# 第2章: 贝叶斯决策理论

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# 统计模式识别方法

#### 生成模型

(Density-based, Bayes decision)

#### **Parametric**

- ✓ Gaussian
- ✓ Dirichlet
- ✓ Bayesian network
- ✓ Hidden Markov model

#### **Non-Parametric**

- ✓ Histogram density
- ✓ Parzen window
- √ K-nearest neighbor

#### Semi-Parametric

√ Gaussian mixture

#### 判别模型 (discriminant/decision function)

- Linear methods
- ✓ Neural network
- ✓ Logistic regression
- ✓ Decision tree
- ✓ Kernel (SVM)
- ✓ Boosting

a.k.a. Non-parametric

# 注意discriminative和 discriminant的区别!

Discriminative model/learning Discriminant function/analysis



### 提纲

- 问题表示
- 最小错误率决策: 2类的例子
- 最小风险决策
- 判别函数和决策面
- 高斯概率密度
- 高斯密度下的判别函数
- 分类错误率



# 导论:问题表示

- 类别:  $\omega_i$ , i = 1,...,c
- 特征矢量  $\mathbf{x} = [x_1, ..., x_d] \in \mathbb{R}^d$
- 先验概率  $P(\omega_i)$   $\sum_{i=1}^{c} P(\omega_i) = 1$
- 概率密度函数(条件概率)  $p(\mathbf{x} \mid \omega_i)$
- 后验概率

$$P(\omega_i \mid \mathbf{x}) = \frac{p(\mathbf{x} \mid \omega_i)P(\omega_i)}{p(\mathbf{x})} = \frac{p(\mathbf{x} \mid \omega_i)P(\omega_i)}{\sum_{j=1}^{c} p(\mathbf{x} \mid \omega_j)P(\omega_j)}$$
$$\sum_{j=1}^{c} P(\omega_i \mid \mathbf{x}) = 1$$

### 最小错误率决策: 2类的例子

- Salmon ( $\omega_1$ ) and sea bass ( $\omega_2$ )
- If we have only prior probability
  - 例如,教室门口判断进来的是男生还是女生,没有任何传感器
  - Decide  $\omega_1$  if  $P(\omega_1) > P(\omega_2)$ , otherwise  $\omega_2$
  - Minimum error decision

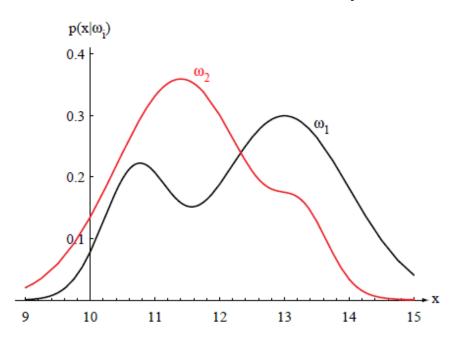
$$P(error) = \begin{cases} P(\omega_2) & \text{if we decide } \omega_1 \\ P(\omega_1) & \text{if we decide } \omega_2 \end{cases}$$

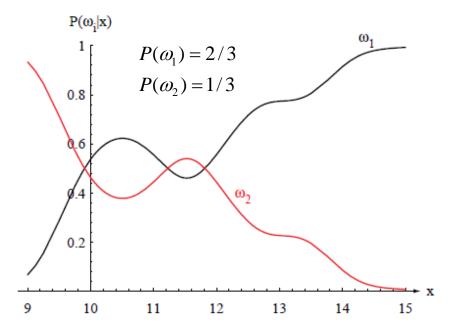
- 教室门口判断性别的例子: 错误率?



### 2类的例子

有传感器(特征)的情况
 Decision based on posterior probabilities





x轴:一维特征空间

$$P(\omega_i \mid \mathbf{x}) = \frac{p(\mathbf{x} \mid \omega_i)P(\omega_i)}{p(\mathbf{x})} = \frac{p(\mathbf{x} \mid \omega_i)P(\omega_i)}{\sum_{i=1}^{c} p(\mathbf{x} \mid \omega_i)P(\omega_i)}$$



#### Decision based on posterior probabilities

$$P(error|x) = \begin{cases} P(\omega_1|x) & \text{if we decide } \omega_2 \\ P(\omega_2|x) & \text{if we decide } \omega_1. \end{cases}$$

Decide  $\omega_1$  if  $P(\omega_1|x) > P(\omega_2|x)$ ; otherwise decide  $\omega_2$ 

$$P(error|x) = \min [P(\omega_1|x), P(\omega_2|x)].$$

Evidence (a.k.a. likelihood)

Decide  $\omega_1$  if  $p(x|\omega_1)P(\omega_1) > p(x|\omega_2)P(\omega_2)$ ; otherwise decide  $\omega_2$ 

- see 
$$P(\omega_i \mid \mathbf{x}) = \frac{p(\mathbf{x} \mid \omega_i)P(\omega_i)}{p(\mathbf{x})}$$

教室门口判断性别的例子:用什么传感器(x)?



