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## The Experiment Report of Machine Learning

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**SCHOOL: SCHOOL OF SOFTWARE ENGINEERING**

**SUBJECT: SOFTWARE ENGINEERING**

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# Recommender System Based on Matrix Decomposition

**Abstract**— *Recommender System applise statistical and knowledge discovery techniques to make the product recommendations. The main idea of the system is CF(Collaborative Fitering).*

*In this paper, we chose the Matrix Factorization(one way of the model based CF)technique to implement it. We implement it both in ALS and SGD, compare them first. Then we study the choice of the two parameters—C and K.*

## I. INTRODUCTION

We do this experiment for the purpose of:

1. Explore the construction of recommended system.
2. Understand the principle of matrix decomposition.
3. Be familiar to the use of gradient descent.
4. Construct a recommendation system under small-scale dataset, cultivate engineering ability

## II. METHODS AND THEORY

The main idea and formulas that use in the paper & the pseudocode of algorithm:

### A. ALS

Objective function:

$$\mathcal{L} = \sum_{u,i} (r_{u,i} - \mathbf{p}_u^\top \mathbf{q}_i)^2 + \lambda (\sum_u n_{\mathbf{p}_u} \|\mathbf{p}_u\|^2 + \sum_i n_{\mathbf{q}_i} \|\mathbf{q}_i\|^2)$$

Optimize **P** while **fixing Q**:

The first order optimality:

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial \mathbf{p}_u} &= 0 \\ \Rightarrow \sum_{r_{u,i} \neq 0} (\mathbf{q}_i \mathbf{q}_i^\top + \lambda n_{\mathbf{p}_u} I) \cdot \mathbf{p}_u &= \mathbf{Q}^\top \cdot \mathbf{R}_{u*}^\top \\ \Rightarrow \mathbf{p}_u &= (\mathbf{q}_i \mathbf{q}_i^\top + \lambda n_{\mathbf{p}_u} I)^{-1} \cdot \mathbf{Q}^\top \cdot \mathbf{R}_{u*}^\top \end{aligned}$$

$\mathbf{R}_{u*}$  denotes the  $u$ -th row of rating matrix  $\mathbf{R}$ .

Update **all**  $\mathbf{p}_u$  with the above formula.

Optimize **Q** while **fixing P**:

The first order optimality:

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial \mathbf{q}_i} &= 0 \\ \Rightarrow \sum_{r_{u,i} \neq 0} (\mathbf{p}_u \mathbf{p}_u^\top + \lambda n_{\mathbf{q}_i} I) \cdot \mathbf{q}_i &= \mathbf{P}^\top \cdot \mathbf{R}_{*i}^\top \\ \Rightarrow \mathbf{q}_i &= (\mathbf{p}_u \mathbf{p}_u^\top + \lambda n_{\mathbf{q}_i} I)^{-1} \cdot \mathbf{P}^\top \cdot \mathbf{R}_{*i} \end{aligned}$$

$\mathbf{R}_{*i}$  denotes the  $i$ -th column of rating matrix  $\mathbf{R}$ .

Update **all**  $\mathbf{q}_i$  with the above formula.

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### Algorithm 2 ALS Algorithm

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- 1: **Require** rating matrix  $\mathbf{R}$ , feature matrices  $\mathbf{P}$ ,  $\mathbf{Q}$  and regularization parameter  $\lambda$ .
  - 2: **Optimize P** while fixing **Q**:  

$$\mathbf{p}_u = (\mathbf{q}_i \mathbf{q}_i^\top + \lambda n_{\mathbf{p}_u} I)^{-1} \cdot \mathbf{Q}^\top \cdot \mathbf{R}_{u*}^\top$$
  - 3: **Optimize Q** while fixing **P**:  

$$\mathbf{q}_i = (\mathbf{p}_u \mathbf{p}_u^\top + \lambda n_{\mathbf{q}_i} I)^{-1} \cdot \mathbf{P}^\top \cdot \mathbf{R}_{*i}$$
  - 4: **Repeat** the above processes until **convergence**.
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## B. SGD

Objective function:

$$\mathcal{L} = (r_{u,i} - \mathbf{p}_u^\top \mathbf{q}_i)^2 + \lambda_p \|\mathbf{p}_u\|^2 + \lambda_q \|\mathbf{q}_i\|^2$$

**Randomly** select an observed sample  $r_{u,i}$ .

Calculate the **prediction error**:

$$E_{u,i} = r_{u,i} - \mathbf{p}_u^\top \mathbf{q}_i$$

Calculate the **gradient**:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{p}_u} = E_{u,i}(-\mathbf{q}_i) + \lambda_p \mathbf{p}_u$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{q}_i} = E_{u,i}(-\mathbf{p}_u) + \lambda_q \mathbf{q}_i$$

