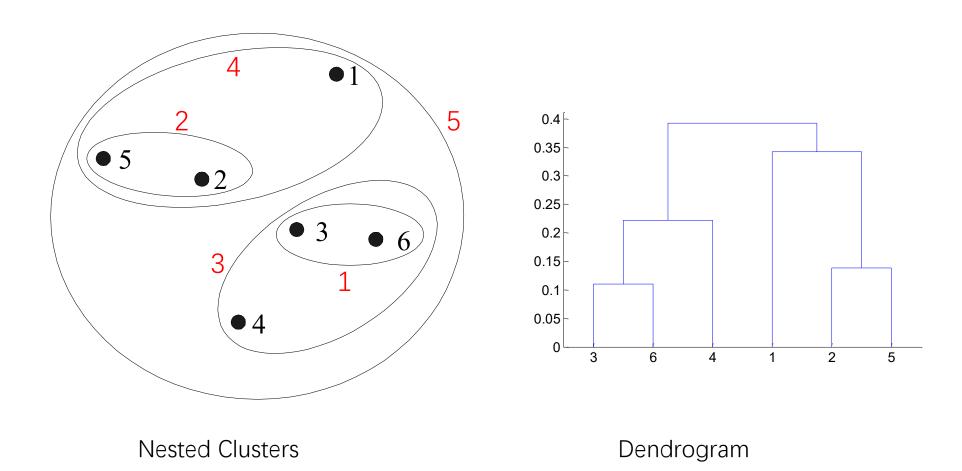
#### Cluster Similarity: MAX or Complete Linkage

- Similarity of two clusters is based on the two least similar (most distant) points in the different clusters
  - Determined by all pairs of points in the two clusters

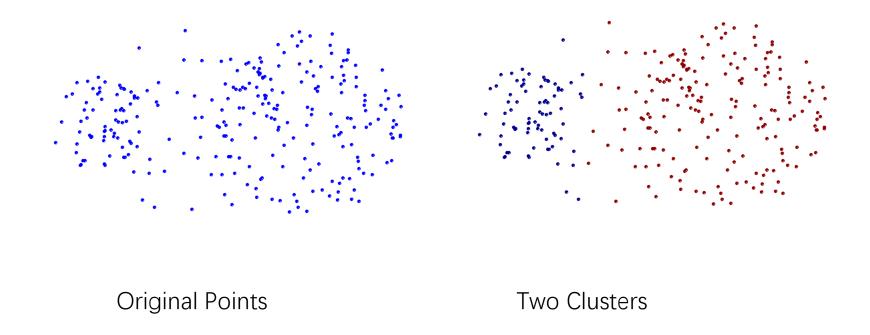
|    | <b>I</b> 1                           | 12   | 13   | <b>14</b> | 15   |
|----|--------------------------------------|------|------|-----------|------|
| 11 | 1.00                                 | 0.90 | 0.10 | 0.65      | 0.20 |
| 12 | 0.90                                 | 1.00 | 0.70 | 0.60      | 0.50 |
| 13 | 0.10                                 | 0.70 | 1.00 | 0.40      | 0.30 |
| 14 | 0.65                                 | 0.60 | 0.40 | 1.00      | 0.80 |
| 15 | 1.00<br>0.90<br>0.10<br>0.65<br>0.20 | 0.50 | 0.30 | 0.80      | 1.00 |



## **Hierarchical Clustering: MAX**

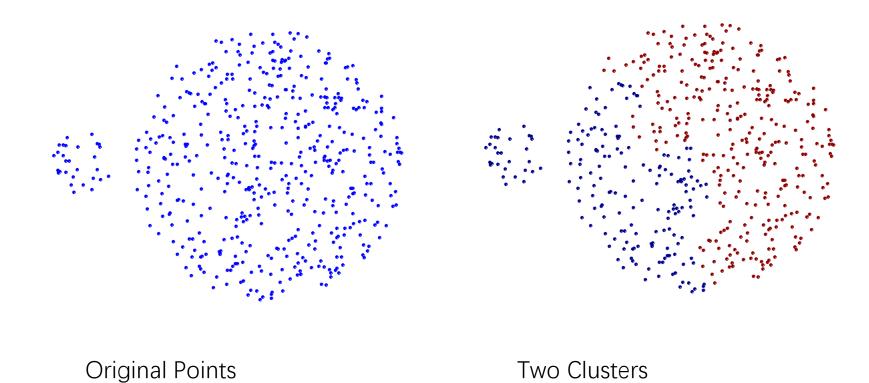


## Strength of MAX



• Less susceptible to noise and outliers

#### Limitations of MAX



- •Tends to break large clusters
- •Biased towards globular clusters

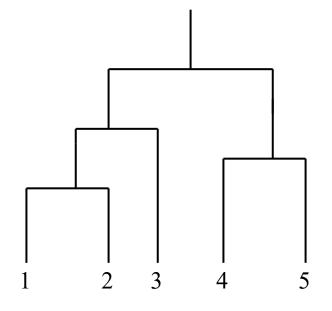
# Cluster Similarity: Group Average

 Proximity of two clusters is the average of pairwise proximity between points in the two clusters.

