



# **ASIAN INSTITUTE OF TECHNOLOGY**

Department of Industrial System Engineering

Proposal Presentation on

## **LICENSE PLATE RECOGNITION IN LOW LIGHTING USING CLAHE-ENHANCED TWO-STAGE YOLOv8 PIPELINE**

**Presenter:**

**Rabin Karki (st125993)**



# 1.Introduction

- VLPR is critical for traffic management, toll collection and securing big organizations and campuses.
- Manual Monitoring of vehicles is inefficient.
- Need for an automated vehicle registration recognition system using computer vision.

## 2. Problem Statement

- Number Plates are hard to detect at low light.
- System struggles to detect plates when two vehicles arrive together.
- Vehicles moving quickly through the gate reduce the clarity of the captured frame.

### Secondary Challenges

- Thai License Plate complex Layout for standard OCR extractors.
- Distinction between similar characters like “8” vs “0” or “B” vs “8”.

## 3. Objective

### Main Objective

- To recognize the vehicle registration number of Thai license plate using CLAHE-Enhanced Two Stage YOLOv8 pipeline

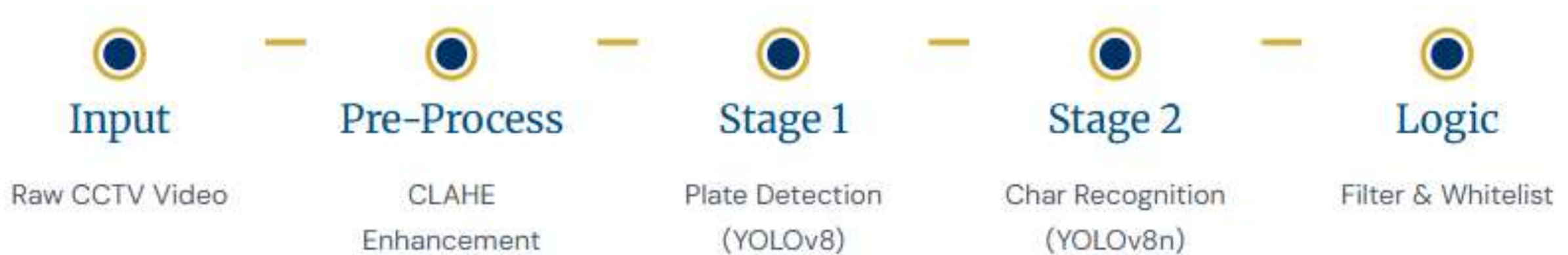
### Specific Objective

- To implement CLAHE to improve visibility in nighttime images.
- To replace standard OCR with a Two-Stage YOLOv8 Pipeline (Detection + Recognition) to eliminate classification errors.

## 4. Literature Review

- Number Plate recognition system often faces challenges in low-light environments.  
*(PMC, 2021)*
- Input images have different types of illumination, mainly due to environmental lighting and vehicle headlights.  
*(IEEE Transactions on circuits and systems for video technology, 2013)*
- Recognizing multiple vehicles becomes more challenging as some plates will have a smaller size or low resolution, and different background colors.  
*(EURASIP Journal on Image and Video Processing, 2021)*
- The Histogram equalization (Contrast Limited adaptive Histogram Equalization) was most effective for enhancing the license plates, improving the edge sharpness and revealing the plates hidden in shadows.  
*(Romanian Journal of Information Technology and Automatic Control)*

## 5. Methodology: System Architecture



```
PROVINCE_CLASSES_TO_IGNORE = [  
    'BKK', 'CRI', 'CBT', 'CPM', 'KBI', 'KPT', 'KSN', 'LEI',  
    'LPG', 'LPN', 'NAN', 'NBI', 'NBP', 'NKI', 'NPT', 'NSN',  
    'PBI', 'PCT', 'PKN', 'PLG', 'PLK', 'PNA', 'PMB', 'PRE',  
    'PTE', 'PTN', 'PWO', 'RBR', 'RET', 'ACR', 'AYA'  
]
```

```
DIGIT_CLASSES = ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '|']
```

