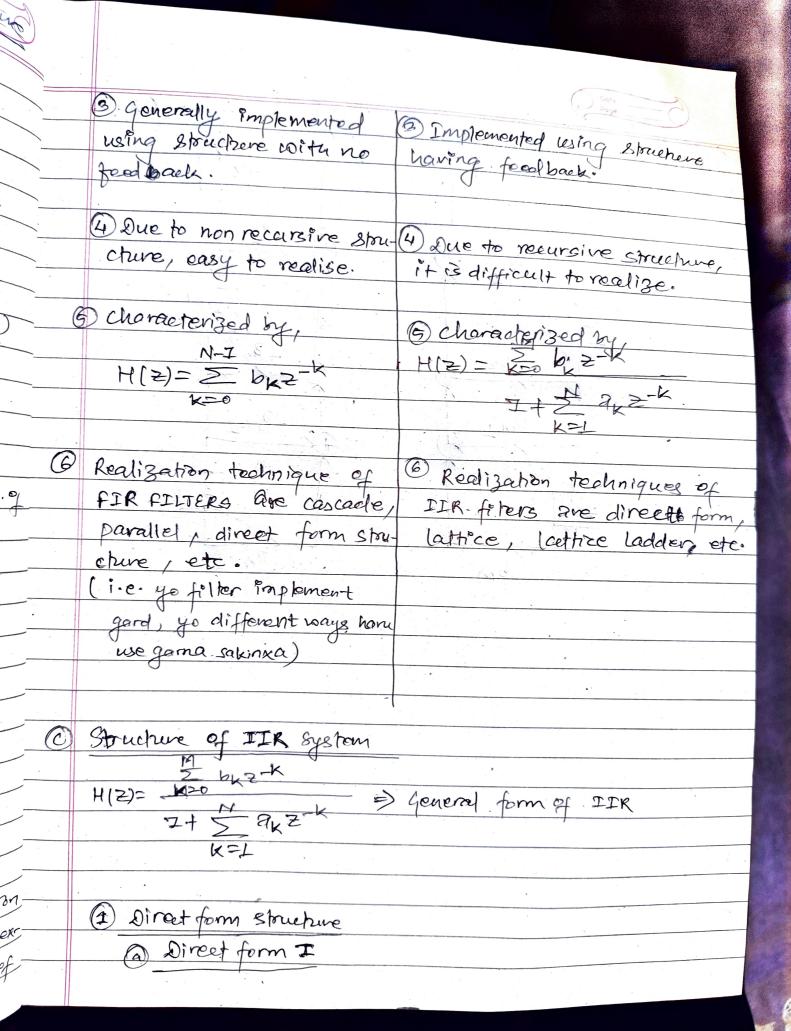
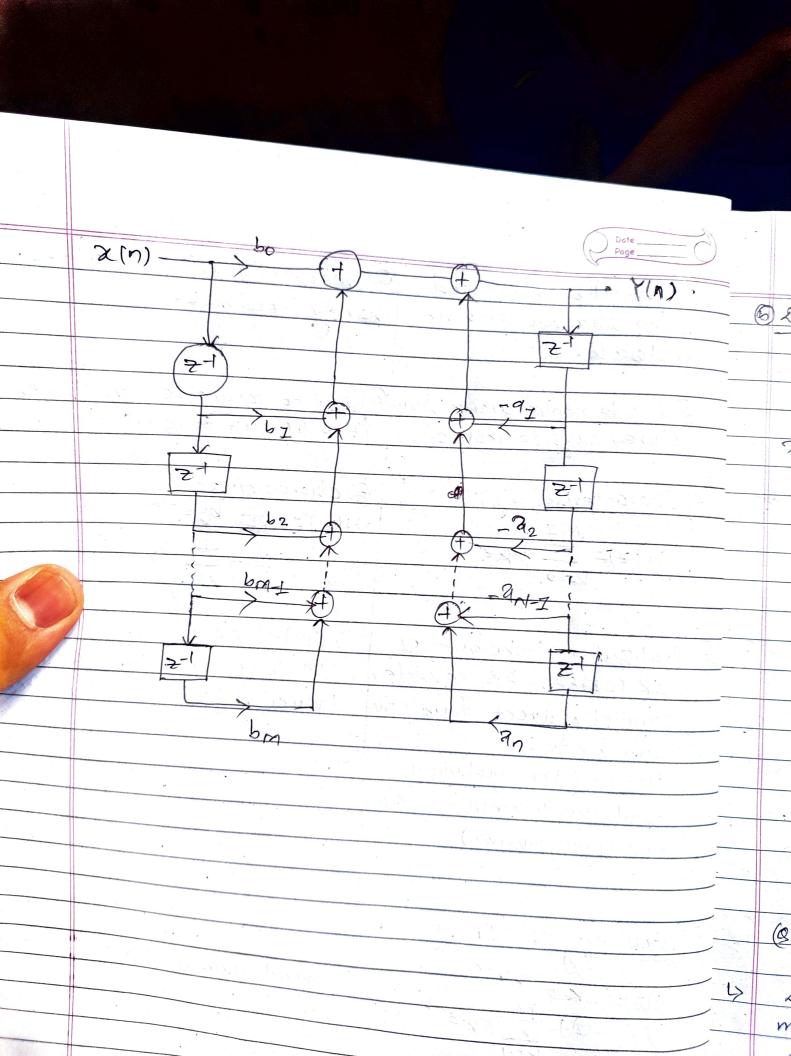
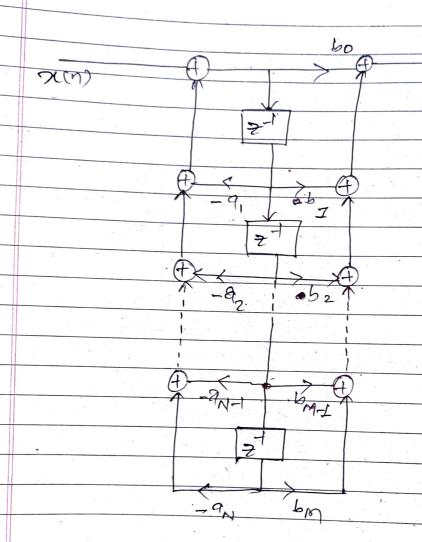
Short chibut 15 marks 13 carried swely Chapter: 4 Discrete Pilter Structure 39 Stouchure A usir The algorithm for implementing the system are better represented in terms of structure which ansists of interconnection of multiplier, adder of delay elements. 42 22(1) ch 21(1)- $\Rightarrow_{\alpha_1(n)+\alpha_2(n)}$ 6 ch 08 2x(n) fig: - Adder fig: - Multiplier (If we want more no of unit delay other than I, 2(ハーエ) 0 Rea Fig: - unit Delay we concade that much no o FI delay component? Da Difference between finite impulse response (FDR) ch and infinite impulse response (IIIR) i. FIR (FIR filters) IIR (IIR filters) 1 In FIR, the Empulse respon @ If infonite number of se sequence is of firnite dura- sample points are used to tion. This means the impulse determine the unit cample response of for follows has response, tuese filters are finite number of non zero term known to be IIR filters H! 2 Depends only upon the present 2 Present response is a function and past input samples. of present & past values of ex-1 citation as well as past values of responses.







6 Direct form structure II (Canonical Spricture)



4

(on) Which structure is best, Direct form (1) or Direct form (1)?

Direct form (1) is best since less no. of delay elements means fast computation and in efficient manner at 1000 cost.