



# EECS 390 – Lecture 23

## Template Metaprogramming II

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# Templates and Function Overloading

- Function templates can be specialized, but functions can also be overloaded, so overloading a function template with a non-template function is more common
- C++ prefers a non-template over a template instantiation if the parameter types are equally compatible with the arguments

```
template <class T>
string to_string(const T &item) {
    std::ostringstream oss;
    return (oss << item).str();
}

string to_string(bool item) {
    return item ? "true" : "false";
}
```

```
to_string(3.14)
-> "3.14"
to_string(true)
-> "true"
```

# SFINAE

- A key to function templates is that ***substitution failure is not an error (SFINAE)***
- This means that it is not an error if a function template fails to instantiate due to the types and expressions in the header being incompatible with the argument
- Instead, the template is removed from consideration

```
template <class T>
auto to_string(const T &item) ->
    decltype(std::to_string(item)) {
    return std::to_string(item);
}
```

Requires compatible  
std::to\_string()

This template fails to  
instantiate, but the  
previous one succeeds

```
to_string(Complex{3, 3.14})
-> "(3,3.14i)"
to_string(3.14)
-> error: call is ambiguous
```

Both templates  
are viable

# Causing a Substitution Failure

- Sometimes we need to cause a substitution failure
- Common tool:

```
template <bool B, class T> struct enable_if {  
    using type = T;  
};
```

```
template <class T> struct enable_if<false, T> {  
};
```

- Example:

```
template <int N> struct factorial {  
    static const typename  
        enable_if<N >= 0, long long>::type value =  
        N * factorial<N - 1>::value;  
};
```

This doesn't  
exist if  $N < 0$ ,  
resulting in an  
error

The standard library defines `std::enable_if` in  
`<type_traits>`.

## Overloading and Variadic Arguments

- We can use the fact that C-style variadic arguments have lowest priority in overload resolution to prefer one overload over another:

```
template <class T>
auto to_string_helper(const T &item, int /*ignored*/)
    -> decltype(std::to_string(item)) {
    return std::to_string(item);
}
```

This overload  
is preferred if  
it is viable

```
template <class T>
string to_string_helper(const T &item, ...) {
    std::ostringstream oss;
    oss << item;
    return oss.str();
}
```

Variadic  
arguments

```
template <class T>
string to_string(const T &item) {
    return to_string_helper(item, 0);
}
```

Dummy int  
argument

# Variadic Templates

- C++ has support for templates that take a variable number of arguments
- Allows definition of variadic classes and functions that are type safe
- Example:

Accepts one  
type argument

Parameter pack  
accepts zero or more  
type arguments

```
template <class First, class... Rest>
struct tuple {
    static const int size = 1 + sizeof...(Rest);
    // more code here
};
```

Size of  
parameter pack

Empty  
parameter  
pack

```
tuple<int> t1;
tuple<double, char, int> t2;
```

Parameter  
pack contains  
char and int

# Pattern Expansion

- An ellipsis to the right of a pattern that contains the name of a parameter pack is expanded into a comma-separated list

```
using first_type = First;  
using rest_type = tuple<Rest...>;
```

```
first_type first;  
rest_type rest;
```

If Rest contains char  
and int, expanded  
to tuple<char, int>

Recursive data  
representation

# Tuple Definition

```
template <class First, class... Rest>
struct tuple {
    static const int size = 1 + sizeof...(Rest);
    using first_type = First;
    using rest_type = tuple<Rest...>;
    first_type first;
    rest_type rest;
    tuple(First f, Rest... r) :
        first(f), rest(r...) {}
};
```

Expands to multiple  
parameters

Base  
case

```
template <class First>
struct tuple<First> {
    static const int size = 1;
    using first_type = First;
    first_type first;
    tuple(First f) : first(f) {}
};
```



# Tuple Access

```
template <class First, class... Rest>
struct tuple {
    first_type first;
    rest_type rest;
};
template <class First>
struct tuple<First> {
    first_type first;
};
```

Move-semantics stuff

```
template <int Index, class Tuple>
auto get(Tuple &&tuple) {
    if constexpr (Index == 0) {
        return std::forward<Tuple>(tuple).first;
    } else {
        return
            get<Index-1>(std::forward<Tuple>(tuple).rest);
    }
}
```

Compile-time  
conditional

# Tuple Access and SFINAE

- We can induce a substitution failure if a different type is passed to our `get()` function template:

```
template<class T>
struct is_tuple : std::false_type {};

template<class... T>
struct is_tuple<tuple<T...>> : std::true_type {};
```