#### 最小风险决策: 贝叶斯决策的一般形式

- 决策代价(loss)
  - True class  $\omega_j$ , decided as  $\alpha_i$   $\lambda_{ij} = \lambda(\alpha_i \mid \omega_j)$ 
    - 有时2类代价相差很大,比如医疗诊断的场合、工业检测、自 动商店判断性别
- Condition risk

$$R(\alpha_i|\mathbf{x}) = \sum_{j=1}^{c} \lambda(\alpha_i|\omega_j) P(\omega_j|\mathbf{x})$$

Overall (expected) risk

$$R = \int R(\alpha(\mathbf{x})|\mathbf{x})p(\mathbf{x}) \ d\mathbf{x}$$

Minimum risk decision (Bayes decision)

$$\arg\min_{i} R(\alpha_{i} \mid x)$$



- Minimum risk decision: 2-class case
  - Condition risk

$$R(\alpha_1|\mathbf{x}) = \lambda_{11}P(\omega_1|\mathbf{x}) + \lambda_{12}P(\omega_2|\mathbf{x})$$
  

$$R(\alpha_2|\mathbf{x}) = \lambda_{21}P(\omega_1|\mathbf{x}) + \lambda_{22}P(\omega_2|\mathbf{x})$$

Decision rule

$$R(\alpha_1 \mid x) < R(\alpha_2 \mid x) \leftrightarrow (\lambda_{21} - \lambda_{11})P(\omega_1 \mid x) > (\lambda_{12} - \lambda_{22})P(\omega_2 \mid x)$$

• Equivalently, decide  $\omega_1$  if

$$(\lambda_{21} - \lambda_{11})\underline{p(\mathbf{x}|\omega_1)P(\omega_1)} > (\lambda_{12} - \lambda_{22})p(\mathbf{x}|\omega_2)P(\omega_2)$$
$$\frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)} > \frac{\lambda_{12} - \lambda_{22}}{\lambda_{21} - \lambda_{11}}\frac{P(\omega_2)}{P(\omega_1)}$$

### 最小错误率分类

Zero-one loss

$$\lambda(\alpha_i | \omega_j) = \begin{cases} 0 & i = j \\ 1 & i \neq j \end{cases} i, j = 1, ..., c$$

$$R(\alpha_i | \mathbf{x}) = \sum_{j=1}^{c} \lambda(\alpha_i | \omega_j) P(\omega_j | \mathbf{x})$$

$$= \sum_{j \neq i} P(\omega_j | \mathbf{x})$$

$$= 1 - P(\omega_i | \mathbf{x})$$

Minimum error decision: Maximum a posteriori (MAP)

Decide 
$$\omega_i$$
 if  $P(\omega_i|\mathbf{x}) > P(\omega_i|\mathbf{x})$  for all  $j \neq i$ 



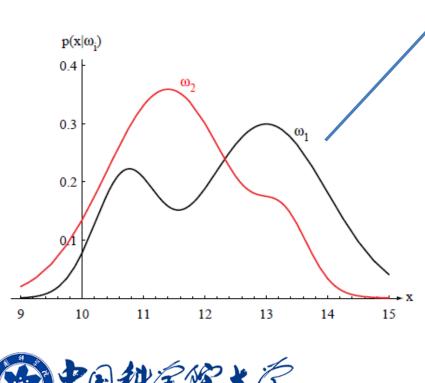
#### • 2-class case

#### – decide $\omega_1$ if

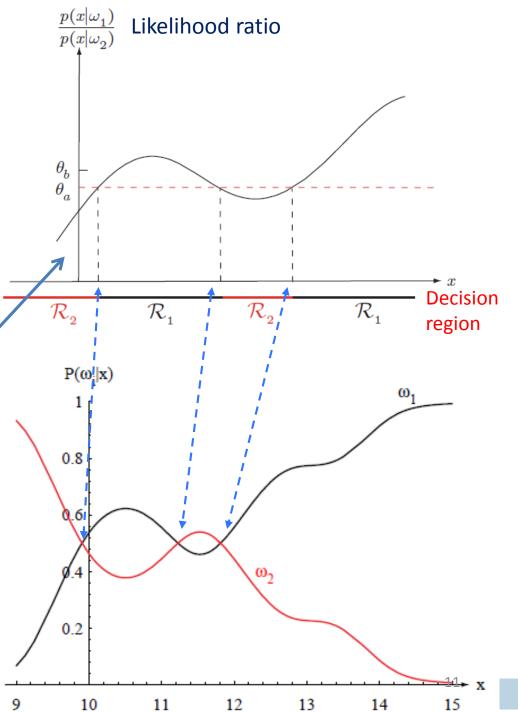
$$\frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)} > \frac{\lambda_{12} - \lambda_{22}}{\lambda_{21} - \lambda_{11}} \frac{P(\omega_2)}{P(\omega_1)}$$

0-1 loss

$$\frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)} > \frac{P(\omega_2)}{P(\omega_1)}$$



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# 带拒识的决策

- 为什么要拒识?
- Formulation (Problem 13, Chapter 2)

$$\textbf{-C+1 classes} \\ \lambda(\alpha_i \mid \omega_j) = \begin{cases} 0, & i = j \\ \lambda_s, & i \neq j \\ \lambda_r, & \text{reject} \end{cases}$$

$$R(\alpha_i|\mathbf{x}) = \sum_{j=1}^{c} \lambda(\alpha_i|\omega_j) P(\omega_j|\mathbf{x})$$

