

Method parameters

Method Calibrating the pH glass electrode
 Method saving date 2019-08-01 11:09:34 UTC+3
 Method version 15
 Method group Main group
 Method status original
 Method saved by (full name)
 Method saved by (short name) Admin

START

Main track

General

Workplace view
 Current view on
 Track view for live window
 Live display 1 Main track
 Live display 2 Main track
 Statistics off
 Conditioning
 Automatic conditioning off

Application note

Calibrating the pH Glass Electrode This is a method to calibrate a pH glass electrode. It consists of three different tracks. In the series start track the rack is initialised and the system prepared for the measurement. Additionally the electrode is removed from the storage beaker and rinsed thoroughly. The main track deals the calibration measurements followed by the rinsing of the electrode. After the measurements the results are calculated, a report is printed and the data saved in the previously defined database 'Robotic Acid Base Analyzer' (can be modified). Procedure: Fill three beakers with Metrohm buffer solutions pH 4, 7 and 9. Make sure that the electrode is properly immersed in the buffer solution. The special beaker for storing the electrode has to be filled with Metrohm storage solution. Remark: To run this method the settings of the 855 Robotic Titrosampler have to be adjusted. The lift positions have to be defined according to the rack and beakers used. As the robotic swing arm is equipped with a sensor the head has to touch the beaker brim when moving to the work position. If this requirement can not be fulfilled no beaker will be recognised. Two special beakers have to be defined including their own work positions. Special beaker 2 is used for rinsing the electrode while special beaker 1 contains storage solution for a proper electrode treatment between the determination series.

Method variables

Name	Type	Assignment	Fixed value	Comment	Monitoring
Sample size	Number	Sample size		Sample size	off
Sample size unit	Text	Sample size unit		Sample size unit	off
Sample position	Number	Sample position		Sample position number	off
ID1	Text	ID1		Sample identification 1	off
ID2	Text	ID2		Sample identification 2	off
ID3	Text	ID3		Sample identification 3	off

Name	Sample size
Type	Number
Assignment	on. Sample size
Fixed value	off.
Check at start	on
Comment	Sample size
Variable monitoring	off
Lower limit	
Upper limit	
Message	
Display message	on
Record message	on
Message by e-mail	off
Use e-mail template	off
E-mail template	
Mail to	
Subject	Message from tiamo - Method 'New method 1' - Command 'Main track'
User	
Mail from	
SMTP Server	
POP3 Server	
Acoustic signal	off
Action	off
Cancel determination	on
Cancel determination and series	off
Name	Sample position
Type	Number
Assignment	on. Sample position
Fixed value	off.
Check at start	on
Comment	Sample position number
Variable monitoring	off
Lower limit	
Upper limit	
Message	
Display message	on
Record message	on
Message by e-mail	off
Use e-mail template	off
E-mail template	
Mail to	
Subject	Message from tiamo - Method 'New method 1' - Command 'Main track'
User	

Mail from	
SMTP Server	
POP3 Server	
Acoustic signal	off
Action	off
Cancel determination	on
Cancel determination and series	off
Name	Sample size unit
Type	Text
Assignment	on.
Fixed value	off.
Check at start	on
Comment	Sample size unit
Name	ID1
Type	Text
Assignment	on.
Fixed value	off.
Check at start	on
Comment	Sample identification 1
Name	ID2
Type	Text
Assignment	on.
Fixed value	off.
Check at start	on
Comment	Sample identification 2
Name	ID3
Type	Text
Assignment	on.
Fixed value	off.
Check at start	on
Comment	Sample identification 3

CAL LOOP **calibration loop pH**
pH **Buffers**

Number of buffers	3
Buffer type	Special
Buffer 1 pH	4
Buffer 2 pH	7.02
Buffer 3 pH	10.06
Request for buffer exchange	off
Subsequent command	calculation

PreBuffer

MOVE Device

Device name 855_1
Device type 855 Robotic Titrosampler
Target
Tower 1
Move Rack position
Number =0+ 'calibration loop pH.LCO'
Beaker test
Display message off
Cancel determination off
Cancel determination and series on
Parameters
Shift rate 20 °/s
Shift direction auto
Swing rate 55 °/s

