

Concurrency in C / C++

<https://youtu.be/zHDcAwhJQIc>

Concurrency in C / C++

There are several ways to achieve concurrent execution in C/C++

Multiple Threads – Threads sharing the same process memory.

Multiple Processes – Completely separate in their own memory.

These are essentially conceptually the same as the options in Python. One difference: there is no interpreter or GIL in C / C++

Accordingly, we must also be careful to use synchronization and communication where appropriate.

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Multiple Threads:

To spawn and manage multiple threads there are a couple of options:

pthreads – POSIX Threads Library (the old way)

<thread> - Starting with C++11 threading was added to the C standard language facilities. (the new way)

Let's start with pthreads.

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Pthreads:

Prior to C++11, there was no threading support directly built into the language itself.

So threading had to be supported through the use of a library.

Pthreads is a POSIX library for C / C++ that adds threading support in a standardized way.

To use pthreads, you just need to include pthread.h.

```
#include<pthread.h>
```

To use pthreads you just need to use it's functions...

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Create a thread:

```
int pthread_create(pthread_t *thread, const pthread_attr_t *attr,  
                  void *(*start_routine)(void*), void *arg);
```

Description: The `pthread_create()` function is used to create a new thread, with attributes specified by `attr`, within a process. If `attr` is `NULL`, the default attributes are used. Upon successful completion, `pthread_create()` stores the ID of the created thread in the location referenced by `thread`.

The thread is created executing `start_routine` with `arg` as its sole argument. If the `start_routine` returns, the effect is as if there was an implicit call to `pthread_exit()` using the return value of `start_routine` as the exit status.

Return: If successful, the `pthread_create()` function returns zero. Otherwise, an error number is returned to indicate the error.

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Join a thread:

```
int pthread_join(pthread_t thread, void **value_ptr);
```

Description: The `pthread_join()` function suspends execution of the calling thread until the target thread terminates, unless the target thread has already terminated.

On return from a successful `pthread_join()` call with a non-NULL `value_ptr` argument, the value passed to `pthread_exit()` by the terminating thread is made available in the location referenced by `value_ptr`.

When a `pthread_join()` returns successfully, the target thread has been terminated.

Return: If successful, the `pthread_join()` function returns zero. Otherwise, an error number is returned to indicate the error.

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Exit a thread:

```
void pthread_exit(void *value_ptr);
```

Description: The `pthread_exit()` function terminates the calling thread and makes the value `value_ptr` available to any successful join with the terminating thread.

An implicit call to `pthread_exit()` is made when a thread other than the thread in which `main()` was first invoked returns from the start routine that was used to create it. The function's return value serves as the thread's exit status.

Return: The `pthread_exit()` function cannot return to its caller.

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Pthreads example:

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

void *thread_func1(void *);
void *thread_func2(void *);

int main(void)
{
    pthread_t t1;
    pthread_t t2;
    int *arg;
    char *ret;

    // start the threads
    printf("Starting Threads\n");
    pthread_create(&t1, NULL, thread_func1, (void *) NULL);
    pthread_create(&t2, NULL, thread_func2, (void *) NULL);

    // continued...
```


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```
// continued...
    // wait for each thread to return
    pthread_join(t2, (void *)&ret);
    free(ret);
    pthread_join(t1, (void *)&ret);
    free(ret);
    printf("\nBoth threads finished!\n");
    return(0);
}

void *thread_func1(void *crap)
{
    for(i=0;i<100;i++)
    {
        printf("1"); fflush(stdout);
    }
    pthread_exit( NULL );
}

void *thread_func2(void *crap)
{
    for(i=0;i<100;i++)
    {
        printf("2"); fflush(stdout);
    }
    pthread_exit( NULL );
}
```

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Example Output:

Starting Threads

11222121221212121212112121121211212121211212121212121212112112112112112112212112112112112112112112212112121212
12112211212121212121122121212212121211121212112122121211221211212112112121212121212212112121212
121222222222222222

```
Both threads finished!
```

Other runs will give different output:

Starting Threads

12212121122112122112212121121212121212112212112121121121221121121212112211
2122121211212211212121122121121122121121121212221211211212211211212112112112121212
222222222222222222

Both threads finished!