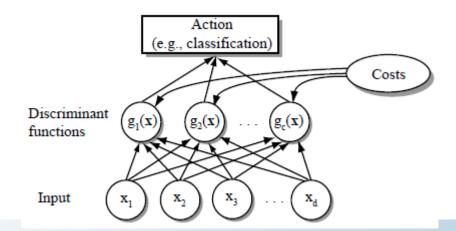
$$R_i(\mathbf{x}) = \begin{cases} \lambda_s [1 - P(\omega_i \mid \mathbf{x})], & i = 1, ..., c \\ \lambda_r, & \text{reject} \end{cases}$$

$$\arg\min_{i} R_{i}(\mathbf{x}) = \begin{cases} \arg\max_{i} P(\omega_{i} \mid \mathbf{x}), & \text{if } \max_{i} P(\omega_{i} \mid \mathbf{x}) > 1 - \lambda_{r} / \lambda_{s} \\ & \text{reject,} & \text{otherwise} \end{cases}$$



# 判别函数、决策面

- 判别函数(Discriminant Function)
  - 表征模式属于每一类的广义似然度 $g_i(\mathbf{x})$ , i=1,...,c
  - 分类决策  $\underset{i}{\operatorname{arg max}} g_{i}(\mathbf{x})$
  - E.g., conditional risk  $g_i(\mathbf{x}) = -R(\alpha_i \mid \mathbf{x})$
  - Posterior probability  $g_i(\mathbf{x}) = P(\omega_i \mid \mathbf{x})$
  - Likelihood  $g_i(\mathbf{x}) = p(\mathbf{x} \mid \omega_i) P(\omega_i)$  $g_i(\mathbf{x}) = \log p(\mathbf{x} \mid \omega_i) + \log P(\omega_i)$



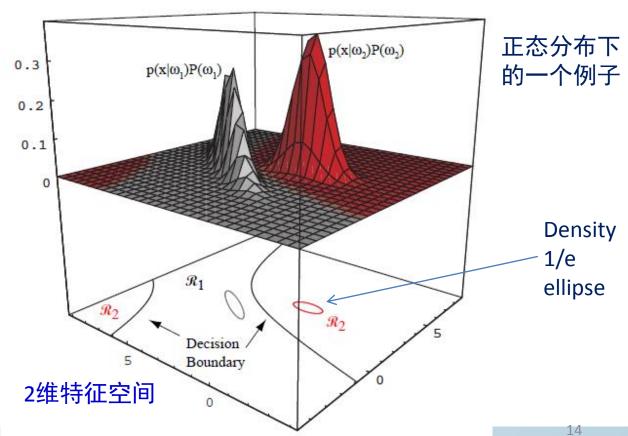
#### • 决策面(Decision surface)

#### - 特征空间中二类判别函数相等的点的集合

$$g(\mathbf{x}) \equiv g_1(\mathbf{x}) - g_2(\mathbf{x}) \qquad g(\mathbf{x}) = P(\omega_1|\mathbf{x}) - P(\omega_2|\mathbf{x}) = \mathbf{0}$$
$$g(\mathbf{x}) = \ln \frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)} + \ln \frac{P(\omega_1)}{P(\omega_2)}$$

有判别函数就可以分 类了,为什么还来求 决策面?

答:加深对特征空间和分类器性质的理解





# 贝叶斯决策用于模式分类

- Bayes决策的关键
  - 类条件概率密度估计
  - 先验概率: 从训练样本估计或假设等概率
  - 决策代价[ $\lambda_{ii}$ ],一般为0-1代价
- 分类器设计
  - 收集训练样本
  - 用每一类的样本估计类条件概率密度  $p(\mathbf{x} \mid \omega_i)$
  - 估计类先验概率
  - 模型参数集:  $\{p(\mathbf{x} | \omega_i, \theta_i), P(\omega_i)\}, i = 1,...,M$
- 分类过程
  - 计算测试样本属于每一类的后验概率
  - 最大后验概率/最小风险决策



### 概率密度估计方法

• 参数法: 假定概率密度函数形式

$$p(\mathbf{x} \mid \omega_i) = p(\mathbf{x} \mid \theta_i)$$

- Distribution: Gaussian, Gamma, Bernouli
- Estimation: maximum-likelihood (ML), Bayesian estimation
- 非参数法: 可以表示任意概率分布
  - Parzen window, k-NN
  - 需要保存所有或大部分样本
- Semi-parametric
  - Distribution: Gaussian mixture (GM)
  - Estimation: expectation-maximization (EM)



# 高斯密度函数

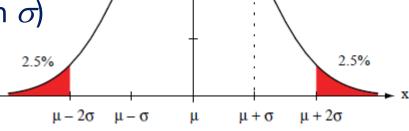
Gaussian density (normal distribution)

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right]$$

- Mean  $\mu$
- Variance  $\sigma^2$  (standard deviation  $\sigma$ )

$$\mu \equiv \mathcal{E}[x] = \int_{-\infty}^{\infty} x p(x) \ dx$$

$$\sigma^2 \equiv \mathcal{E}[(x-\mu)^2] = \int_{-\infty}^{\infty} (x-\mu)^2 p(x) \ dx$$



p(x)

$$H(p(x)) = -\int p(x) \ln p(x) dx$$

- 在给定均值和方差的所有分布中,正态分布的熵最大(Problem 20, Chapter 2)
- 根据Central Limit Theorem, 大量独立随机变量之和趋近正态分布
- 实际环境中,很多类别的特征分布趋近正态分布