Has value member that is false

```
template <int Index, class Tuple,
          class = std::enable_if_t<
            is_tuple<
              std::remove_reference_t<Tuple>
            >::value,
            void
          >>
```

Template parameter becomes void if tuple passed in, fails to substitute otherwise

```
auto get(Tuple &&tuple) { /* ... */ }
```

# Structured Bindings

- C++ has “structured bindings” that allow tuple-like types to be unpacked into separate variables:

```
tuple<int, double, char> t{3, 4.1, 'c'};
auto [i, d, c] = t; // i = 3, d = 4.1, c = 'c'
```

- To make this work, we need the following:

```
namespace std {
    template<class... T>
        struct tuple_size<::tuple<T...>> {
            static const int value = ::tuple<T...>::size;
        };
    template<std::size_t I, class T, class... U>
        struct tuple_element<I, ::tuple<T, U...>> :
            tuple_element<I-1, ::tuple<U...>> {};
    template<class T, class... U>
        struct tuple_element<0, ::tuple<T, U...>> {
            using type = T;
        };
}
```

Specialization of  
`std::tuple_size`  
for our tuples

Specializations of  
`std::tuple_element`  
to compute the  
element types for  
our tuples

# Multidimensional Arrays

- We can use metaprogramming to implement a multidimensional array abstraction in C++
- **Point**: a multidimensional index, represented by a sequence of integers

```
point<3> p = pt(3, -4, 5);
```

- **Domain**: a range of indices, represented by a lower-bound and an upper-bound point

```
rectdomain<3> rd{pt(3, -4, 5), pt(5, -2, 8)};
```

- **Array**: constructed over a domain, indexed with a point

```
ndarray<double, 3> A{rd};  
A[p] = 3.14;
```

# Points

- We can implement a point as follows:

Data  
representation

```
template <int N> struct point {  
    int coords[N];  
    int &operator[](int i) {  
        return coords[i];  
    }  
    const int &operator[](int i) const {  
        return coords[i];  
    }  
};
```

Function to  
construct a  
point

```
template <class... Is>  
point<sizeof...(Is)> pt(Is... is) {  
    return point<sizeof...(Is)>{{is...}};  
}
```

Inner initializer list  
is for initializing  
coords array

# Point Operations

- Point operations have a common structure:

```
template <int N>
point<N> operator+(const point<N> &a,
                   const point<N> &b) {
    point<N> result;
    for (int i = 0; i < N; i++)
        result[i] = a[i] + b[i];
    return result;
}
```

```
template <int N>
bool operator==(const point<N> &a,
                const point<N> &b) {
    bool result = true;
    for (int i = 0; i < N; i++)
        result = result && (a[i] == b[i]);
    return result;
}
```

# Generalized Macro

## ► General structure:

```
#define POINT_OP(op, rettype, header, action) \
    template <int N>                          \
    rettype operator op(const point<N> &a,    \
                        const point<N> &b) {   \
        header;                               \
        for (int i = 0; i < N; i++)          \
            action;                           \
        return result;                       \
    }
```

## ► Arithmetic structure:

```
#define POINT_ARITH_OP(op)                   \
    POINT_OP(op, point<N>, point<N> result, \
              result[i] = a[i] op b[i])
```

# Implementing Operations

- We can implement the operations as follows:

```
POINT_ARITH_OP(+);  
POINT_ARITH_OP(-);  
POINT_ARITH_OP(*);  
POINT_ARITH_OP(/);
```

```
#define POINT_COMP_OP(op, start, combiner)      \  
    POINT_OP(op, bool, bool result = start,    \  
              result = result combiner         \  
              (a[i] op b[i]), result)
```

```
POINT_COMP_OP(==, true, &&);  
POINT_COMP_OP(!=, false, ||);  
POINT_COMP_OP(<, true, &&);  
POINT_COMP_OP(<=, true, &&);  
POINT_COMP_OP(>, true, &&);  
POINT_COMP_OP(>=, true, &&);
```



# Rectangular Domains

► Interface:

```
template <int N>
struct rectdomain {
    point<N> lwb;
    point<N> upb;

    int size() const;

    struct iterator;

    iterator begin() const;

    iterator end() const;
};
```

Exclusive  
upper bound



```
rectdomain<3> rd{pt(1, 2, 3),
                 pt(3, 4, 5)}
for (auto p : rd)
    cout << p << endl;
```

```
(1,2,3)
(1,2,4)
(1,3,3)
(1,3,4)
(2,2,3)
(2,2,4)
(2,3,3)
(2,3,4)
```

