EECS 280 - Lecture 7

Abstract Data Types in C

Abstraction

 Procedural abstraction separates what a function does from how it works.

```
// EFFECTS: extracts one column of data from a tab
// separated values file (.tsv)
// Prints errors to stdout and exits with non-zero
// status on errors
std::vector<double> extract_column(
    std::string filename, std::string column_name);
```

Data abstraction separates what an Abstract
 Data Type (ADT) does from how it works.

```
string str1 = "hello ";
string str2 = "jello";
cout << str1 + str2 << endl; // Prints "hello jello"</pre>
```

C-Style ADTs: Data Representation

- Let's say we want to represent triangles.
- First, pick a data representation:
 - Three side lengths a, b, c as **members** of a **struct**.
- This is an implementation detail.

```
struct Triangle {
   double a;
   double b;
   double c;
};

int main() {
   Triangle t1 = { 3, 4, 5 };
   Triangle t2 = { 2, 2, 2 };
}
```

```
The Stack
main hide

t2 Triangle

0x1024 2. a

0x1032 2. b

0x1040 2. c

t1 Triangle

0x1000 3. a

0x1008 4. b

0x1016 5. c
```

C-Style ADTs: Interface Functions

- Define functions for Triangle behaviors.
- These determine the interface for a triangle.

```
struct Triangle {
  double a, b, c;
};

double Triangle_perimeter(const Triangle *tri) {
  return tri->a + tri->b + tri->c;
}
```

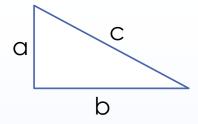
The code in here is part of the implementation.

The first parameter is a pointer to the Triangle struct we want to work with.

```
int main() {
  Triangle t1 = { 3, 4, 5 };
  cout << Triangle_perimeter(&t1) << endl;
}</pre>
```

When you call the function, pass it the address of the Triangle you want to work with.

C-Style ADTs



We use pass-by-pointer so that we can work with the original object.

```
Memory
```

```
struct Triangle {
  double a, b, c;
};

double Triangle_perimeter(const Triangle *tri) {
  return tri->a + tri->b + tri->c;
}

int main() {
  Triangle t1 = { 3, 4, 5 };
  cout << Triangle_perimeter(&t1) << endl;
}</pre>
```

Let's say we want to add a function to scale triangles by a given factor.

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```
struct Triangle {
  double a, b, c;
};
int main() {
  Triangle t1 = \{ 2, 2, 2 \};
  Triangle_scale(&t1, 2); // Scale by x2
  cout << Triangle perimeter(&t1) << endl; // prints 12</pre>
```

```
a
        b
```

```
void Triangle scale(const Triangle *tri,
                    double s) {
 tri->a *= s;
 tri->b *= s;
 tri->c *= s;
```

```
void Triangle scale(Triangle tri,
                    double s) {
 tri.a *= s;
 tri.b *= s;
 tri.c *= s;
```

```
void Triangle scale(Triangle *tri,
                    double s) {
  a *= s;
  b *= s:
  c *= s;
```

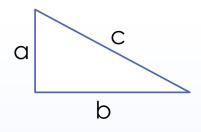
```
void Triangle scale(Triangle *tri,
                    double s) {
 tri->a *= s;
 tri->b *= s;
 tri->c *= s;
```

```
void Triangle_scale(double s) {
  t1.a *= s;
  t1.b *= s;
  t1.c *= s;
```

Question

Which of these Triangle_scale functions are written correctly?

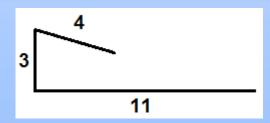


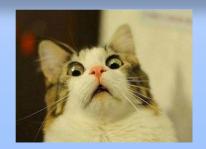


We have no check

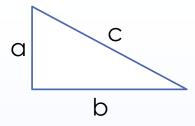
- There are some issues with the way we're initializing the triangle.
- What's wrong with this code?