• Multivariate normal density  $p(\mathbf{x}) \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ 

$$- 公式要牢记 p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\mathbf{\Sigma}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^t \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right]$$

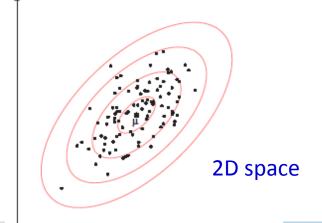
- $\mu \equiv \mathcal{E}[\mathbf{x}] = \int \mathbf{x} p(\mathbf{x}) \ d\mathbf{x} \qquad \mu_i = \mathcal{E}[x_i]$ Mean
- Covariance matrix

$$egin{align*} oldsymbol{\Sigma} \equiv \mathcal{E}[(\mathbf{x} - oldsymbol{\mu})(\mathbf{x} - oldsymbol{\mu})^t] = \int (\mathbf{x} - oldsymbol{\mu})(\mathbf{x} - oldsymbol{\mu})^t p(\mathbf{x}) \; d\mathbf{x} & egin{bmatrix} \sigma_{11} & \sigma_{12} & ... & \sigma_{1d} \ \sigma_{21} & \sigma_{22} & ... & \sigma_{2d} \ dots & dots & dots & dots & dots \ \end{array} \ & \vdots & dots & dots & dots \ & dots & dots & dots & dots \ \end{array} \ egin{bmatrix} \sigma_{11} & \sigma_{12} & ... & \sigma_{1d} \ \sigma_{21} & \sigma_{22} & ... & \sigma_{2d} \ dots & dots & dots & dots \ \end{array} \ & \vdots & dots & dots & dots \ \end{array} \ & \vdots & dots & dots \ \end{array} \ egin{bmatrix} \sigma_{11} & \sigma_{12} & ... & \sigma_{1d} \ \sigma_{21} & \sigma_{22} & ... & \sigma_{2d} \ dots & dots & dots \ \end{array} \ & \vdots & dots & dots \ \end{array} \ egin{bmatrix} \sigma_{11} & \sigma_{12} & ... & \sigma_{1d} \ \end{array} \ & \vdots & dots & dots \ \end{array} \ & \vdots & dots & dots & dots \ \end{array} \ egin{bmatrix} \sigma_{21} & \sigma_{22} & ... & \sigma_{2d} \ dots & dots \ \end{array} \ & \vdots & dots & dots \ \end{array} \ egin{bmatrix} \sigma_{d1} & \sigma_{d2} & ... & \sigma_{dd} \ \end{bmatrix}$$

If  $x_i$  and  $x_j$  are statistically independent,  $\sigma_{ij} = 0$ 

- 等密度点轨迹: hyperellipsoid
- Mahalanobis distance

$$r^2 = (\mathbf{x} - \boldsymbol{\mu})^t \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$$





#### **Break**



# 协方差矩阵的性质

- 实对称矩阵
- Eigenvalues & eigenvecters (本征值,本征向量)

$$\Sigma \phi_{i} = \lambda_{i} \phi_{i} \qquad \Phi = [\phi_{1} \phi_{2} \cdots \phi_{d}] \qquad \Lambda = diag[\lambda_{1}, \lambda_{2}, \cdots, \lambda_{d}]$$
Orthonormal
$$\Phi^{T} \Phi = I$$

$$\Phi^{T} = \Phi^{-1} \qquad \phi_{i}^{t} \phi_{j} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

$$\Sigma \Phi = \Phi \Lambda \iff \Sigma = \Phi \Lambda \Phi^{T} \iff \Sigma = \sum_{i=1}^{d} \lambda_{i} \phi_{i} \phi_{i}^{T}$$

• 矩阵对角化

$$\Phi^{T} \Sigma \Phi = \Lambda = \begin{vmatrix} \lambda_{1} & 0 & \dots & 0 \\ 0 & \lambda_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_{d} \end{vmatrix} \longleftrightarrow \phi_{i}^{T} \Sigma \phi_{i} = \lambda_{i}$$



- 应用: Principal component analysis (PCA)
  - 一种降维(特征提取)方法
  - 将随机矢量投影到低维子空间, 使子空间投影的重建误差最小
  - 选择本征值最大的m (m<d)个本征向量作为子空间的基(basis)

线性空间中正交变换( $\Phi^T\Phi = I$ ) 不影响欧氏距离

$$\sum_{j=1}^{d} [(\mathbf{x} - \mu)^{T} \phi_{j}]^{2} = ||\mathbf{x} - \mu||^{2}$$

子空间投影  $\mu + \sum_{j=1}^{m} [(\mathbf{x} - \mu)^T \phi_j] \phi_j$ 

投影重建误差

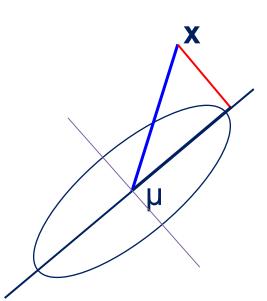
$$r_E = ||\mathbf{x} - \mu||^2 - \sum_{j=1}^m [(\mathbf{x} - \mu)^T \phi_j]^2 = \sum_{j=m+1}^d [(\mathbf{x} - \mu)^T \phi_j]^2$$

