## Advanced Set Representation Methods

AVL trees. 2-3(-4) Trees. Union-Find Set ADT

#### **Advanced Set Representation. AVL Trees**

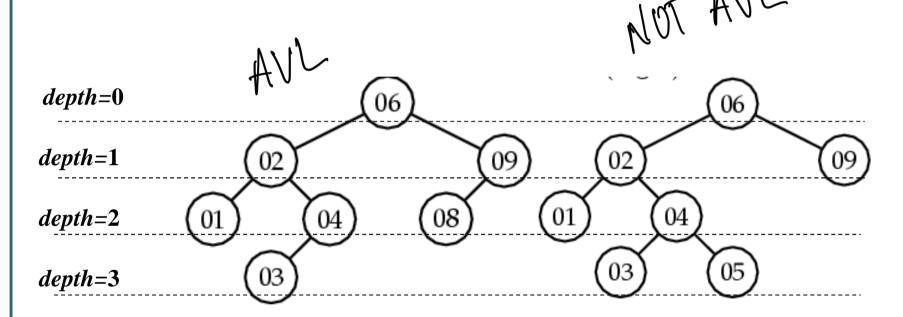
- Problem with BSTs: worst case operation may take O(n) time. One solution:
- AVL tree: binary search tree with a balance condition:

For every node in an AVL tree T, the height of the left  $(T_{\rm L})$  and right  $(T_{\rm R})$  subtrees can differ by at most 1:  $|h_L - h_R| \le 1$ 

- Balance condition must be easy to maintain, and it ensures that the tree depth is  $O(\log n)$
- Requiring that the left and right subtrees have the same height does not suffice (tree may not be shallow)

#### Two BSTs

Which BST is AVL?



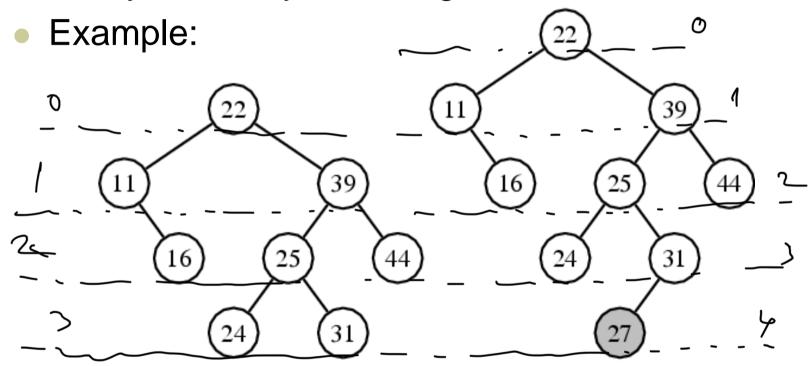
For every node in an AVL tree T, the height of the left  $(T_{\rm L})$  and right  $(T_{\rm R})$  subtrees can differ by at most 1:  $|h_L - h_R| \le 1$ 

## **AVL Tree Height**

- Claim: height of an AVL tree storing n keys is  $O(\log n)$
- Proof
  - Let n(h) denote the number of nodes of an AVL tree of height h.
  - It is easy to see that n(1) = 1 and n(2) = 2
  - For n > 2, an AVL tree of height h contains:
    - the root node,
    - one AVL subtree of height h-1 and
    - another of height h-2.
  - That is, n(h) = 1 + n(h-1) + n(h-2)
  - Knowing n(h-1) > n(h-2), we get n(h) > 2n(h-2). By induction n(h) > 2n(h-2), n(h) > 4n(h-4), n(h) > 8n(n-6), ...,  $n(h) > 2^{i}n(h-2i)$
  - Solving the base case we get:  $n(h) > 2^{h/2-1}$
  - Taking logarithms:  $h < 2\log n(h) + 2$
- Thus the height of an AVL tree is  $O(\log n)$

#### **Insertion in an AVL Tree**

- Insertion is as in a binary search tree
- Always done by attaching an external node.



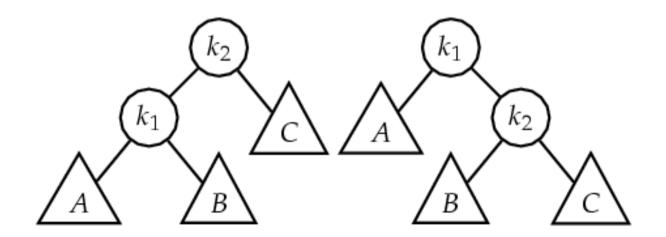
After insertion the tree may need rebalancing

## **AVL** tree rebalancing

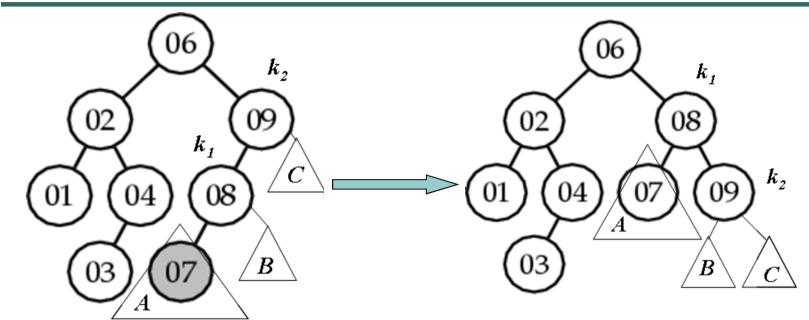
- Two kinds of rotation:
  - single rotation (left or right)
  - double rotation
    - **left-right**: *left rotation* around the *left child* of a node followed by a *right rotation* around the *node itself*
    - right-left: right rotation around the left child of a node followed by a left rotation around the node itself
- Rotation features:
  - Nodes not in the subtree of the node rotated are unaffected
  - A rotation takes constant time
  - Before and after the rotation tree is still BST
  - Code for left rotation is symmetric to code for a right rotation

