# Rabbit VM RFC

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# 1 Why?

I would like to make a RISC architecture that is capable of comfortably sitting on top of nearly any other architecture. If it's possible to compile to Rabbit, then a program can run on more or less any hardware or virtualized architecture.

Rabbit can be optimized per-architecture, while maintaining the same interface. It may, for example, take advantage of Intel's SIMD behind the scenes.

# 2 What?

### 2.1 Definitions

**space:** A register or memory location.

## 2.2 Registers

Registers are 32 bits wide.

Value	Register	Use
0x0	zero	Contains 0. MIPS style.
0x1 0x9	r1 r9	General purpose.
OxA	ip	Instruction pointer.
0xB	sp	Stack pointer.
0xC	ret	Returned value.
0xD	tmp	Temporary register.
0xE	flags	Flags used for comparison.

#### 2.2.1 Flags

Bit	Flag	Meaning
0x0	SF	Sign flag. On if sign bit of result is on.
0x1	ZF	Zero flag. On if result is zero or numbers were the same.
0x2 0x20		Reserved.

### 2.3 Instruction set

#### 2.3.1 Real instructions

When it makes sense, the destination register is the first argument to an instruction. The last argument to the following instructions may also be an immediate value, denoted with a prefix of \$: move, add, sub, mul, div, shr, shl, nand, xor, br, brz, brnz.

Value	Instruction	Usage	Explanation	Description
0x0	halt	halt		Stop the execution of the
0x1	move	move %rB, %rC	r[B] := r[C]	Move one space into ano
0x2	add	add %rA, %rB, %rC	r[A] := r[B] + r[C]	Add two spaces into a th
0x3	sub	sub %rA, %rB, %rC	r[A] := r[B] - r[C]	Subtract two spaces into
0x4	mul	mul %rA, %rB, %rC	r[A] := r[B] * r[C]	Multiply two spaces into
0x5	div	div %rA, %rB, %rC	r[A] := r[B] / r[C]	Divide two spaces into a
0x6	shr	shr %rA, %rB, %rC	r[A] := r[B] >> r[C]	Shift right one space a n
0x7	shl	shl %rA, %rB, %rC	$r[A] := r[B] \ll r[C]$	Shift left one space a nu
8x0	nand	nand %rA, %rB, %rC	r[A] := not(r[B] & r[C])	NAND two spaces.
0x9	xor	xor %rA, %rB, %rC	$r[A] := r[B] ^ r[C]$	XOR two spaces.
0xA	br	br %rC	goto r[C]	Branch.
0xB	brz	brz %rC	if (ZF set) goto r[C]	Branch if ZF is set.
0xC	brnz	brnz %rC	if (!(ZF set)) goto r[C]	Branch if ZF is not set.
0xD	in	in %rC	r[C] := getchar()	Read one character from
0xE	out	out %rC	<pre>putchar(r[C])</pre>	Print one character from

### 2.3.2 Assembler macros

The last argument to the following macros may also be an immediate value, denoted with a prefix of \$: cmp, not, push, call.

$\overline{Macro}$	Usage	Expansion
cmp	cmp A, B	sub %tmp, A, B
not	not A, B	nand A, B, B
or	or A, B, C	(A nand A) nand (B nand B)
and	and A, B, C	nand A, B, C $//$ not A, A
push	push A	move (%sp), A $//$ sub %sp, %sp, \$1
pop	pop A	add %sp, %sp, $1/$ move A, (%sp)
call	call A	${\tt push~\%ip~//~br~A}$
ret	ret	pop %ip

## 2.4 Addressing modes

There are two addressing modes: %reg and (%reg). The former uses the value in the register, and the latter uses the word at the address in the register.

### 3 How?

#### 3.1 Instruction formats

# vvvvvvvvvvvvvvvvvvvvvvvvvvv

#### Immediate value

Every bit in "Dead space" must be turned off. If one is turned on, the result is undefined.

If the immediate bit is on, then the instruction disregards  ${\tt rC}$  and instead looks for its third argument in the 32 bits after the first instruction. For example:

represents a move instruction with the immediate bit set. It will therefore look for an immediate value in the following word (in this case, the value is 7), and then store it in r1.

Addition works in a similar fashion:

represents an add instruction with the immediate bit set. It looks for an immediate value in the following word (in this case, 1), adds it to the value

in r1, then stores the result in r1. So this instruction would be an increment instruction.

The addressing mode bits are simple; if a register's addressing mode bit is on, then the address in the register is dereferenced when the instruction is being executed, and that data is used instead. For example:

#### 

Performs an addition operation that adds the contents of zero with r1 and stores the result in memory at the address in r7.

#### 3.2 Stages of compilation

#### 3.2.1 TODO Preprocessing

The preprocessor will be responsible for macro expansion and label to address translation. Macros exist in the form of instruction expansions, done behind the scenes.

### 3.2.2 TODO Peephole optimization

### 3.2.3 TODO Assembling

### 3.3 TODO

### 3.3.1 Floating point

Floating point computation is left to the client (an exercise for the reader, if you will).

#### 3.3.2 Memory layout

The memory layout is completely flat right now.