期望

$$\mathscr{E}(r_E) = \mathscr{E}\left\{\sum_{j=m+1}^d [(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\phi}_j]^2\right\} = \mathscr{E}\left\{\sum_{j=m+1}^d \boldsymbol{\phi}_j^T (\mathbf{x} - \boldsymbol{\mu}) (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\phi}_j\right\}$$

$$= \sum_{j=m+1}^{d} \boldsymbol{\phi}_{j}^{T} \mathcal{E}[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^{T}] \boldsymbol{\phi}_{j} = \sum_{j=m+1}^{d} \boldsymbol{\phi}_{j}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}_{j} = \sum_{j=m+1}^{d} \lambda_{j}$$





# 线性变换的高斯分布

- 线性变换  $y = A^t x$ 
  - A<sup>t</sup>A=1: 正交变换(坐标轴旋转)
  - 变换后的分布仍为正态分布

$$p(\mathbf{y}) \sim N(\mathbf{A}^t \boldsymbol{\mu}, \mathbf{A}^t \boldsymbol{\Sigma} \mathbf{A})$$

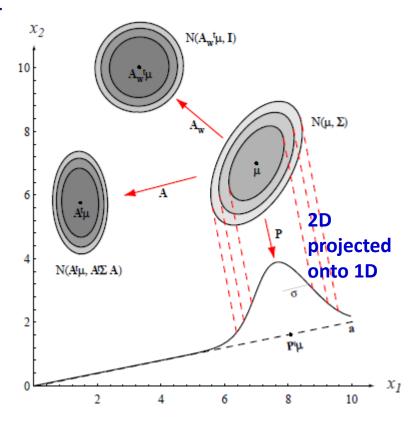
Diagonalization

$$A = \Phi$$

$$A^t \Sigma A = \Lambda$$

Whitening transform

$$\mathbf{A}_{w} = \mathbf{\Phi} \mathbf{\Lambda}^{-1/2}$$
 $A_{w}^{t} \Sigma A_{w} = \mathbf{\Lambda}^{-1/2} \mathbf{\Phi}^{t} \Sigma \mathbf{\Phi} \mathbf{\Lambda}^{-1/2}$ 
 $= \mathbf{\Lambda}^{-1/2} \mathbf{\Lambda} \mathbf{\Lambda}^{-1/2} = I$ 





# 相关知识:特征提取/降维

- Dimensionality reduction
- Feature extraction
  - Feature generation: original data d→x
  - Linear feature extraction  $\mathbf{x} = \mathbf{A}^T \mathbf{d}$
- Feature selection (for reduction and performance)
  - Feature subset selection: a learning/optimization problem
- Feature transform (for extraction or reduction)
  - Linear transform  $\mathbf{y} = \mathbf{A}^T \mathbf{x}$
  - Nonlinear transform: may increase dimensionality, e.g. kernel PCA, kernel LDA
- Handcrafted feature
- Feature learning
  - Automatic feature generation, e.g. convolutional neural network (CNN)



# 高斯密度下的判别函数

• 判别函数  $g_i(\mathbf{x}) = \ln p(\mathbf{x}|\omega_i) + \ln P(\omega_i)$ 

$$\begin{split} p(\mathbf{x} \mid \omega_i) &= \frac{1}{(2\pi)^{d/2} |\Sigma_i|^{1/2}} \exp\left[-\frac{1}{2} (\mathbf{x} - \mu_i) \Sigma_i^{-1} (\mathbf{x} - \mu_i)\right] \\ g_i(\mathbf{x}) &= -\frac{1}{2} (\mathbf{x} - \mu_i)^t \Sigma_i^{-1} (\mathbf{x} - \mu_i) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\Sigma_i| + \ln P(\omega_i) \end{split}$$

- Quadratic discriminant function (QDF)
- 在不同covariance假设条件下得到一些特殊形式

• Case 1:  $\Sigma_i = \sigma^2 I$  (去掉与类别无关项)

$$g_i(\mathbf{x}) = -\frac{\|\mathbf{x} - \boldsymbol{\mu}_i\|^2}{2\sigma^2} + \ln P(\omega_i)$$

- Euclidean distance  $\|\mathbf{x} \boldsymbol{\mu}_i\|^2 = (\mathbf{x} \boldsymbol{\mu}_i)^t (\mathbf{x} \boldsymbol{\mu}_i)$ 
  - Nearest mean/distance classifier
- 展开二次式  $(x \mu_i)^t (x \mu_i)$

$$g_i(\mathbf{x}) = -\frac{1}{2\sigma^2} [\mathbf{x}^t \mathbf{x} - 2\boldsymbol{\mu}_i^t \mathbf{x} + \boldsymbol{\mu}_i^t \boldsymbol{\mu}_i] + \ln P(\omega_i)$$

- 忽略与类别无关项,得到线性判别函数

$$g_i(\mathbf{x}) = \mathbf{w}_i^t \mathbf{x} + w_{i0}$$

$$\mathbf{w}_i = \frac{1}{\sigma^2} \mu_i \qquad w_{i0} = \frac{-1}{2\sigma^2} \mu_i^t \mu_i + \ln P(\omega_i)$$



- Case 1:  $\Sigma_i = \sigma^2 I$  (continued)
  - 二类决策面(判别函数相等的点构成)