## **AVL Single Rotations**

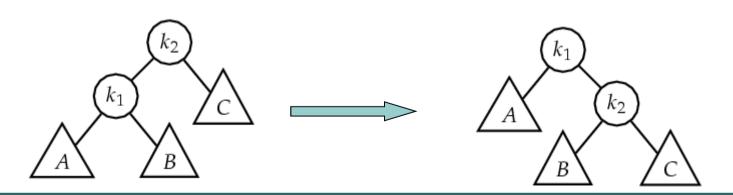
- Single Rotation
  - $k_1 < k_2$
  - lacktriangle all elements in subtree  $oldsymbol{A}$  are smaller than  $k_1$
  - lacktriangle all elements in subtree C are larger than  $k_2$
  - lacktriangle all elements in subtree B are in between  $k_1$  and  $k_2$



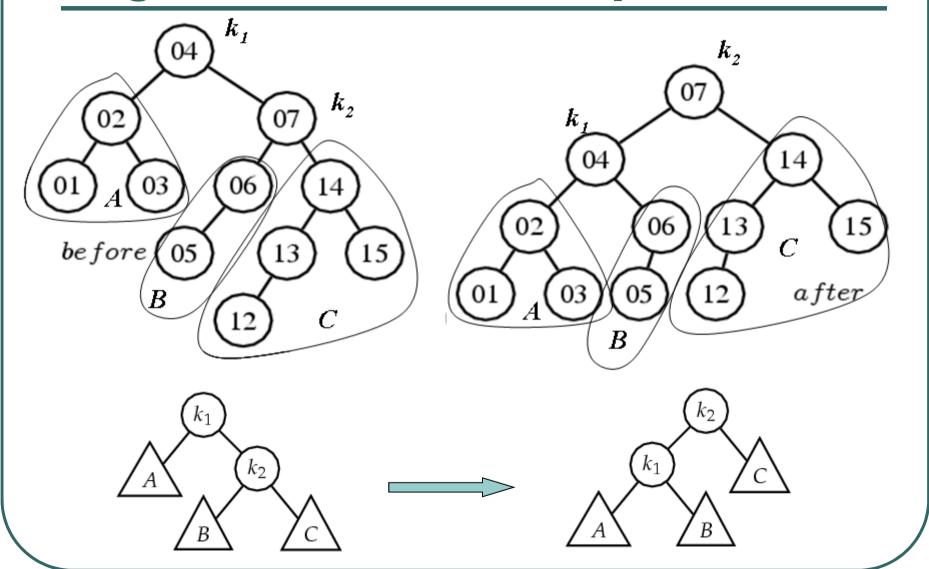
## **Single Rotation Right Example**



Note that subtrees B and C are empty



## **Single Rotation Left Example**



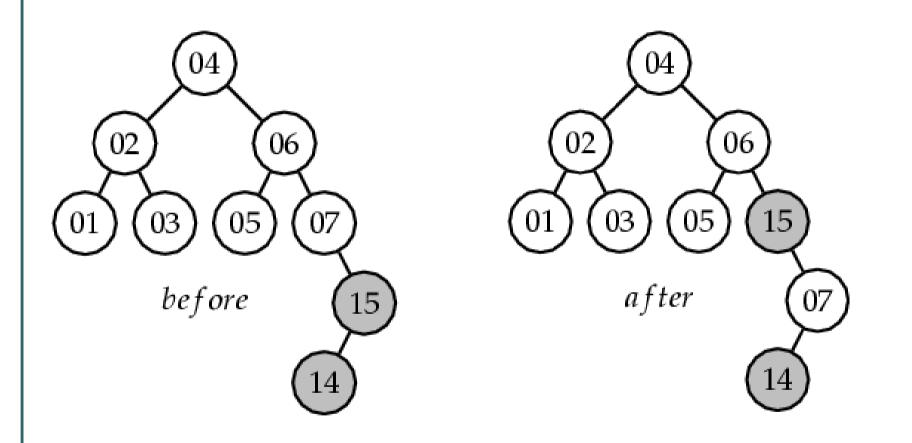
## **AVL Implementation Detail**

```
typedef struct
  ElementT element;
 AVLPtr left;
 AVLPtr right;
  int height;
} AVLNode;
typedef AVLNode *AVLPtr;
```

## **AVL Single Rotations**

```
void snglRotRight( AVLPtr *k2 )
 AVLPtr k1;
 k1 = (*k2)->left;
 (*k2)->left = k1->right;
 k1->right = *k2;
 (*k2)->height = max(height)
   (*k2)->left),
              height( (*k2)->right)
   ) + 1;
 k1->height = max( height( k1-
   >left),
            (*k2)->height) + 1;
 *k2 = k1; /* assign new root */
/* snglRotLeft is symmetric */
```