## 6. System Configuration & Runtime Settings

```
# Main settings
frame_skip = 3
confidence_threshold = 0.3
enable_display = True

# Low Light Enhancement Settings
enable_low_light_enhance = True
clahe_clip_limit = 2.0           # CLAHE contrast limit
clahe_tile_size = (8, 8)        # CLAHE tile grid size
display_size = (480, 360)       # Frame display size
```

- Frame Skip(3):** Process every 3rd frame to optimize real-time performance without missing slow-moving vehicles.
- Confidence Threshold (0.3):** Balanced to maximize Recall (detecting dirty/dim plates) while relying on Stage 2 logic to filter false positives.
- CLAHE Clip Limit (2.0):** Prevents the histogram equalization from over-amplifying background noise in extremely dark scenes.

## 7. Experimental Setup

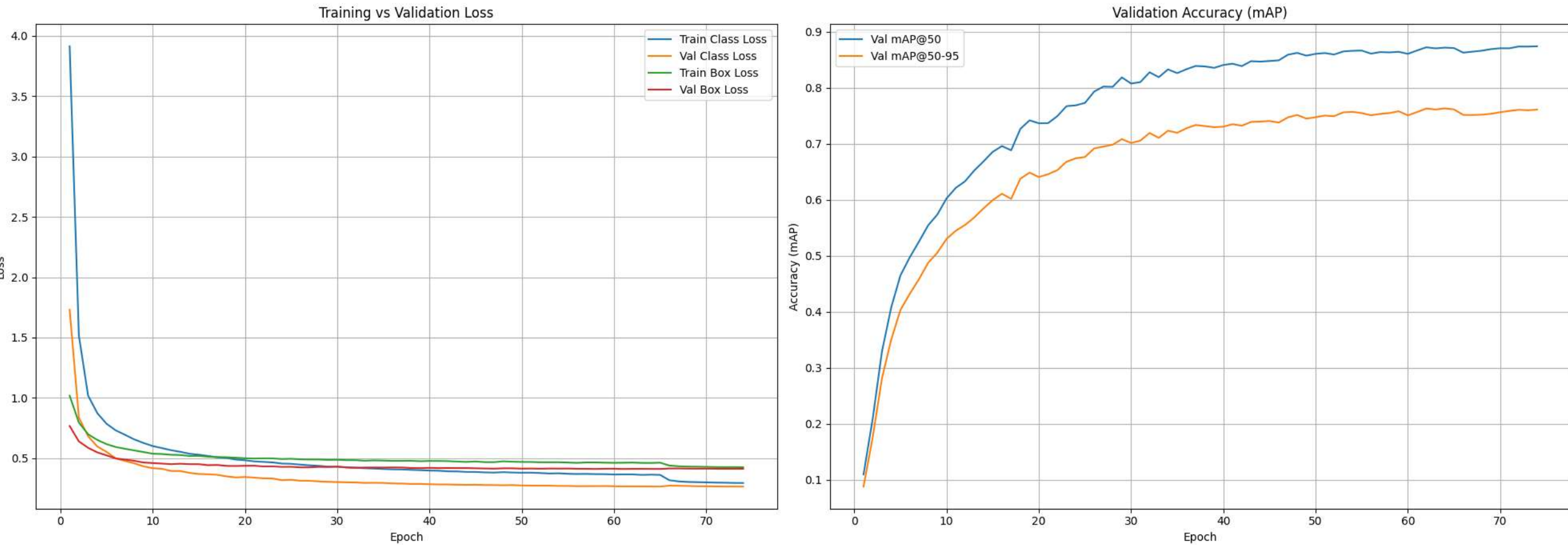
### ➤ Training Configuration

- Model: YOLOv8n (Nano)
- Hardware: Google Colab T4-GPU
- Training Data: 7260 images (Roboflow)
- Testing Data: 138 CCTV Video Frames
- Epochs: 75 (SGD Optimizer)