```
int main() {
  Triangle t1 = { 3, 4, 11 };
  Triangle_scale(&t1, 2);
  cout << Triangle_perimeter(&t1) << endl;
}</pre>
on the values used to
initialize the Triangle
  member variables.
```









Define an initializer function

```
struct Triangle {
  double a, b, c;
};
void Triangle init(Triangle *tri, double a in,
                   double b in, double c in) {
  // TODO: Check the a, b, c, values we get
 tri->a = a in;
 tri->b = b in;
 tri->c = c in;
int main() {
 Triangle t1;
  Triangle_init(&t1, 3, 4, 5);
 Triangle_scale(&t1, 2);
  cout << Triangle_perimeter(&t1) << endl;</pre>
```

Representation Invariants

- A problem for compound types...
 - Some combinations of member values don't make sense together.

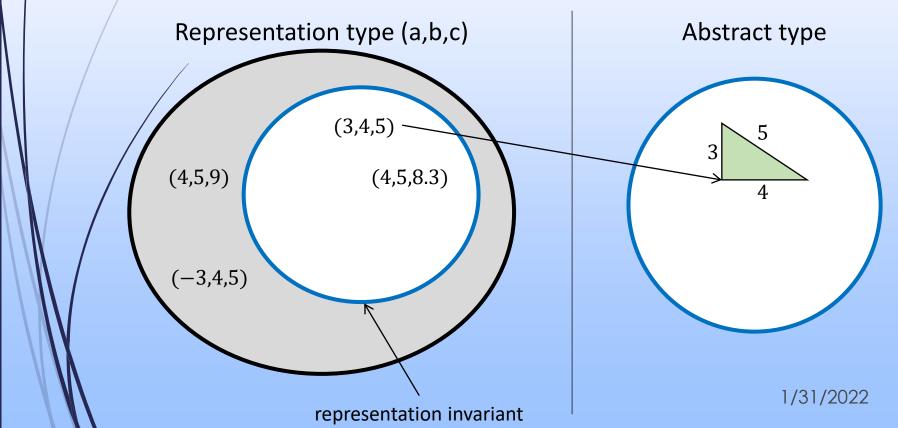
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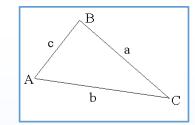
- We use representation invariants to express the conditions for a valid compound object.
- For Triangle:

Positive Edge	Triangle
Lengths	Inequality
0 < a	a + b > c
0 < b	a + c > b
0 < c	b + c > a

Representation vs. Abstraction

- We pick some way to represent our abstract concept with data. (e.g. 3 doubles)
- Only some possible values in the representation are valid (meaningful in the abstraction).



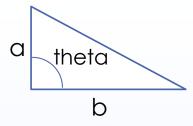


C-Style ADTs (structs)

Check invariants using assert.

```
struct Triangle {
  double a, b, c;
};
void Triangle init(Triangle *tri, double a in,
                   double b_in, double c_in) {
  assert(0 < a in && 0 < b in && 0 < c in);
  assert(a in + b in > c in && a in + c in > b in &&
         b_in + c_in > a_in);
 tri->a = a in;
 tri->b = b in;
 tri->c = c in;
                       This will now cause a
                         failed assertion.
int main() {
  Triangle t1;
  Triangle_init(&t1, 3, 4, 11);
```

C-Style ADTs (structs)



- Other representations are possible.
 - Different representation invariants!

```
struct Triangle {
  double a;
                     Different
  double b;
                 implementation.
  double theta;
};
int main() {
                 Same interface.
  Triangle t1;
  Triangle_init(&t1, 3, 4, 5);
  Triangle_scale(&t1, 2);
  cout << Triangle_perimeter(&t1) << endl;</pre>
```

Respect the Interface!

What's wrong with this code?

```
int main() {
  Triangle t1;
  Triangle_init(&t1, 3, 4, 5);

// Print out the perimeter (BAD)
  cout << t1.a + t1.b + t1.c << endl;
}</pre>
```

```
struct Triangle {
  double a;
  double b;
  double theta;
};
```

The existence of a member called c is an implementation detail, not part of the interface!

Plain Old Data

A simple compound type can be defined as Plain Old Data (POD), where the interface and implementation are the same.