Since both threads are executing concurrently their execution will be non-deterministic.

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Pthreads Synchronization:

Since concurrent execution is non-deterministic, we need mechanisms to control that execution.

Pthreads offers three mechanisms for thread synchronization:

`pthread_join()` - Wait until another thread completes. We've already used this!

mutexes - Mutual exclusion lock: Can be locked and unlocked to control access to a critical section. This enforces mutual exclusion.

condition variables - data type `pthread_cond_t` that supports `wait()`, `signal()`, and `broadcast()` functions.

These are analogous to the synchronization mechanisms we've seen before.

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Pthreads mutexes:

Mutexes are identical to Lock() objects we've been using in Python.

```
/* global mutex can be accessed by multiple threads */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;

/* some thread function */
void *some_thread_func(void *args)
{
    pthread_mutex_lock( &mutex1 );
    // some critical section protected by the mutex.
    pthread_mutex_unlock( &mutex1 );
}
```

We can have as many mutexes as necessary.

We can have as many threads share a set of locks as necessary.

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Pthreads condition variables:

The condition variable mechanism allows threads to suspend execution and relinquish the processor until some condition is true.

A condition variable must always be associated with a mutex to avoid a race condition created by one thread preparing to wait and another thread which may signal the condition before the first thread actually waits on it resulting in a deadlock. If this happens, the thread will be waiting for a signal that will never be sent.

Let's look at an example...

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Pthreads condition variables (wait):

```
pthread_mutex_t condition_mutex = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t  condition_cond  = PTHREAD_COND_INITIALIZER;

void *thread_function1(void*args)
{
    //some code here
    pthread_mutex_lock( &condition_mutex );
    while( /* some condition that we want to wait upon */ )
    {
        pthread_cond_wait( &condition_cond, &condition_mutex );
    }
    //perform the condition protected action.
    pthread_mutex_unlock( &condition_mutex );
    //some code here
}
```

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Pthreads condition variables (signal):

```
void *thread_function2(void*args)
{
    //some code here
    pthread_mutex_lock( &condition_mutex );
    if( /*some condition that releases the hold*/ )
    {
        pthread_cond_signal( &condition_cond );
        //could also use:
        // pthread_cond_broadcast( &condition_cond ); which is like signal_all.
    }
    pthread_mutex_unlock( &condition_mutex );
    //some code here
}
```

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Concurrency in C++11. (The NEW way!)

