DEEP LEARNING

Trainer: Dr. Darshan Ingle



4. Hinge Loss

• Used for classification.

Code

```
def Hinge(yHat, y):
  return np.max(0, 1 - yHat * y)
```

5. Huber Loss

- Typically used for regression.
- It's less sensitive to outliers than the MSE as it treats error as square only inside an interval.

$$L_{\delta} = egin{cases} rac{1}{2}(y-\hat{y})^2 & if \left|(y-\hat{y})
ight| < \delta \ \delta((y-\hat{y})-rac{1}{2}\delta) & otherwise \end{cases}$$

Code

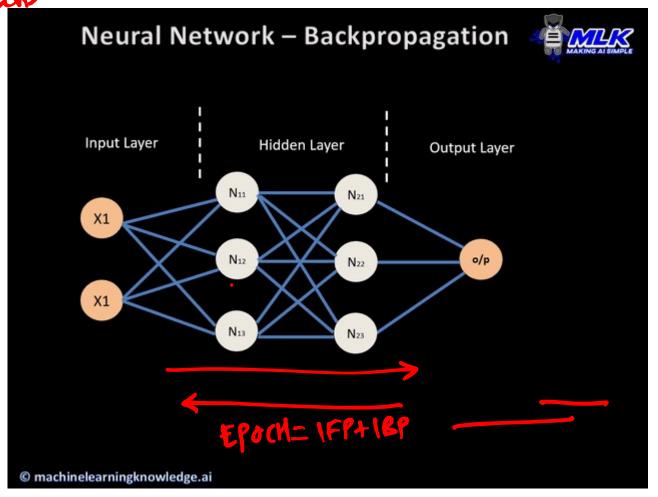
def Huber(yHat, y, delta=1.):

return np.where(np.abs(y-yHat) < delta,.5*(y-yHat)**2 , delta*(np.abs(y-yHat)-0.5*delta))

1. Gradient Descent (all points)
2. Mini Batch GD (one batch)
3. Stachastic GD (one

point)

Optimizers



Optimizers

- What is Optimizer?
- It is very important to tweak the weights of the model during the training process, to make our predictions as correct and optimized as possible. But how exactly do you do that?
- How do you change the parameters of your model, by how much, and when?

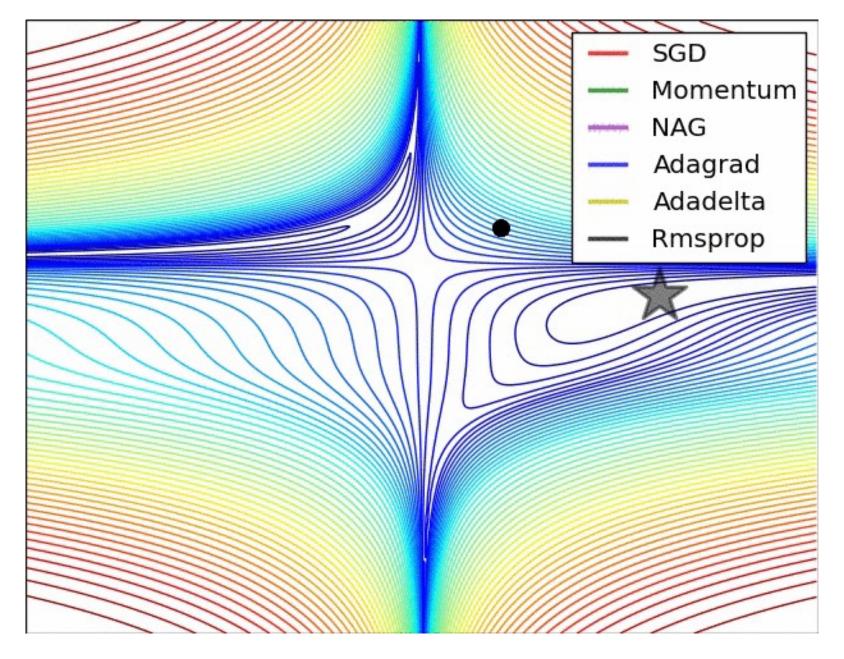
Ans: Optimizers. They tie together the loss Function & Model purameters by radating the model in response to opport Loss function.

Optimizers

- Below are list of example optimizers
- Adagrad
- Adadelta
- Adam
- Conjugate Gradients
- BFGS
- Momentum
- Nesterov Momentum
- Newton's Method
- RMSProp
- SGD

Optimizers

 Picking the right optimizer with the right parameters, can help you squeeze the last bit of accuracy out of your neural network model.



Adagrad Optimizer to 1 = 0.001

- Adagrad (short for adaptive gradient) adaptively sets the learning rate according to a parameter.
- Pavaneters that he a higher gradient/frequent updates so that we don't overchast the minimum value. should he slower Learning vate
- a low gradient/infrquent updates that they get brained quiday.