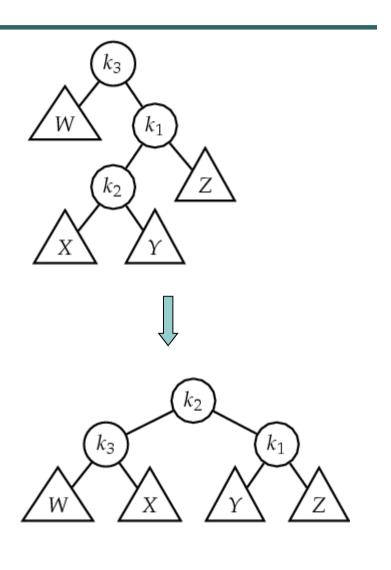
## **Single Rotation not enough**



#### **AVL Double Rotation**

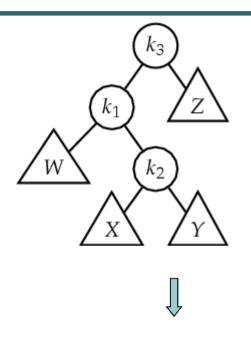
- Right-left
  - $k_2 < k_1, k_3 < k_1, k_3 < k_2$
  - right rotation around the left child of a node followed by
  - a left rotation around the node itself
  - Rotate to make k<sub>2</sub> topmost node

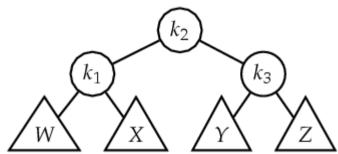
```
void dblRotLeft( AVLPtr k3 )
{
    /* rotate between k1 and k2 */
    snglRotRight ( (*k3)->left );
    /* rotate between k3 and k2 */
    snglRotLeft ( k3 );
```



#### **AVL Double Rotation**

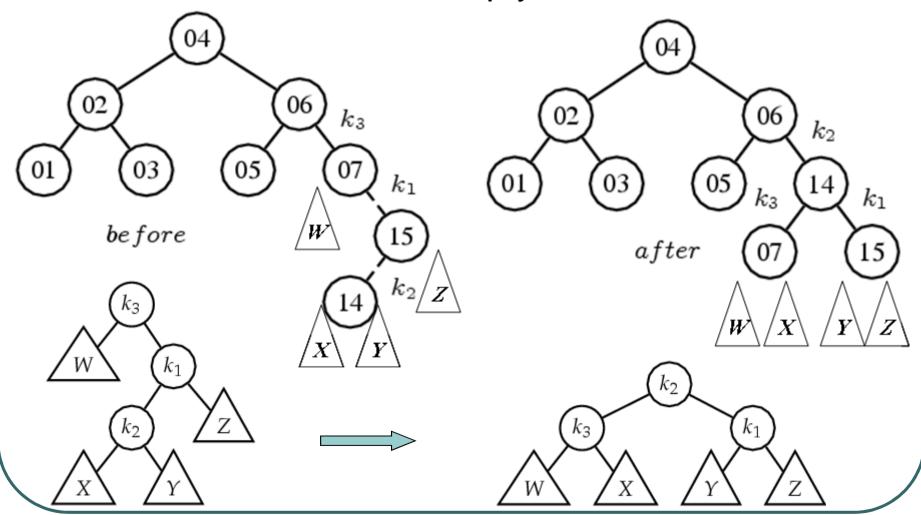
- Left-right:
  - $k_1 < k_2, k_1 < k_3, k_2 < k_3$
  - left rotation around the left child of a node followed by a
  - right rotation around the node itself
  - Rotate to make  $k_2$  topmost node





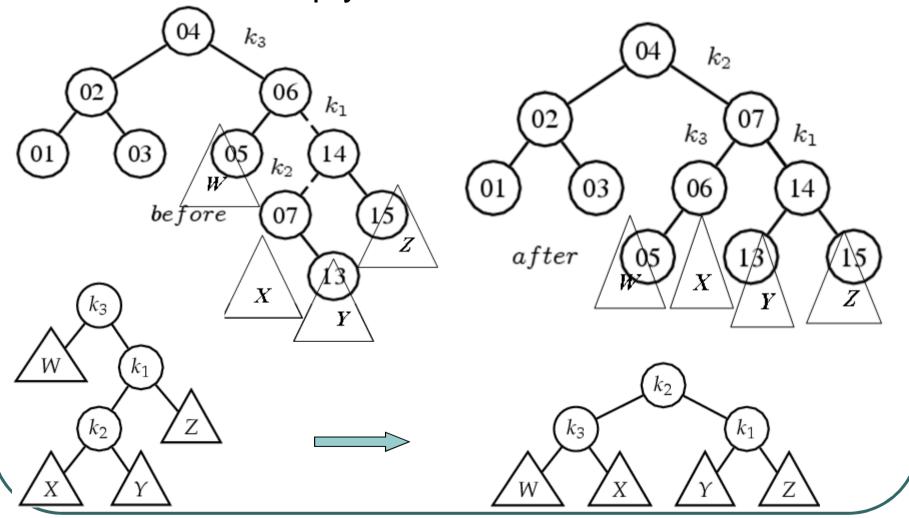
## **AVL Right-left Double Rotation Example 1**