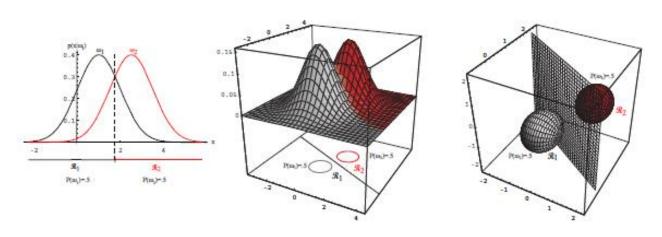
$$g_i(\mathbf{x}) = g_j(\mathbf{x})$$

$$\Longrightarrow \mathbf{w}^t(\mathbf{x} - \mathbf{x}_0) = 0 \qquad \mathbf{w} = \boldsymbol{\mu}_i - \boldsymbol{\mu}_j \qquad \qquad \mathbf{W}: 法向量 \\ \mathbf{v} = \mathbf{u}_1 - \boldsymbol{\mu}_2 = \mathbf{u}$$

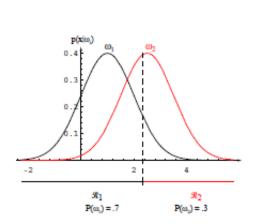
$$\mathbf{w} = \mathbf{u}_i - \boldsymbol{\mu}_j \qquad \qquad \mathbf{w} = \mathbf{u}_i - \boldsymbol{\mu}_j \qquad \qquad \mathbf{w} = \mathbf{u}_i - \boldsymbol{\mu}_j$$

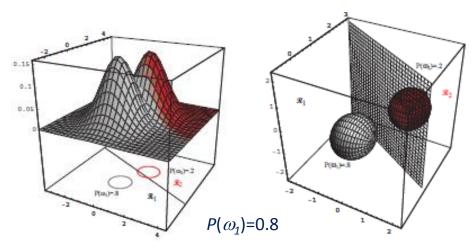
$$\mathbf{v} = \frac{1}{2}(\boldsymbol{\mu}_i + \boldsymbol{\mu}_j) - \frac{\sigma^2}{\|\boldsymbol{\mu}_i - \boldsymbol{\mu}_j\|^2} \ln \frac{P(\omega_i)}{P(\omega_j)} (\boldsymbol{\mu}_i - \boldsymbol{\mu}_j) \qquad \text{位置移向先验 }$$
概率小的类别

- 1D, 2D, 3D的情况
  - 当 $P(\omega_1)=P(\omega_2)$ , 决策面为二类均值的等分面

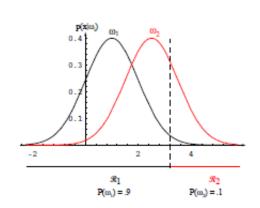


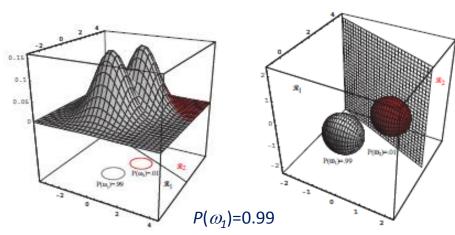
#### - 当先验概率变化,决策面发生平移





#### 移向概率 小的类别





• Case 2:  $\Sigma_i = \Sigma$ 

$$g_i(\mathbf{x}) = -\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_i)^t \boldsymbol{\Sigma}_i^{-1}(\mathbf{x} - \boldsymbol{\mu}_i) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\boldsymbol{\Sigma}_i| + \ln P(\omega_i)$$

$$g_i(\mathbf{x}) = -\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_i)^t \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu}_i) + \ln P(\omega_i)$$

- 展开二次式  $(x-\mu_i)^t \Sigma^{-1}(x-\mu_i)$ 

线性判别函数!  $g_i(\mathbf{x}) = \mathbf{w}_i^t \mathbf{x} + w_{i0}$ 

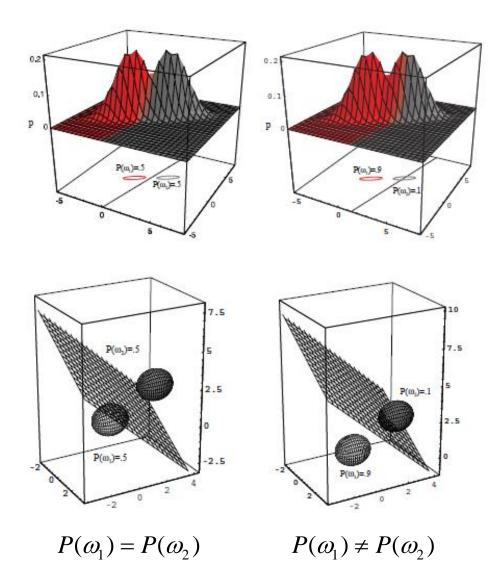
$$\mathbf{w}_i = \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_i \qquad w_{i0} = -\frac{1}{2} \boldsymbol{\mu}_i^t \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_i + \ln P(\omega_i)$$

- 二类决策面  $g_i(\mathbf{x}) = g_j(\mathbf{x})$ 

$$\mathbf{w}^{t}(\mathbf{x} - \mathbf{x}_{0}) = 0 \qquad \mathbf{w} = \mathbf{\Sigma}^{-1}(\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{j})$$
$$\mathbf{x}_{0} = \frac{1}{2}(\boldsymbol{\mu}_{i} + \boldsymbol{\mu}_{j}) - \frac{\ln\left[P(\boldsymbol{\omega}_{i})/P(\boldsymbol{\omega}_{j})\right]}{(\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{j})^{t}\mathbf{\Sigma}^{-1}(\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{j})}(\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{j})$$

