# Building a CNN to classify images in the CIFAR-10 Dataset

We will work with the CIFAR-10 Dataset. This is a well-known dataset for image classification, which consists of 60000 32x32 color images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images.

The 10 classes are:

- 0. airplane
- 1. automobile
- 2. bird
- 3. cat
- 4. deer
- 5. dog
- 6. frog
- 7. horse
- 8. ship
- 9. truck

For details about CIFAR-10 see: <a href="https://www.cs.toronto.edu/~kriz/cifar.html">https://www.cs.toronto.edu/~kriz/cifar.html</a>)

For a compilation of published performance results on CIFAR 10, see: <a href="http://rodrigob.github.io/are">http://rodrigob.github.io/are</a> we there yet/build/classification datasets results.html (http://rodrigob.github.io/are we there yet/build/classification datasets results.html)

## **Building Convolutional Neural Nets**

In this exercise we will build and train our first convolutional neural networks. In the first part, we walk through the different layers and how they are configured. In the second part, you will build your own model, train it, and compare the performance.

```
In [3]: from __future__ import print_function
    import keras
    from keras.datasets import cifar10
    from keras.preprocessing.image import ImageDataGenerator
    from keras.models import Sequential
    from keras.layers import Dense, Dropout, Activation, Flatten
    from keras.layers import Conv2D, MaxPooling2D

import matplotlib.pyplot as plt
%matplotlib inline
```

Using TensorFlow backend.

```
In [4]: # The data, shuffled and split between train and test sets:
        (x train, y train), (x test, y test) = cifar10.load data()
        print('x_train shape:', x_train.shape)
        print(x_train.shape[0], 'train samples')
        print(x_test.shape[0], 'test samples')
        x_train shape: (50000, 32, 32, 3)
        50000 train samples
        10000 test samples
In [5]: ## Each image is a 32 x 32 x 3 numpy array
        x train[444].shape
Out[5]: (32, 32, 3)
In [6]: ## Let's look at one of the images
        print(y_train[444])
        plt.imshow(x train[444]);
        [9]
          0
          5
         10
         15
         20
         25
         30
                       15
                   10
                            20
In [7]: | num classes = 10
        y train = keras.utils.to categorical(y train, num classes)
        y test = keras.utils.to categorical(y test, num classes)
In [8]: # now instead of classes described by an integer between 0-9 we have a v
        ector with a 1 in the (Pythonic) 9th position
        y train[444]
Out[8]: array([0., 0., 0., 0., 0., 0., 0., 0., 1.], dtype=float32)
In [9]: # As before, let's make everything float and scale
        x train = x train.astype('float32')
        x test = x test.astype('float32')
        x train /= 255
        x test /= 255
```

# **Keras Layers for CNNs**

- Previously we built Neural Networks using primarily the Dense, Activation and Dropout Layers.
- Here we will describe how to use some of the CNN-specific layers provided by Keras

#### Conv2D

```
keras.layers.convolutional.Conv2D(filters, kernel_size, strides=(1, 1), padd
ing='valid', data_format=None, dilation_rate=(1, 1), activation=None, use_bi
as=True, kernel_initializer='glorot_uniform', bias_initializer='zeros', kern
el_regularizer=None, bias_regularizer=None, activity_regularizer=None, kerne
l_constraint=None, bias_constraint=None, **kwargs)
```

A few parameters explained:

- filters: the number of filter used per location. In other words, the depth of the output.
- kernel size: an (x,y) tuple giving the height and width of the kernel to be used
- strides: an (x,y) tuple giving the stride in each dimension. Default is (1,1)
- input shape: required only for the first layer

Note, the size of the output will be determined by the kernel size, strides

### MaxPooling2D

keras.layers.pooling.MaxPooling2D(pool\_size=(2, 2), strides=None, padding='valid',
data format=None)

- pool size: the (x,y) size of the grid to be pooled.
- strides: Assumed to be the pool size unless otherwise specified

#### **Flatten**

Turns its input into a one-dimensional vector (per instance). Usually used when transitioning between convolutional layers and fully connected layers.