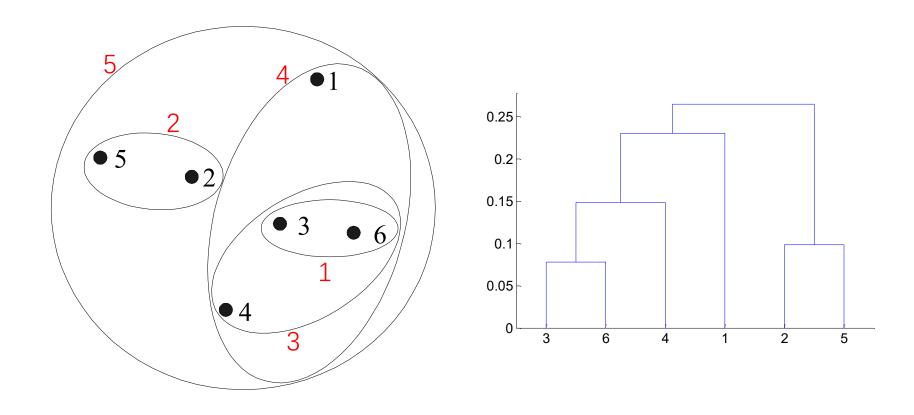
$$proximity(Cluster_{i}, Cluster_{j}) = \frac{\sum_{\substack{p_{i} \in Cluster_{i} \\ p_{j} \in Cluster_{j}}} proximity(p_{i}, p_{j})}{|Cluster_{i}| * |Cluster_{i}|}$$

• Need to use average connectivity for scalability since total proximity favors large clusters

|    | <b>I</b> 1 | 12   | 13   | <b>1</b> 4 | 15                                   |
|----|------------|------|------|------------|--------------------------------------|
| 11 | 1.00       | 0.90 | 0.10 | 0.65       | 0.20                                 |
| 12 | 0.90       | 1.00 | 0.70 | 0.60       | 0.50                                 |
| 13 | 0.10       | 0.70 | 1.00 | 0.40       | 0.30                                 |
| 14 | 0.65       | 0.60 | 0.40 | 1.00       | 0.80                                 |
| 15 | 0.20       | 0.50 | 0.30 | 0.80       | 0.20<br>0.50<br>0.30<br>0.80<br>1.00 |



## Hierarchical Clustering: Group Average



**Nested Clusters** 

Dendrogram

## Hierarchical Clustering: Group Average

Compromise between Single and Complete Link

- Strengths
  - Less susceptible to noise and outliers

- Limitations
  - Biased towards globular clusters

#### Hierarchical Clustering: Time and Space requirements

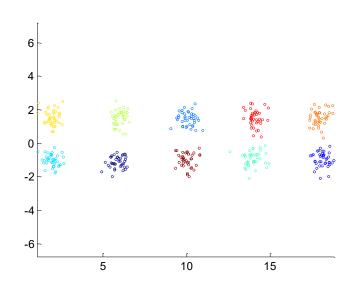
- $O(N^2)$  space since it uses the proximity matrix.
  - N is the number of points.
- O(N<sup>3</sup>) time in many cases
  - There are N steps and at each step the size, N<sup>2</sup>, proximity matrix must be updated and searched
  - Complexity can be reduced to  $O(N^2 \log(N))$  time for some approaches

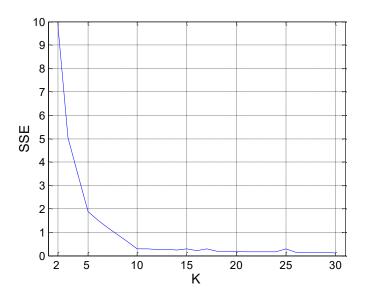
#### Hierarchical Clustering: Problems and Limitations

- Once a decision is made to combine two clusters, it cannot be undone
- No objective function is directly minimized
- Different schemes have problems with one or more of the following:
  - Sensitivity to noise and outliers
  - Difficulty handling different sized clusters and convex shapes
  - Breaking large clusters