## 8. Experimental Results

Training & Validation Metrics



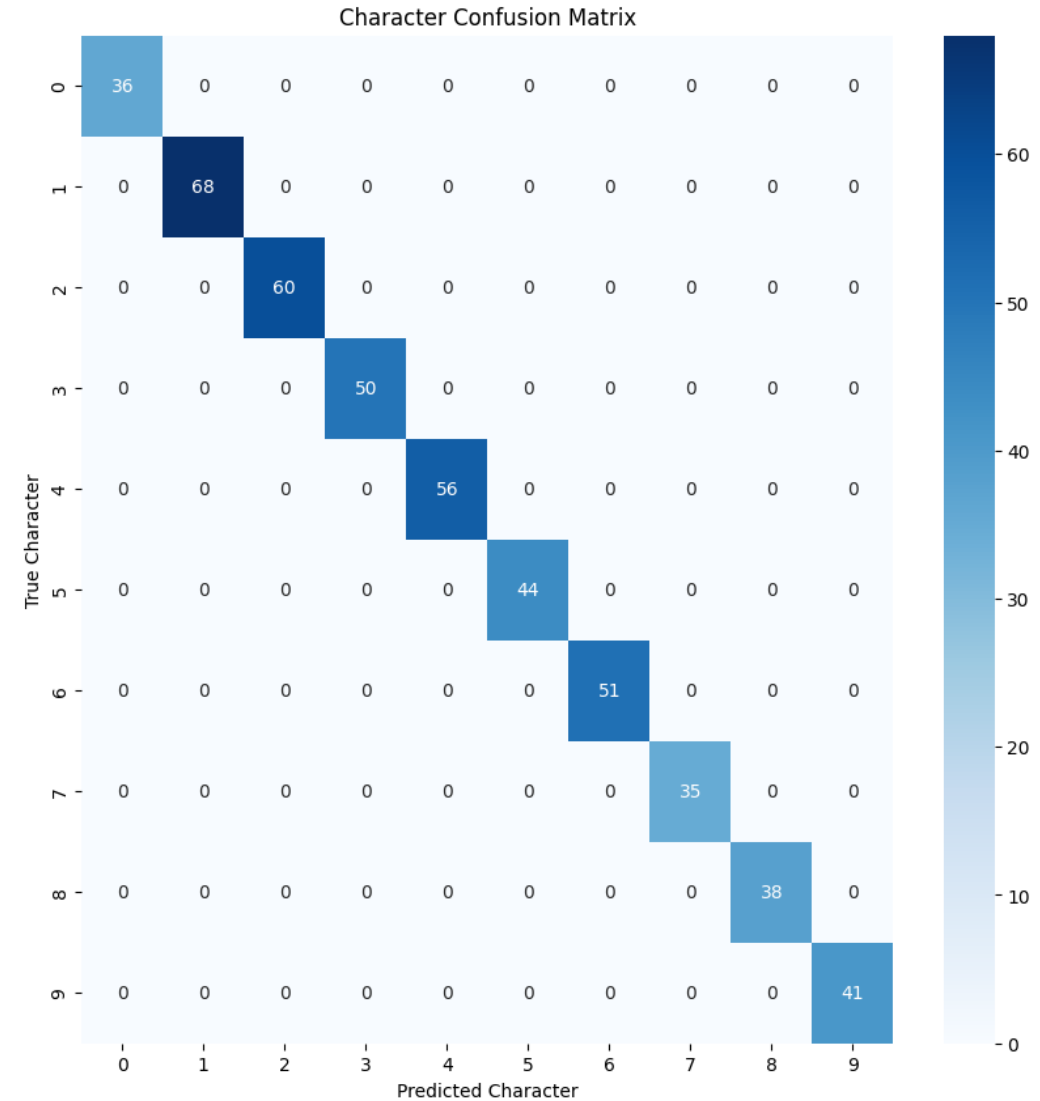
