Paths in Graphs: Most Direct Route

Michael Levin

Higher School of Economics

Graph Algorithms Data Structures and Algorithms

Outline

- Paths and Distances
- 2 Breadth-first Search
- 3 Implementation and Analysis
- 4 Proof of Correctness
- 5 Shortest-path Tree

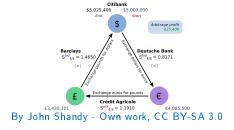












The most direct route

What is the minimum number of flight segments to get from Hamburg to Moscow?

The most direct route

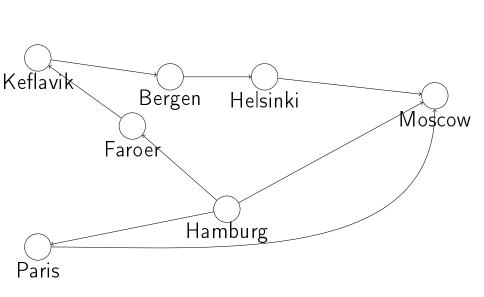
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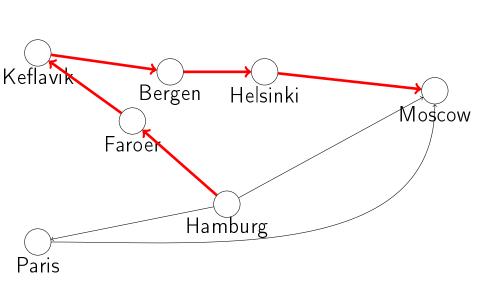


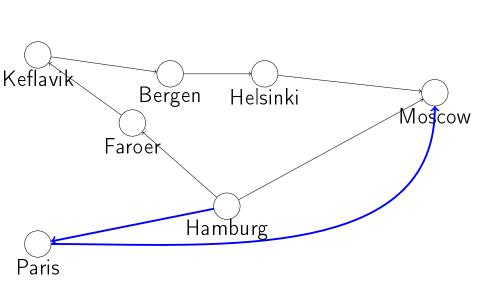
The most direct route

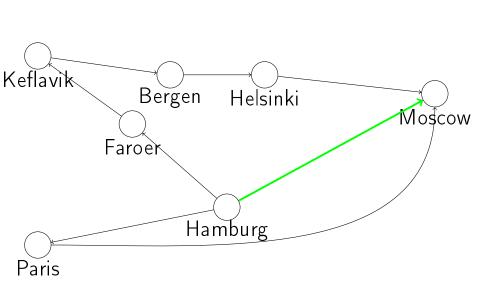
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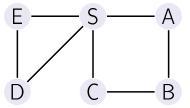






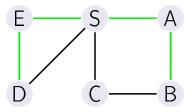
Paths and lengths

Length of the path L(P) is the number of edges in the path.



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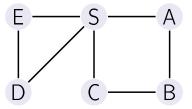
$$L(D-E-S-A-B)=4$$

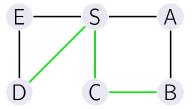
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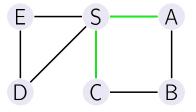
$$L(D - E - S - A - B) = 4$$

 $L(D - S - C - B) = 3$

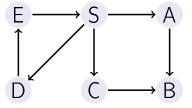


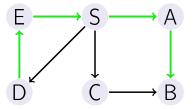


$$d(D, B) = 3$$

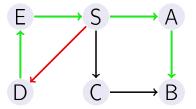


$$d(D,B) = 3$$
$$d(C,A) = 2$$

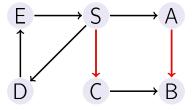




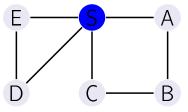
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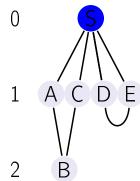
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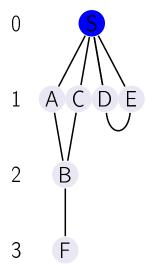


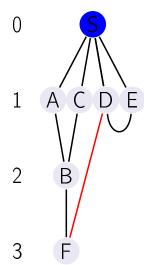
$$d(D,B) = 4$$
$$d(C,A) = \infty$$

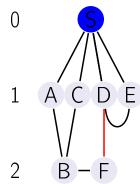


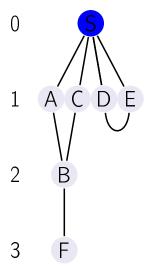


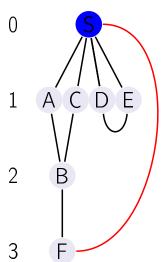


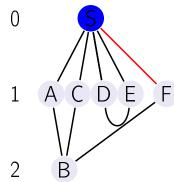


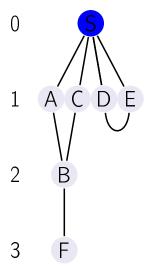


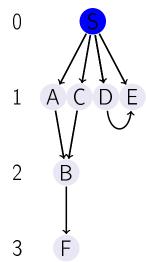


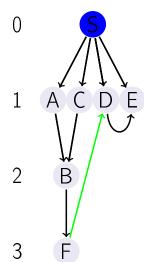


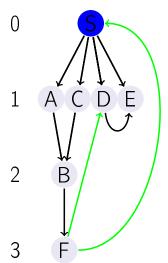




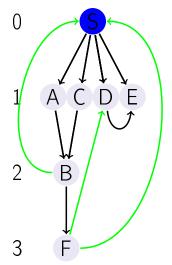




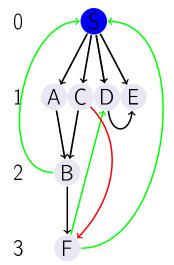




Distance layers

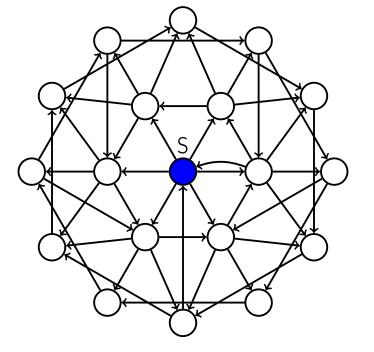


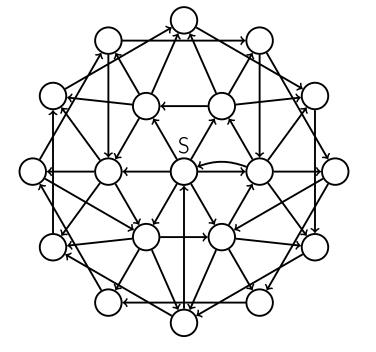
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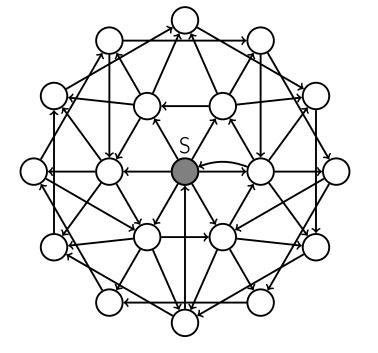


