assignment_07

November 5, 2021

1 Supervised image denoising

1.1 Import libraries

```
[]: from google.colab import drive drive.mount('/content/drive')
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

```
[]: import torch
     import torchvision
     from torch.utils.data import Dataset
     from os import listdir
     from os.path import join
     from torchvision.transforms import Compose, ToTensor, ToPILImage, Resize,
     →Lambda, Normalize, Grayscale
     from torch.utils.data import DataLoader
     from PIL import Image
     import matplotlib.pyplot as plt
     import numpy as np
     import torch.nn as nn
     import torch.nn.functional as F
     import torch.optim as optim
     from math import log10
     from tqdm.notebook import tqdm
     import os
```

1.2 Load data

```
[]: directory_data = 'drive/MyDrive/'
filename_data = 'assignment_07_data.npz'
data = np.load(os.path.join(directory_data, filename_data))

original_train = data['original_train']
noise_train = data['noise_train']
```

```
original_test = data['original_test']
         = data['noise_test']
noise test
print('size of original_train : ', original_train.shape)
print('size of noise_train
                    : ', noise_train.shape)
print('size of original_test : ', original_test.shape)
print('size of noise test
                  : ', noise test.shape)
print('number of training image :', original_train.shape[0])
print('height of training image :', original_train.shape[1])
print('width of training image :', original_train.shape[2])
print('number of testing image :', original_test.shape[0])
print('height of testing image :', original_test.shape[1])
print('width of testing image :', original_test.shape[2])
```

```
*************
size of original train: (2000, 64, 64)
size of noise_train
              : (2000, 64, 64)
*************
size of original_test: (900, 64, 64)
size of noise_test
              : (900, 64, 64)
************
number of training image: 2000
height of training image: 64
width of training image : 64
*************
number of testing image: 900
height of testing image: 64
width of testing image : 64
**************
```

1.3 Hyper parameters

```
[]: device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')

number_epoch = 500
size_minibatch = 8
learning_rate = 0.1
momentum = 0.9
weight_decay = 0.0001
```

1.4 Costumize dataloader for pytorch

```
class dataset (Dataset):
    def __init__(self, original,noise):
    self.original = original
    self.noise = noise

def __getitem__(self, index):
    original = self.original[index]
    noise = self.noise[index]

    original = torch.FloatTensor(original).unsqueeze(dim=0)
    noise = torch.FloatTensor(noise).unsqueeze(dim=0)

    return (original , noise)

def __len__(self):
    return self.original.shape[0]
```

1.5 Construct datasets and dataloaders for training and testing

```
[]: dataset_train = dataset(original_train, noise_train)
dataset_test = dataset(original_test, noise_test)

dataloader_train = DataLoader(dataset_train, batch_size=size_minibatch,

⇒shuffle=True, drop_last=True, num_workers=2)
dataloader_test = DataLoader(dataset_test, batch_size=size_minibatch,

⇒shuffle=False, drop_last=True, num_workers=2)
```

1.6 Shape of the data with data loader

1.7 Class for the neural network

```
[]: class Network(nn.Module):
         def init (self):
             super(Network,self).__init__()
             # Encoder
             self.e_layer1 = nn.Sequential(
                             nn.Conv2d(in_channels=1, out_channels=256,_u
      →kernel_size=3, stride=1, padding=1, bias=True),
                             nn.MaxPool2d(2,2),
                             nn.ReLU(),
                             nn.BatchNorm2d(256),
             )
             # Decoder
             # self.d_layer1 = nn.Sequential(
                               nn.Upsample(scale_factor=2, mode='bilinear',_
      \rightarrow align_corners=False),
                               nn.Conv2d(in_channels=16, out_channels=8,_
      →kernel_size=3, stride=1, padding=1, bias=True),
                               nn.ReLU().
             #
                               nn.BatchNorm2d(8),
             # )
             self.d_layer1 = nn.Sequential(
                             nn.Upsample(scale_factor=2, mode='bilinear',_
      →align_corners=False),
                             nn.Conv2d(in_channels=256, out_channels=1,__
      →kernel_size=3, stride=1, padding=1, bias=True),
                             nn.Sigmoid(),
             )
```