Subtrees W, X, Y, Z are empty



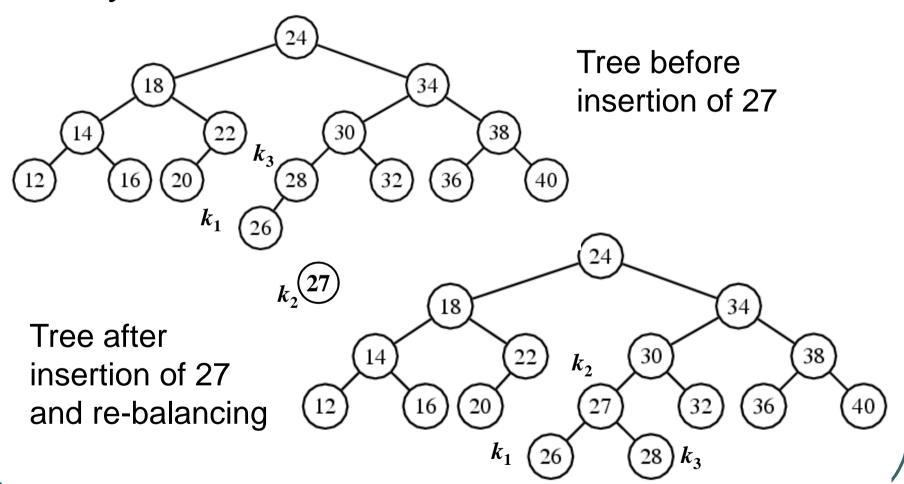
## **AVL Right-left Double Rotation Example 2**

Subtree X is empty



## **AVL Double Rotation example**

A symmetric case of double rotation



#### **AVL Trees. When to use rotations**

- Balance factor:  $height(T_L) height(T_R)$
- Use
  - Single rotation left: when a node is inserted in the right subtree of the right child (B) of the nearest ancestor (A) with balance factor -2
  - Single rotation right: when a node is inserted in the left subtree of the left child (B) of the nearest ancestor (A) with balance factor +2.
  - Right-left double rotation: when a node is inserted in the left subtree of the right child (B) of the nearest ancestor (A) with balance factor -2.
  - Left-right double rotation: when a node is inserted in the right subtree of the left child (B) of the nearest ancestor (A) with balance factor +2.

#### **AVL Trees. Deletions**

- A node is deleted using the standard inorder successor (predecessor) logic for binary search trees
- Imbalance is fixed using rotations
- Identify the parent of the actual node that was deleted, then:
  - If the left child was deleted, the balance factor at the parent decreased by 1.
  - If the right child was deleted, the balance factor at the parent increased by 1.

## **AVL Trees. Deletions. Rebalancing (I)**

- Let A be the node where balance must be restored.
- If the deleted node was in A's right subtree, then let B be the root of A's left subtree. Then:
  - B has balance factor 0 or +1 after deletion -- then perform a single right rotation
  - B has balance factor -1 after deletion -- then perform a left-right rotation
- If the deleted node was in A's left subtree, then let B be the root of A's right subtree. Then:
  - B has balance factor 0 or -1 after deletion -- then perform a single left rotation
  - B has balance factor +1 after deletion -- then perform a right-left rotation

## **AVL Trees. Deletions. Rebalancing (II)**

- Unlike insertion, one rotation may not be enough to restore balance to the tree. If this is the case, then locate the next node where the balance factor is "bad" (call this A):
- If A's balance factor is positive, then let B be A's left child
  - If B's left subtree height is larger than B's right subtree height, then perform a single right rotation.
  - If B's left subtree height is smaller than B's right subtree height, then perform a left-right rotation.
  - If B's left subtree height is equal to B's right subtree height, then perform either rotation.

## **AVL Trees. Deletions. Rebalancing (III)**

- If A's balance factor is negative, then let B be A's right child
  - If B's right subtree height is larger than B's left subtree height, then perform a single left rotation.
  - If B's right subtree height is smaller than B's left subtree height, then perform a right-left rotation.
  - If B's right subtree height is equal to B's left subtree height, then perform either rotation.

## **AVL** trees demo

Demos from:

http://webpages.ull.es/users/jriera/Docencia/AVL/AVL%20tree%20applet.htm

http://www.site.uottawa.ca/~stan/csi2514/applets/avl/BT.html

 Replacement for AVL trees: Red-Black trees (not discussed here)

## Running times for AVL tree operations

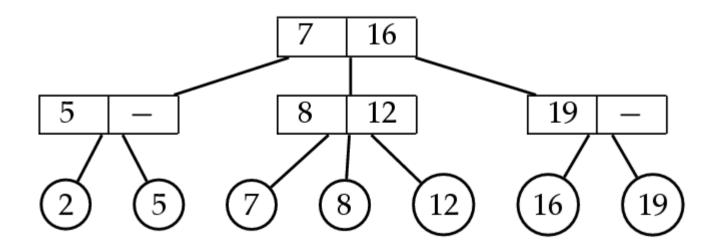
- a single restructure is O(1)
  - using a linked-structure binary tree
- find is  $O(\log n)$ 
  - height of tree is  $O(\log n)$ , no restructures needed
- insert is  $O(\log n)$ 
  - initial find is  $O(\log n)$
  - restructuring up the tree, maintaining heights is  $O(\log n)$
- remove is  $O(\log n)$ 
  - initial find is  $O(\log n)$
  - restructuring up the tree, maintaining heights is  $O(\log n)$

#### 2-3 Trees

- 2-3 tree properties:
  - Each interior node has two or three children.
  - Each path from the root to a leaf has the same length.
  - A tree with zero or one node(s) is a special case of a 2-3 tree.
- Representing sets with 2-3 trees:
  - Elements are placed at the leaves
  - If element a is to the left of element b, then a < b must hold.
  - Ordering of elements based on one field of a record: a key.
  - At each interior node: key of the smallest descendant of the second child and, if there is a third child, key of the smallest descendant of third child.