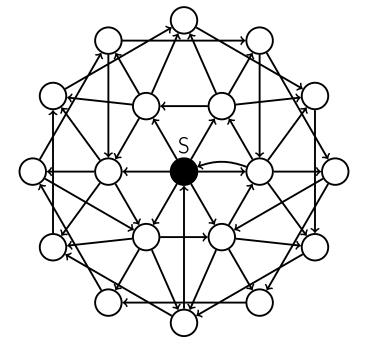
Outline

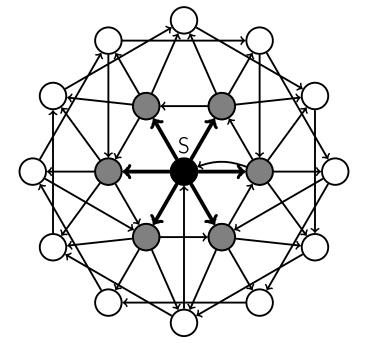
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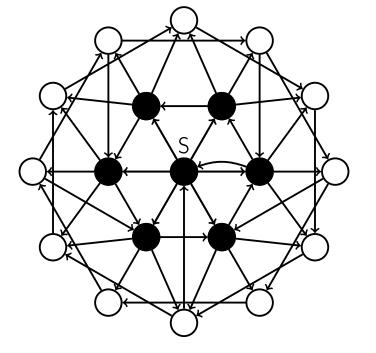