LIFT **LIFT 6**

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Target
Tower 1
Lift position Work position mm
Parameters
Lift rate 25 mm/s

STIR **STIR 7**

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Stirrer
Stirrer 1
Stirrer type unknown
Stirring rate 5
Action
Switch on off
Switch off off
Duration on
Time 10.0 s

LIFT **LIFT 8**

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Target
Tower 1

Lift position Shift position mm
Parameters
Lift rate 25 mm/s

MOVE to sample

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Target
Tower 1
Move Rack position
Number =3 + 'calibration loop pH.LCO'
Beaker test
Display message off
Cancel determination. off
Cancel determination and series on
Parameters
Shift rate 20 °/s
Shift direction auto
Swing rate 55 °/s

LIFT LIFT 3

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Target
Tower 1
Lift position Work position mm
Parameters
Lift rate 25 mm/s

CAL MEAS CAL MEAS pH**pH General/Hardware**

Device
Device name 855_1
Device type 855 Robotic Titrosampler

Sensor
Measuring input 1
Sensor pH electrode
Temperature measurement automatic

Stirrer
Stirrer 1
Stirring rate 5
Switch off automatically on

Measuring parameters

Measurement with drift control
Signal drift 1 mV/min

Min. waiting time 30 s
Max. waiting time 154 s
Measuring interval 2.0 s

Temperature
Temperature 21 °C

MOVE to rinsing beaker

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Move Special beaker
Number 1

Beaker test

Display message off
Cancel determination on
Cancel determination and series off

Parameters

Shift rate 20 °/s
Shift direction auto
Swing rate 55 °/s

LIFT LIFT 4

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Lift position Work position mm

Parameters

Lift rate 25 mm/s

PUMP rinse and aspirate

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Pumps

Tower 1
Pump(s) 1

Action

Switch on off
Switch off off
Duration on
Time 3 s

calculation

CALC

Result name	Formula	Unit	Decimal places	Assignment	Statistics
slope	= 'calibration loop pH.SLO'	%	2	RS01	off
zero point	= 'calibration loop pH.ENP'		2	RS02	off

Result name	slope
Formula	= 'calibration loop pH.SLO'
Unit	%
Decimal places	2
Assignment	RS01
Statistics	off
Description	RS.'Result name'[.VAL] Result value.
Result monitoring	off
Save result as common variable	off
Common variable	
Save result as titer	off
Solution name	
Result name	zero point
Formula	= 'calibration loop pH.ENP'
Unit	
Decimal places	2
Assignment	RS02
Statistics	off
Description	RS.'Result name'[.VAL] Result value.
Result monitoring	off
Save result as common variable	off
Common variable	
Save result as titer	off
Solution name	

REPORT

report

Report template	
Report template	calibration report
Report output	
Printer	off
PDF file	off

DATABASE **database**

Database	
tiamo	

SERIES **START** **Series start track**

RACK initialize rack

Device
Device name 855_1
Device type 855 Robotic Titrosampler
Rack test off

MOVE to rinse beaker

Device
Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Move Special beaker
Number 1

Beaker test

Display message off
Cancel determination on
Cancel determination and series off

Parameters

Shift rate 20 °/s
Shift direction auto
Swing rate 55 °/s

LIFT LIFT 2

Device
Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Lift position Rinse position mm

Parameters

Lift rate 25 mm/s

PUMP aspirate and rinse

Device
Device name 855_1
Device type 855 Robotic Titrosampler

Pumps

Tower 1
Pump(s) 1

Action

Switch on off
Switch off off
Duration on
Time 5 s

Series end track

SERIES
END**MOVE MOVE 9**

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Move Special beaker
Number 2

Beaker test

Display message on
Cancel determination off
Cancel determination and series off

Parameters

Shift rate 20 °/s
Shift direction auto
Swing rate 55 °/s

LIFT LIFT 1

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Target

Tower 1
Lift position Rinse position mm

Parameters

Lift rate 25 mm/s

STIR STIR 10

Device

Device name 855_1
Device type 855 Robotic Titrosampler

Stirrer

Stirrer 1
Stirrer type unknown
Stirring rate 8

Action

Switch on off
Switch off off
Duration on
Time 10.0 s