- 注意跟μ₁-μ₂的关系,决策面不一定与之垂直
- 当 $P(\omega_1) = P(\omega_2)$  , 决策面经过 $(\mu_1 + \mu_2)/2$



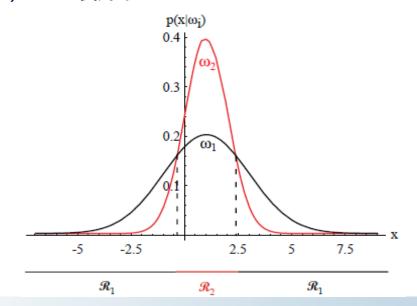




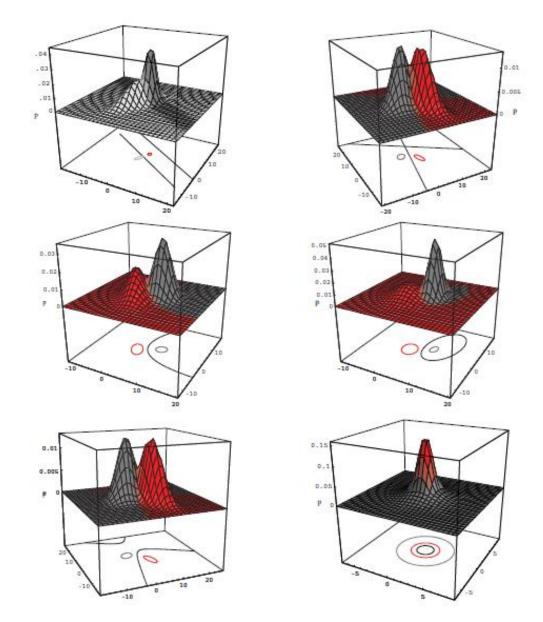
• Case 3:  $\Sigma_i$ = arbitrary

$$\begin{split} g_i(\mathbf{x}) &= -\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_i)^t \boldsymbol{\Sigma}_i^{-1}(\mathbf{x} - \boldsymbol{\mu}_i) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\boldsymbol{\Sigma}_i| + \ln P(\omega_i) \\ g_i(\mathbf{x}) &= \mathbf{x}^t \mathbf{W}_i \mathbf{x} + \mathbf{w}_i^t \mathbf{x} + w_{i0} \\ \mathbf{W}_i &= -\frac{1}{2} \boldsymbol{\Sigma}_i^{-1} \qquad \mathbf{w}_i = \boldsymbol{\Sigma}_i^{-1} \boldsymbol{\mu}_i \\ w_{i0} &= -\frac{1}{2} \boldsymbol{\mu}_i^t \boldsymbol{\Sigma}_i^{-1} \boldsymbol{\mu}_i - \frac{1}{2} \ln |\boldsymbol{\Sigma}_i| + \ln P(\omega_i) \end{split}$$