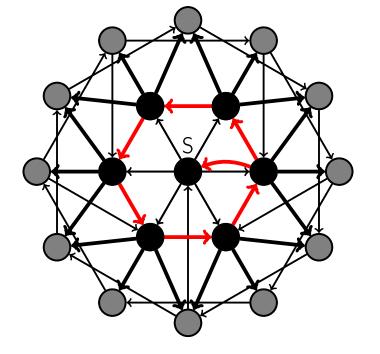


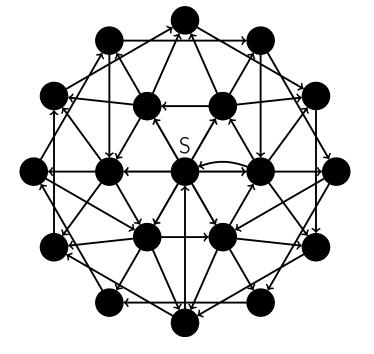


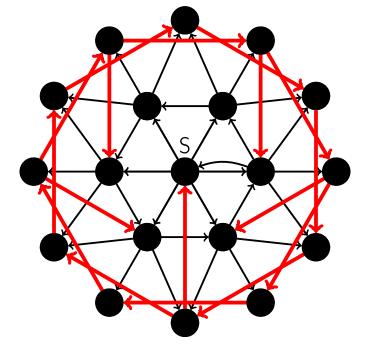


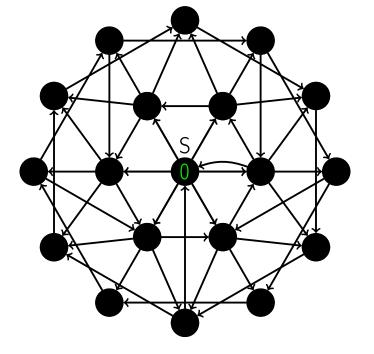


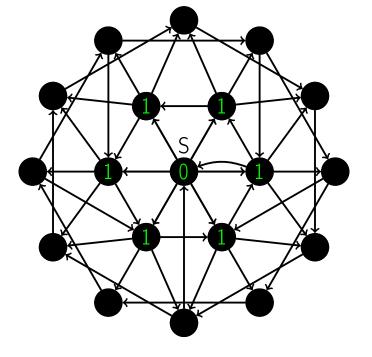


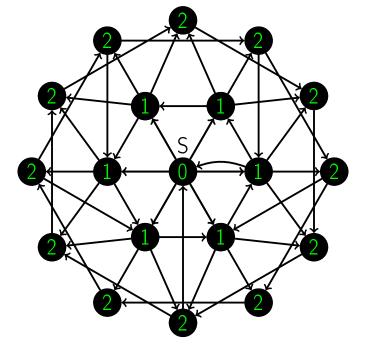


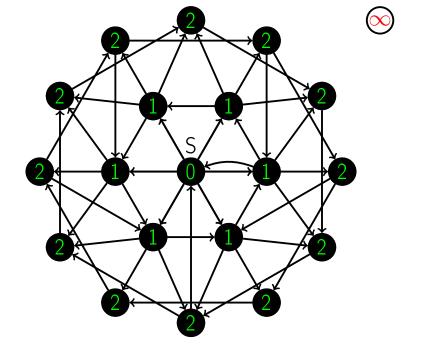


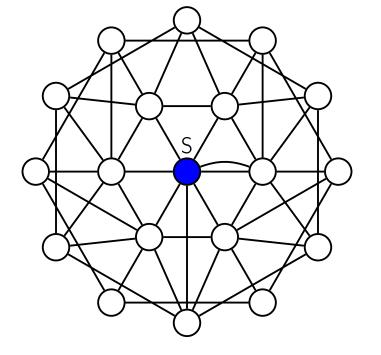


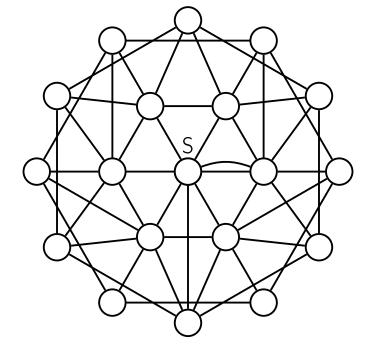


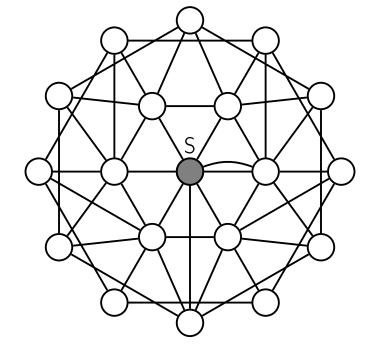


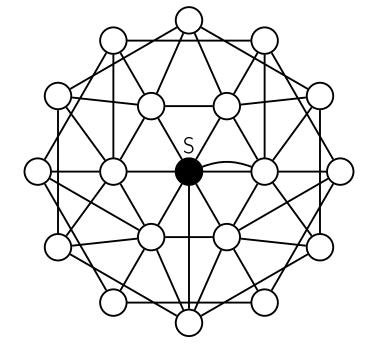


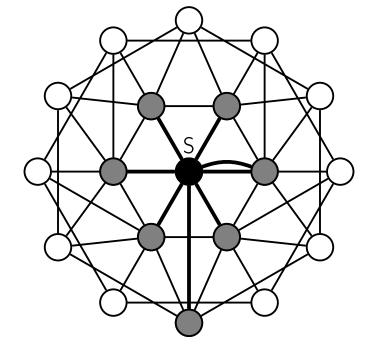


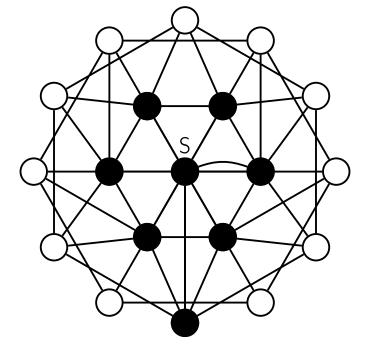


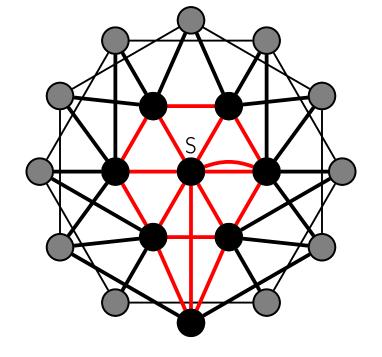


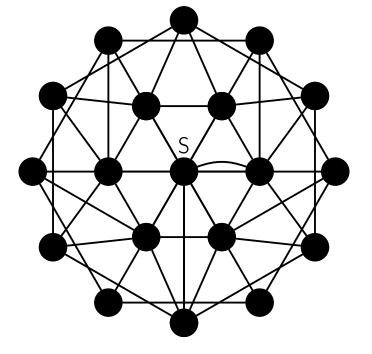


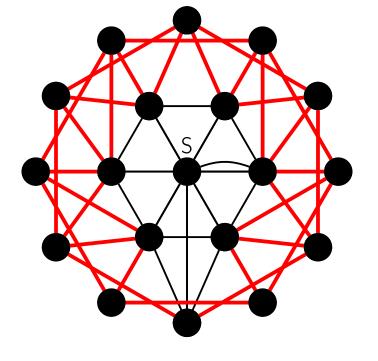


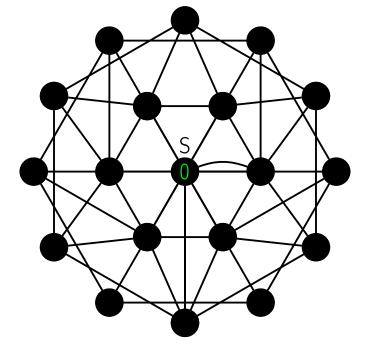


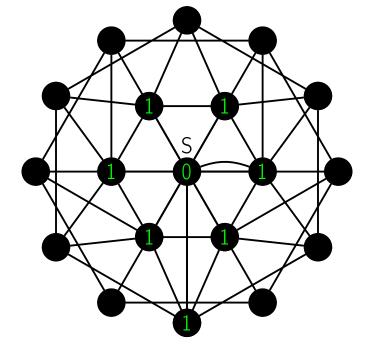


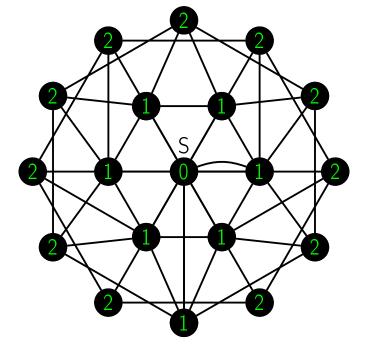


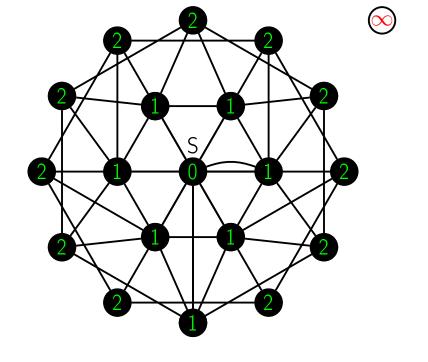


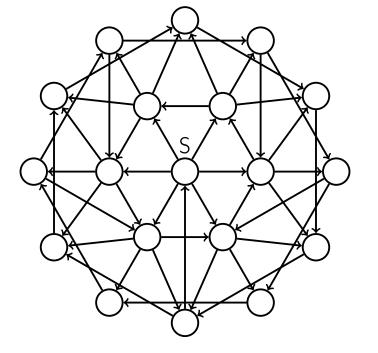


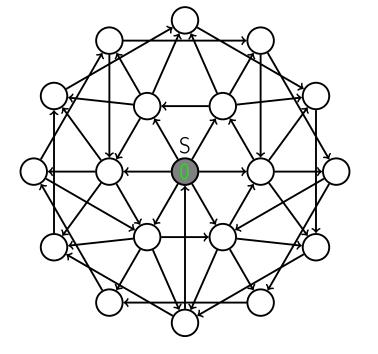


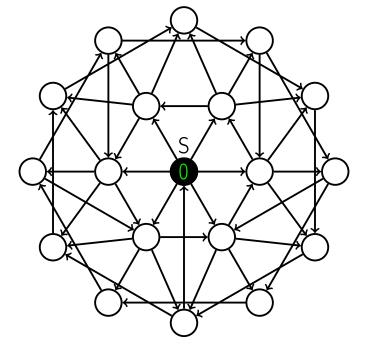


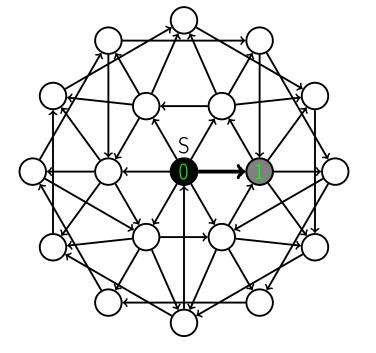


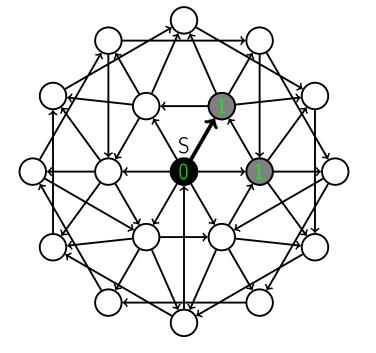


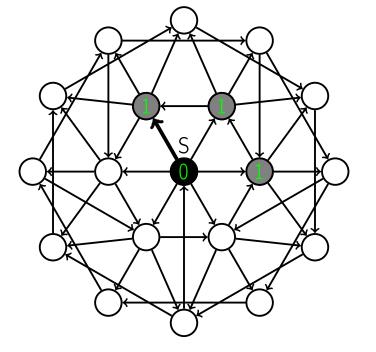


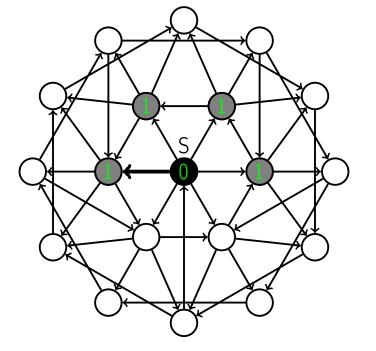


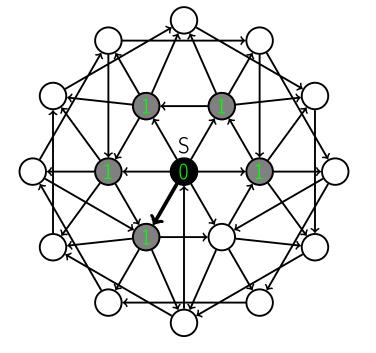


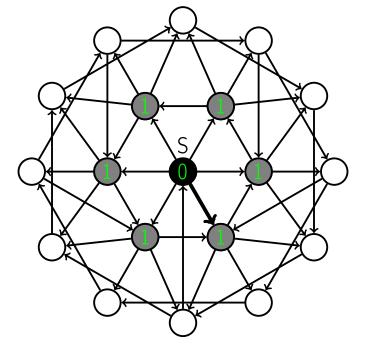


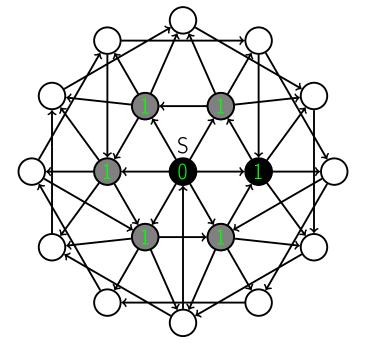


