

## Method parameters

Method . . . . . Calibrating the pH glass electrode  
Method saving date . . . . . 2019-08-01 11:09:34 UTC+3  
Method version . . . . . 15  
Method group . . . . . Main group  
Method status . . . . . original  
Method saved by (full name) . . . . .  
Method saved by (short name) . . . . . Admin

## START

### Main track

#### General

Workplace view  
Current view . . . . . on  
Track view for live window  
Live display 1 . . . . . Main track  
Live display 2 . . . . . Main track  
Statistics . . . . . off  
Conditioning  
Automatic conditioning . . . . . off

#### Application note

Calibrating the pH Glass Electrode This is a method to calibrate a pH glass electrode. It consists of three different tracks. In the series start track the rack is initialised and the system prepared for the measurement. Additionally the electrode is removed from the storage beaker and rinsed thoroughly. The main track deals the calibration measurements followed by the rinsing of the electrode. After the measurements the results are calculated, a report is printed and the data saved in the previously defined database 'Robotic Acid Base Analyzer' (can be modified). Procedure: Fill three beakers with Metrohm buffer solutions pH 4, 7 and 9. Make sure that the electrode is properly immersed in the buffer solution. The special beaker for storing the electrode has to be filled with Metrohm storage solution. Remark: To run this method the settings of the 855 Robotic Titrosampler have to be adjusted. The lift positions have to be defined according to the rack and beakers used. As the robotic swing arm is equipped with a sensor the head has to touch the beaker brim when moving to the work position. If this requirement can not be fulfilled no beaker will be recognised. Two special beakers have to be defined including their own work positions. Special beaker 2 is used for rinsing the electrode while special beaker 1 contains storage solution for a proper electrode treatment between the determination series.

#### Method variables

Name	Type	Assignment	Fixed value	Comment	Monitoring
Sample size	Number	Sample size		Sample size	off
Sample size unit	Text	Sample size unit		Sample size unit	off
Sample position	Number	Sample position		Sample position number	off
ID1	Text	ID1		Sample identification 1	off
ID2	Text	ID2		Sample identification 2	off
ID3	Text	ID3		Sample identification 3	off

Name . . . . . **Sample size**  
 Type . . . . . Number  
 Assignment . . . . . on. . . . . Sample size  
 Fixed value . . . . . off. . . . .  
 Check at start . . . . . on  
 Comment . . . . . Sample size  
 Variable monitoring . . . . . off  
 Lower limit . . . . .  
 Upper limit . . . . .  
 Message . . . . .  
 Display message . . . . . on  
 Record message . . . . . on  
 Message by e-mail . . . . . off  
   Use e-mail template . . . . . off  
   E-mail template . . . . .  
   Mail to . . . . .  
   Subject . . . . . Message from tiamo - Method 'New method 1' - Command 'Main track'  
   User . . . . .  
   Mail from . . . . .  
   SMTP Server . . . . .  
   POP3 Server . . . . .  
 Acoustic signal . . . . . off  
 Action . . . . . off  
 Cancel determination . . . . . on  
 Cancel determination and series . . . . . off

Name . . . . . **Sample position**  
 Type . . . . . Number  
 Assignment . . . . . on. . . . . Sample position  
 Fixed value . . . . . off. . . . .  
 Check at start . . . . . on  
 Comment . . . . . Sample position number  
 Variable monitoring . . . . . off  
 Lower limit . . . . .  
 Upper limit . . . . .  
 Message . . . . .  
 Display message . . . . . on  
 Record message . . . . . on  
 Message by e-mail . . . . . off  
   Use e-mail template . . . . . off  
   E-mail template . . . . .  
   Mail to . . . . .  
   Subject . . . . . Message from tiamo - Method 'New method 1' - Command 'Main track'  
   User . . . . .

