

# **Advanced Data Structures and Algorithms**

*Comprehensive Assignment Solutions*

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## 1 Graph Algorithms

**Question 2.** Explain why Dijkstra's algorithm cannot be applied to graphs with negative edge weights.

**Detailed Solution:**

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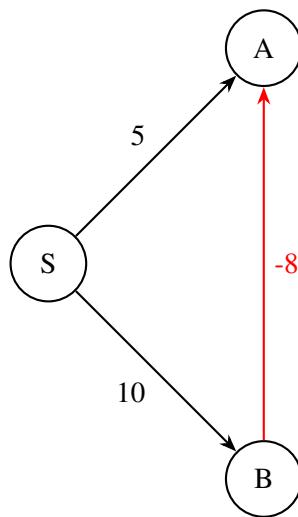
### The Greedy Choice Property

Dijkstra's algorithm relies fundamentally on a greedy strategy. It maintains a set of "visited" or "finalized" nodes for which the shortest path from the source is known. The core assumption is: *"Once a node  $u$  is added to the finalized set, its shortest path distance  $d[u]$  is optimal and will never change."*

This assumption holds for non-negative weights because extending a path can only increase (or keep constant) the total distance. You can never find a "shortcut" to a finalized node by going through a new, longer path.

### Failure Mode with Negative Edges

When negative edges exist, this assumption collapses. Consider the following graph:  $S \rightarrow A$  (cost 5),  $S \rightarrow B$  (cost 10),  $B \rightarrow A$  (cost -8).



### Dijkstra's Execution Trace:

1. Start at  $S$ . Neighbors are  $A(5)$  and  $B(10)$ .
2. Dijkstra picks the smallest distance:  $A$  with distance 5. It **finalizes**  $A$ .

3. It then processes  $B$  (distance 10). From  $B$ , it sees an edge to  $A$  with weight -8.
4. New path to  $A$  via  $B$ :  $10 + (-8) = 2$ .
5. This is smaller than the "finalized" distance of 5.

## Conclusion

Dijkstra's algorithm finalized  $A$  prematurely. It does not go back to re-process finalized nodes. Consequently, it computes incorrect shortest path distances. For graphs with negative weights, the **Bellman-Ford algorithm** must be used, which can handle negative edges and detect negative cycles.

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