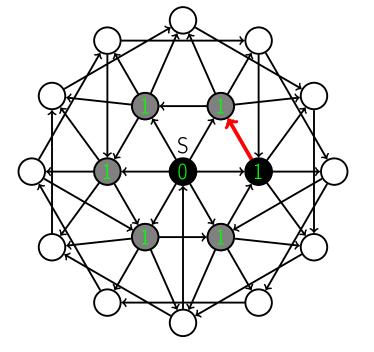


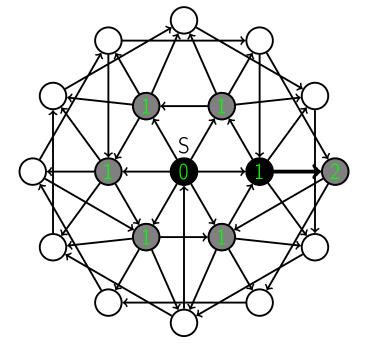


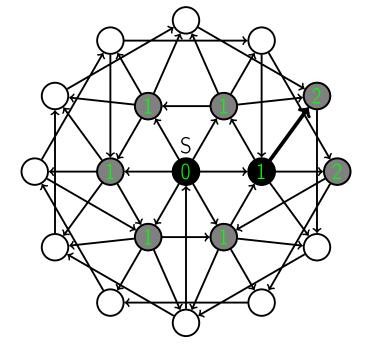


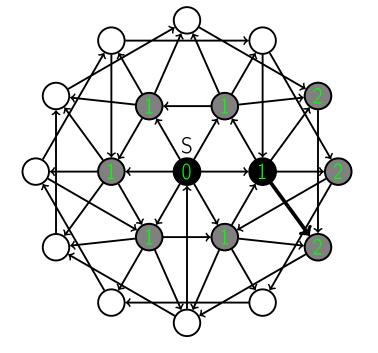


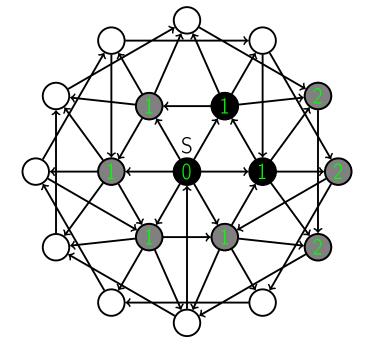


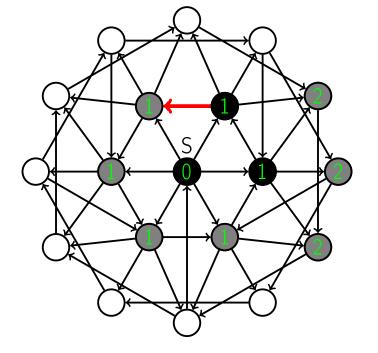


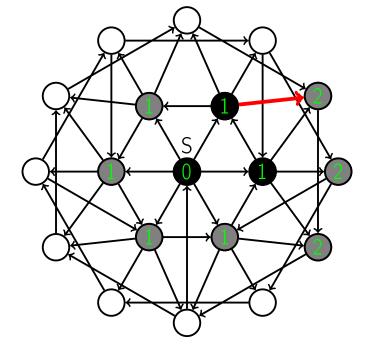


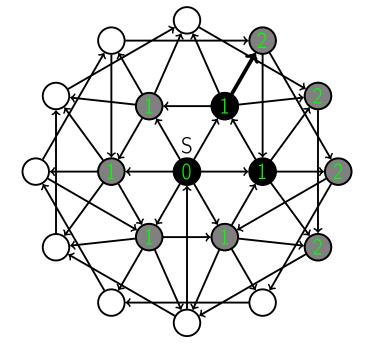


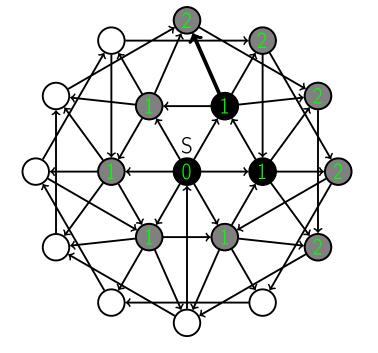


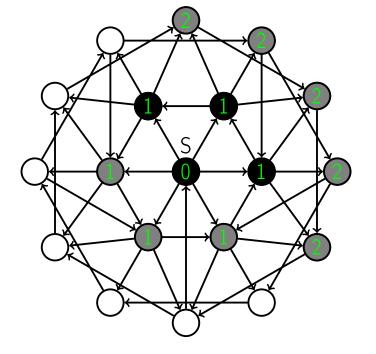


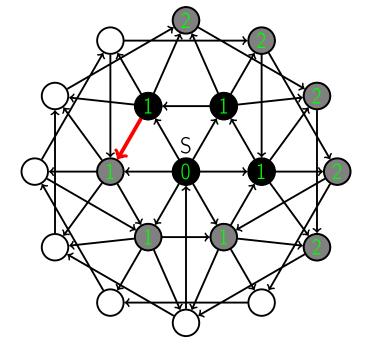


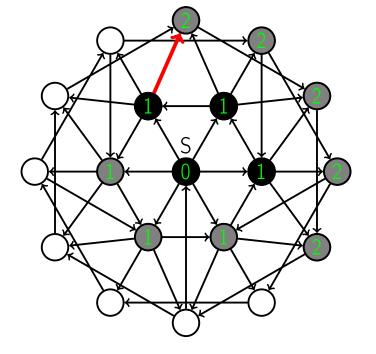


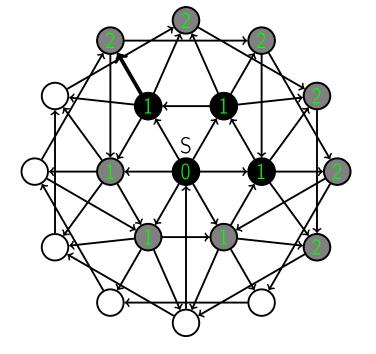


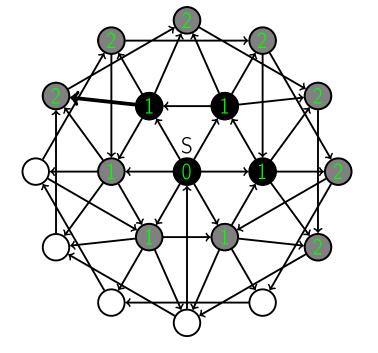


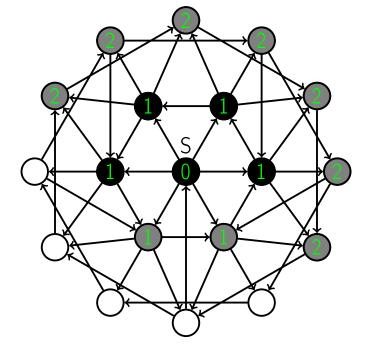


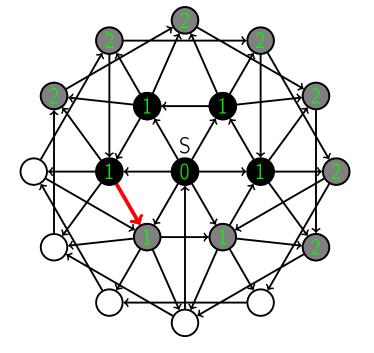


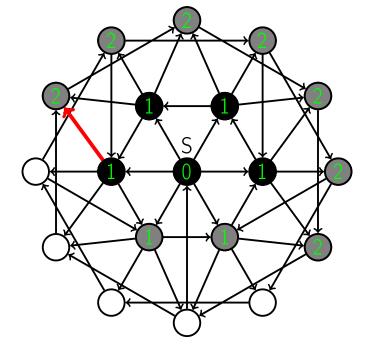


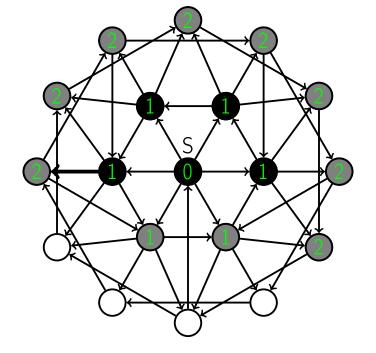


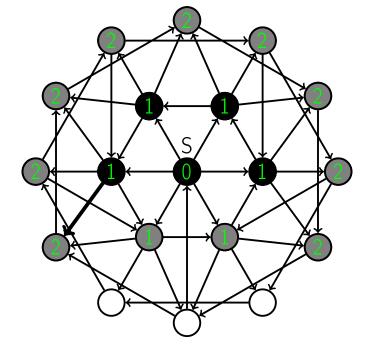


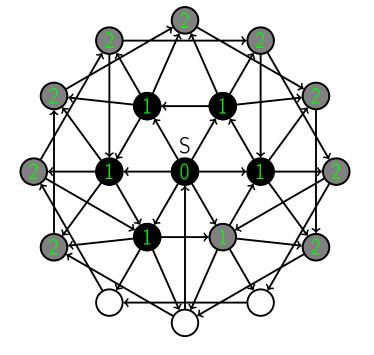


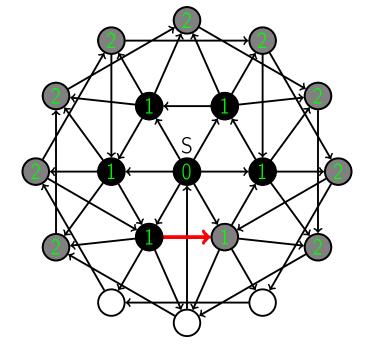


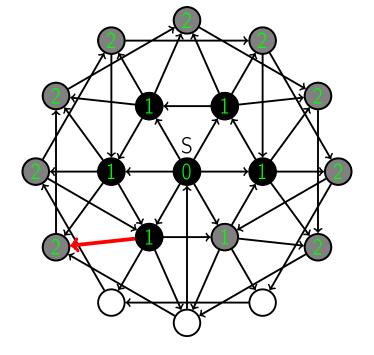


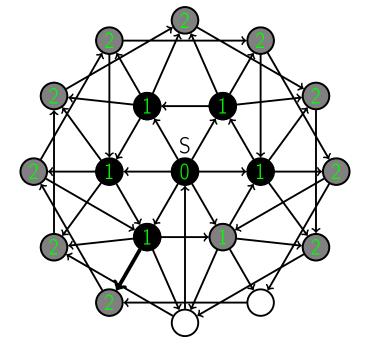


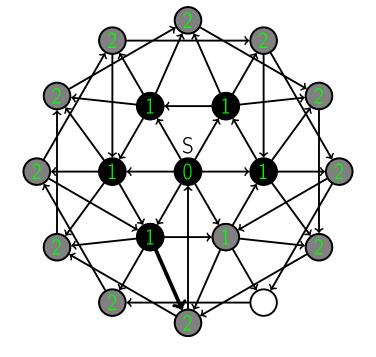


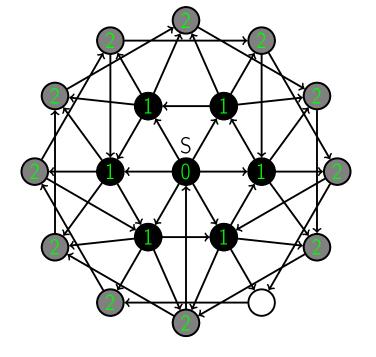


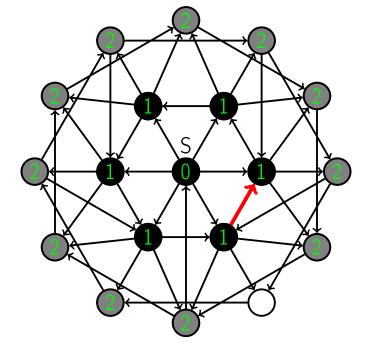


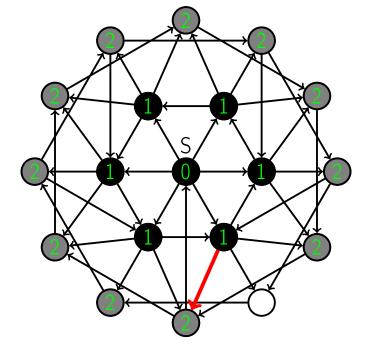


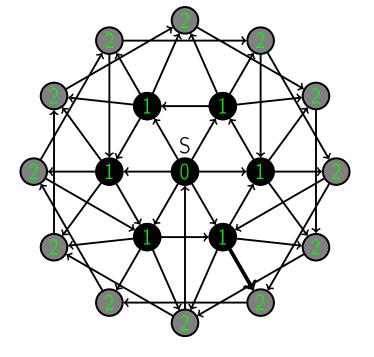


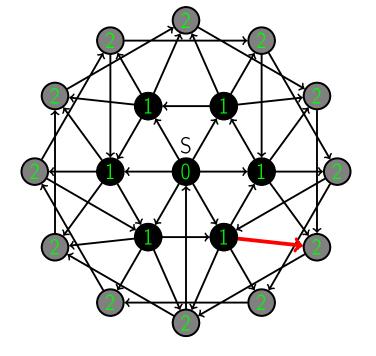


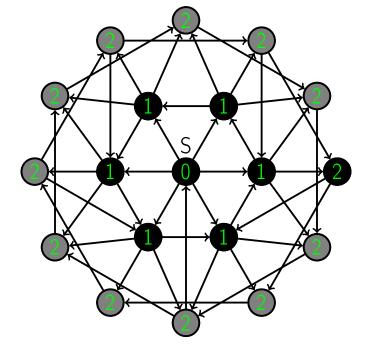