Mail from . . . . .  
SMTP Server . . . . .  
POP3 Server . . . . .  
Acoustic signal . . . . . off  
Action . . . . . off  
Cancel determination . . . . . on  
Cancel determination and series . . . . . off

Name . . . . . **Sample size unit**  
Type . . . . . Text  
Assignment . . . . . on. . . . . Sample size unit  
Fixed value . . . . . off.  
Check at start . . . . . on  
Comment . . . . . Sample size unit

Name . . . . . **ID1**  
Type . . . . . Text  
Assignment . . . . . on. . . . . ID1  
Fixed value . . . . . off.  
Check at start . . . . . on  
Comment . . . . . Sample identification 1

Name . . . . . **ID2**  
Type . . . . . Text  
Assignment . . . . . on. . . . . ID2  
Fixed value . . . . . off.  
Check at start . . . . . on  
Comment . . . . . Sample identification 2

Name . . . . . **ID3**  
Type . . . . . Text  
Assignment . . . . . on. . . . . ID3  
Fixed value . . . . . off.  
Check at start . . . . . on  
Comment . . . . . Sample identification 3

**CAL LOOP  
pH**

**calibration loop pH**

**Buffers**

Number of buffers . . . . . 3  
Buffer type . . . . . Special  
Buffer 1 pH . . . . . 4  
Buffer 2 pH . . . . . 7.02  
Buffer 3 pH . . . . . 10.06  
Request for buffer exchange . . . . . off  
Subsequent command . . . . . calculation

**PreBuffer**

**MOVE**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Target  
Tower . . . . . 1  
Move . . . . . Rack position  
Number . . . . . =0+ 'calibration loop pH.LCO'  
Beaker test  
Display message . . . . . off  
Cancel determination . . . . . off  
Cancel determination and series . . . . . on  
Parameters  
Shift rate . . . . . 20 %/s  
Shift direction . . . . . auto  
Swing rate . . . . . 55 %/s

**LIFT****LIFT 6**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Target  
Tower . . . . . 1  
Lift position . . . . . Work position mm  
Parameters  
Lift rate . . . . . 25 mm/s

**STIR****STIR 7**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Stirrer  
Stirrer . . . . . 1  
Stirrer type . . . . . unknown  
Stirring rate . . . . . 5  
Action  
Switch on . . . . . off  
Switch off . . . . . off  
Duration . . . . . on  
Time . . . . . 10.0 s

**LIFT****LIFT 8**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Target  
Tower . . . . . 1

Lift position . . . . . Shift position mm  
Parameters  
Lift rate . . . . . 25 mm/s

## MOVE

### to sample

#### Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

#### Target

Tower . . . . . 1  
Move . . . . . Rack position  
Number . . . . . =3 + 'calibration loop pH.LCO'

#### Beaker test

Display message . . . . . off  
Cancel determination . . . . . off  
Cancel determination and series . . . . . on

#### Parameters

Shift rate . . . . . 20 %/s  
Shift direction . . . . . auto  
Swing rate . . . . . 55 %/s

## LIFT

### LIFT 3

#### Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

#### Target

Tower . . . . . 1  
Lift position . . . . . Work position mm

#### Parameters

Lift rate . . . . . 25 mm/s

## CAL MEAS pH

### CAL MEAS pH

#### General/Hardware

##### Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

##### Sensor

Measuring input . . . . . 1  
Sensor . . . . . pH electrode  
Temperature measurement . . . . . automatic

##### Stirrer

Stirrer . . . . . 1  
Stirring rate . . . . . 5  
Switch off automatically . . . . . on

#### Measuring parameters

##### Measurement with drift control

Signal drift . . . . . 1 mV/min

Min. waiting time . . . . . 30 s  
Max. waiting time . . . . . 154 s  
Measuring interval . . . . . 2.0 s  
Temperature  
Temperature . . . . . 21 °C

**MOVE to rinsing beaker**

Device  
Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Target  
Tower . . . . . 1  
Move . . . . . Special beaker  
Number . . . . . 1  
Beaker test  
Display message . . . . . off  
Cancel determination . . . . . on  
Cancel determination and series . . . . . off  
Parameters  
Shift rate . . . . . 20 °/s  
Shift direction . . . . . auto  
Swing rate . . . . . 55 °/s