```
struct Pixel {
                           (255,0,0)
                                       (0,255,0)
                                                    (0,0,255)
  int r; // red
  int g; // green
                           (0,0,0)
                                                  (100,100,100)
                                      (255, 255, 255)
  int b; // blue
};
                                      (124,63,63)
                         (101,151,183)
                                                   (163,73,164)
int main() {
  Pixel p = \{ 255, 0, 0 \};
  cout << p.r << " "
        << p.g << " "
        << p.b << endl;
```

Composing ADTs

One ADT might be a member of another.

```
struct Professor {
 int age;
 Triangle favTriangle;
};
      Always remember to initialize member ADTs, either by
    using an _init function or as a copy of a pre-existing ADT.
void Professor_init(Professor *prof, int age, int side) {
  prof->age = age;
  Triangle_init(&prof->favTriangle, side, side);
void Professor_init(Professor *prof, int age,
                    const Triangle &favTriangle) {
  prof->age = age;
  prof->favTriangle = favTriangle;
```

Abstraction Layers

ADTs can be composed to for multiple layers of abstraction.

Image "what".

	0	1	2	3	4			
0	(0,0,0)	(0,0,0)	(255,255,250)	(0,0,0)	(0,0,0)			
1	(255,255,250)	(126,66,0)	(126,66,0)	(126,66,0)	(255,255,250)			
2	(126,66,0)	(0,0,0)	(255,219,183)	(0,0,0)	(126,66,0)			
3	(255,219,183)	(255,219,183)	(0,0,0)	(255,219,183)	(255,219,183)			
4	(255,219,183)	(0,0,0)	(134,0,0)	(0,0,0)	(255,219,183)			

Image.cpp

Image "how", using Matrix "what".

	0	1	2	3	4
0	0	0	255	0	0
1	255	126	126	126	255
2	126	0	255	0	126
3	255	255	0	255	255
4	255	0	134	0	255

	0	1	2	3	4
0	0	0	255	0	0
1	255	66	66	66	255
2	66	0	219	0	66
3	219	219	0	219	219
4	219	0	0	0	219

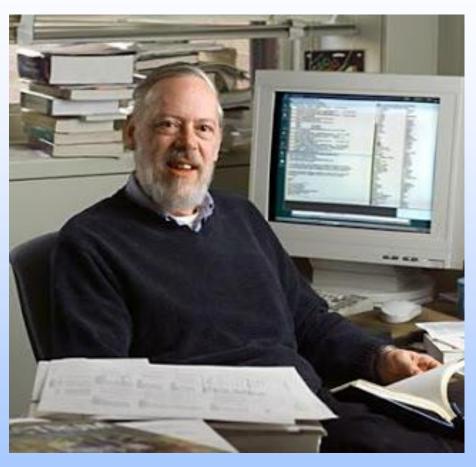
	0		2	3	4
0	0	0	250	0	0
1	250	0	0	0	250
2	0	0	183	0	0
3	183	183	0	183	183
4	183	0	0	0	183

Matrix.cpp

Matrix "how".

0	0	2 5 5	0	0	2 5 5	1 2 6	1 2 6	1 2 6	2 5 5	1 2 6	0	2 5 5	0	1 2 6	2 5 5	2 5 5	0	2 5 5	2 5 5	2 5 5	0	1 3 4	0	2 5 5
Ω	1	2	3	1	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24

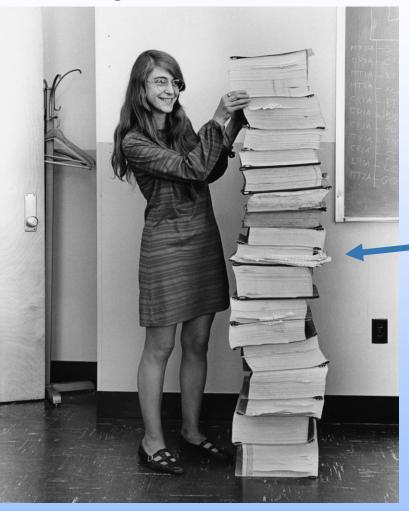
Dennis Ritchie



Creator of the C Programming Language

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Margaret Hamilton

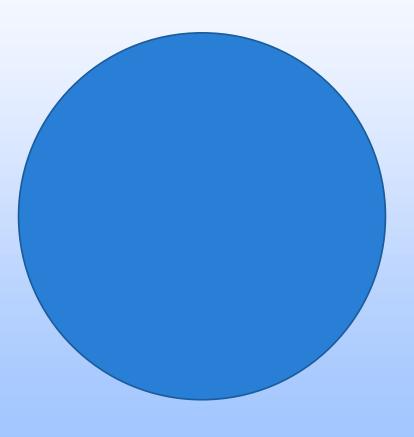


This giant stack is the printed code for the Apollo Project's Navigation System!

Lead Developer for Flight Software NASA's Apollo Program

1/31/2022

We'll start again in one minute.



Review: Types of Testing

Unit testing

- One piece at a time (e.g., a function)
- Find and fix bugs early! Less work.
 - Test smaller, less complex, easier to understand units.
 - You just wrote the code: easier to debug

System testing

- Entire project (code base)
- Do this after unit testing

Regression testing

 Automatically run all unit and system tests after a code change

Kinds of Test Cases

Consider test cases for the Matrix_at function from project 2...

