```
%% MathTools Lab 1 (HW0)
%Date: Sep 5th 2024
%% Question 1
%a)
%Testing 1: Project [3, 4] onto [0.6, 0.8]
v = [3, 4];
u = [0.6, 0.8];
length_projected_vector = project(v, u);
disp(length_projected_vector);
   2.7785
%Testing 1: Project [7, 8, 9] onto [0, 0, 1]
v = [7, 8, 9];
u = [0, 0, 1];
length_projected_vector = project(v, u);
disp(length_projected_vector);
    9
%% Question 1
%b)
%Testing Gram—Schmidt process
v = [3, 4];
u = [0.6, 0.8];
[coordinates_v, matrix_uw] = changeOfCoords(v, u);
disp('Coordinates of v in the new coordinate system:');
Coordinates of v in the new coordinate system:
disp(coordinates_v);
   5.0000
  -0.0000
disp('Matrix [u, w]:');
Matrix [u, w]:
disp(matrix_uw);
   0.6000
           -0.8000
   0.8000
            0.6000
```

plot([0,v(1)],[0,v(2)]);hold on;

```
plot([0,u(1)],[0,u(2)]);hold on;
plot([0,coordinates_v(1)], [0,coordinates_v(2)]); hold on;
legend('v','u','coordinates_v');
```

```
testing = (matrix_uw * coordinates_v)';
disp(testing);
```

3.0000 4.0000

```
%% Functions
%1a)
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function length_projected_vector = project(v, u)

%ensure that u is a unit factor
if norm(u) ~= 1
    error('change u to a unit vector')
end

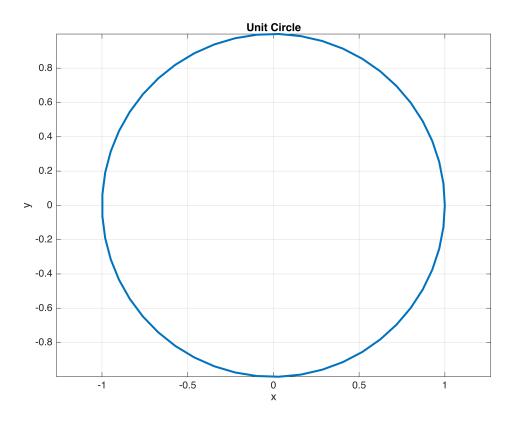
%projecting v onto u
%proj_v_on_u = dot(v, u) * u;
proj_v_on_u = (v.*u).*u;
%length_projected_vector = norm(proj_v_on_u);
```

```
length_projected_vector = sqrt(sum(proj_v_on_u.^2));
end
%1b)
function [coordinates_v, matrix_uw] = changeOfCoords(v, u)
% v: created orthogonal vector in a new "coordinate system"
% u: one of the new axes (will be normalized)
%making u an unit vector
u = u / norm(u);
u = u / sqrt(sum(u.^2));
%creating an orthogonal unit vector w
w = [-u(2), u(1)];
%List the matrix
matrix_uw = [u(:), w(:)];
%compute the coordinates
coordinates_v = matrix_uw \ v(:);
end
```

```
%% Question 2
%define theta
theta = linspace(0, 2*pi, 50);

%coordinates of the unit circle
x = cos(theta);
y = sin(theta);

% Plot the unit circle
figure;
plot(x, y, 'LineWidth', 2);
axis equal; xlabel('x'); ylabel('y');
title('Unit Circle');
grid on;
```



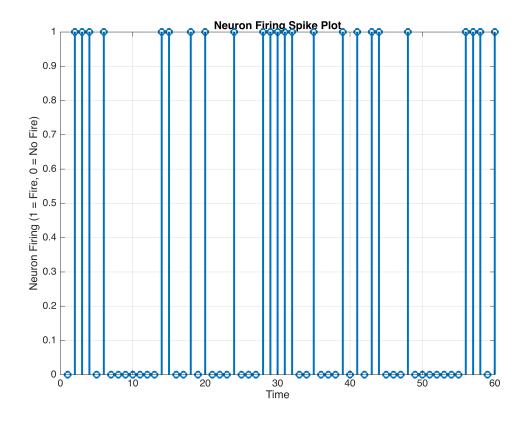
```
%% Question 3a)
input_vector = rand(8,1);
scalar_threshold = 0.5;
%testing
decision = neuron(input_vector, scalar_threshold);
disp('Input vector:');
Input vector:
disp(input_vector);
   0.9503
   0.4980
   0.8175
   0.7357
   0.1582
   0.7916
   0.0137
   0.7235
disp('Does the neuron fire? (1 = yes, 0 = no)');
Does the neuron fire? (1 = yes, 0 = no)
disp(decision);
    1
%% Question 3b)
scalar_threshold = 0.5;
T = 60;
%3c)
time_vector = 1:T;
plot_vector = zeros(1, T);
for xx = time_vector
    plot_vector(xx) = neuron0verTime(scalar_threshold, T);
end
Firing activity over time:
Firing activity over time:
Firing activity over time:
Firing activity over time:
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- Firing activity over time:
- Firing activity over time: 0

```
Firing activity over time:
figure;
stem(time_vector, plot_vector, 'LineWidth', 2);hold on;
xlabel('Time');
ylabel('Neuron Firing (1 = Fire, 0 = No Fire)');
title('Neuron Firing Spike Plot');
grid on;
```



%3a)

```
function decision = neuron(input_vector, scalar_threshold)
dendrite1 = mean(input_vector);
dendrite2 = mean(input_vector(5:8));
dendrite3 = input_vector(8);
%check firing or not
check_firing = 0;
if dendrite1 > scalar_threshold
    check_firing = check_firing +1;
end
if dendrite2 > scalar_threshold
    check_firing = check_firing +1;
end
if dendrite3 > scalar_threshold
    check_firing = check_firing +1;
end
if check_firing >=2
    decision = 1;
else
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```
decision = 0;
end

end

%3b)
function decision_over_time = neuronOverTime(scalar_threshold, T)
input_vector = rand(1, T);
padded_input = [zeros(1, 7), input_vector];

for t = 1:T
    real_inputs = padded_input(t:t+7)';
    decision_over_time = neuron(real_inputs, scalar_threshold);
end

    disp('Firing activity over time:');
    disp(decision_over_time);
end
```