#### Internal Measures: SSE

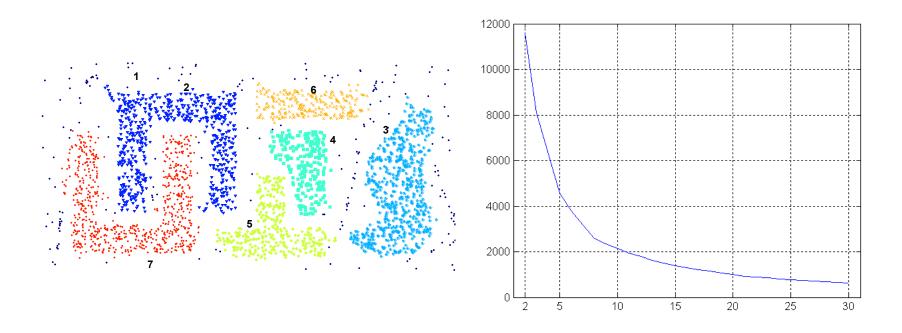
- Clusters in more complicated figures aren't well separated
- Internal Index: Used to measure the goodness of a clustering structure without respect to external information
  - SSE
- SSE is good for comparing two clusterings or two clusters (average SSE).
- Can also be used to estimate the number of clusters.





### Internal Measures: SSE

• SSE curve for a more complicated data set



SSE of clusters found using K-means

## Unsupervised Measures: Cohesion and Separation

- Cluster Cohesion: Measures how closely related are objects in a cluster
  - Example: SSE
- Cluster Separation: Measure how distinct or well-separated a cluster is from other clusters
- Example: Squared Error
  - Cohesion is measured by the within cluster sum of squares (SSE)

$$SSE = \sum_{i} \sum_{x \in C_i} (x - m_i)^2$$

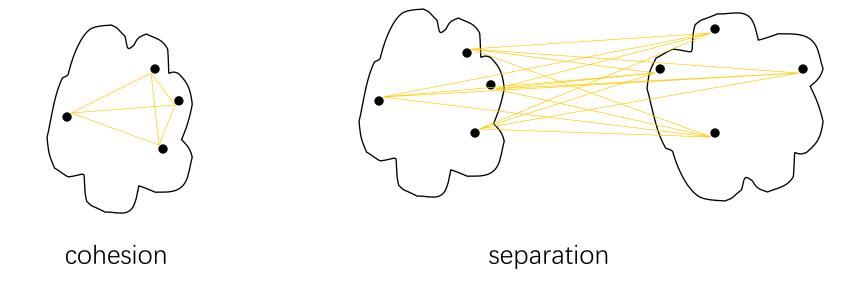
• Separation is measured by the between cluster sum of squares

$$SSB = \sum_{i} |C_i| (m - m_i)^2$$

Where  $|C_i|$  is the size of cluster i

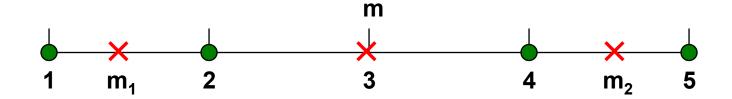
## **Cohesion and Separation**

- A proximity graph based approach can also be used for cohesion and separation.
  - Cluster cohesion is the sum of the weight of all links within a cluster.
  - Cluster separation is the sum of the weights between nodes in the cluster and nodes outside the cluster.



## **Cohesion and Separation**

- Example: SSE
  - SSB + SSE = constant



**K=1 cluster:** 
$$SSE = (1 - 3)$$

$$SSE = (1-3)^2 + (2-3)^2 + (4-3)^2 + (5-3)^2 = 10$$
$$SSB = 4 \times (3-3)^2 = 0$$
$$Total = 10 + 0 = 10$$

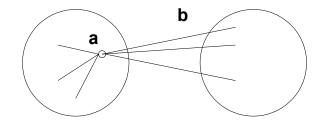
**K=2 clusters:** 
$$SSE = (1 - 1.5)^2 + (2 - 1.5)^2 + (4 - 4.5)^2 + (5 - 4.5)^2 = 1$$
  
 $SSB = 2 \times (3 - 1.5)^2 + 2 \times (4.5 - 3)^2 = 9$   
 $Total = 1 + 9 = 10$ 

#### Internal Measures: Silhouette Coefficient

- Silhouette Coefficient combine ideas of both cohesion and separation, but for individual points, as well as clusters and clusterings
- For an individual point, *i* 
  - Calculate **a** = average distance of *i* to the points in its cluster
  - Calculate  $b = \min$  (average distance of i to points in another cluster)
  - The silhouette coefficient for a point is then given by

$$s = 1 - a/b$$
 if  $a < b$ , (or  $s = b/a - 1$  if  $a \ge b$ , not the usual case)

- Typically between 0 and 1.
- The closer to 1 the better.