Objective function:

$$\mathcal{L} = (r_{u,i} - \mathbf{p}_u^\top \mathbf{q}_i)^2 + \lambda_p \|\mathbf{p}_u\|^2 + \lambda_q \|\mathbf{q}_i\|^2$$

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Calculate the **gradient**:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{p}_u} = E_{u,i}(-\mathbf{q}_i) + \lambda_p \mathbf{p}_u$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{q}_i} = E_{u,i}(-\mathbf{p}_u) + \lambda_q \mathbf{q}_i$$

Update the feature matrices **P** and **Q** with **learning rate**  $\alpha$ :

$$\mathbf{p}_u = \mathbf{p}_u + \alpha(E_{u,i}\mathbf{q}_i - \lambda_p \mathbf{p}_u)$$

$$\mathbf{q}_i = \mathbf{q}_i + \alpha(E_{u,i}\mathbf{p}_u - \lambda_q \mathbf{q}_i)$$

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### Algorithm 4 SGD Algorithm

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- 1: **Require** feature matrices **P**, **Q**, observed set  $\Omega$ , regularization parameters  $\lambda_p$ ,  $\lambda_q$  and learning rate  $\alpha$ .
- 2: **Randomly** select an observed sample  $r_{u,i}$  from observed set  $\Omega$ .
- 3: Calculate the **gradient** w.r.t to the objective function:

$$E_{u,i} = r_{u,i} - \mathbf{p}_u^\top \mathbf{q}_i$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{p}_u} = E_{u,i}(-\mathbf{q}_i) + \lambda_p \mathbf{p}_u$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{q}_i} = E_{u,i}(-\mathbf{p}_u) + \lambda_q \mathbf{q}_i$$

- 4: **Update** the feature matrices **P** and **Q** with learning rate  $\alpha$  and gradient:

$$\mathbf{p}_u = \mathbf{p}_u + \alpha(E_{u,i}\mathbf{q}_i - \lambda_p \mathbf{p}_u)$$

$$\mathbf{q}_i = \mathbf{q}_i + \alpha(E_{u,i}\mathbf{p}_u - \lambda_q \mathbf{q}_i)$$

- 5: **Repeat** the above processes until **convergence**.
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## III. EXPERIMENT

### 1. Data Set

We use MovieLens-100k dataset in the experiment, consisting 100000 comments from 943 users out of 1682 movies.

### 2. Implentation

ALS:

```
def ALS_fit(self, epoch, r_matrix_train,
            r_matrix_test, train_pre, test_pre, I, I_t, n_comments, n_comments_t):
    R = r_matrix_train
    E = np.eye(self.k)
    t_pre = train_pre

    it_num = []
    train_loss = []
    test_loss = []
    train_rmse = []
    test_rmse = []

    #开始进行交替最小二乘法
    for ep in range(epoch):

        print('ep' + str(ep+1) + ' success')
        print(self.loss(r_matrix_train, train_pre, I))
        it_num.append(ep)
        train_loss.append( self.loss(r_matrix_train, train_pre, I) )
        test_loss.append( self.loss(r_matrix_test, test_pre, I_t) )
        train_rmse.append( self.rmse(r_matrix_train, I, n_comments) )
        test_rmse.append( self.rmse(r_matrix_test, I_t, n_comments_t) )

        for i in range(self.P.shape[1]):
            if(t_pre[0][i] > 0):
                Q = I[i] * self.Q

                self.P[:,i] =
                np.asarray( np.mat( (Q.dot(Q.T) + self.lamda *
                t_pre[0][i] * E) ).I ).dot(Q).dot(R[i, :].T)

        I2 = I.T
        for i in range(self.Q.shape[1]):
            if(t_pre[1][i] > 0):
                P = I2[i] * self.P

                self.Q[:,i] =
                np.asarray( np.mat( (P.dot(P.T) + self.lamda *
                t_pre[1][i] * E) ).I ).dot(P).dot(R[:, i])

        if(ep>0 and abs(train_rmse[ep-1]-train_rmse[ep])<=0.001):
            break

    return it_num, train_loss, test_loss, train_rmse, test_rmse
```

