

The MATPOWER case format also allows for additional fields to be included in the structure. The OPF is designed to recognize fields named `A`, `l`, `u`, `H`, `Cw`, `N`, `fparm`, `z0`, `z1` and `zu` as parameters used to directly extend the OPF formulation as described in Section 7.1. Other user-defined fields may also be included, such as the `reserves` field used in the example code throughout Section 7.2. The `loadcase` function will automatically load any extra fields from a case file and, if the appropriate 'savecase' callback function (see Section 7.2.5) is added via `add_userfcn`, `savecase` will also save them back to a case file.

Table B-1: Bus Data (`mpc.bus`)

name	column	description
<code>BUS_I</code>	1	bus number (positive integer)
<code>BUS_TYPE</code>	2	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
<code>PD</code>	3	real power demand (MW)
<code>QD</code>	4	reactive power demand (MVar)
<code>GS</code>	5	shunt conductance (MW demanded at $V = 1.0$ p.u.)
<code>BS</code>	6	shunt susceptance (MVar injected at $V = 1.0$ p.u.)
<code>BUS_AREA</code>	7	area number (positive integer)
<code>VM</code>	8	voltage magnitude (p.u.)
<code>VA</code>	9	voltage angle (degrees)
<code>BASE_KV</code>	10	base voltage (kV)
<code>ZONE</code>	11	loss zone (positive integer)
<code>VMAX</code>	12	maximum voltage magnitude (p.u.)
<code>VMIN</code>	13	minimum voltage magnitude (p.u.)
<code>LAM_P<sup>†</sup></code>	14	Lagrange multiplier on real power mismatch ( $u$ /MW)
<code>LAM_Q<sup>†</sup></code>	15	Lagrange multiplier on reactive power mismatch ( $u$ /MVar)
<code>MU_VMAX<sup>†</sup></code>	16	Kuhn-Tucker multiplier on upper voltage limit ( $u$ /p.u.)
<code>MU_VMIN<sup>†</sup></code>	17	Kuhn-Tucker multiplier on lower voltage limit ( $u$ /p.u.)

<sup>†</sup> Included in OPF output, typically not included (or ignored) in input matrix. Here we assume the objective function has units  $u$ .

Table B-2: Generator Data (`mpc.gen`)

name	column	description
GEN_BUS	1	bus number
PG	2	real power output (MW)
QG	3	reactive power output (MVA <sub>r</sub> )
QMAX	4	maximum reactive power output (MVA <sub>r</sub> )
QMIN	5	minimum reactive power output (MVA <sub>r</sub> )
VG	6	voltage magnitude setpoint (p.u.)
MBASE	7	total MVA base of machine, defaults to <code>baseMVA</code>
GEN_STATUS	8	machine status, $> 0$ = machine in-service $\leq 0$ = machine out-of-service
PMAX	9	maximum real power output (MW)
PMIN	10	minimum real power output (MW)
PC1*	11	lower real power output of PQ capability curve (MW)
PC2*	12	upper real power output of PQ capability curve (MW)
QC1MIN*	13	minimum reactive power output at PC1 (MVA <sub>r</sub> )
QC1MAX*	14	maximum reactive power output at PC1 (MVA <sub>r</sub> )
QC2MIN*	15	minimum reactive power output at PC2 (MVA <sub>r</sub> )
QC2MAX*	16	maximum reactive power output at PC2 (MVA <sub>r</sub> )
RAMP_AGC*	17	ramp rate for load following/AGC (MW/min)
RAMP_10*	18	ramp rate for 10 minute reserves (MW)
RAMP_30*	19	ramp rate for 30 minute reserves (MW)
RAMP_Q*	20	ramp rate for reactive power (2 sec timescale) (MVA <sub>r</sub> /min)
APF*	21	area participation factor
MU_PMAX <sup>†</sup>	22	Kuhn-Tucker multiplier on upper $P_g$ limit ( $u$ /MW)
MU_PMIN <sup>†</sup>	23	Kuhn-Tucker multiplier on lower $P_g$ limit ( $u$ /MW)
MU_QMAX <sup>†</sup>	24	Kuhn-Tucker multiplier on upper $Q_g$ limit ( $u$ /MVA <sub>r</sub> )
MU_QMIN <sup>†</sup>	25	Kuhn-Tucker multiplier on lower $Q_g$ limit ( $u$ /MVA <sub>r</sub> )

\* Not included in version 1 case format.

<sup>†</sup> Included in OPF output, typically not included (or ignored) in input matrix. Here we assume the objective function has units  $u$ .

Table B-3: Branch Data (`mpc.branch`)

name	column	description
F_BUS	1	“from” bus number
T_BUS	2	“to” bus number
BR_R	3	resistance (p.u.)
BR_X	4	reactance (p.u.)
BR_B	5	total line charging susceptance (p.u.)
RATE_A	6	MVA rating A (long term rating)
RATE_B	7	MVA rating B (short term rating)
RATE_C	8	MVA rating C (emergency rating)
TAP	9	transformer off nominal turns ratio, (taps at “from” bus, impedance at “to” bus, i.e. if $r = x = 0$ , $tap = \frac{ V_f }{ V_t }$ )
SHIFT	10	transformer phase shift angle (degrees), positive $\Rightarrow$ delay
BR_STATUS	11	initial branch status, 1 = in-service, 0 = out-of-service
ANGMIN*	12	minimum angle difference, $\theta_f - \theta_t$ (degrees)
ANGMAX*	13	maximum angle difference, $\theta_f - \theta_t$ (degrees)
PF <sup>†</sup>	14	real power injected at “from” bus end (MW)
QF <sup>†</sup>	15	reactive power injected at “from” bus end (MVar)
PT <sup>†</sup>	16	real power injected at “to” bus end (MW)
QT <sup>†</sup>	17	reactive power injected at “to” bus end (MVar)
MU_SF <sup>‡</sup>	18	Kuhn-Tucker multiplier on MVA limit at “from” bus ( $u$ /MVA)
MU_ST <sup>‡</sup>	19	Kuhn-Tucker multiplier on MVA limit at “to” bus ( $u$ /MVA)
MU_ANGMIN <sup>‡</sup>	20	Kuhn-Tucker multiplier lower angle difference limit ( $u$ /degree)
MU_ANGMAX <sup>‡</sup>	21	Kuhn-Tucker multiplier upper angle difference limit ( $u$ /degree)

\* Not included in version 1 case format. The voltage angle difference is taken to be unbounded below if  $ANGMIN < -360$  and unbounded above if  $ANGMAX > 360$ . If both parameters are zero, the voltage angle difference is unconstrained.

<sup>†</sup> Included in power flow and OPF output, ignored on input.

<sup>‡</sup> Included in OPF output, typically not included (or ignored) in input matrix. Here we assume the objective function has units  $u$ .