

Lagrangian Mechanics Problem Set

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0$$

1. Compute the following partial derivatives

(a) $\frac{\partial}{\partial x} y \ln(x^2) - xw^2 + e^w$

(b) $\frac{\partial}{\partial y} y \ln(x^2) - xw^2 + e^w$

(c) $\frac{\partial}{\partial x} \cos(xy) + y^2$

(d) $\frac{\partial}{\partial x} y \ln(x^2) - xw^2 + e^w$

(e) $\frac{\partial}{\partial x} y^x + x^y$

(f) $\frac{\partial}{\partial y} \cos(\sqrt{x^\pi}) - \ln(x!)$

(g) $\frac{\partial}{\partial x} \sqrt{x+y}$

2. In Figure 1 we show a box of mass m sliding down a ramp of mass M . The ramp moves without friction on the horizontal plane and is located by coordinate x_1 . The box also slides without friction on the ramp and is located by coordinate x_2 with respect to the ramp. Find \ddot{x}_1

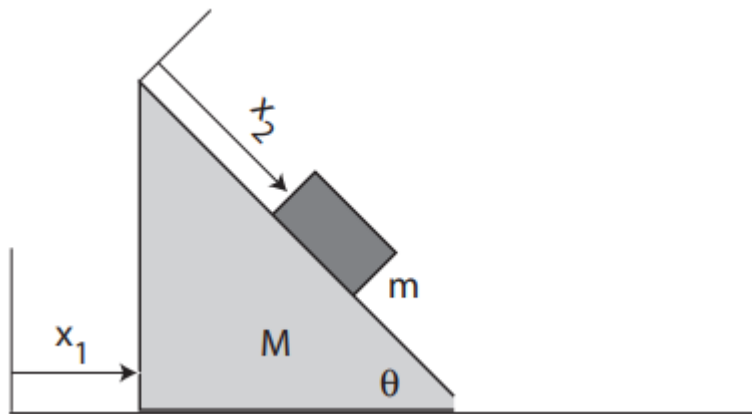
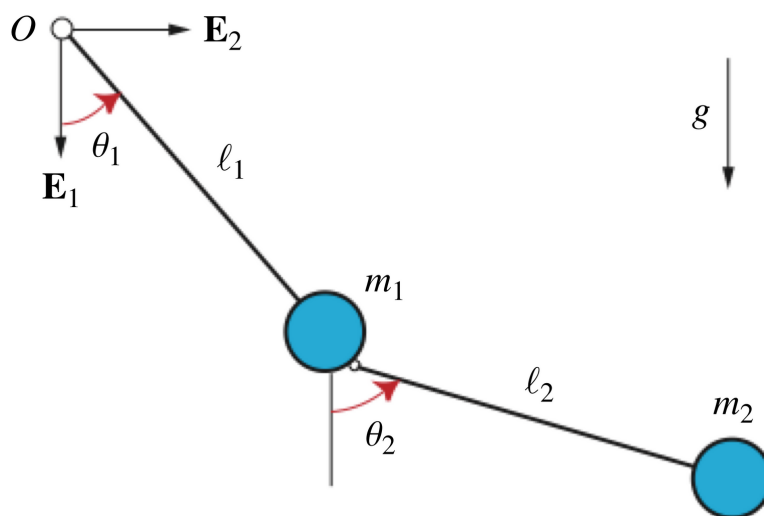


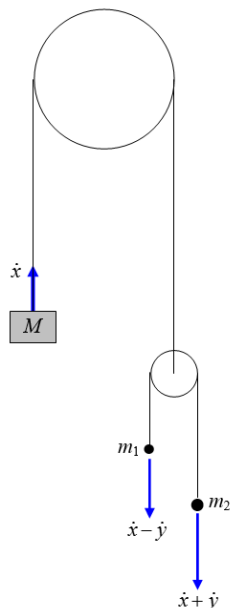
Figure 1

3. A particle is subjected to the potential $V(x) = -Fx$, where F is a constant. The particle travels from $x = 0$ to $x = a$ in a time interval t_0 . Assume the motion of the particle can be expressed in the form $x(t) = A + Bt + Ct^2$. Find the values of A , B , and C such that the action is a minimum.

4. A pendulum of length ℓ_2 and mass m_2 is strung to the bob of another pendulum of length ℓ_1 and mass m_1 . Use lagrangian mechanics to devise a set of formulas that describe the motion of this system (you will not be able to find a formula for θ_1 and θ_2 . Don't worry, just go as far as you can)



5. The upper pulley is fixed in position. Both pulleys rotate freely without friction about their axes. Both pulleys are “light” in the sense that their rotational inertias are small and their rotation contributes negligibly to the kinetic energy of the system. The rims of the pulleys are rough, and the ropes do not slip on the pulleys. The gravitational acceleration is g . The mass M moves upwards at a rate \dot{x} with respect to the upper, fixed, pulley, and the smaller pulley moves downwards at the same rate. The mass m_1 moves upwards at a rate \dot{y} with respect to the small pulley, and consequently its speed in laboratory space is $\dot{x} - \dot{y}$. The speed of the mass m_2 is therefore $\dot{x} + \dot{y}$ in laboratory space. The object is to find \ddot{x} and \ddot{y} in terms of g .



6. Figure 2 shows a simple pendulum consisting of a string of length r and a bob of mass m that is attached to a support of mass M . The support moves without friction on the horizontal plane. Find what \ddot{x} must be if we want $\ddot{\theta} = 0$

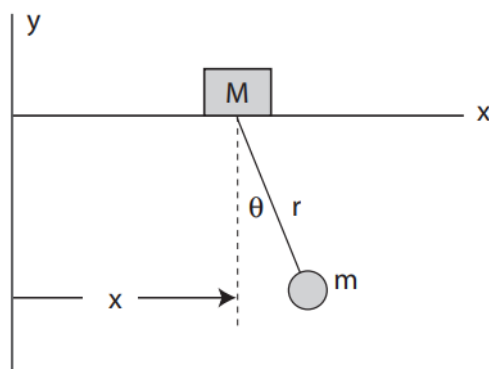


Figure 2