```
# Network
   self.network = nn.Sequential(
                 self.e_layer1,
                 #self.e_layer2,
                 self.d_layer1,
                 #self.d_layer2,
   )
   self.initialize_weight()
def forward(self,x):
   out = self.network(x)
   return out
# -----
# initialize weights
def initialize_weight(self):
   for m in self.network.modules():
      if isinstance(m, nn.Conv2d):
          nn.init.xavier_uniform_(m.weight)
          #nn.init.constant_(m.weight, 0.1)
          if m.bias is not None:
             nn.init.constant_(m.bias, 1)
             pass
      elif isinstance(m, nn.BatchNorm2d):
          nn.init.constant_(m.weight, 1)
          nn.init.constant_(m.bias, 1)
      elif isinstance(m, nn.Linear):
          nn.init.xavier_uniform_(m.weight)
          #nn.init.constant_(m.weight, 0.1)
          if m.bias is not None:
             nn.init.constant_(m.bias, 1)
```

```
pass
```

1.8 Build the network

```
[]: model = Network().to(device)
optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate,
→momentum=momentum , weight_decay=weight_decay)
```

1.9 Compute prediction (denoised image)

```
[]: def compute_prediction(model, input):
    denoise = model(input)
    return denoise
```

1.10 Compute loss

1.11 Compute PSNR metric

```
[]: def compute_PSNR (loss):
    if (loss==0.):
        PSNR=100
    else :
        PSNR=10*log10(1/loss)
    return PSNR
```

1.12 Variable for the learning curves

```
[]: loss_mean_train = np.zeros(number_epoch)
loss_std_train = np.zeros(number_epoch)
PSNR_mean_train = np.zeros(number_epoch)
PSNR_std_train = np.zeros(number_epoch)
loss_mean_test = np.zeros(number_epoch)
```

```
loss_std_test = np.zeros(number_epoch)
PSNR_mean_test = np.zeros(number_epoch)
PSNR_std_test = np.zeros(number_epoch)
```

1.13 Train

```
[]: def train(model, dataloader):
       loss_epoch
                  = []
       psnr_epoch
                  = []
       model.train()
       for index_batch, (original, noise) in enumerate(dataloader):
          original = original.to(device)
          noise
               = noise.to(device)
    # complete the following codes
                         = compute_prediction(model,noise)
          denoise
          loss, loss_value = compute_loss(denoise,original)
    = compute_PSNR(loss_value)
          psnr
          optimizer.zero_grad()
          loss.backward()
          optimizer.step()
          loss_epoch.append(loss_value)
          psnr_epoch.append(psnr)
       loss_mean_epoch = np.mean(loss_epoch)
                     = np.std(loss_epoch)
       loss_std_epoch
       psnr_mean_epoch = np.mean(psnr_epoch)
       psnr_std_epoch = np.std(psnr_epoch)
       loss
                = {'mean' : loss_mean_epoch, 'std' : loss_std_epoch}
                = {'mean' : psnr_mean_epoch, 'std' : psnr_std_epoch}
       psnr
       return (loss, psnr)
```

1.14 Test

```
[]: def test(model, dataloader):
       loss_epoch
                  = []
                = []
       psnr_epoch
       model.eval()
       for index_batch, (original, noise) in enumerate(dataloader):
          original = original.to(device)
          noise
                = noise.to(device)
          #__
      # complete the following codes
                          = compute_prediction(model,noise)
          denoise
          loss, loss_value = compute_loss(denoise,original)
     psnr
                           = compute_PSNR(loss_value)
          loss_epoch.append(loss_value)
          psnr_epoch.append(psnr)
       loss_mean_epoch = np.mean(loss_epoch)
loss_std_epoch = np.std(loss_epoch)
       psnr_mean_epoch = np.mean(psnr_epoch)
       psnr_std_epoch = np.std(psnr_epoch)
                 = {'mean' : loss_mean_epoch, 'std' : loss_std_epoch}
       loss
                = {'mean' : psnr_mean_epoch, 'std' : psnr_std_epoch}
       psnr
       return (loss, psnr)
```

1.15 train and test

```
for i in tqdm(range(number_epoch)):
  #__
  # training
_____
  (loss_train, psnr_train) = train(model, dataloader_train)
  loss_mean_train[i] = loss_train['mean']
  loss_std_train[i]
                = loss_train['std']
  PSNR_mean_train[i] = psnr_train['mean']
  PSNR_std_train[i] = psnr_train['std']
_____
  # testing
  #__
(loss_test, psnr_test) = test(model, dataloader_test)
  loss_mean_test[i] = loss_test['mean']
  loss_std_test[i] = loss_test['std']
  PSNR_mean_test[i] = psnr_test['mean']
  PSNR_std_test[i] = psnr_test['std']
0%1
        | 0/500 [00:00<?, ?it/s]
```

2 DO NOT MODIFY THE CODES FROM HERE, BUT EXECUTE THEM

2.1 Plot functions