```
// REQUIRES: mat points to a valid Matrix
// 0 <= row && row < Matrix_height(mat)
// 0 <= column && column < Matrix_width(mat)
// EFFECTS: Returns a pointer to the element in the Matrix
// at the given row and column.
int* Matrix_at(Matrix* mat, int row, int column);</pre>
```

Don't write these.

Not needed for P2.

Type Prohibited	ASSERT_EQUAL(*Matrix_at("cat", 2, 2), 42)
REQUIRES Prohibited	ASSERT_EQUAL(*Matrix_at($\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$, 1, -1), 42)
Simple	ASSERT_EQUAL(*Matrix_at($\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$, 1, 1), 5)
(Edge) Special	ASSERT_EQUAL(*Matrix_at($\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$, 2, 2), 9)
Stress	Matrix_init(big, 400, 400); Matrix_fill(big, 1); ASSERT_TRUE(Matrix_equal(big, $\begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{bmatrix}$));

Simple Test

```
// Fills a 3x5 Matrix with a value and checks that
// Matrix_at returns that value for each element.
TEST(test_fill_basic) {
                                   Create Matrix object
  Matrix *mat = new Matrix; ◀
                                   in dynamic memory<sup>1</sup>.
  const int width = 3;
                                    The result is a pointer
  const int height = 5;
                                     to the new object.
  const int value = 42;
  Matrix_init(mat, width, height);
  Matrix_fill(mat, value);
  for (int row = 0; row < height; ++row) {</pre>
    for (int col = 0; col < width; ++col) {</pre>
      ASSERT_EQUAL(*Matrix_at(mat, row, col), value);
                     Delete Matrix object when
  delete mat;
                        we no longer need it.
```

¹We create Matrix and Image objects in dynamic memory because the default stack size on most of our machines is too small to store them on the stack.

Bad Edge Test

```
// Places the maximum value at a corner of the
// matrix and tests that Matrix_max finds it.
TEST(edge_test_max) {
 Matrix *mat = new Matrix;
  const int width = 3;
  const int height = 5;
 Matrix_init(mat, width, height);
  for (int i = 0; i < width * height; ++i) {</pre>
    mat->data[i] = i;
                               Breaks the
                                Matrix
 mat->data[14] = 99; 4
                               interface.
  ASSERT_EQUAL(Matrix_max(mat), 99);
  delete mat;
```

Respect the Interface!

What's wrong with this code?

```
for (int i = 0; i < width * height; ++i) {
   mat->data[i] = i;
}
mat->data[14] = 99
```

- The existence of a member called data and its layout is an implementation detail, not part of the interface!
- Instead, use the interface functions, even when testing.

