1 Note

Hi Zoe, thanks for the tip. I have corrected it now.

2 Chapter 4 The Response Distribution

Problem 4.1 Match the following functions that play a role in Bayesian modeling with the descriptions:

Functions:

- (a) Distribution of the posterior mean estimate
- (b) Prior distribution
- (c) Likelihood function
- (d) Posterior distribution
- (e) Measurement distribution

Descriptions:

- (a) Is the result of inference on an individual trial
- (b) Describes how potentially noisy observations are generated
- (c) Can be directly compared to human responses in a psychophysical experiment
- (d) Is often modeled as a Gaussian function centered at the measurement
- (e) May reflect statistics in the natural world

My answers are as following:

$$(a) \rightarrow (c)$$

The distribution of the posterior mean estimate can be directly compared to behavioral data in psychophysical experiments, as it represents the central tendency of Bayesian inference on each trial.

$$(b) \rightarrow (e)$$

Prior represents beliefs before observing data and reflects statistics from past experience.

$$(c) \rightarrow (d)$$

The likelihood function is usually a Gaussian function centered at the measurement.

$$(d) \rightarrow (a)$$

The posterior distribution is the result of inference on an individual trial, combining prior and likelihood information to update the belief about the true stimulus.

$$(e) \rightarrow (b)$$

The noisy observation is generated by stimulus + noise, which is the description of measurement distribution.