```
[]: def plot_data_grid(data, index_data, nRow, nCol):
         fig, axes = plt.subplots(nRow, nCol, constrained_layout=True, figsize=(nCol_
      \rightarrow* 3, nRow * 3))
         for i in range(nRow):
             for j in range(nCol):
                         = i * nCol + j
                         = index_data[k]
                 index
                 axes[i, j].imshow(data[index], cmap='gray', vmin=0, vmax=1)
                 axes[i, j].xaxis.set_visible(False)
                 axes[i, j].yaxis.set_visible(False)
         plt.show()
[]: def plot_data_tensor_grid(data, index_data, nRow, nCol):
         fig, axes = plt.subplots(nRow, nCol, constrained_layout=True, figsize=(nCol_
      \rightarrow* 3, nRow * 3))
         data = data.detach().cpu().squeeze(axis=1)
         for i in range(nRow):
             for j in range(nCol):
                         = i * nCol + j
                        = index_data[k]
                 index
                 axes[i, j].imshow(data[index], cmap='gray', vmin=0, vmax=1)
                 axes[i, j].xaxis.set_visible(False)
                 axes[i, j].yaxis.set_visible(False)
         plt.show()
[]: def plot_curve_error(data_mean, data_std, x_label, y_label, title):
         plt.figure(figsize=(8, 6))
         plt.title(title)
         alpha = 0.3
```

plt.plot(range(len(data_mean)), data_mean, '-', color = 'red')

```
plt.fill_between(range(len(data_mean)), data_mean - data_std, data_mean +_u
     →data_std, facecolor = 'blue', alpha = alpha)
         plt.xlabel(x_label)
         plt.ylabel(y_label)
         plt.tight_layout()
         plt.show()
[ ]: def print_curve(data, index):
         for i in range(len(index)):
             idx = index[i]
             val = data[idx]
             print('index = %2d, value = %12.10f' % (idx, val))
[]: def get_data_last(data, index_start):
         data_last = data[index_start:]
         return data_last
[]: def get_max_last_range(data, index_start):
         data_range = get_data_last(data, index_start)
         value = data_range.max()
         return value
[]: def get_min_last_range(data, index_start):
         data_range = get_data_last(data, index_start)
         value = data_range.min()
         return value
```

3 functions for presenting the results

```
[]: def function_result_01():
    print('[plot examples of the training clean images]')
```

```
print('')
        nRow = 5
        nCol = 4
        index_data = np.arange(0, nRow * nCol)
        original_train = dataset_train.original[index_data]
        plot_data_grid(original_train, index_data, nRow, nCol)
[]: def function_result_02():
        print('[plot examples of the training noisy images]')
        print('')
        nRow = 5
        nCol = 4
        index data = np.arange(0, nRow * nCol)
        noise_train = dataset_train.noise[index_data]
        plot_data_grid(noise_train, index_data, nRow, nCol)
[]: def function_result_03():
        print('[plot examples of the training denoising results]')
        print('')
        nRow = 5
        nCol = 4
        index_data
                            = np.arange(0, nRow * nCol)
                            = torch.FloatTensor(dataset_train.original[index_data]).
         image train
      →unsqueeze(dim=1).to(device)
        prediction_train
                          = compute_prediction(model, image_train)
        plot_data_tensor_grid(prediction_train, index_data, nRow, nCol)
[]: def function result 04():
        print('[plot examples of the testing clean images]')
        print('')
        nRow = 5
        nCol = 4
        index_data = np.arange(0, nRow * nCol)
        original_test = dataset_test.original[index_data]
        plot_data_grid(original_test, index_data, nRow, nCol)
```