```
*Matrix_at(mat, 4, 2) = 99;
```

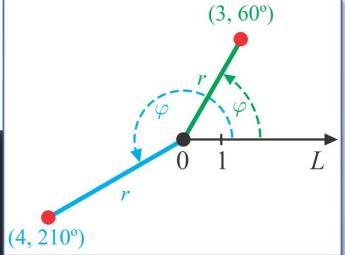
Good Edge Test

```
// Places the maximum value at a corner of the
// matrix and tests that Matrix_max finds it.
TEST(edge_test_max) {
 Matrix *mat = new Matrix;
  const int width = 3;
  const int height = 5;
  const int max value = 99;
 Matrix_init(mat, width, height);
  for (int row = 0; row < height; ++row) {</pre>
   for (int col = 0; col < width; ++col) {</pre>
      *Matrix at(mat, row, col) = row * width + col;
  *Matrix_at(mat, 4, 2) = max_value;
 ASSERT_EQUAL(Matrix_max(mat), max_value);
  delete mat;
```

Review: Test-Driven Development

- 1. First, write tests for the desired behavior.
- 2. Then write implementations with the goal of passing those tests.
- 3. Go to step 1.
 - You may have thought of more tests while writing the implementation.
 - There should be lots of back and forth between testing and implementing!
 - If you find a bug, make sure you have a test case that exposes the bug.

```
struct Polar {
   double r;
   double phi;
};
struct for data
representation.
```



Initializer Function

Polar Functions

```
struct Polar {
  double r;
  double phi;
};
                                (4, 210^{\circ})
void Polar_init(Polar* p, double radius,
                 double angle) {
  p->r = radius;
                    Then, make an initial attempt
  p->phi = angle;
                      at writing implementations.
double Polar_radius(const Polar* p) {
  return p->r;
double Polar_angle(const Polar* p) {
  return p->phi;
```

```
struct Polar {
  double r;
 double phi;
};
void Polar_init(Polar* p, double radius,
                double angle);
double Polar_radius(const Polar* p);
double Polar_angle(const Polar* p);
TEST(test_basic) {
 Polar p;
                            Finally, run tests to check if
  Polar_init(&p, 5, 45);
                            the implementation works.
  ASSERT_EQUAL(Polar_radius(&p), 5); // OK
 ASSERT_EQUAL(Polar_angle(&p), 45); // OK
```

struct Polar {

double r;

```
double phi;
                               (4,210^{\circ})
// INVARIANTS
                        Wait! Not done yet!
// 0 <= radius
// 0 <= angle < 360
TEST(test_invariants) {
  Polar p;
  Polar_init(&p, -5, 225);
  ASSERT_EQUAL(Polar_radius(&p), 5);
  ASSERT_EQUAL(Polar_angle(&p), 45);
  Polar_init(&p, 5, 405);
  ASSERT_EQUAL(Polar_radius(&p), 5);
  ASSERT_EQUAL(Polar_angle(&p), 45);
```

```
(3, 60^{\circ})
```

What didn't we think of?

```
If you "discover" a
   new bug or
  something you
haven't accounted
for, FIRST write new
   test cases to
   check for it!
```

p->phi = p->phi + 180;

p->phi = angle;

if (radius < 0) {

```
(3, 60^{\circ})
0 \quad 1 \quad L
(4, 210^{\circ})
```

```
Then, modify your implementation with the goal of passing all the tests (including the new ones).
```

```
struct Polar {
  double r;
  double phi;
};
// INVARIANTS
// 0 <= radius
// 0 <= angle < 360
                           Finally, run tests to check if
                          the implementation works.
int test_invariants() {
  Polar p;
  Polar_init(&p, -5, 225);
  ASSERT_EQUAL(Polar_radius(&p), 5); // OK
  ASSERT_EQUAL(Polar_angle(&p), 45); // FAIL
  Polar_init(&p, 5, 405);
  ASSERT_EQUAL(Polar_radius(&p), 5);
  ASSERT_EQUAL(Polar_angle(&p), 45);
```