Adagrad Optimizer



$$\omega^{f} = \omega^{f-1} - J \cdot \frac{2m^{f-1}}{9\Gamma}$$

Adagrad:
$$|\omega_t = \omega_{t-1} - 1$$

who
$$= \frac{1}{2} \left(\frac{\partial L}{\partial \omega_i} \right)^2$$

Adagrad Optimizer

Adagrad Optimizer Disadvantage

we are squaring in oft. much possible that It beams a v.uv. high no. as the #iterations increas. 1. We & when are almost same.

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1. We are almost same.

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RMSProp and Adadelta

RMSProp and Adadelta (They overcome disadu. of Adagrad)

are almost the same. Only difference is that they are created by different team.

They simply aim to control

44, L.R. J. We wit this, but we don't write to decrease to a

uv. Small no.

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RMSProp Optimizer

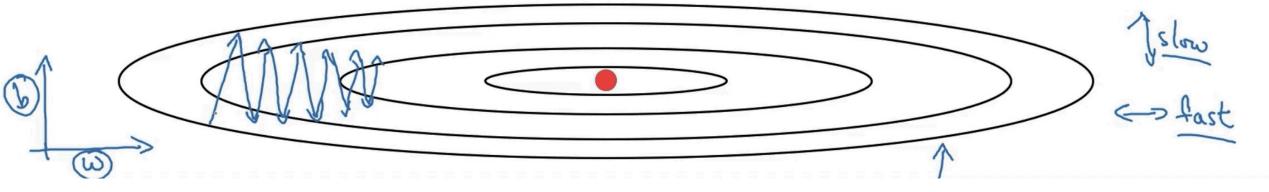
 Another adaptive learning rate optimization algorithm, Root Mean Square Prop (RMSProp) works by keeping an exponentially weighted average of the squares of past gradients. RMSProp then divides the learning rate by this average to speed up convergence.

- s the exponentially weighted average of past squares of gradients
- W weight tensor
- β hyperparameter to be tuned
- α the learning rate
- ϵ very small value to avoid dividing by zero

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RMSProp Optimizer

RMSprop



Adagrad Optimizer

$$egin{aligned} g_t^i &= rac{\partial \mathcal{J}(w_t^i)}{\partial W} \ W &= W - lpha rac{\partial \mathcal{J}(w_t^i)}{\sqrt{\sum_{r=1}^t ig(g_r^iig)^2 + arepsilon}} \end{aligned}$$

Note

 g_t^i - the gradient of a parameter, :math: `Theta` at an iteration t.

lpha - the learning rate

 ϵ - very small value to avoid dividing by zero

Adagrad Optimizer

```
def Adagrad(data):
  gradient_sums = np.zeros(theta.shape[0])
  for t in range(num_iterations):
    gradients = compute_gradients(data, weights)
    gradient_sums += gradients ** 2
    gradient_update = gradients / (np.sqrt(gradient_sums + epsilon))
    weights = weights - Ir * gradient_update
  return weights
```

- Adadelta optimization is a stochastic gradient descent method that is based on adaptive learning rate per dimension to address two drawbacks:
 - The continual decay of learning rates throughout training
 - The need for a manually selected global learning rate
- Adadelta is a more robust extension of Adagrad that adapts learning rates based on a moving window of gradient updates, instead of accumulating all past gradients.
- This way, Adadelta continues learning even when many updates have been done.
- Compared to Adagrad, in the original version of Adadelta you don't have to set an initial learning rate. In this version, initial learning rate can be set, as in most other Keras optimizers.

- AdaDelta belongs to the family of stochastic gradient descent algorithms, that provide adaptive techniques for hyperparameter tuning. Adadelta is probably short for 'adaptive delta', where delta here refers to the difference between the current weight and the newly updated weight.
- The main disadvantage in Adagrad is its accumulation of the squared gradients. During the training process, the accumulated sum keeps growing. As the accumulated sum increases, learning rate starts to shrink and eventually become infinitesimally small, at which point the algorithm is no longer able to acquire additional knowledge.

- Adadelta is a more robust extension of Adagrad that adapts learning rates based on a moving window of gradient updates, instead of accumulating all past gradients. This way, Adadelta continues learning even when many updates have been done.
- With Adadelta, we do not even need to set a default learning rate, as it has been eliminated from the update rule.