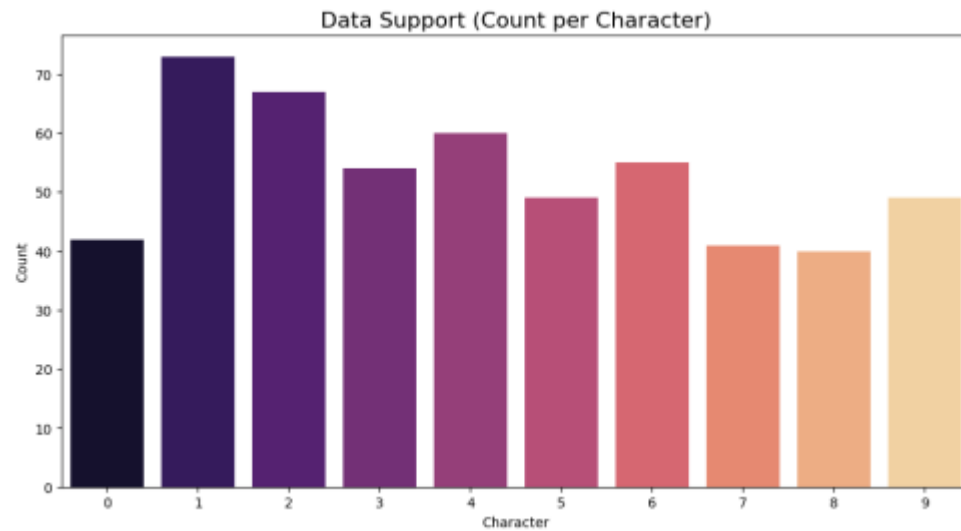
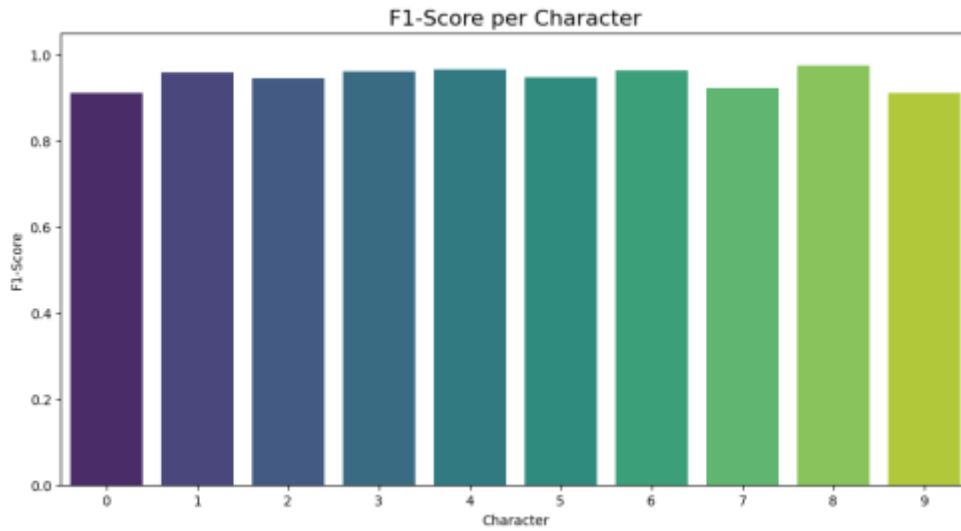
## 8. Quantitative Results