```
[]: def function_result_05():
        print('[plot examples of the testing noise images]')
        print('')
        nRow = 5
        nCol = 4
        index_data = np.arange(0, nRow * nCol)
        noise_test = dataset_test.noise[index_data]
        plot_data_grid(noise_test, index_data, nRow, nCol)
[]: def function_result_06():
        print('[plot examples of the testing denoising results]')
        print('')
        nRow = 5
        nCol = 4
        index data
                      = np.arange(0, nRow * nCol)
                     = torch.FloatTensor(dataset_test.original[index_data]).
        image_test

    unsqueeze(dim=1).to(device)

        prediction_test = compute_prediction(model, image_test)
        plot_data_tensor_grid(prediction_test, index_data, nRow, nCol)
[]: def function_result_07():
        print('[plot the training loss]')
        print('')
        plot_curve_error(loss_mean_train, loss_std_train, 'epoch', 'loss', 'loss_u
     []: def function_result_08():
        print('[plot the training PSNR]')
        print('')
        plot_curve_error(PSNR_mean_train, PSNR_std_train, 'epoch', 'PSNR', 'PSNRL
     []: def function_result_09():
        print('[plot the testing loss]')
        print('')
```

```
plot_curve_error(loss_mean_test, loss_std_test, 'epoch', 'loss', 'loss_u
      []: def function result 10():
        print('[plot the testing PSNR]')
        print('')
        plot_curve_error(PSNR_mean_test, PSNR_std_test, 'epoch', 'PSNR', 'PSNRL'
     []: def function_result_11():
        print('[print the training loss at the last 10 epochs]')
        print('')
        data_last = get_data_last(loss_mean_train, -10)
        index = np.arange(0, 10)
        print_curve(data_last, index)
[]: def function result 12():
        print('[print the training PSNR at the last 10 epochs]')
        print('')
        data_last = get_data_last(PSNR_mean_train, -10)
        index = np.arange(0, 10)
        print_curve(data_last, index)
[]: def function result 13():
        print('[print the testing loss at the last 10 epochs]')
        print('')
        data_last = get_data_last(loss_mean_test, -10)
        index = np.arange(0, 10)
        print_curve(data_last, index)
[]: def function_result_14():
        print('[print the testing PSNR at the last 10 epochs]')
        print('')
        data_last = get_data_last(PSNR_mean_test, -10)
        index = np.arange(0, 10)
        print_curve(data_last, index)
```

```
[]: def function_result_15():
    print('[print the best training PSNR within the last 10 epochs]')
    print('')
    value = get_max_last_range(PSNR_mean_train, -10)
    print('best training PSNR = %12.10f' % (value))

[]: def function_result_16():
    print('[print the best testing PSNR within the last 10 epochs]')
    print('')
    value = get_max_last_range(PSNR_mean_test, -10)
    print('best testing PSNR = %12.10f' % (value))
```

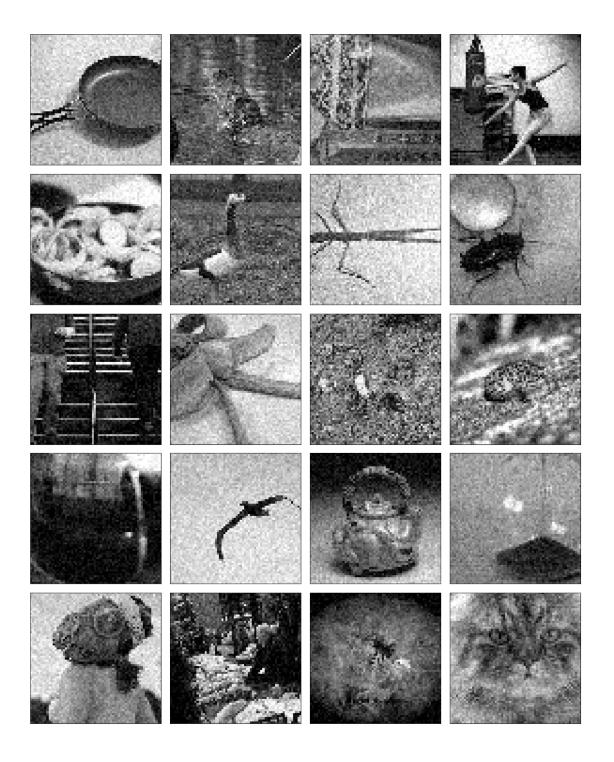
4 RESULTS

[plot examples of the training clean images]