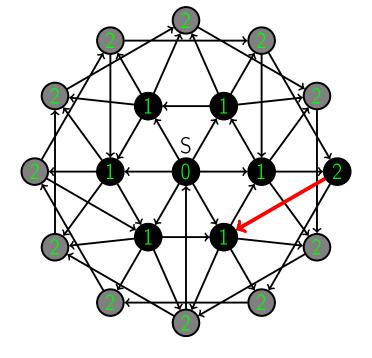


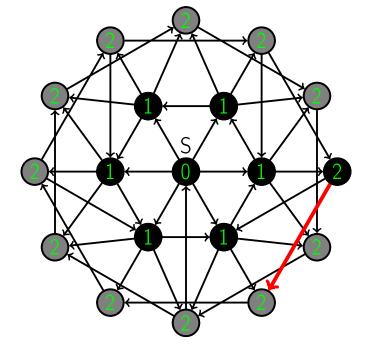


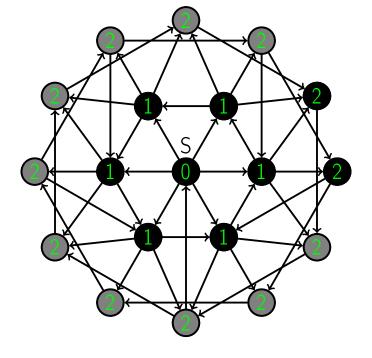


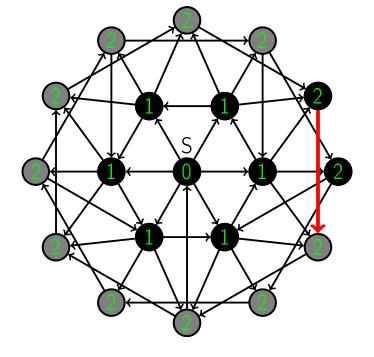


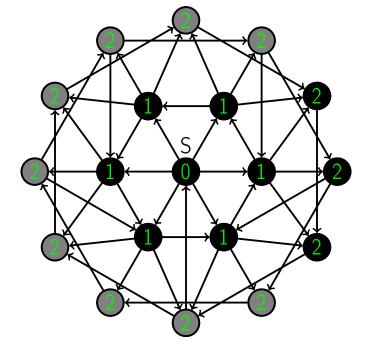


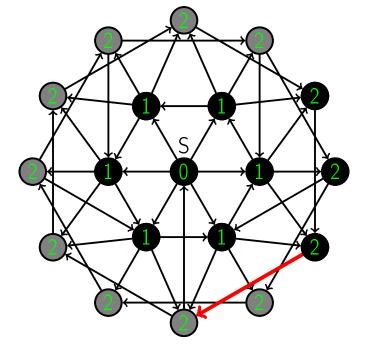


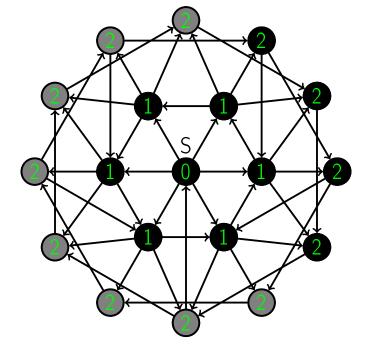


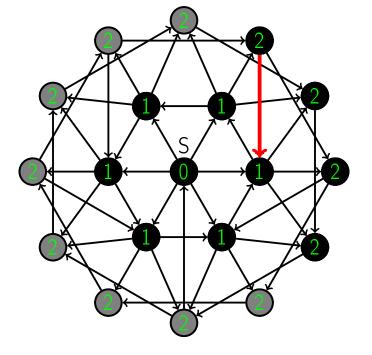


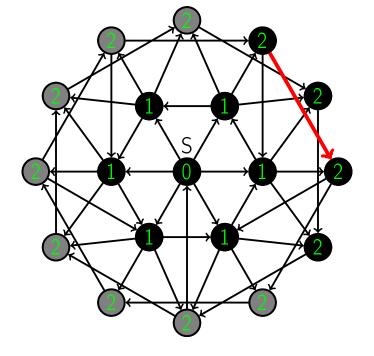


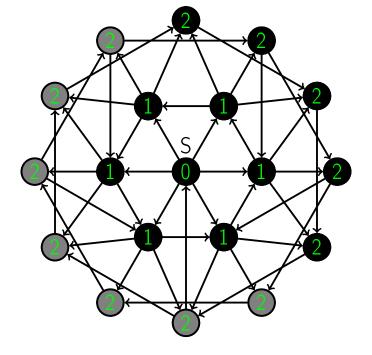


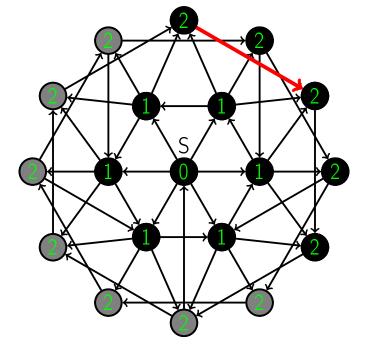


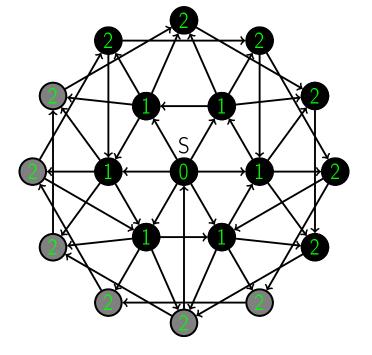


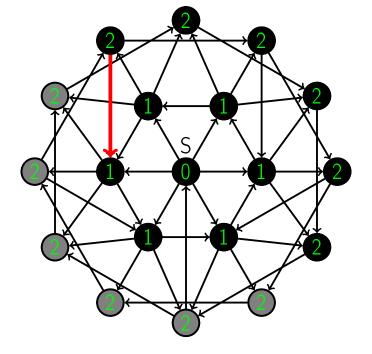


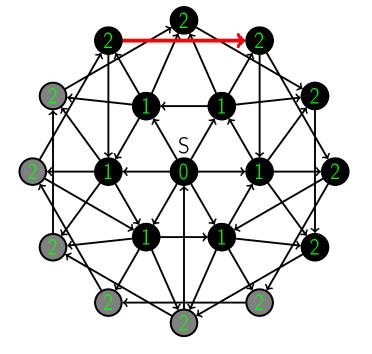


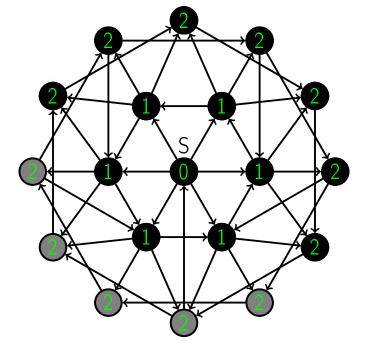


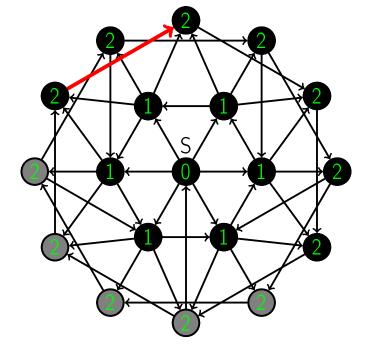


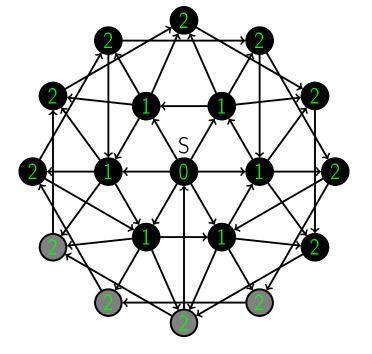


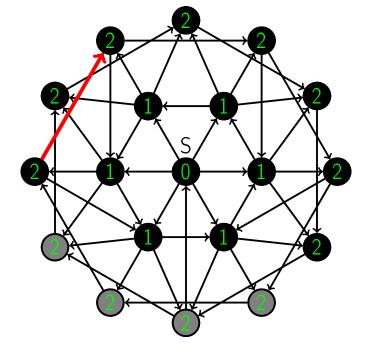


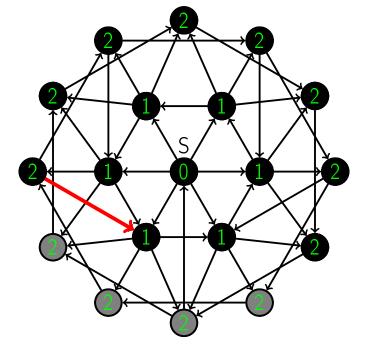


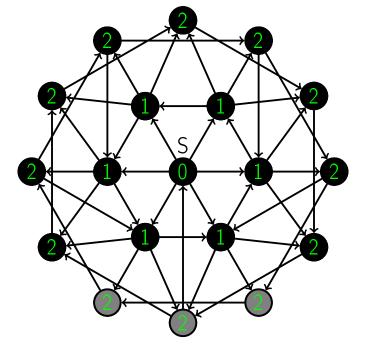


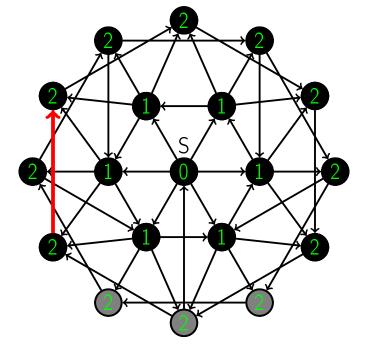


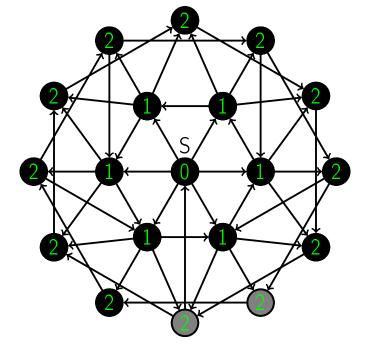


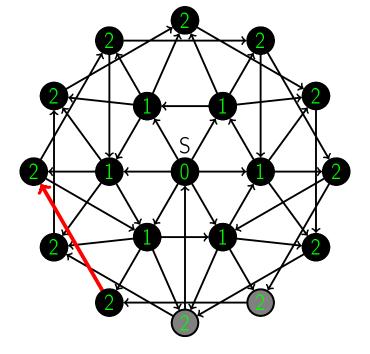


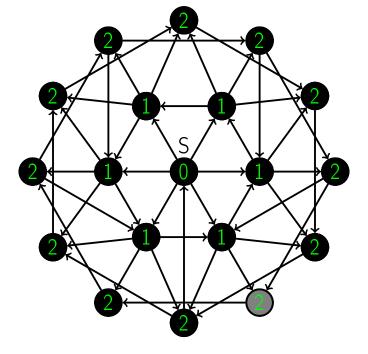


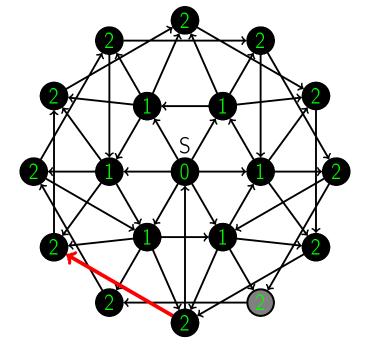


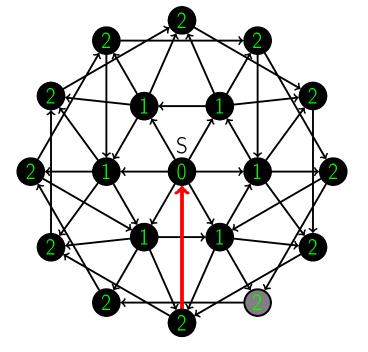


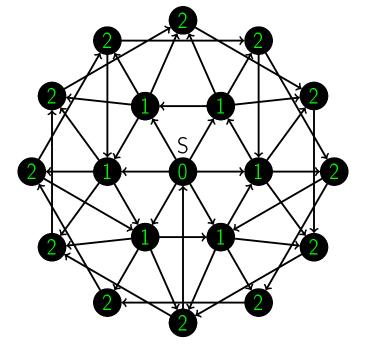


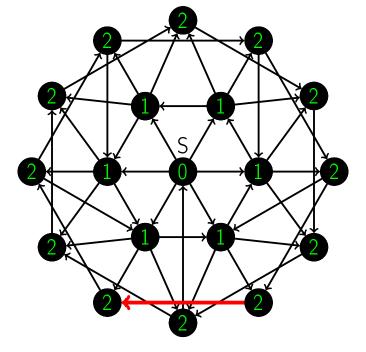


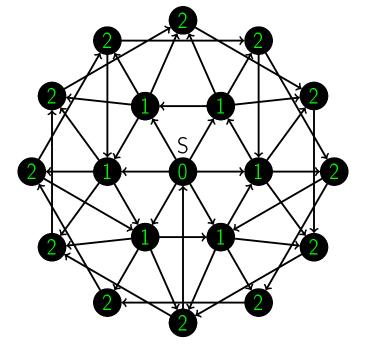