- The model achieved a **Weighted Average Precision of 1.00** on the test set of 530 characters.

Class	Precision	Recall	F1-Score	Support
0	0.97	0.86	0.91	42
1	0.99	0.93	0.96	73
2	1.00	0.90	0.94	67
3	1.00	0.93	0.96	54
4	1.00	0.93	0.97	60
5	1.00	0.90	0.95	49
6	1.00	0.93	0.96	55
7	1.00	0.85	0.92	41
8	1.00	0.95	0.97	40
9	1.00	0.84	0.91	49
Micro Average	1.00	0.90	0.95	530
Macro Average	1.00	0.90	0.95	530
Weighted Average	1.00	0.90	0.95	53



## 9. Visual Results

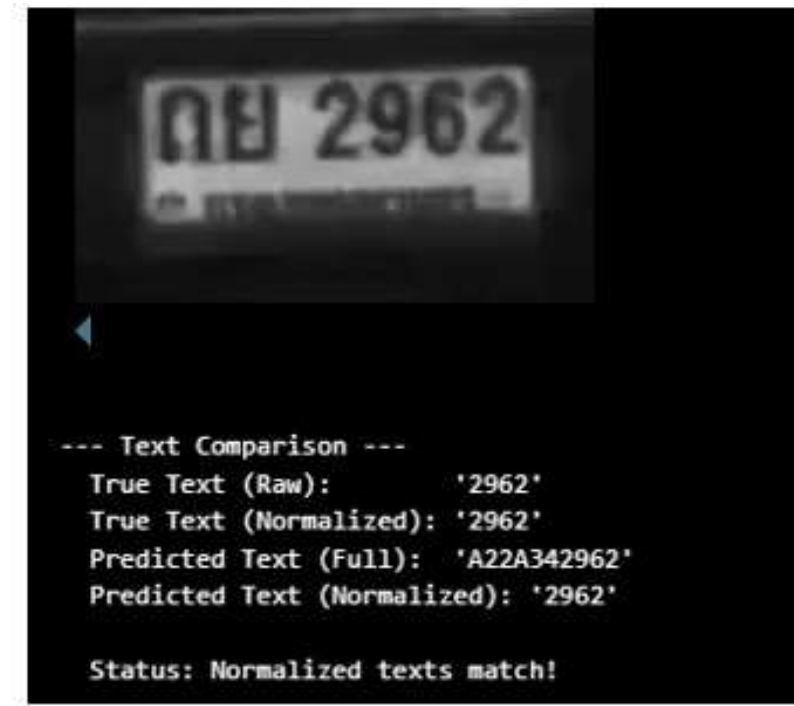
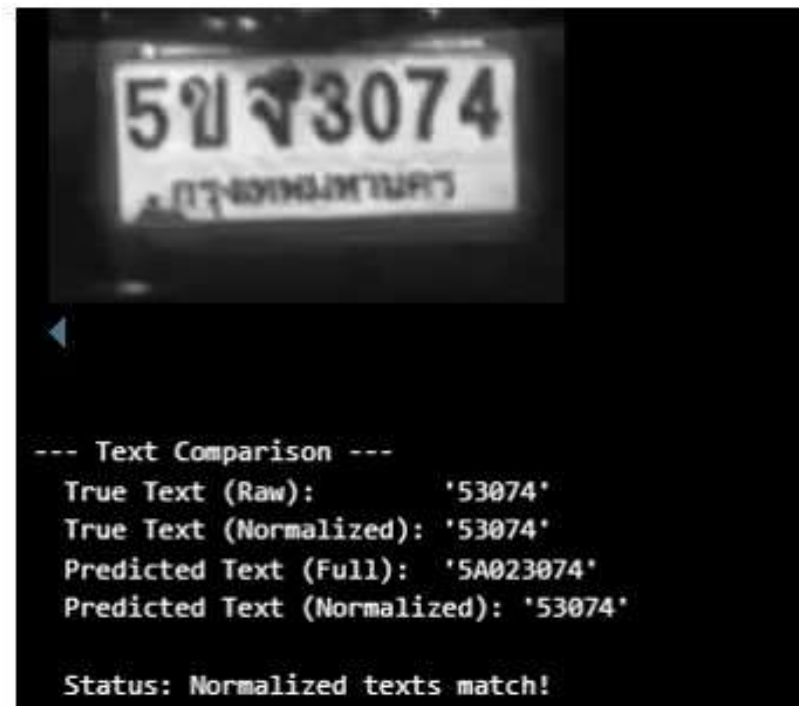
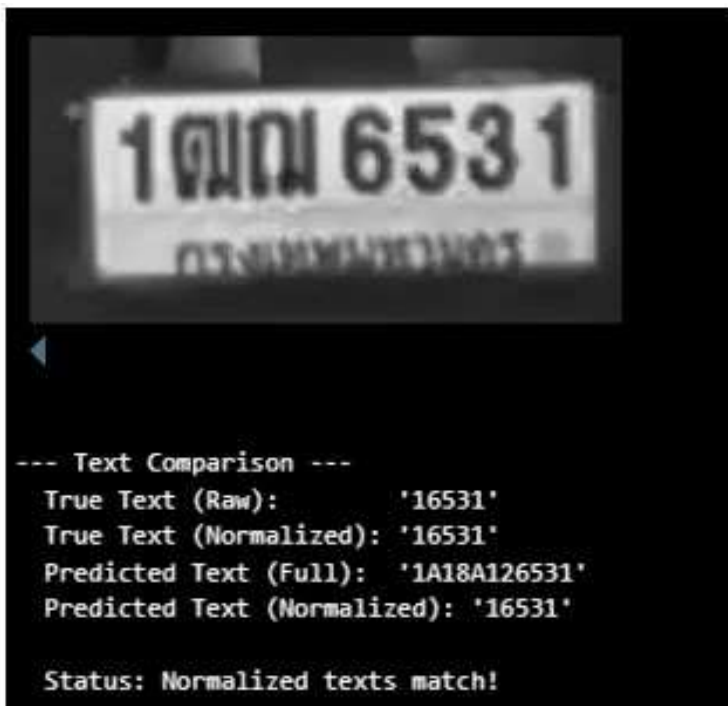