**LIFT LIFT 4**

Device  
Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Target  
Tower . . . . . 1  
Lift position . . . . . Work position mm  
Parameters  
Lift rate . . . . . 25 mm/s

**PUMP rinse and aspirate**

Device  
Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Pumps  
Tower . . . . . 1  
Pump(s) . . . . . 1  
Action  
Switch on . . . . . off  
Switch off . . . . . off  
Duration . . . . . on  
Time . . . . . 3 s

**calculation**

## CALC

Result name	Formula	Unit	Decimal places	Assignment	Statistics
slope	= 'calibration loop pH.SLO'	%	2	RS01	off
zero point	= 'calibration loop pH.ENP'		2	RS02	off

Result name . . . . . **slope**  
 Formula . . . . . = 'calibration loop pH.SLO'  
 Unit . . . . . %  
 Decimal places . . . . . 2  
 Assignment . . . . . RS01  
 Statistics . . . . . off  
 Description . . . . . RS.'Result name'[.VAL] Result value.  
 Result monitoring . . . . . off  
 Save result as common variable . . . . . off  
     Common variable . . . . .  
 Save result as titer . . . . . off  
     Solution name . . . . .

Result name . . . . . **zero point**  
 Formula . . . . . = 'calibration loop pH.ENP'  
 Unit . . . . .  
 Decimal places . . . . . 2  
 Assignment . . . . . RS02  
 Statistics . . . . . off  
 Description . . . . . RS.'Result name'[.VAL] Result value.  
 Result monitoring . . . . . off  
 Save result as common variable . . . . . off  
     Common variable . . . . .  
 Save result as titer . . . . . off  
     Solution name . . . . .

## REPORT

**report**  
 Report template  
     Report template . . . . . calibration report  
 Report output  
     Printer . . . . . off  
     PDF file . . . . . off

## DATABASE

### database

Database

tiamo

## SERIES START

### Series start track

**RACK initialize rack**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler  
Rack test . . . . . off

**MOVE to rinse beaker**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

## Target

Tower . . . . . 1  
Move . . . . . Special beaker  
Number . . . . . 1

## Beaker test

Display message . . . . . off  
Cancel determination . . . . . on  
Cancel determination and series . . . . . off

## Parameters

Shift rate . . . . . 20 %/s  
Shift direction . . . . . auto  
Swing rate . . . . . 55 %/s

**LIFT LIFT 2**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

## Target

Tower . . . . . 1  
Lift position . . . . . Rinse position mm

## Parameters

Lift rate . . . . . 25 mm/s

**PUMP aspirate and rinse**

## Device

Device name . . . . . 855\_1  
Device type . . . . . 855 Robotic Titrosampler

## Pumps

Tower . . . . . 1  
Pump(s) . . . . . 1

## Action

Switch on . . . . . off  
Switch off . . . . . off  
Duration . . . . . on  
Time . . . . . 5 s

**Series end track**



**SERIES  
END****MOVE****MOVE 9**

## Device

Device name . . . . . 855\_1

Device type . . . . . 855 Robotic Titrosampler

## Target

Tower . . . . . 1

Move . . . . . Special beaker

Number . . . . . 2

## Beaker test

Display message . . . . . on

Cancel determination . . . . . off

Cancel determination and series . . . . . off

## Parameters

Shift rate . . . . . 20 °/s

Shift direction . . . . . auto

Swing rate . . . . . 55 °/s

**LIFT****LIFT 1**

## Device

Device name . . . . . 855\_1

Device type . . . . . 855 Robotic Titrosampler

## Target

Tower . . . . . 1

Lift position . . . . . Rinse position mm

## Parameters

Lift rate . . . . . 25 mm/s

**STIR****STIR 10**

## Device

Device name . . . . . 855\_1

Device type . . . . . 855 Robotic Titrosampler

## Stirrer

Stirrer . . . . . 1

Stirrer type . . . . . unknown

Stirring rate . . . . . 8

## Action

Switch on . . . . . off

Switch off . . . . . off

Duration . . . . . on

Time . . . . . 10.0 s