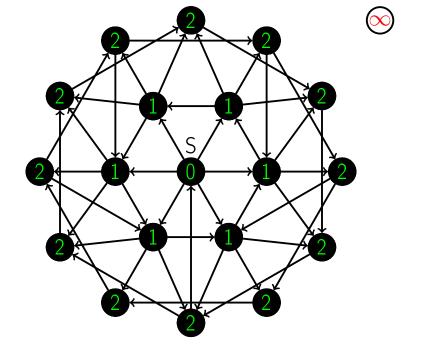












Outline

- Paths and Distances
- 2 Breadth-first Search
- 3 Implementation and Analysis
- 4 Proof of Correctness
- Shortest-path Tree

Breadth-first search

BFS(G,S)

```
for all u \in V:
   dist[u] \leftarrow \infty
dist[S] \leftarrow 0
Q \leftarrow \{S\} {queue containing just S}
while Q is not empty:
   u \leftarrow \text{Dequeue}(Q)
   for all (u, v) \in E:
      if dist[v] = \infty:
         Enqueue(Q, v)
          \operatorname{dist}[v] \leftarrow \operatorname{dist}[u] + 1
```

Running time

Lemma

The running time of breadth-first search is O(|E| + |V|).

Proof

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Each vertex is enqueued at most once

Running time

Lemma

The running time of breadth-first search is O(|E| + |V|).

Proof

- Each vertex is enqueued at most once
- Each edge is examined either once (for directed graphs) or twice (for undirected graphs)

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Reachability

Definition

Node u is reachable from node S if there is a path from S to u

Lemma

Reachable nodes are discovered at some point, so they get a finite distance estimate from the source. Unreachable nodes are not discovered at any point, and the distance to them stays infinite.