Implementation is something like this,

$$v_t =
ho v_{t-1} + (1-
ho)
abla^2_ heta J(heta)$$
 $\Delta heta = rac{\sqrt{w_t + \epsilon}}{\sqrt{v_t + \epsilon}}
abla_ heta J(heta)$ $heta = heta - \eta \Delta heta$ $w_t = heta w_t$ arshim (c.l. $-
ho) \Delta heta^2$

```
def Adadelta(weights, sqrs, deltas, rho, batch size):
 eps_stable = 1e-5
  for weight, sqr, delta in zip(weights, sqrs, deltas):
    g = weight.grad / batch size
    sqr[:] = rho * sqr + (1. - rho) * nd.square(g)
    cur_delta = nd.sqrt(delta + eps_stable) / nd.sqrt(sqr + eps_stable) * g
    delta[:] = rho * delta + (1. - rho) * cur_delta * cur_delta
    # update weight in place.
    weight[:] -= cur delta
```

Gradient Descent (Vanilla Main aD)

Stochastic Gradient Descent

already covered earlier.

Stochastic Gradient Descent

Stochastic Gradient Descent

Pros (1) Relatively fast compared to older GD approaches. @ eosier to learn for beginners, : it is not math heavy.

Cons

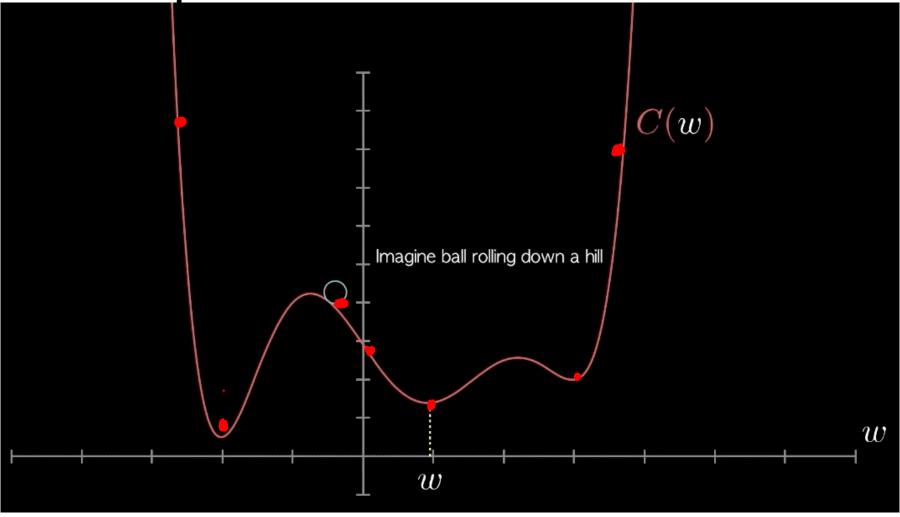
- 1) Converges slow than newer algorithms
- (2) Has more problems with being stuck in a local minimum than newer approaches.
- approaches out perform SGD in terms of opinizing cost fundice.

Stochastic Gradient Descent with Momentum

Stochastic Gradient Descent with Momentum

Stochastic Gradient Descent with Momentum

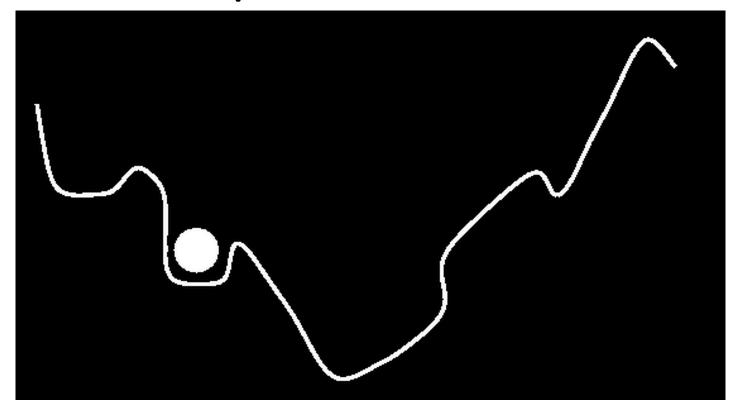
- Simply put, the momentum algorithm helps us progress faster in the neural network, negatively or positively, to the ball analogy. This helps us get to a local minimum faster.
- Motivation for momentum
- For each time we roll the ball down the hill (for each epoch), the ball rolls faster towards the local minima in the next iteration. This makes us more likely to reach a better local minima (or perhaps global minima) than we could have with SGD.



When optimizing the cost function for a weight, we might imagine a ball rolling down a hill amongst many hills. We hope that we get to some form of optimum.

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- The slope of the cost function is not actually such a smooth curve, but it's easier to plot to show the concept of the ball rolling down the hill.
- The function will often be much more complex, hence we might actually get stuck in a local minimum or significantly slowed down.
- Obviously, this is not desirable.
- The terrain is not smooth, it has obstacles and weird shapes in very high-dimensional space for instance, the concept would look like this in 2D:



• In the above case, we are stuck at a local minimum, and the motivation is clear – we need a method to handle these situations, perhaps to never get stuck in the first place.