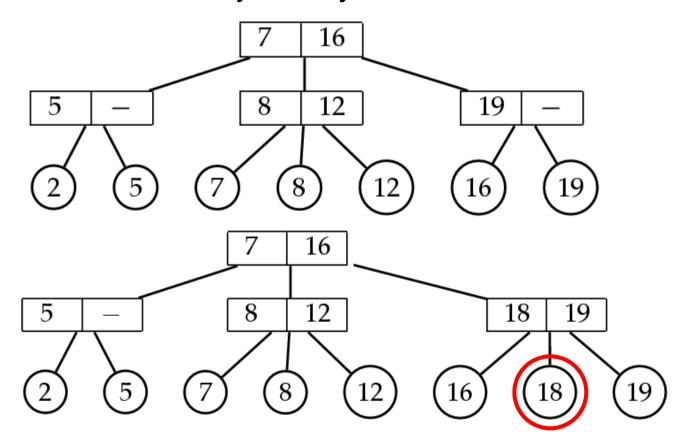
#### 2-3 trees

- A 2-3 tree of k levels has between  $2^{k-1}$  and  $3^{k-1}$  leaves, i.e.
  - representing a set of n elements requires at least  $1+\log_3 n$  levels and no more than  $1+\log_2 n$  levels. Thus, path lengths in the tree are  $O(\log n)$ .