```
struct Polar {
  double r;
  double phi;
};
void Polar_init(Polar* p, double radius,
                 double angle) {
  p->r = abs(radius);
  p->phi = angle;
  if (radius < 0) {</pre>
    p->phi = fmod(p->phi + 180, 360);
                        Oops. We forgot to mod by
                      360. Our tests caught this bug!
```

```
struct Polar {
 double r;
 double phi;
// INVARIANTS
// 0 <= radius
// 0 <= angle < 360
                       Finally, run tests to check if
Polar p;
 Polar_init(&p, -5, 225);
 ASSERT_EQUAL(Polar_radius(&p), 5); // OK
 ASSERT_EQUAL(Polar_angle(&p), 45); // OK
                                 Another bug! Back to
 Polar_init(&p, 5, 405);
 ASSERT_EQUAL(Polar_radius(&p), 5) implementing again...
 ASSERT_EQUAL(Polar_angle(&p), 45); // FAIL
```

"Guard against Murphy, not Machiavelli!1

 Do: Try to write test cases to catch bugs that people would realistically make.

"Tricky because it's all border. Could expose a bug."

 Don't: Try to write test cases to catch bugs introduced by a devious coder.

ASSERT_EQUAL(*Matrix_at(
$$\begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{bmatrix}$$
, 42, 42), 1)

"Tricky because maybe the element at (42, 42) secretly doesn't work."

Thorough testing with "small" test cases is sufficient to find most bugs within a system.

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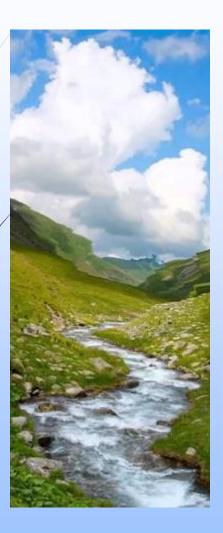
The Small Scope Hypothesis

Think about what makes two test cases meaningfully different for the function's behavior.

- Beyond a small size, just making test cases bigger doesn't make them meaningfully different.
- Testing with a 4x4 Matrix is just as good as a 5x5 Matrix

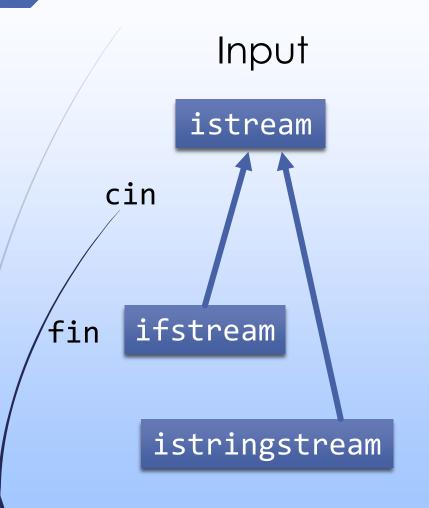
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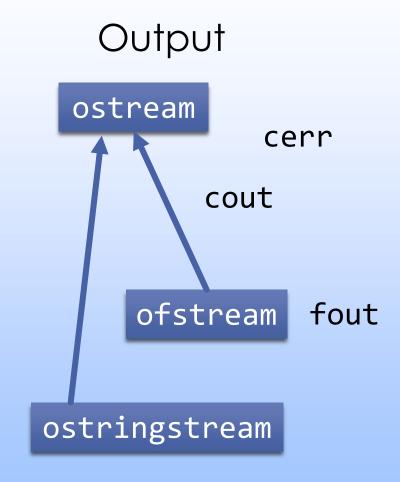
C++ Streams



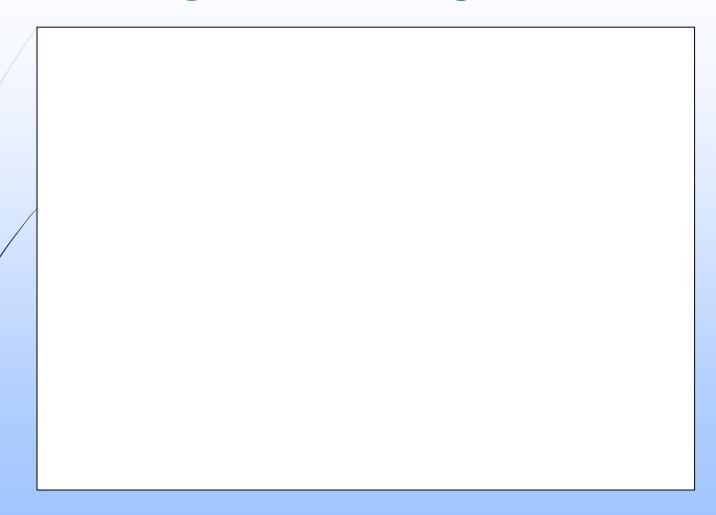
- A stream acts as an abstraction over...
 - A source from which we can read data as input.
 - A sink to which we can write data as output.
 - Support character-based I/O from the terminal, files, etc.
- We've already been using a variety of streams:
 - cout, cin, file I/O, etc.

Different Kinds of Streams





stringstreams: Big Idea



Stringstreams and Testing

- istringstream
 - An input stream that uses a string as its source.
 - Useful for simulating stream input from a "hardcoded" string.