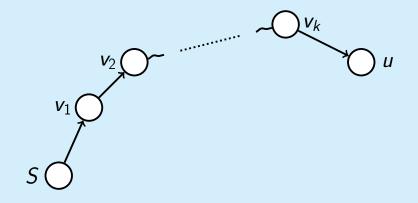
Proof

) u

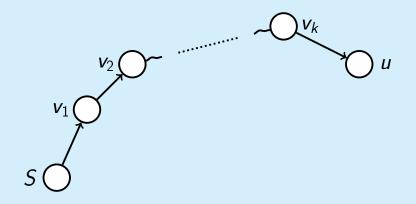
 $S \bigcirc$

lacksquare u — reachable undiscovered closest to S

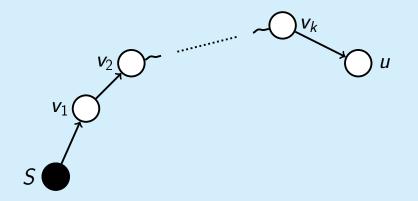
Proof



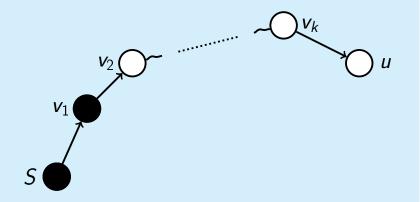
- lacktriangleq u reachable undiscovered closest to S
- lacksquare $S-v_1-\cdots-v_k-u$ shortest path



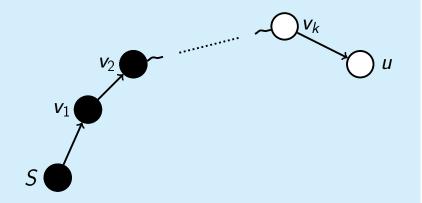
- u reachable undiscovered closest to S■ $S - v_1 - \cdots - v_k - u$ — shortest path
- \mathbf{u} is discovered while processing \mathbf{v}_k



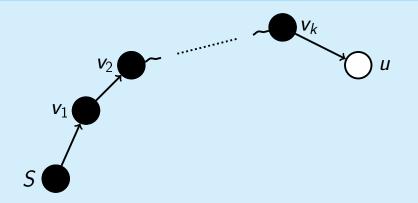
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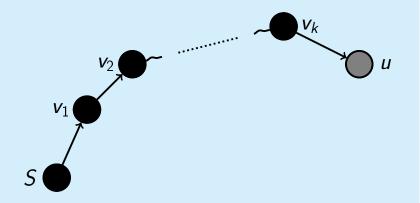
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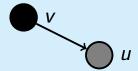


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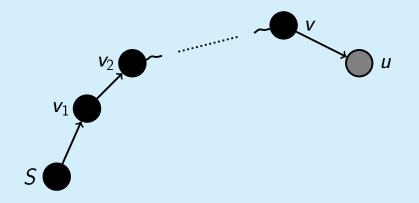


■ *u* — first unreachable discovered





- *u* first unreachable discovered
- *u* was discovered while processing *v*



- *u* first unreachable discovered
- *u* was discovered while processing *v*
- *u* is reachable through *v*

Order Lemma

Lemma

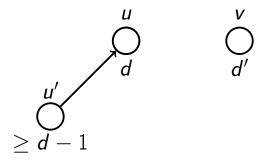
By the time node u at distance d from S is dequeued, all the nodes at distance at most d have already been discovered (enqueued).