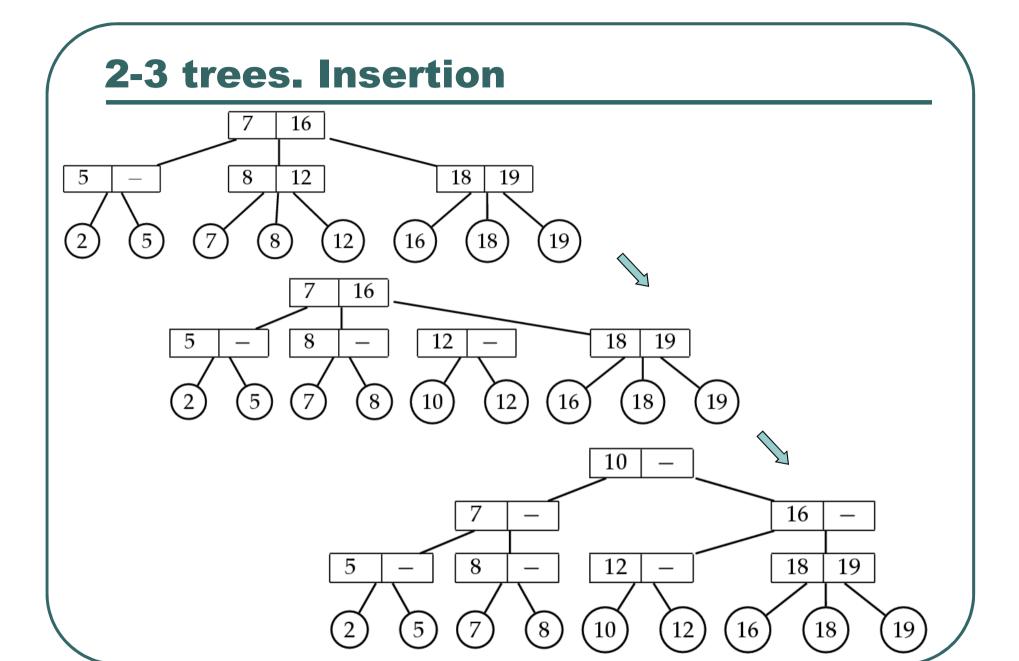
## 2-3 trees. Insertion - 2 children

- If parent node has only two children:
  - insert in order, adjust keys



#### 2-3 trees. Insertion - 3 children

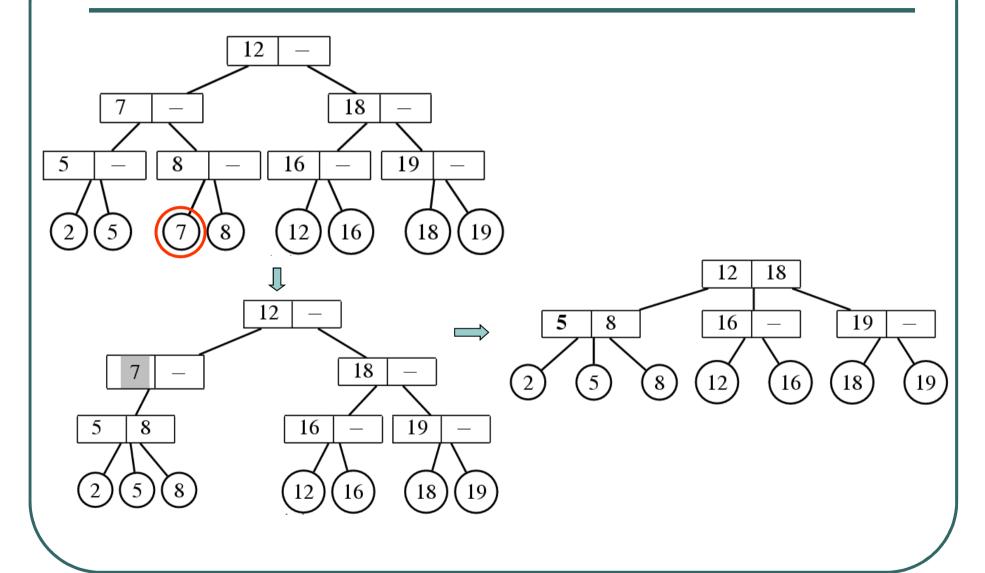
- If parent node node already has three children:
  - We cannot have four nodes, and thus we have to split parent in two nodes node and node'.
  - The two smallest elements among the four children of node stay with node,
  - The two larger will become the children of node'
  - Continue process up the tree
  - Special case when splitting the root



#### 2-3 trees. Deletion

- Leaf deletion could leave parent with only 1 child
  - Parent=root: delete node and let its lone child be the new root
  - Otherwise, let p be the parent of node
    - if *p* has another child, and that child of *p* has three children, then we can transfer the proper one to *node;* done;
    - if the children of *p*, have only two children, transfer the lone child of *node* to an adjacent sibling of *node*, and delete *node*;
    - p has only one child, repeat all the above, recursively, with p in place of node.

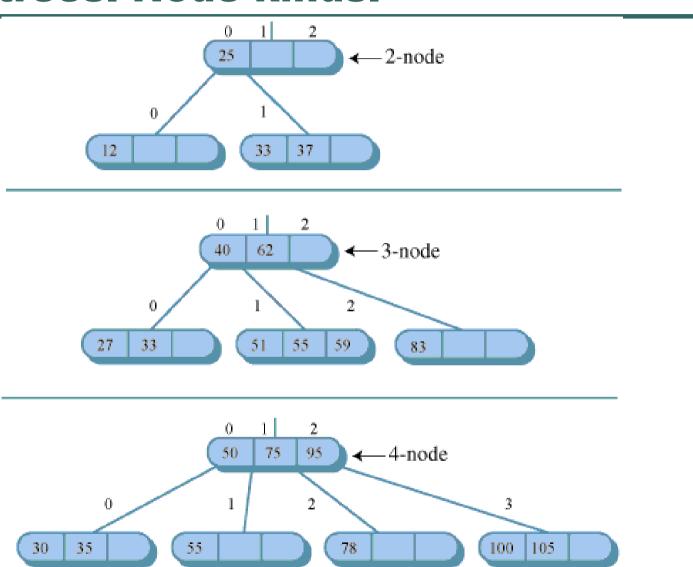
#### 2-3 trees. Deletion



#### 2-3-4 trees.

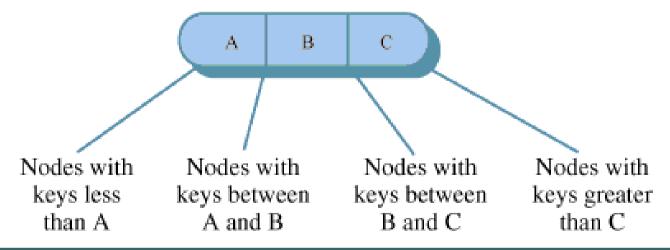
- 2-3-4 tree refer to how many links to child nodes can potentially be contained in a given node. For non-leaf nodes, three arrangements:
  - A node with one data item always has two children
  - A node with two data items always has three children
  - A node with three data items always has four children
  - In short, a non-leaf node must always have one more child than it has data items.
- Symbolically, if the number of child links is L and the number of data items is D, then L = D + 1
- Empty nodes are not allowed.

## 2-3-4 trees. Node kinds.



## 2-3-4 trees. Properties and example.

- All children in the subtree rooted at child 0 have key values less than key 0.
- All children in the subtree rooted at child 1 have key values greater than key 0 but less than key 1.
- All children in the subtree rooted at child 2 have key values greater than key 1 but less than key 2.
- All children in the subtree rooted at child 3 have key values greater than key 2.



# 2-3-4 trees. Example.

#### 2-3-4 Trees. Insertion

#### Insertion procedure:

- similar to insertion in 2-3 trees
- items are inserted at the leafs
- since a 4-node cannot take another item,
   4-nodes are split up during insertion process

#### Strategy

- on the way from the root down to the leaf: split up all 4-nodes "on the way"
- insertion can be done in one pass (remember: in 2-3 trees, a reverse pass might be necessary)

#### 2-3-4 Trees. Deletion

### Deletion procedure:

- similar to deletion in 2-3 trees
- items are deleted at the leafs
   > swap item of internal node with inorder successor
- note: a 2-node leaf creates a problem

## Strategy (different strategies possible)

- on the way from the root down to the leaf: turn 2-nodes (except root) into 3-nodes
- deletion can be done in one pass (remember: in 2-3 trees, a reverse pass might be necessary)