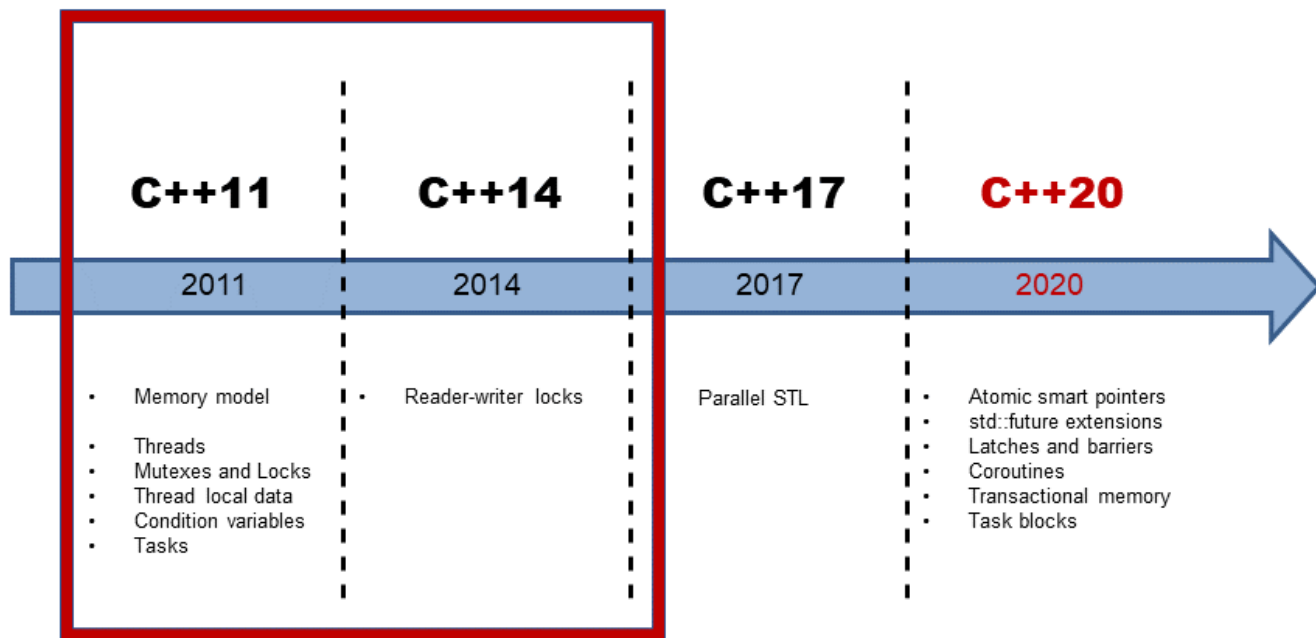
Starting in C++11 threads and other concurrency support mechanisms were added to the standard language facilities.

This means that we don't necessarily have to use a library like the POSIX pthreads library to write concurrent code.

Let's take a quick look at this...

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Concurrency in C++11. (The NEW way!)



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Simple Threading in C++11:

```
#include <iostream>
#include <thread>

void thread_func1(void);
void thread_func2(void);

using namespace std;

int main()
{
    cout << "Starting threads" << endl;
    thread t1(thread_func1);
    thread t2(thread_func2);
    t1.join();
    t2.join();
    cout << endl << "Both threads done!" << endl;
    return 0;
}

//continued...
```

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```
//...continued

void thread_func1(void)
{
    int i;
    for(i=0;i<100;i++)
    {
        printf("1"); fflush(stdout);
    }
}

void thread_func2(void)
{
    int i;
    for(i=0;i<100;i++)
    {
        printf("2"); fflush(stdout);
    }
}
```

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Synchronization in C++11:

C++ mutexes are just like pthreads mutexes.

```
/* global mutex can be accessed by multiple threads */
std::mutex mutex1;

/* some thread function */
void some_thread_func(void)
{
    mutex1.lock();
    // some critical section protected by the mutex.
    mutex1.unlock();
}
```

Again, we can have as many mutexes as necessary.

And, we can have many threads share mutexes as necessary.

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Synchronization in C++11:

C++11 also supports other synchronization primitives:

mutex (C++11) - provides basic mutual exclusion facility

timed_mutex (C++11) - provides mutual exclusion facility which implements locking with a timeout

recursive_mutex (C++11) - provides mutual exclusion facility which can be locked recursively by the same thread.

recursive_timed_mutex (C++11) - provides mutual exclusion facility which can be locked recursively by the same thread and implements locking with a timeout.

lock_guard (C++11) - implements a strictly scope-based mutex ownership wrapper.

unique_lock (C++11) - implements movable mutex ownership wrapper.

condition_variable (C++11) - provides a condition variable associated with a `std::unique_lock`.

condition_variable_any (C++11) - provides a condition variable associated with any lock type.

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Other Concurrency Features in C++11 and beyond...

C++11 and later versions provide many features related to concurrent execution.

- Locks (other types)
- Condition Variables
- Futures and Async
- Latches and Barriers
- Semaphores
- Parallel algorithms

For more details consult the C++ documentation:

<https://en.cppreference.com/w/cpp/thread>

There are also C interfaces to threading support that have been added in C11:

<https://en.cppreference.com/w/c/thread>

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That's all for today!

Stay Safe!