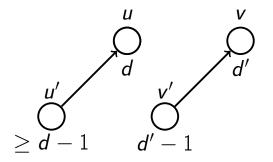
Consider the first time the order was broken



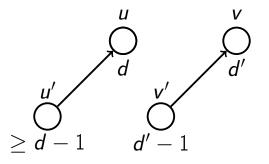
Consider the first time the order was broken $d' \leq d$

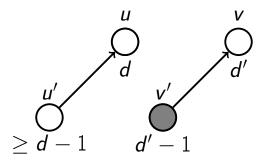


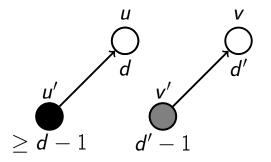
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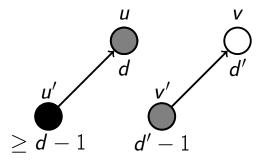


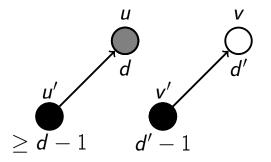
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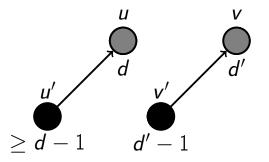


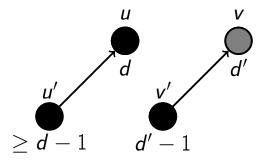












Lemma

When node u is discovered (enqueued), dist[u] is assigned exactly d(S, u).

Proof

■ Use mathematical induction

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- Base: when S is discovered, dist[S] is assigned 0 = d(S, S)

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- Inductive step: suppose proved for all nodes at distance $\leq k$ from $S \rightarrow$ prove for nodes at distance k+1

Proof

■ Take a node v at distance k+1 from S

- Take a node v at distance k+1 from S
- v was discovered while processing u

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- $d(S, v) \leq d(S, u) + 1 \Rightarrow d(S, u) \geq k$

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- ullet v is discovered after u is dequeued, so d(S,u) < d(S,v) = k+1
- So d(S, u) = k, and $\operatorname{dist}[v] \leftarrow \operatorname{dist}[u] + 1 = k + 1$

Queue: $d \mid d \mid d \mid \ldots \mid d \mid d \mid d + 1 \mid d + 1 \mid \ldots \mid d + 1 \mid$

Lemma

At any moment, if the first node in the queue is at distance d from S, then all the nodes in the queue are either at distance d from S or at distance d+1 from S. All the nodes in the queue at distance d go before (if any) all the nodes at distance d+1.

Proof

All nodes at distance d were enqueued before first such node is dequeued, so they go before nodes at distance d+1

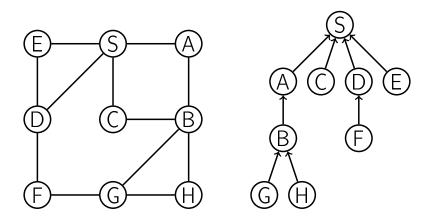
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- Nodes at distance d-1 were enqueued before nodes at d, so they are not in the queue anymore
- Nodes at distance > d + 1 will be discovered when all d are gone

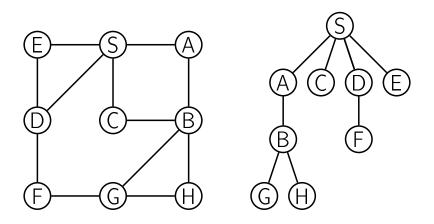
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Shortest-path tree

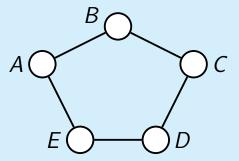


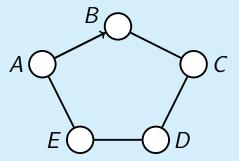
Shortest-path tree

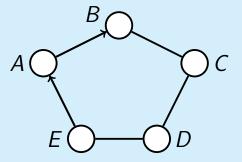


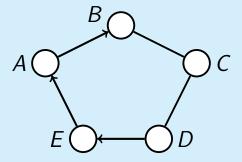
Lemma

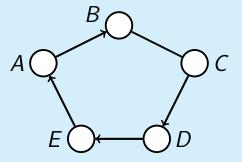
Shortest-path tree is indeed a tree, i.e. it doesn't contain cycles (it is a connected component by construction).

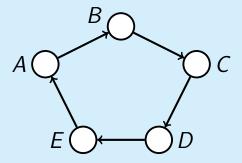


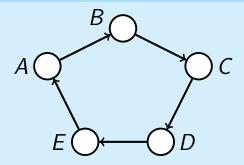




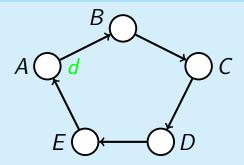




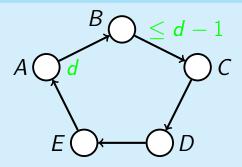




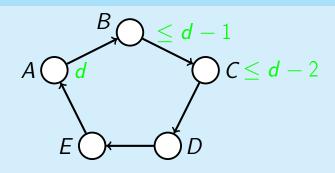
- Only one outgoing edge from each node
- Distance to S decreases after going by edge



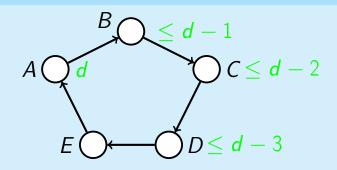
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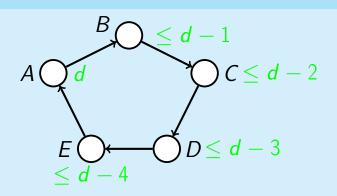
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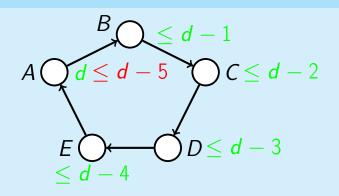
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- Only one outgoing edge from each node
- Distance to *S* decreases after going by edge



- Only one outgoing edge from each node
- Distance to S decreases after going by edge



- Only one outgoing edge from each node
- $lue{}$ Distance to S decreases after going by edge

Constructing shortest-path tree

BFS(G, S)

```
for all u \in V:
   dist[u] \leftarrow \infty, prev[u] \leftarrow nil
dist[S] \leftarrow 0
Q \leftarrow \{S\} {queue containing just S}
while Q is not empty:
   u \leftarrow \text{Dequeue}(Q)
   for all (u, v) \in E:
       if dist[v] = \infty:
          Enqueue(Q, v)
          \operatorname{dist}[v] \leftarrow \operatorname{dist}[u] + 1, \operatorname{prev}[v] \leftarrow u
```

Reconstructing Shortest Path

ReconstructPath(S, u, prev)

```
result \leftarrow empty
while u \neq S:
result.append(u)
u \leftarrow \text{prev}[u]
return Reverse(result)
```

 Can find the minimum number of flight segments to get from one city to another

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- Works in O(|E| + |V|)