#### Demo: 2-3-4 trees

Demo from:

http://www.cs.unm.edu/~rlpm/499/ttft.html

Local:

Demos\2-3-4trees\TTFT.jar

# Disjoint Sets with the UNION and FIND Operations

- Applicable to problems where:
  - start with a collection of objects, each in a set by itself;
  - combine sets in some order, and from time to time
  - ask which set a particular object is in
- Equivalence classes:
  - If set S has an equivalence relation (reflexive, symmetrical, transitive) defined on it, then the set S can be partitioned into disjoint subsets  $S_1$ ,  $S_2$ , ... S with  $\int S_{\nu} = S$
- Equivalence problem:
  - given a set S and a sequence of statements of the form a = b
  - process the statements in order in such a way that at any time we are able to determine in which equivalence class a given element belongs

#### **Union-find set ADT**

 Example statements (see previous slide)

$$S = \{1, 2, ..., 7\}$$

$$1 \equiv 2, 5 \equiv 6, 3 \equiv 4, 1 \equiv 4$$

$$\begin{array}{ll} 1 \equiv 2 & \{1,2\}\{3\}\{4\}\{5\}\{6\}\{7\} \\ 5 \equiv 6 & \{1,2\}\{3\}\{4\}\{5,6\}\{7\} \\ 3 \equiv 4 & \{1,2\}\{3,4\}\{5,6\}\{7\} \\ 1 \equiv 4 & \{1,2,3,4\}\{5,6\}\{7\} \end{array}$$

## Operations:

- union(A, B) takes the union of the components A and B and calls the result either A or B, arbitrarily.
- find(x), a function that returns the name for the component of which x is a member.
- initial(A, x) creates a component named A that contains only the element x.

## **Union-find set ADT. Implementations**

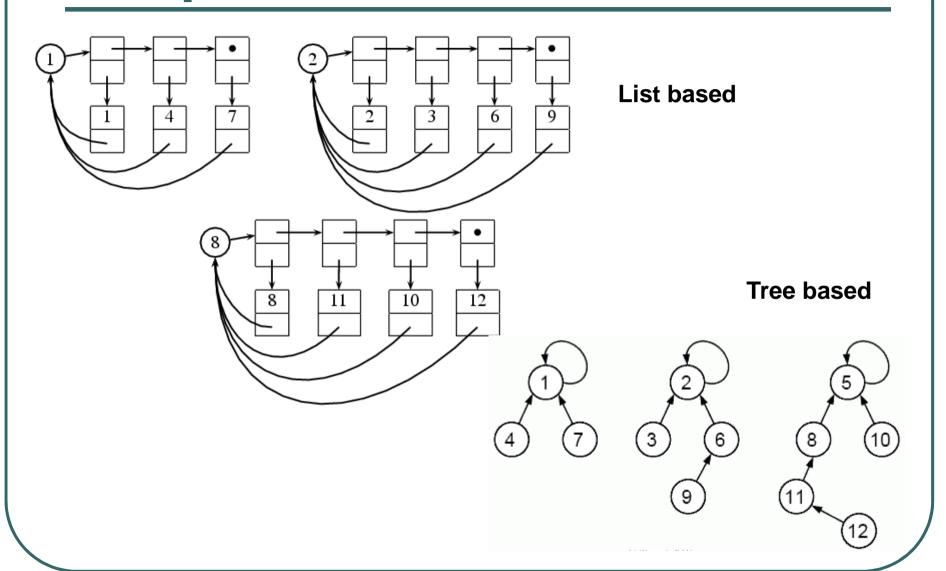
#### List-based

- Each set is stored in a sequence represented with a linked-list
- Each node should store an object containing the element and a reference to the set name

#### Tree based

- Each element is stored in a node, which contains a pointer to a set name
- A node v whose set pointer points back to v is also a set name
- Each set is a tree, rooted at a node with a selfreferencing set pointer

## **Examples**



### **Union-find set. List based implementation**

```
struct /* table giving set containing each member */
const int n = /* appropriate value */
typedef int NameT;
typedef int ElementT;
                                               NameT setName ;
typedef struct ufset
                                               int nextElement;
                                              } setNames[ n ];
 struct /* headers for set lists */
                                             } UFSetT;
  int count:;
  int firstElement ;
 } setHeaders[ n ];
                3
                              0
                0
                                            5
         6
                       firstElement
                                                set Name
                                                             nextElement
              count
                    setHeaders
                                                        set Names
```

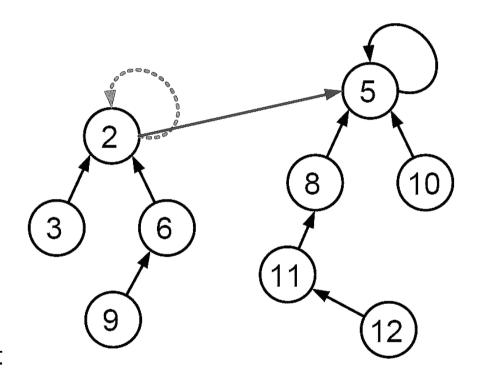
## **Union-find sets. Tree representation**

- Maintain S as a collection of trees (a forest), one per partition
- Initially, there are n trees, each containing a single element
- find(i) returns the root of the tree containing i
- union(i, j) merges the trees containing i and j
- Typical traversals not needed, so no need for pointers to children, but we need pointers to parent
- Parent pointers can be stored in an array: parent[i]
   (=-1 for root)