## 10. Ablation Study

Configuration	Result / Observation
YOLOv8 + Raw Image	Fails in dark; no plate detected.
YOLOv8 + CLAHE	Plate detected; characters unclear.
CLAHE + Easy OCR	Incorrect characters; 8/9 confusion.
CLAHE + Custom YOLOv8	Accurate but includes province text.
<b>CLAHE + Custom YOLO + Logic</b>	<b>Best accuracy; clean numeric output.</b>

## 11. Visual Analysis

- The system logic successfully filters out noise (Thai characters) and normalizes the prediction to digits only.





# References

- Lubna, Mufti, N., & Shah, S. A. A. (2021). Automatic Number Plate Recognition:A Detailed Survey of Relevant Algorithms. *Sensors (Basel, Switzerland)*, 21(9), 3028. <https://doi.org/10.3390/s21093028>.
- S. Du, M. Ibrahim, M. Shehata and W. Badawy, "Automatic License Plate Recognition (ALPR): A State-of-the-Art Review," in *IEEE Transactions on Circuits and Systems for Video Technology*, vol. 23, no. 2, pp. 311-325, Feb. 2013, doi: 10.1109/TCSVT.2012.2203741.
- Khan, K., Imran, A., Rehman, H.Z.U. *et al.* Performance enhancement method for multiple license plate recognition in challenging environments. *J Image Video Proc.* **2021**, 30 (2021).
- SRIDHAR, R., SURESH, R. A., BABU, S., & RAVISANKAR, P. (2025). Improving low-light image quality for object detection and license plate recognition. *Romanian Journal of Information Technology & Automatic Control/Revista Română de Informatică și Automatică*, 35(2).
- J. Redmon, S. Divvala, R. Girshick, and A. Farhadi, “You Only Look Once: Unified, Real-Time Object Detection,” in Proc. IEEE Conf. Comput. Vis. Pattern Recognit. (CVPR), 2016.
- C. N. E. Anagnostopoulos, I. E. Anagnostopoulos, V. Loumos, and E. Kayafas, “License Plate Recognition: A Tutorial,” *IEEE Intell. Transp. Syst. Mag.*, vol. 6, no. 1, pp. 48–58, 2014.
- S. M. Pizer, E. P. Amburn, J. D. Austin, R. Cromartie, A. Geselowitz, T. Greer, B. M. ter Haar Romeny, J. B. Zimmerman, and K. Zuiderveld, “Adaptive Histogram Equalization and its Variations,” *Comput. Vis. Graph. Image Process.*, vol. 39, no. 3, pp. 355–368, 1987.
- R. Laroca, E. Severo, L. A. Zanlorensi, L. S. Oliveira, G. R. Gonçalves, W. R. Schwartz, and D. Menotti, “A Robust Real-Time Automatic License Plate Recognition Based on the YOLO Detector,” in Proc. Int. Joint Conf. Neural Netw. (IJCNN), 2018

THANK YOU