EECS 482: Introduction to Operating Systems

Lecture 5: Monitors

Prof. Ryan Huang

Administration

Project 1 due this Wednesday

Reminder: honor code

- You may use online resources including ChatGPT, Copilot only for general programming help
- You may NOT use them for help specific to EECS 482 projects

Monitors

Two mechanisms: one for each type of synchronization

- Locks for mutual exclusion
- Condition variables for ordering constraints

A monitor = a lock + the condition variables associated with that lock

Mesa vs. Hoare monitors

Mesa

```
while (!condition)
  wait(cond_var);
```

- When waiter is woken, the condition might have changed
 - another thread got the lock first
- So it must re-check the condition it was waiting for

Hoare

```
if (!condition)
  wait(cond_var);
```

- Special priority to the wokenup waiter
- Signal thread immediately gives up lock
 - reacquires lock after waiter unlocks

We (and most/all Oses) use Mesa monitors

- Waiter is solely responsible for ensuring condition is met
- Always use while(...) {wait}

Monitor programming: overall design

Step 1: Think about each thread independently

- Each thread should try to make as much forward progress as possible (be greedy)
- A thread should wait only when it is unable to proceed

Step 2: List the shared data needed for the problem (e.g., w, x, y, z)

Monitor programming: mutex

Step 2: List the shared data needed for the problem (e.g., w, x, y, z)

- lock...unlock around accesses to shared data
- Coarse-grained versus fine-grained locking

lock A lock B

Monitor programming: ordering

Step 4: List before-after conditions and assign condition variables to each condition

When is a thread unable to make progress?

Use one condition variable for each before-after condition

 Condition variable belongs to the lock that protects the shared data that is used to evaluate the condition

Waiting thread uses while (condition) {cv.wait}

Signaling thread calls signal or broadcast when it changes state that may allow another thread to proceed

Typical monitor code

```
lock
// wait if needed
while (condition) {
    wait
do stuff
signal or broadcast about the stuff you did
unlock
```

Producer-consumer (bounded buffer)

Producers fill a shared buffer; consumers empty it

Need to synchronize actions of producers and consumers



Why use a shared buffer?

- Allows producers and consumers to operate somewhat independently (more concurrency)

Used in many situations

- Unix pipes (grep "keyword" foo.txt | wc -l)
- Project 1

Problem definition

- Coke machine can hold at most MAX cokes
- Delivery person (producer) adds one coke to machine
- Consumer buys one coke

Step 1: Think about threads independently

- Delivery threads add cokes, consumer threads remove cokes

Step 2: Identify shared state

- State of coke machine: int numCokes

Step 3: Assign locks

- One lock (mutex cokeLock) to protect all shared data

Step 4: List before-after conditions and assign a condition variable to each condition

- Consumers wait while there are no cokes (numCokes == 0)
 - cv waitingConsumers
- Delivery persons wait while the cokes are full (numCokes== MAX)
 - cv waitingProducers

Consumer() Producer() // add coke to machine // take coke out of machine

```
int numCokes
mutex cokeLock
cv waitingConsumers, waitingProducers
```

```
Consumer()
cokeLock.lock()
while (numCokes == 0) {
    waitingConsumers.wait(cokeLock)
// take coke out of machine
numCokes--
waitingProducers.signal()
cokeLock.unlock()
```

```
Producer()
cokeLock.lock()
while (numCokes == MAX) {
    waitingProducers.wait(cokeLock)
// add coke to machine
numCokes++
waitingConsumers.signal()
cokeLock.unlock()
```

Reducing number of signals?

```
int numCokes
mutex cokeLock
cv waitingConsumers, waitingProducers
```

```
Consumer()
cokeLock.lock()
while (numCokes == 0) {
    waitingConsumers.wait(cokeLock)
// take coke out of machine
numCokes--
waitingProducers.signal()
cokeLock.unlock()
```

```
Producer()
cokeLock.lock()
while (numCokes == MAX) {
    waitingProducers.wait(cokeLock)
// add coke to machine
numCokes++
if (numCokes == 1)
    waitingConsumers.signal()
cokeLock.unlock()
```

Would this still work?

Reducing number of signals

numCokes = 0

C1 and C2 waiting on waitingConsumers

P1 increments numCokes to 1 and signals

P2 increments numCokes to 2, but does not signal

Only one of C1 and C2 wakes up!

Reducing condition variables?

```
int numCokes
mutex cokeLock
cv waiting
```

```
Consumer()
cokeLock.lock()
while (numCokes == 0) {
    waiting.wait(cokeLock)
// take coke out of machine
numCokes--
waiting.signal()
cokeLock.unlock()
```

```
Producer()
cokeLock.lock()
while (numCokes == MAX) {
    waiting.wait(cokeLock)
// add coke to machine
numCokes++
waiting.signal()
cokeLock.unlock()
```

16

Would this still work?

Reducing condition variables

Say MAX = 1, and numCokes = 0

C1 and C2 wait

P1 increments numCokes to 1 and signals

- Wakes up C1

P2 waits because numCokes = MAX

C1 decrements numCokes to 0 and signals

- May wake up C2!

Why is this bad?

Reader-writer locks

Example: multiple threads would like to read or write Wolverine Access course catalog

Threads need to acquire lock to read or write shared data

Student:

lock()
browse course catalog
unlock()

Administrator:

lock()
change course catalog
unlock()

Any concern with this code?

How to safely allow more concurrency?

How to safely allow more concurrency?

Idea: threads disclose whether they intend to read or write the shared data through separate read/write lock methods

Student:

```
browse course catalog
aniock() readerUnlock()
```

Administrator:

```
change course catalog

unlock() writerUnlock()
```

Allow multiple concurrent readers, if no threads are writing data

Allow a single writer, if no other threads are reading or writing

Another level of abstraction

Applications

Operating System

Hardware

Even higher-level synchronization operations (readerLock, readerUnlock, writerLock, writerUnlock)

Higher-level synchronization operations (lock, monitor, semaphore)

Atomic operations (load/store, interrupt enable/disable, test&set)

Step 1: Think about threads independently

Step 2: Identify shared state (to implement reader-writer lock methods)

- numReaders, numWriters

Step 3: Assign locks to shared state:

- mutex rwLock

Step 4: List the before-after conditions and assign a condition variable for each condition:

- readerLock waits while numWriters>0
 - cv waitingReaders
- writerLock waits while numReaders>0 || numWriters>0
 - cv waitingWriters

```
int numReaders, numWriters
mutex rwLock
cv waitingReaders, waitingWriters
```

```
writerLock() {
}
```

```
readerUnlock() {
}
```

```
writerUnlock() {
}
```

```
int numReaders, numWriters
mutex rwLock
cv waitingReaders, waitingWriters
```

```
readerLock () {
    rwLock.lock()
    while (numWriters>0) {
        waitingReaders.wait(rwlock)
    }
    numReaders++
    rwLock.unlock()
}
```

```
writerLock() {
    rwLock.lock()
    while (numReaders>0 || numWriters>0) {
        waitingWriters.wait(rwLock)
    }
    numWriters++
    rwLock.unlock()
}
```

```
readerUnlock() {
    rwLock.lock()
    numReaders--
    waitingWriters.signal()
    rwLock.unlock()
}
```

```
writerUnlock() {
    rwLock.lock()
    numWriters--
    waitingReaders.broadcast()
    waitingWriters.signal()
    rwLock.unlock()
}
```

What will happen if a writer finishes and there are several waiting readers and writers?

How long will a writer wait?

How to give priority to a waiting writer?