### **First CNN**

Below we will build our first CNN. For demonstration purposes (so that it will train quickly) it is not very deep and has relatively few parameters. We use strides of 2 in the first two convolutional layers which quickly reduces the dimensions of the output. After a MaxPooling layer, we flatten, and then have a single fully connected layer before our final classification layer.

```
In [10]: # Let's build a CNN using Keras' Sequential capabilities
         model_1 = Sequential()
         ## 5x5 convolution with 2x2 stride and 32 filters
         model_1.add(Conv2D(32, (5, 5), strides = (2,2), padding='same',
                           input shape=x train.shape[1:]))
         model_1.add(Activation('relu'))
         ## Another 5x5 convolution with 2x2 stride and 32 filters
         model_1.add(Conv2D(32, (5, 5), strides = (2,2)))
         model_1.add(Activation('relu'))
         ## 2x2 max pooling reduces to 3 \times 3 \times 32
         model_1.add(MaxPooling2D(pool_size=(2, 2)))
         model 1.add(Dropout(0.25))
         ## Flatten turns 3x3x32 into 288x1
         model 1.add(Flatten())
         model 1.add(Dense(512))
         model_1.add(Activation('relu'))
         model_1.add(Dropout(0.5))
         model 1.add(Dense(num classes))
         model_1.add(Activation('softmax'))
         model 1.summary()
```

WARNING:tensorflow:From /anaconda3/envs/cecs551/lib/python3.6/site-pack ages/tensorflow/python/framework/op\_def\_library.py:263: colocate\_with (from tensorflow.python.framework.ops) is deprecated and will be remove d in a future version.

Instructions for updating:

Colocations handled automatically by placer.

WARNING:tensorflow:From /anaconda3/envs/cecs551/lib/python3.6/site-pack ages/keras/backend/tensorflow\_backend.py:3445: calling dropout (from tensorflow.python.ops.nn\_ops) with keep\_prob is deprecated and will be removed in a future version.

Instructions for updating:

Please use `rate` instead of `keep\_prob`. Rate should be set to `rate = 1 - keep\_prob`.

Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	16, 16, 32)	2432
activation_1 (Activation)	(None,	16, 16, 32)	0
conv2d_2 (Conv2D)	(None,	6, 6, 32)	25632
activation_2 (Activation)	(None,	6, 6, 32)	0
<pre>max_pooling2d_1 (MaxPooling2</pre>	(None,	3, 3, 32)	0
dropout_1 (Dropout)	(None,	3, 3, 32)	0
flatten_1 (Flatten)	(None,	288)	0
dense_1 (Dense)	(None,	512)	147968
activation_3 (Activation)	(None,	512)	0
dropout_2 (Dropout)	(None,	512)	0
dense_2 (Dense)	(None,	10)	5130
activation_4 (Activation)	(None,	10)	0

Total params: 181,162 Trainable params: 181,162 Non-trainable params: 0

We still have 181K parameters, even though this is a "small" model.

```
WARNING:tensorflow:From /anaconda3/envs/cecs551/lib/python3.6/site-pack
ages/tensorflow/python/ops/math ops.py:3066: to int32 (from tensorflow.
python.ops.math ops) is deprecated and will be removed in a future vers
ion.
Instructions for updating:
Use tf.cast instead.
Train on 50000 samples, validate on 10000 samples
Epoch 1/15
1.7198 - acc: 0.3726 - val loss: 1.4148 - val acc: 0.4861
Epoch 2/15
1.4487 - acc: 0.4801 - val loss: 1.2905 - val acc: 0.5304
1.3352 - acc: 0.5206 - val_loss: 1.2465 - val_acc: 0.5463
Epoch 4/15
1.2671 - acc: 0.5476 - val_loss: 1.1455 - val_acc: 0.5948
Epoch 5/15
1.2177 - acc: 0.5674 - val_loss: 1.1780 - val_acc: 0.5817
Epoch 6/15
50000/50000 [==============] - 21s 423us/step - loss:
1.1856 - acc: 0.5804 - val_loss: 1.4959 - val_acc: 0.5037
Epoch 7/15
1.1474 - acc: 0.5967 - val loss: 1.0747 - val acc: 0.6270
Epoch 8/15
1.1278 - acc: 0.6024 - val loss: 1.0719 - val acc: 0.6252
1.1095 - acc: 0.6123 - val loss: 1.1115 - val acc: 0.6179
Epoch 10/15
1.0993 - acc: 0.6163 - val loss: 1.0177 - val acc: 0.6425
Epoch 11/15
1.0831 - acc: 0.6243 - val loss: 1.1835 - val acc: 0.5964
Epoch 12/15
1.0734 - acc: 0.6291 - val_loss: 1.0251 - val_acc: 0.6429
Epoch 13/15
1.0679 - acc: 0.6290 - val loss: 1.0583 - val acc: 0.6290
Epoch 14/15
1.0672 - acc: 0.6315 - val loss: 1.0903 - val acc: 0.6276
Epoch 15/15
1.0672 - acc: 0.6344 - val loss: 1.0234 - val acc: 0.6450
```