## **Union-find sets. Tree implementation**

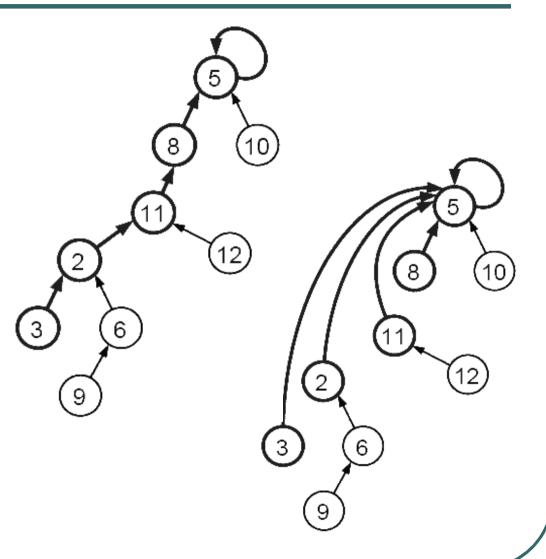
## Union-find sets. Speeding up

- Union by size (rank):
  - When performing a union, make the root of smaller tree point to the root of the larger
- Implies O(n log n) time for performing n unionfind operations:
  - Each time we follow a pointer, we are going to a subtree of size at least double the size of the previous subtree
  - Thus, we will follow at most  $O(\log n)$  pointers for any find.



## Union-find sets. Speeding up

- Path compression:
  - After performing a find, compress all the pointers on the path just traversed so that they all point to the root
- Implies O(n log\* n)
   time for performing
   n union- find



### Using union by rank and path compression

```
\begin{array}{lll} \operatorname{MakeSet}(x) & \operatorname{Link}(x,y) \\ 1 & p[x] \leftarrow x & 1 & \operatorname{if} r[x] > r[y] \\ 2 & r[x] \leftarrow 0 & 2 & \operatorname{then} p[y] \leftarrow x \\ & 3 & \operatorname{else} \ p[x] \leftarrow y \\ \operatorname{FINDSET}(x) & 4 & \operatorname{if} r[x] = r[y] \\ 1 & \operatorname{if} x \neq p[x] & 5 & \operatorname{then} r[y] \leftarrow r[y] + 1 \\ 2 & \operatorname{then} p[x] \leftarrow \operatorname{FINDSET}(p[x]) \\ 3 & \operatorname{return} p[x] & \operatorname{UNION}(x,y) \\ & 1 & \operatorname{Link}(\operatorname{FINDSET}(x), \operatorname{FINDSET}(y)) \end{array}
```

• Time bound of  $O(m\alpha(n))$  where  $\alpha(n)$  is a very slowly growing function

## **Union-find ADT demo**

Demo from:

http://www.cs.unm.edu/~rlpm/499/uf.html

Local:

Demos\UnionFind\UnionFind.jar

## A very quickly growing function and its inverse

• For integers  $k \ge 0$  and  $j \ge 1$ , define  $A_k(j)$ :

$$A_k(j) = \begin{cases} j+1, & \text{if } k = 0\\ A_{k-1}^{(j+1)}(j), & \text{if } k \ge 1 \end{cases}$$

- where  $A_{k-1}{}^{0}(j)=j$ ,  $A_{k-1}{}^{(i)}(j)=A_{k-1}(A_{k-1}{}^{(i-1)}(j))$  for  $i \ge 1$ .
- k is called the <u>level</u> of the function and
- i in the above is called iterations.
- A<sub>k</sub>(j) strictly increase with both j and k.
- Let us see how quick the increase is

## A very quickly growing function and its inverse

- Let us see  $A_k(1)$ : for k=0,1,2,3,4.
  - $A_0(1)=1+1=2$
  - $A_1(1)=2\times 1+1=3$
  - $A_2(1)=2^{1+1}\times(1+1)-1=7$
  - $A_3(1)=A_2^{(1+1)}(1)=A_2^{(2)}(1)=A_2(A_2(1))=A_2(7)=2^{7+1}(7+1)$ -1=2<sup>8</sup>×8-1=2047
  - $A_4(1)=A_3^2(1)=A_3(A_3(1))=A_3(2047)=A_2^{(2048)}(2047)$
  - $\rightarrow$  >  $A_2(2047) = 2^{2048} \times 2048 1 > 2^{2048} = (2^4)^{512} = (16)^{512}$
  - >>10<sup>80</sup>. (estimated number of atoms in universe)

## Inverse of $A_k(n)$ : $\alpha(n)$

- $\alpha(n)=\min\{k: A_k(1) \ge n\}$
- $\alpha(n)$ = 0 for  $0 \le n \le 2$ 
  - 1 n = 3
  - 2 for  $4 \le n \le 7$
  - 3 for  $8 \le n \le 2047$
  - 4 for  $2048 \le n \le A_4(1)$ .
- Extremely slow increasing function.
- $\alpha(n) \leq 4$  for all practical purpose.

## Reading

- AHU, chapter 5, sections 5.4, 5.5
- Preiss, chapter: Search Trees section AVL
   Search Trees
- CLR, chapter 22, sections 1-4
- CLRS chapter 21
- Notes