```
#
# RESULT # 02
```

[plot examples of the training noisy images]



[plot examples of the training denoising results]

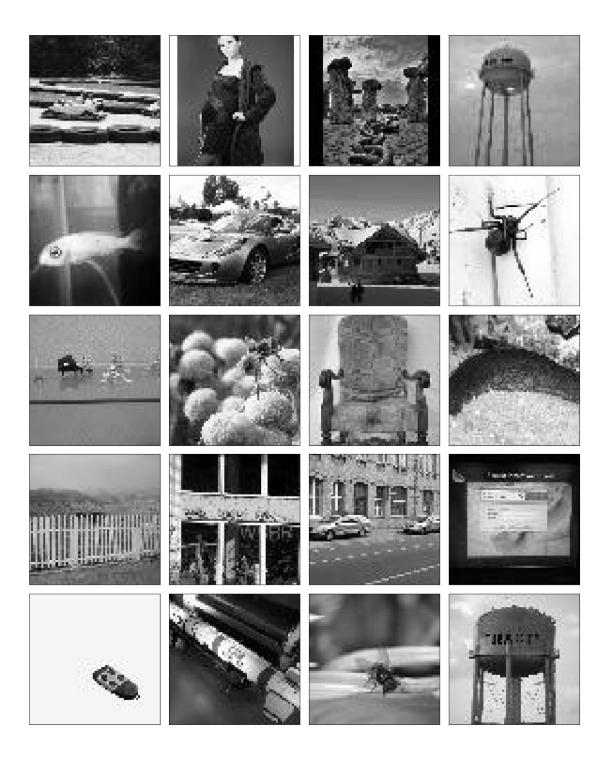


#

RESULT # 04

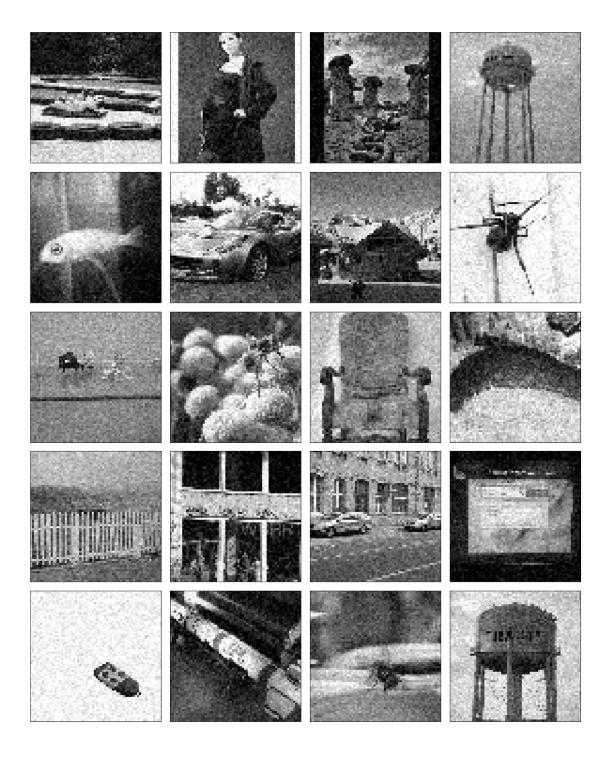
#

[plot examples of the testing clean images]