Out[11]: <keras.callbacks.History at 0xb35e2de48>

#### **Exercise**

Our previous model had the structure:

Conv -> Conv -> MaxPool -> (Flatten) -> Dense -> Final Classification

(with appropriate activation functions and dropouts)

- 1. Build a more complicated model with the following pattern: Conv -> Conv -> MaxPool -> Conv -> Conv -> Conv -> MaxPool -> (Flatten) -> Dense -> Final Classification (Use strides of 1 for all convolutional layers.)
- 1. How many parameters does your model have? How does that compare to the previous model?
- 1. Train it for 5 epochs. What do you notice about the training time, loss and accuracy numbers (on both the training and validation sets)?

```
In [16]: # Please provide your solution here
         # Create model 2 as mentioned in the exercise
         model_2 = Sequential()
         ## Conv -> Conv -> MaxPool -> Conv -> Conv -> MaxPool -> (Flatten) -> De
         nse -> Final Classification
         model 2.add(Conv2D(32, (5,5), strides = (1,1), padding='same', input_sha
         pe=x train.shape[1:]))
         model_2.add(Activation('relu'))
         model_2.add(Conv2D(32, (5,5), strides = (1,1)))
         model 2.add(Activation('relu'))
         model 2.add(MaxPooling2D(pool_size=(2, 2)))
         model 2.add(Dropout(0.5))
         model_2.add(Conv2D(32, (3,3), strides = (1,1)))
         model_2.add(Activation('relu'))
         model_2.add(Conv2D(16, (3,3), strides = (1,1)))
         model_2.add(Activation('relu'))
         model_2.add(MaxPooling2D(pool_size=(2, 2)))
         model_2.add(Dropout(0.5))
         ## Flatten turns 3x3x32 into 288x1
         model 2.add(Flatten())
         model_2.add(Dense(512))
         model 2.add(Activation('relu'))
         model 2.add(Dropout(0.5))
         model 2.add(Dense(num classes))
         model 2.add(Activation('softmax'))
         model 2.summary()
```

Layer (type)	Output	Shape	Param #
conv2d_11 (Conv2D)	(None,	32, 32, 32)	2432
activation_17 (Activation)	(None,	32, 32, 32)	0
conv2d_12 (Conv2D)	(None,	28, 28, 32)	25632
activation_18 (Activation)	(None,	28, 28, 32)	0
max_pooling2d_6 (MaxPooling2	(None,	14, 14, 32)	0
dropout_9 (Dropout)	(None,	14, 14, 32)	0
conv2d_13 (Conv2D)	(None,	12, 12, 32)	9248
activation_19 (Activation)	(None,	12, 12, 32)	0
conv2d_14 (Conv2D)	(None,	10, 10, 16)	4624
activation_20 (Activation)	(None,	10, 10, 16)	0
max_pooling2d_7 (MaxPooling2	(None,	5, 5, 16)	0
dropout_10 (Dropout)	(None,	5, 5, 16)	0
flatten_4 (Flatten)	(None,	400)	0
dense_7 (Dense)	(None,	512)	205312
activation_21 (Activation)	(None,	512)	0
dropout_11 (Dropout)	(None,	512)	0
dense_8 (Dense)	(None,	10)	5130
activation_22 (Activation)	(None,	10)	0

Total params: 252,378 Trainable params: 252,378 Non-trainable params: 0

```
Train on 50000 samples, validate on 10000 samples
     Epoch 1/5
     0253 - acc: 0.2327 - val loss: 1.7483 - val acc: 0.3580
     Epoch 2/5
     7265 - acc: 0.3528 - val_loss: 1.6286 - val_acc: 0.4019
     Epoch 3/5
     6110 - acc: 0.4030 - val loss: 1.5099 - val acc: 0.4497
     Epoch 4/5
     5437 - acc: 0.4320 - val loss: 1.4623 - val acc: 0.4670
     Epoch 5/5
     50000/50000 [============== ] - 198s 4ms/step - loss: 1.
     4848 - acc: 0.4530 - val loss: 1.3440 - val acc: 0.5064
Out[17]: <keras.callbacks.History at 0xb323b8e10>
```

## My answers:

The new model has 252,378 parameters, as compared to the 181,162 parameters in the previous model.

Also, after trying several combinations of the filters and convolutional layers, model\_2 yields an accuracy of **50.64%**. Also, the training as well as testing loss and accuracy show that both the models learn but simply adding more layers does not result in an increase in the accuracy, since with a deeper network, we would need more training time to coverge the model.