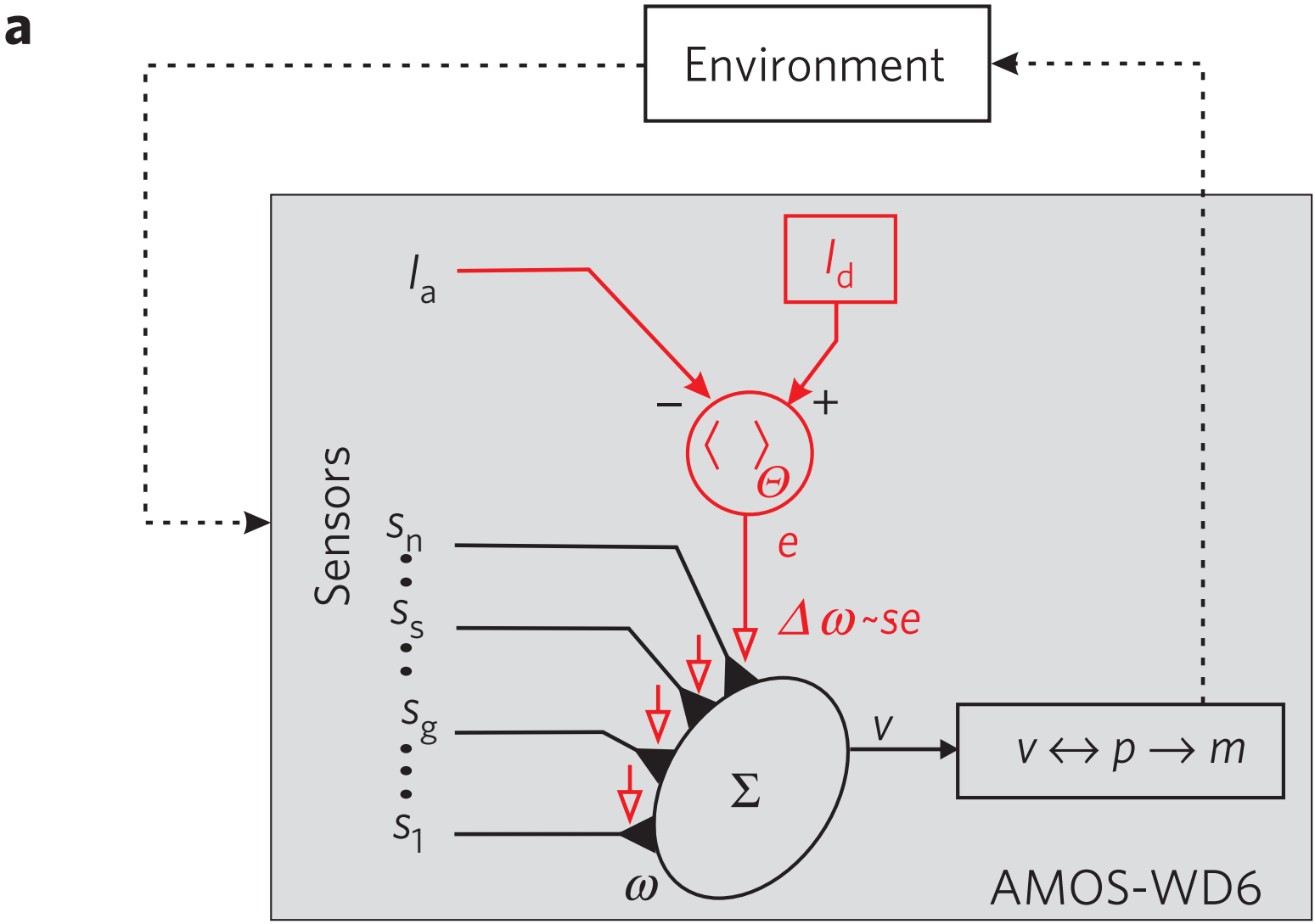
a
Environment
I_a
I_d
−
+
$\langle\ \rangle_\Theta$
e
$\Delta\omega \sim se$
Sensors
s_n
s_s
s_g
s_1
Σ
ω
v
$v \leftrightarrow p \rightarrow m$
AMOS-WD6