• Now we know why we should use momentum, let's introduce more specifically what it means, by explaining the mathematics behind it.

Explanation of momentum

• Momentum is where we add a temporal element into our equation for updating the parameters of a neural network – that is, an element of time.

- Let's add those elements now. the temporal element, the explanation of vtvt.
- If you want to play with momentum and learning rate, I recommend visiting distill's page for Why Momentum Really Works.
- https://distill.pub/2017/momentum/

Pros (Faster convergence than traditional SGD. Cons (Faster convergence than traditional SGD. (Faster convergence than traditional SGD.

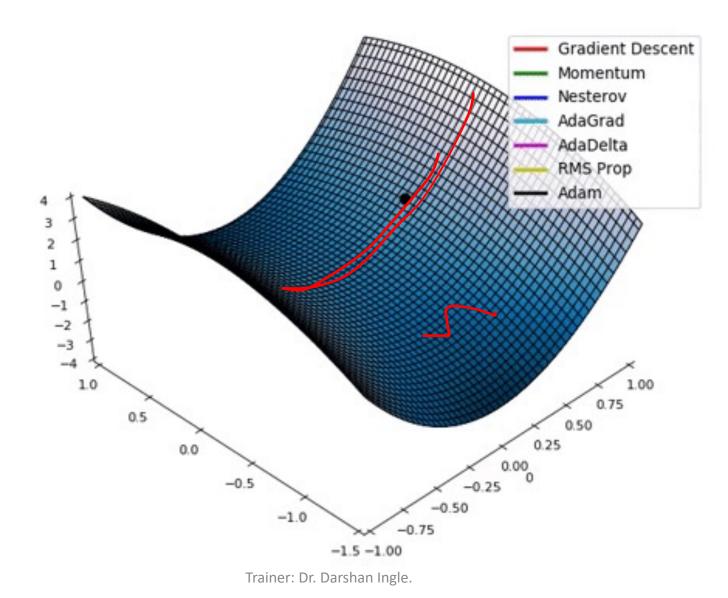
 Used in conjunction Stochastic Gradient Descent (sgd) or Mini-Batch Gradient Descent, Momentum takes into account past gradients to smooth out the update. This is seen in variable v which is an exponentially weighted average of the gradient on previous steps. This results in minimizing oscillations and faster convergence.

$$egin{aligned} v_{dW} &= eta v_{dW} + (1-eta) rac{\partial \mathcal{J}}{\partial W} \ W &= W - lpha v_{dW} \end{aligned}$$

Note

- ullet v the exponentially weighted average of past gradients
- $\frac{\partial \mathcal{J}}{\partial W}$ cost gradient with respect to current layer weight tensor
- ullet W weight tensor
- eta hyperparameter to be tuned
- lpha the learning rate

- Adaptive Moment Estimation (Adam) is the next optimizer, and probably also the optimizer that performs the best on average. Taking a big step forward from the SGD algorithm to explain Adam does require some explanation of some clever techniques from other algorithms adopted in Adam, as well as the unique approaches Adam brings.
- Adam uses Momentum and Adaptive Learning Rates to converge faster. We have already explored what Momentum means, now we are going to explore what adaptive learning rates means.



- Adaptive Moment Estimation (Adam) combines ideas from both RMSProp and Momentum. It computes adaptive learning rates for each parameter and works as follows.
- First, it computes the exponentially weighted average of past gradients (v_{dW}) .
- Second, it computes the exponentially weighted average of the squares of past gradients (s_{dW}) .
- Third, these averages have a bias towards zero and to counteract this a bias correction is applied $(v_{dW}^{corrected}, s_{dW}^{corrected})$.

Lastly, the parameters are updated using the information from the

calculated averages.

$$egin{aligned} v_{dW} &= eta_1 v_{dW} + (1-eta_1) rac{\partial \mathcal{J}}{\partial W} \ s_{dW} &= eta_2 s_{dW} + (1-eta_2) (rac{\partial \mathcal{J}}{\partial W})^2 \ v_{dW}^{corrected} &= rac{v_{dW}}{1-(eta_1)^t} \ s_{dW}^{corrected} &= rac{s_{dW}}{1-(eta_1)^t} \ W &= W - lpha rac{v_{dW}^{corrected}}{\sqrt{s_{dW}^{corrected}} + arepsilon} \end{aligned}$$

Note

- v_{dW} the exponentially weighted average of past gradients
- ullet s_{dW} the exponentially weighted average of past squares of gradients
- β_1 hyperparameter to be tuned
- eta_2 hyperparameter to be tuned
- $\frac{\partial \mathcal{J}}{\partial W}$ cost gradient with respect to current layer
- ullet W the weight matrix (parameter to be updated)
- α the learning rate
- ullet ϵ very small value to avoid dividing by zero

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