```
TEST(test_image_basic) {
 // A hardcoded PPM image
 string input = "P3\n2 2\n255\n255 0 0 0 255 0 \n";
 input += "0 0 255 255 255 \n";
 // Use istringstream for simulated input
 istringstream ss input(input);
                                          Can pass an
 Image *img = new Image;
                                      istringstream where
 Image init(img, ss input);
                                    an istream is expected.
 ASSERT_EQUAL(Image_width(img), 2);
 Pixel red = { 255, 0, 0 };
 ASSERT_TRUE(Pixel_equal(Image_get_pixel(img, 0, 0), red));
 delete img;
```

Stringstreams and Testing

- ostringstream
 - An output stream that writes into a string.
 - Useful for capturing output as a string that can be checked for correctness.

```
TEST(test_matrix_basic) {
 Matrix *mat = new Matrix;
 Matrix_init(mat, 3, 3);
 Matrix_fill(mat, 0);
 Matrix_fill_border(mat, 1);
 // Hardcoded correct output
 string output_correct = "3 3\n1 1 1 \n1 0 1 \n1 1 1 \n";
                                            Can pass an
 // Capture output in ostringstream
                                       ostringstream where
 ostringstream ss_output;
                                      an ostream is expected.
 Matrix_print(mat, ss_output);
 ASSERT_EQUAL(ss_output.str(), output_correct);
 delete mat;
```

Stream Output (Reference)

- To write output into a stream, use the insertion operator (<<).</p>
- The behavior is specific to the type of value inserted into the stream.

```
char c;
cout << c;
string s;
cout << s;

double d;
cout << d;

char *cstr;
cout << cstr;</pre>
```

Writes a single character into the stream.

Writes the characters from the string into the stream.

Writes the double value formatted in floating point notation.

Assumes it's pointing to a cstring. Prints out characters until '\0' is found.

Stream Input (Reference)

- To read input from a stream, use the extraction operator (>>).
- The behavior is specific to the type of object you are extracting into.

```
char c;
cin >> c;

string s;
cin >> s;

int i;
cin >> i;

double d;
cin >> d;
```

Reads in a single character.

Reads in one "word", delimited by whitespace.

Attempts to parse the next characters from the stream as an integer value.

Attempts to parse the next characters from the stream as a floating point value.

How do << and >> work? (Reference)

- The << and >> operators are binary operators.
 - LHS is a stream object.
 - For <<, the RHS is a value to insert into the stream.</p>
 - For >>, the RHS is an object to store the value extracted out of the stream.
- The << and >> operators have two parts:
 - Side effect: Reading/Writing
 - Evaluation: Turns back into the stream on the LHS.
 - This allows chaining of several read/write operations.