- 二类决策面:  $g_1(\mathbf{x})=g_2(\mathbf{x})$ , hyperquadratics
  - 等均值的情况下, 1D的例子

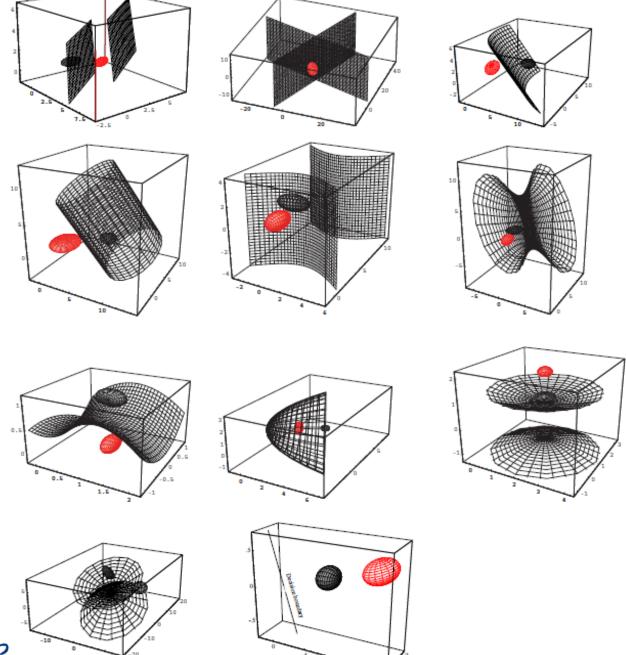


#### 2D的例子 (z轴是概率密度)

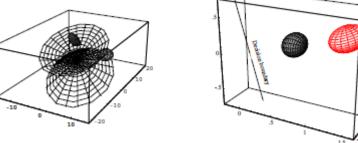




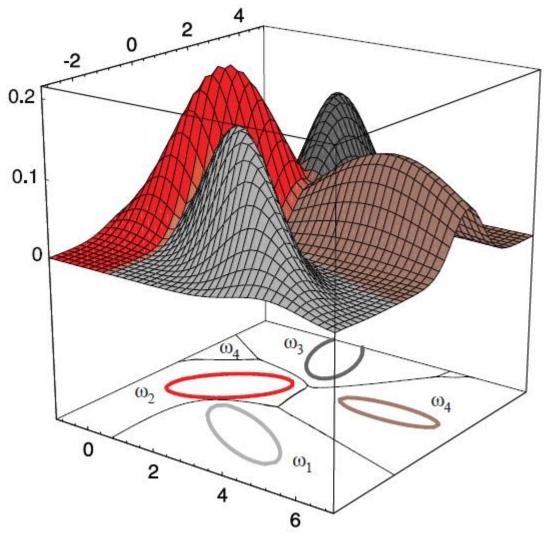
#### 3D的例子







#### 2D, 4类的例子





#### 一个具体例子

$$-2$$
类,2D  $P(\omega_1) = P(\omega_2) = 0.5$ 

$$\mu_1 = \begin{bmatrix} 3 \\ 6 \end{bmatrix}; \quad \Sigma_1 = \begin{pmatrix} 1/2 & 0 \\ 0 & 2 \end{pmatrix} \qquad \Sigma_1^{-1} = \begin{pmatrix} 2 & 0 \\ 0 & 1/2 \end{pmatrix}$$

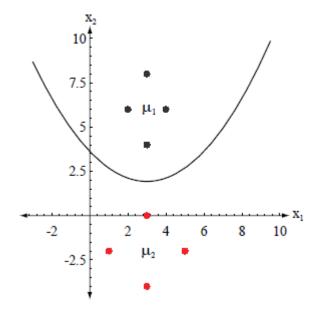
$$\mu_2 = \begin{bmatrix} 3 \\ -2 \end{bmatrix}; \quad \Sigma_2 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \qquad \Sigma_2^{-1} = \begin{pmatrix} 1/2 & 0 \\ 0 & 1/2 \end{pmatrix}$$

$$\Sigma_1^{-1} = \left( \begin{array}{cc} 2 & 0 \\ 0 & 1/2 \end{array} \right)$$

$$\Sigma_2^{-1} = \left( \begin{array}{cc} 1/2 & 0 \\ 0 & 1/2 \end{array} \right)$$

#### - 决策面 g<sub>1</sub>(x)=g<sub>2</sub>(x)

$$x_2 = 3.514 - 1.125x_1 + 0.1875x_1^2$$



# 分类错误率

#### • 2类的情况

$$P(error) = P(\mathbf{x} \in \mathcal{R}_2, \omega_1) + P(\mathbf{x} \in \mathcal{R}_1, \omega_2)$$

$$= P(\mathbf{x} \in \mathcal{R}_2 | \omega_1) P(\omega_1) + P(\mathbf{x} \in \mathcal{R}_1 | \omega_2) P(\omega_2)$$

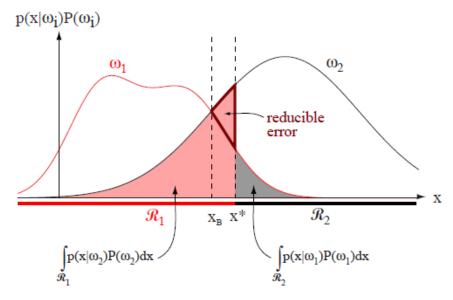
$$= \int_{\mathcal{R}_2} p(\mathbf{x} | \omega_1) P(\omega_1) d\mathbf{x} + \int_{\mathcal{R}_1} p(\mathbf{x} | \omega_2) P(\omega_2) d\mathbf{x}.$$

#### • 一般情况

$$P(correct) = \sum_{i=1}^{c} P(\mathbf{x} \in \mathcal{R}_{i}, \omega_{i})$$

$$= \sum_{i=1}^{c} P(\mathbf{x} \in \mathcal{R}_{i} | \omega_{i}) P(\omega_{i})$$

$$= \sum_{i=1}^{c} \int_{\mathcal{R}_{i}} p(\mathbf{x} | \omega_{i}) P(\omega_{i}) d\mathbf{x}$$



决策面为x<sub>B</sub>时为最小错误率分类

#### • 最大后验概率决策(0-1 loss)的情况

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$$P(correct) = \int_{\mathbf{x}} \max_{i} P(\mathbf{x} \mid \omega_{i}) P(\omega_{i}) d\mathbf{x}$$

$$= \int_{\mathbf{x}} \max_{i} P(\omega_{i} \mid \mathbf{x}) P(\mathbf{x}) d\mathbf{x}$$

$$P(error) = \int_{\mathbf{x}} \left[ 1 - \max_{i} P(\omega_{i} \mid \mathbf{x}) \right] P(\mathbf{x}) d\mathbf{x}$$

$$p(\omega_{i} \mid x)$$

$$p(x \mid \omega_{i})$$

$$p(x \mid \omega_{i})$$

$$1 - \max_{i} P(\omega_{i} \mid \mathbf{x})$$

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# 讨论

- 贝叶斯分类器(基于贝叶斯决策的分类器)是最优的吗?
  - 最小风险、最大后验概率决策
  - 最优的条件: 概率密度、风险能准确估计
  - 具体的参数法、非参数法是贝叶斯分类器的近似,实际中难以达到最优
  - 判别模型:回避了概率密度估计,以较小复杂度估计 后验概率或判别函数
  - 一什么方法能胜过贝叶斯分类器:在不同的特征空间才有可能!



### 下次课内容

- 第2章
  - 离散变量的贝叶斯决策
  - 复合模式分类
- 第3章
  - 最大似然参数估计
  - 贝叶斯估计