SGD:

```
def SGD_fit(self, epoch, lr, r_matrix_train,
            r_matrix_test, train_pre, test_pre, I, I_t, n_comments, n_comments_t):
    R = r_matrix_train
    users, items = R.nonzero()

    it_num = []
    train_loss = []
    test_loss = []
    train_rmse = []
    test_rmse = []

    #amount = len(users)
    for ep in range(epoch):

        print('ep' + str(ep+1) + ' success')
        #print(self.loss(r_matrix_test, test_pre, I_t))
        print(self.loss(r_matrix_train, train_pre, I))
        it_num.append(ep)
        train_loss.append( self.loss(r_matrix_train, train_pre, I) )
        test_loss.append( self.loss(r_matrix_test, test_pre, I_t) )
        train_rmse.append( self.rmse(r_matrix_train, I, n_comments) )
        test_rmse.append( self.rmse(r_matrix_test, I_t, n_comments_t) )

        for u,i in zip(users,items):
            e = R[u][i] - dot(self.P[:,u].T, self.Q[:,i])
            self.P[:,u] += lr * (e * self.Q[:,i] - self.lamda * self.P[:,u])
            self.Q[:,i] += lr * (e * self.P[:,u] - self.lamda * self.Q[:,i])

        if(ep>0 and abs(train_rmse[ep-1]-train_rmse[ep])<=0.001):
            break

    return it_num, train_loss, test_loss, train_rmse, test_rmse
```

### 3. Experiment:

#### Default setting

Set

$k = 20$ ,  $\text{lamda} = 0.1$

$\text{lr} = 0.01$  (for SGD)

#### Explanation about my loss

I set the loss function to multiply 0.5 (loss = 0.5 \* loss), because I do not want to multiply 2 when taking the derivative.

A. Just running the program to  
See the result:

#### a. result

Set

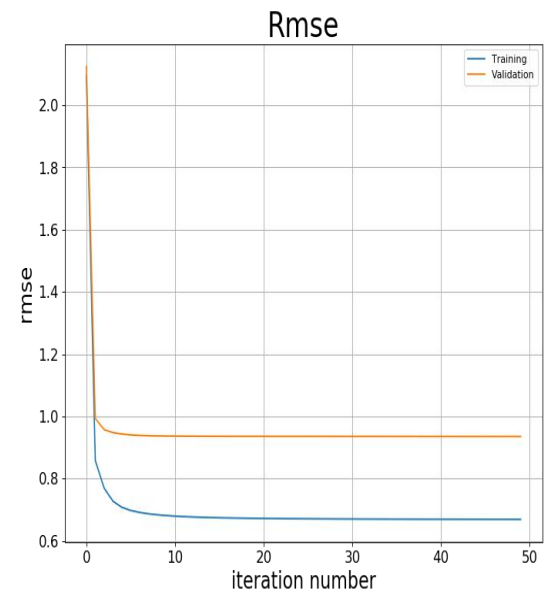
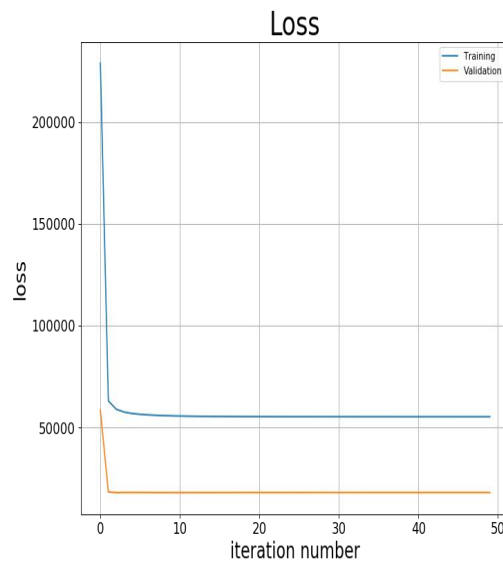
Iteration = 50

$k = 20$ ,  $\text{lamda} = 0.1$

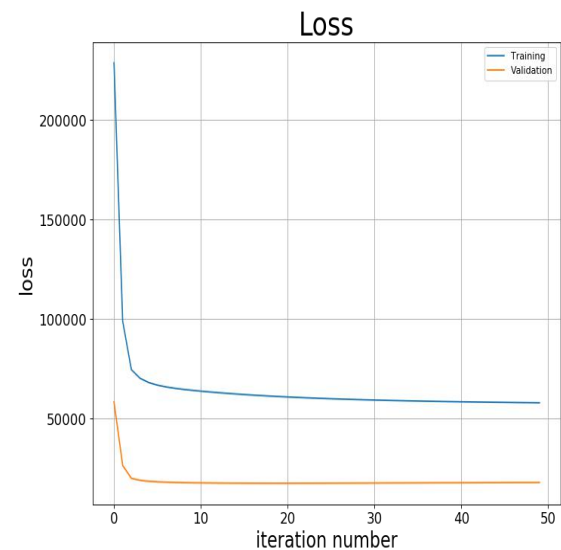
$\text{lr} = 0.01$  (for SGD)