Can calculate the Average Silhouette width for a cluster or a clustering

#### External Measures of Cluster Validity: Entropy and Purity

Table 5.9. K-means Clustering Results for LA Document Data Set

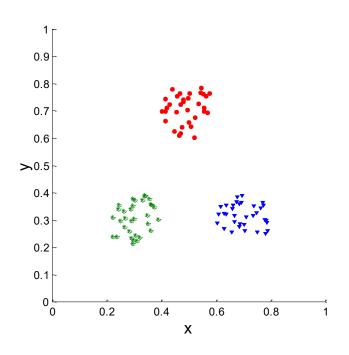
| Cluster | Entertainment | Financial | Foreign | Metro | National | Sports | Entropy | Purity |
|---------|---------------|-----------|---------|-------|----------|--------|---------|--------|
| 1       | 3             | 5         | 40      | 506   | 96       | 27     | 1.2270  | 0.7474 |
| 2       | 4             | 7         | 280     | 29    | 39       | 2      | 1.1472  | 0.7756 |
| 3       | 1             | 1         | 1       | 7     | 4        | 671    | 0.1813  | 0.9796 |
| 4       | 10            | 162       | 3       | 119   | 73       | 2      | 1.7487  | 0.4390 |
| 5       | 331           | 22        | 5       | 70    | 13       | 23     | 1.3976  | 0.7134 |
| 6       | 5             | 358       | 12      | 212   | 48       | 13     | 1.5523  | 0.5525 |
| Total   | 354           | 555       | 341     | 943   | 273      | 738    | 1.1450  | 0.7203 |

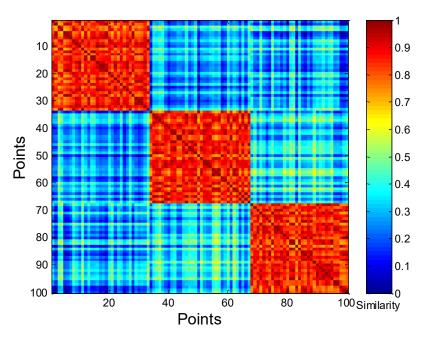
entropy For each cluster, the class distribution of the data is calculated first, i.e., for cluster j we compute  $p_{ij}$ , the 'probability' that a member of cluster j belongs to class i as follows:  $p_{ij} = m_{ij}/m_j$ , where  $m_j$  is the number of values in cluster j and  $m_{ij}$  is the number of values of class i in cluster j. Then using this class distribution, the entropy of each cluster j is calculated using the standard formula  $e_j = \sum_{i=1}^L p_{ij} \log_2 p_{ij}$ , where the L is the number of classes. The total entropy for a set of clusters is calculated as the sum of the entropies of each cluster weighted by the size of each cluster, i.e.,  $e = \sum_{i=1}^K \frac{m_i}{m} e_j$ , where  $m_j$  is the size of cluster j, K is the number of clusters, and m is the total number of data points.

**purity** Using the terminology derived for entropy, the purity of cluster j, is given by  $purity_j = \max p_{ij}$  and the overall purity of a clustering by  $purity = \sum_{i=1}^{K} \frac{m_i}{m} purity_j$ .

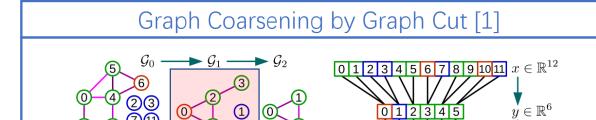
### Judging a Clustering Visually by its Similarity Matrix

• Order the similarity matrix with respect to cluster labels and inspect visually.



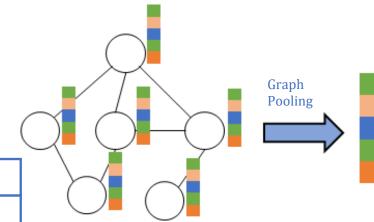


#### **Hierarchical Pooling**

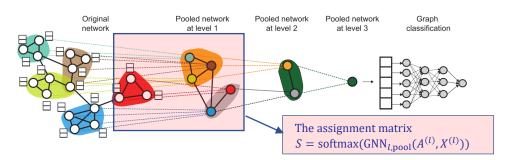


Graph Pooling with pre-defined subgraph by graph cut algorithm.

normalized cut



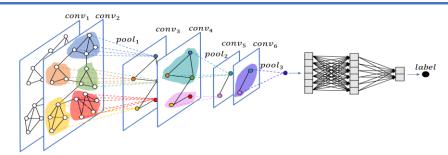
#### Differentiable Graph Pooling (DIFFPOOL)[2]



Learn the cluster assignment matrix to aggregate the node representations in a hierarchical way.

#### EigenPooling [3]

 $z \in \mathbb{R}^3$ 



Incorporate the node features and local structures to obtain a better assignment matrix.

#### **Slides Credit**

- [1] Tan et al. K-means in Introduction to Data Mining.
- [2] Subhransu Maji. Clustering in CMPSCI689