```
#
# RESULT # 05
```

[plot examples of the testing noise images]



[plot examples of the testing denoising results]

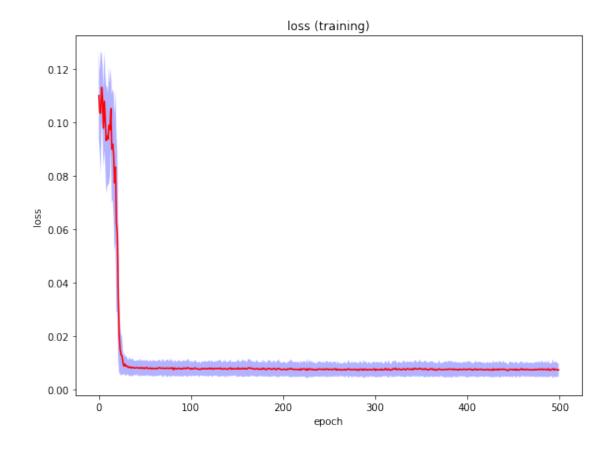


#

RESULT # 07

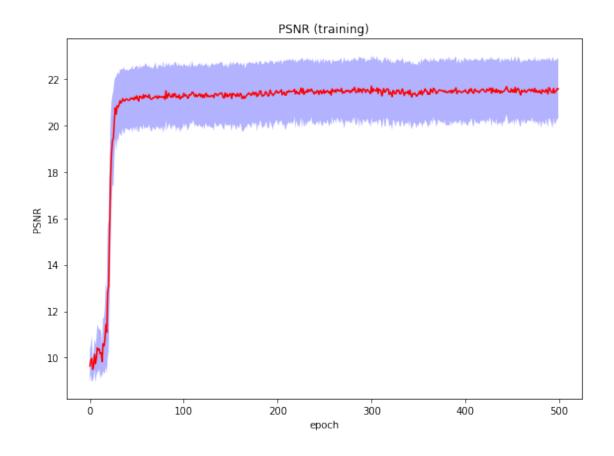
#

[plot the training loss]

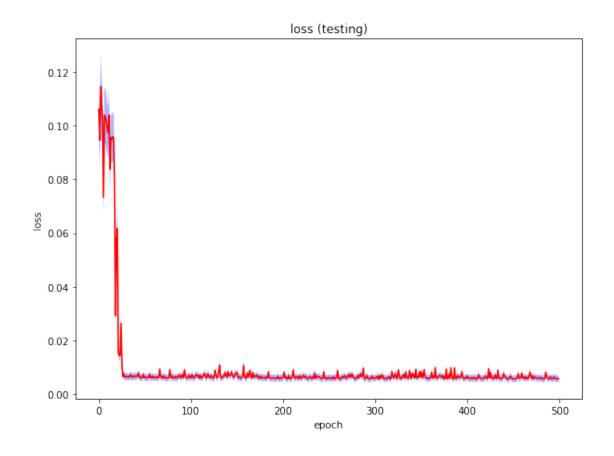




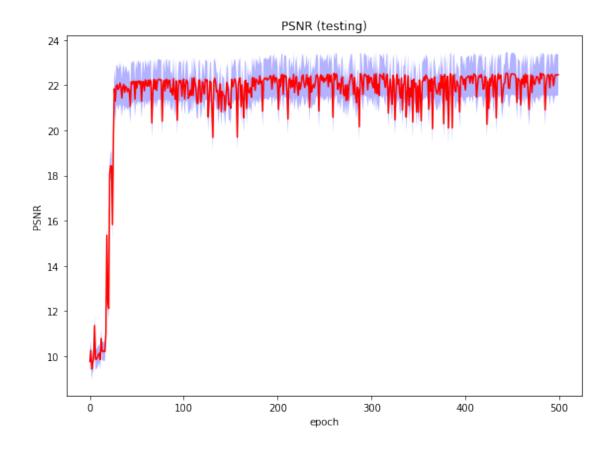
[plot the training PSNR]



[plot the testing loss]



[plot the testing PSNR]



[print the training loss at the last 10 epochs]

```
index = 0, value = 0.0072790234
index = 1, value = 0.0074423958
index = 2, value = 0.0075753644
index = 3, value = 0.0077536066
index = 4, value = 0.0072317056
index = 5, value = 0.0076201677
index = 6, value = 0.0075205406
index = 7, value = 0.0074213842
index = 8, value = 0.0072590623
index = 9, value = 0.0072939374
```

```
# RESULT # 12
[print the training PSNR at the last 10 epochs]
index = 0, value = 21.5832241613
index = 1, value = 21.4867989431
index = 2, value = 21.4364820133
index = 3, value = 21.4227068090
index = 4, value = 21.6046217554
index = 5, value = 21.4080423482
index = 6, value = 21.4816717632
index = 7, value = 21.5080287184
index = 8, value = 21.6012141503
index = 9, value = 21.5844034491
# RESULT # 13
[print the testing loss at the last 10 epochs]
index = 0, value = 0.0065836407
index = 1, value = 0.0058320655
index = 2, value = 0.0057772769
index = 3, value = 0.0058598632
index = 4, value = 0.0064515677
index = 5, value = 0.0059959378
index = 6, value = 0.0057942235
index = 7, value = 0.0058181359
index = 8, value = 0.0058008575
index = 9, value = 0.0057928766
# RESULT # 14
[print the testing PSNR at the last 10 epochs]
index = 0, value = 21.8895612746
index = 1, value = 22.4364757526
index = 2, value = 22.4811760703
```

```
index = 3, value = 22.4165728093
  index = 4, value = 21.9816613640
  index = 5, value = 22.3141353617
  index = 6, value = 22.4673756426
  index = 7, value = 22.4487729235
  index = 8, value = 22.4614343401
  index = 9, value = 22.4695872789
  # RESULT # 15
  [print the best training PSNR within the last 10 epochs]
  best training PSNR = 21.6046217554
  # RESULT # 16
  [print the best testing PSNR within the last 10 epochs]
  best testing PSNR = 22.4811760703
[]:
```