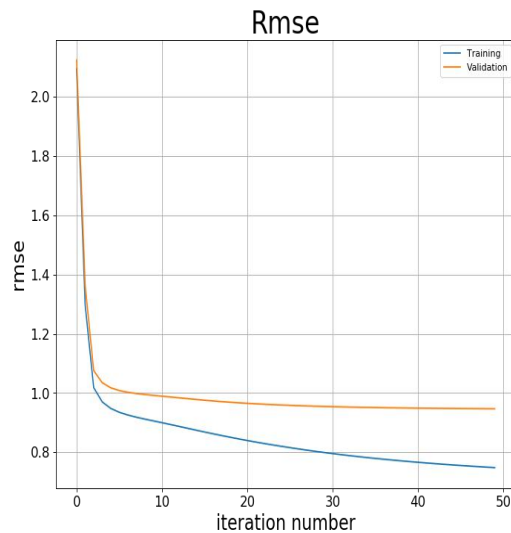
P, Q init with random  
(42 seed)

ALS:



SGD:





*b. Analysis:*

They can converge after iteration. The implementation may be right.

*B. Compare the ALS and SGD*

*a. Speed of convergence:*

Set  $K = 5, 20, 50$  to compare the speed:

*ALS:*

```
收敛耗时:
68.68455362319946
drawing, please wait
训练集上的rmse:
0.8021495994357293
验证集上的rmse:
0.9305916222210723
```

```
收敛耗时:
156.2533040046692
drawing, please wait
训练集上的rmse:
0.6688881807131867
验证集上的rmse:
0.9351614966958692
```

```
收敛耗时:
281.5046417713165
drawing, please wait
训练集上的rmse:
0.6113981481762778
验证集上的rmse:
0.9353843760822285
```

*SGD:*

```
收敛耗时:
494.3064298629761
drawing, please wait
训练集上的rmse:
0.9210679131296331
验证集上的rmse:
1.0440300339546669
```

```
收敛耗时:
493.03716468811035
drawing, please wait
训练集上的rmse:
0.7623435866607963
验证集上的rmse:
1.0297135890862759
```

```
收敛耗时:
523.23153424263
drawing, please wait
训练集上的rmse:
0.6907068964572054
验证集上的rmse:
0.9556509024129339
```

*b. Analysis*

*b.1*

We can see as the  $K$  increases, ALS's speed increases, but SGD does not have much obvious change.

It accords with computational complexity:

ALS:

$$O(|\Omega|k^2 + (m + n)k^3)$$

SGD:

$$O(|\Omega|k)$$

### b.2

But we can see ALS's convergence is faster.

So, in this experiment, what I set K just 1~50, ALS's speed is faster.

### C. Test on parameters K, C:

Set K = 5, 20, 50

C = 0.01, 0.1, 0.3, 1

I set that if the train rmse change between two iteration is less than 0.001, it will be seen as convergence.

Do tests with ALS

#### a. The result table

| landa/k | 0.01                         | 0.1         | 0.3        | 1           |
|---------|------------------------------|-------------|------------|-------------|
| 5       | 0.775209063                  | 0.803969643 | 0.94486837 | 1.355317513 |
|         | 1.064854795                  | 0.932579931 | 0.98822204 | 1.379623015 |
|         |                              |             |            |             |
| 20      | 0.487880448                  | 0.674630299 | 0.94466182 | 1.355349426 |
|         | 1.236632499                  | 0.935898293 | 0.98924916 | 1.379215598 |
|         |                              |             |            |             |
| 50      | 0.195590682                  | 0.616475335 | 0.94494501 | 1.355354654 |
|         | 1.189968099                  | 0.935655001 | 0.99589012 | 1.382268661 |
|         |                              |             |            |             |
|         | the training rmse is beyond  |             |            |             |
|         | the validation rmse is below |             |            |             |
|         | t_rmse/v_rmse                |             |            |             |
|         |                              |             |            |             |

#### b. Analysis

The lamda cannot be set to a too larger value, or the train rmse and the validation rmse will be unsatisfied both.

The result of k, which indicate to the factor impacting the rating is different with my first assumption. K can not be too large too.

So, at last lamda = 0.3 and k = 5, may be good.

## IV. CONCLUSION

In the experiment we construct the recommended system using MF. We have a deeper understanding on MF after using two ways to implement it and compare the ways.

The SGD in this experiment is different with which in former three. And we get the new understanding on it after using it on this way.

At last, by applying what we learned to implement a real system, our engineering ability gets much improved.