# Array Interface

```

template <class T, int N>
struct ndarray {
private:
    rectdomain<N> domain;
    int sizes[N];
    T *data;

    int indexof(const point<N> &index) const;

public:
    ndarray(const rectdomain<N> &dom);
    ndarray(const ndarray &rhs);
    ndarray &operator=(const ndarray &rhs);
    ~ndarray();

    T &operator[](const point<N> &index);
    const T &operator[](const point<N> &index) const;
};

```

Dimensionality

Element type

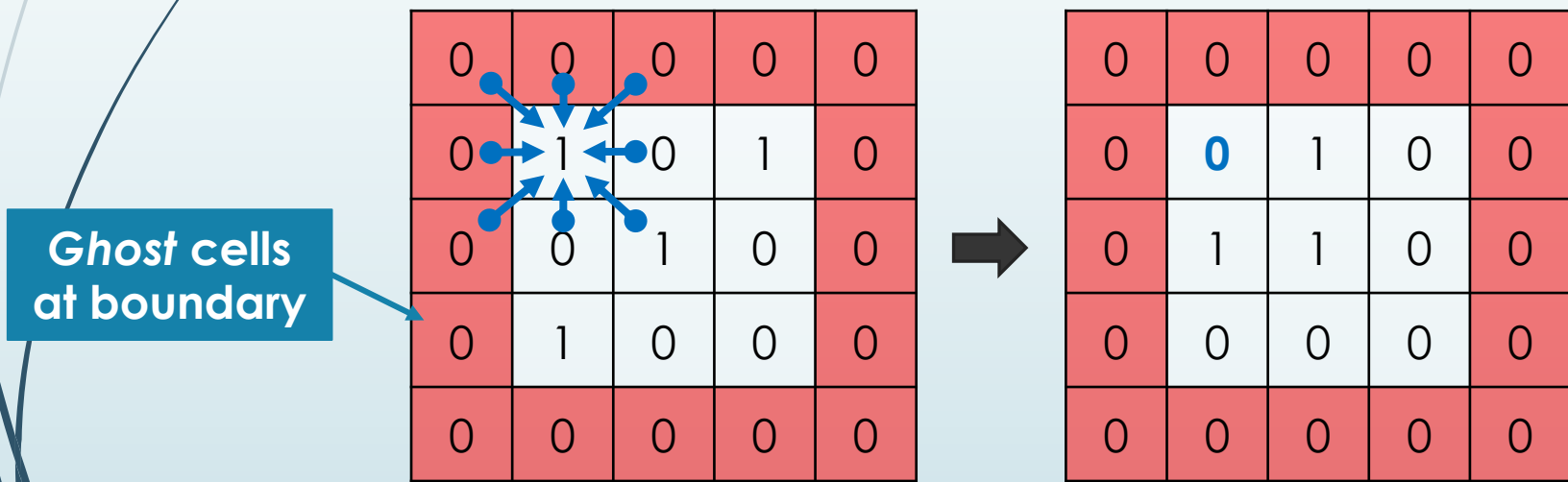
Translates  
multidimensional  
to linear index

Linear data  
representation

The Big 3

# Stencil

- A **stencil** is an iterative computation that updates grid points according to the previous value of neighboring points
- In the **Jacobi** method, the updates are **out of place**, so that new values are recorded in a different grid than old values



# Stencil Data Structures

- Domains and arrays for 3D heat equation:

```
point<3> start = pt(0, 0, 0);  
point<3> end = pt(xdim, ydim, zdim);
```

Domain with  
ghost cells

```
rectdomain<3> domain{start - pt(1, 1, 1),  
                      end + pt(1, 1, 1)};  
rectdomain<3> interior{start, end};
```

```
ndarray<double, 3> gridA(domain);  
ndarray<double, 3> gridB(domain);
```

Include ghost  
cells in array

# Stencil Loop

- A single timestep:

```
for (auto p : interior) {  
    gridB[p] =  
        gridA[p + pt( 0,  0,  1)] +  
        gridA[p + pt( 0,  0, -1)] +  
        gridA[p + pt( 0,  1,  0)] +  
        gridA[p + pt( 0, -1,  0)] +  
        gridA[p + pt( 1,  0,  0)] +  
        gridA[p + pt(-1,  0,  0)] +  
        WEIGHT * gridA[p];  
}
```

- Can be made significantly faster with custom loop construct, using macros, lambdas, and template metaprogramming (see the notes for details)