Symlectic Geometry

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Symplectic geometry is a branch of differential geometry that studies symplectic manifolds, which are smooth manifolds equipped with a closed, non-degenerate 2-form called a symplectic form. It originated from classical mechanics.

Definition 1 (Symlectic manifold). Let M be a smooth manifold of even dimension 2m and let $\omega \in \Omega^2(M)$ be a closed non degenerate 2-form i.e.

$$d\omega = 0$$
 and $\omega^m = \omega \wedge \omega \wedge \cdots \wedge \omega \neq 0$,

Then ω is called a *simplectic form* and the pair (M,ω) is called a *simplectic manifold*.

ekvivalentni definice nedegenerovanosti.

Narozdil od riemannovske geometrie nelze pouzit partitions of unity na konstrukci metriky. napsat poznamku o koncenci se psanim dimenze manifoldu :D

Example 2 (Canonical symplectic structure). Let $M = \mathbb{R}^{2m}$ with the global coordinates $q_1, \ldots, q_m, p_1, \ldots, p_m$. and let ω be a form s.t.,

$$\omega = \sum_{i=1}^{m} dp_i \wedge dq_i.$$

Then

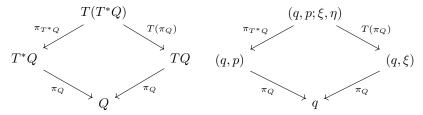
$$\omega^m = m! \cdot (-1)^{m(m-1)/2} \cdot dp_1 \wedge \dots \wedge dp_m \wedge dq_1 \wedge \dots \wedge dq_m$$

We call R^2m with the form ω the canonical symplectic structure.

Example 3 (Cotangent bundle is a symplectic manifold.). Let Q be a manifold, and consider the manifold $M = T^*Q$. Then there is a canonical 1-form $\theta \in \Omega^1(M)$ given by

$$\theta(X) = \langle \pi_{T^*Q}(X), T(\pi_Q)(X) \rangle, \quad X \in T(T^*Q), \tag{1}$$

where $\langle \cdot, \cdot \rangle$ is the natural pairing between tangent and cotangent spaces and the projections are the following:



Let $q = (q^1, \ldots, q^n) : U \to \mathbb{R}^n$ be a chart on Q, the we have the induced chart $T^*q : T^*U \to \mathbb{R}^n \times \mathbb{R}^n$, where $T_x^*q = (T_xq^{-1})^*$, we put $p_i := \langle e_i, T^*q(\cdot) \rangle : T^*U \to \mathbb{R}$. Then $(q^1, \ldots, q^n, p_1, \ldots, p_n) : T^*U \to \mathbb{R}^n \times (\mathbb{R}^n)^*$ are the induced coordinates and locally in these coordinates

$$\theta(q,p) = \sum_{i=1}^{n} \left(\theta\left(\frac{\partial}{\partial q^{i}}\right) dq^{i} + \theta\left(\frac{\partial}{\partial p_{i}}\right) dp_{i} \right) = \sum_{i=1}^{n} p_{i} dq^{i} + 0, \tag{2}$$

since
$$\theta\left(\frac{\partial}{\partial q^i}\right) = \theta_{R^n}\left((q, p; e_i, 0)\right) = \langle p, e_i \rangle = p_i$$
.

Now we define the 2-form $\omega \in \Omega^2(T^*Q)$ by

$$\omega := -d\theta \stackrel{\text{locally}}{=} \sum_{i=1}^{n} dq^{i} \wedge dp_{i}. \tag{3}$$

We see that the 2-form ω is non-degenerate.

Definition 4. The form $\theta \in \Omega^1(M)$ from (1), locally given by (2), is called the *tautological 1-form* on T^*Q . The induced 2-form ω from (3) is called the *canonical symplectic structure* on T^*Q .

dukaz ze je neni degen?

Definition 5. Let $X: J \times M \to TM$ be a smooth mapping such that $\pi_M \circ X = pr_2$, where J is open. Then we call X a *time dependent vector field* on a manifold M.

There is an associated vector field $\bar{X} \in \mathfrak{X}(J \times M)$, given by $\bar{X}(t,x) = (\frac{\partial}{\partial t}, X(t,x)) \in T_t \mathbb{R} \times T_x M$.

Definition 6. Let X be a time dependent vector field on a manifold M and let $\Phi^X: J \times J \times M \to M$ be a map defined on a maximal neighborhood of $\Delta_J \times M$ satisfying the differential equation

$$\frac{d}{dt}\Phi^{X}(t,s,x) = X\left(t,\Phi^{X}(t,s,x)\right)$$

$$\Phi^{X}(s,s,x) = x$$
(4)

Definition 6 is equivalent with

$$(t, \Phi^X(t, s, x)) = Fl^{\bar{X}}(t - s, (s, x)),$$

so the evolution operator exits and is unique on a maximal integral curve and satisfies

$$\Phi_{t,s}^X = \Phi_{t,r}^X \circ \Phi_{r,s}^X$$
, where $\Phi_{t,r}^X(x) = \Phi(t,s,x)$.

Lemma 7. Let f_t be a curve of diffeomorphisms on a manifold M locally defined for each t such that $f_0 = Id$. Defined two time dependent vector fields

$$\xi_t(x) := (T_x f_t)^{-1} \frac{\partial}{\partial t} f_t(x), \quad \eta_t(x) := \left(\frac{\partial}{\partial t} f_t\right) \left(f_t^{-1}(x)\right)$$
 (5)

Then $T(f_t) \cdot \xi_t = \frac{\partial}{\partial t} f_t = \eta_t \circ f_t$, so ξ_t and η_t are f_t -related. Let $\omega \in \Omega^k(M)$. Then

$$i_{\mathcal{E}_t} f_t^* \omega = f_t^* i_{n_t} \omega, \tag{6}$$

$$\frac{\partial}{\partial t} f_t^* \omega = f_t^* \mathcal{L}_{\eta_t} \omega = \mathcal{L}_{\xi_t} f_t^* \omega. \tag{7}$$

Proof.

$$\begin{split} (i_{\xi_{t}}f_{t}^{*}\omega)_{x}\left(X_{2},\ldots,X_{k}\right) &= (f_{t}^{*}\omega)_{x}\left(\xi_{t}(x),X_{2},\ldots,X_{k}\right) \\ &= \omega_{f_{t}(x)}\left(T_{x}f_{t}\cdot\xi_{t}(x),T_{x}f_{t}\cdot X_{2},\ldots,T_{x}f_{t}\cdot X_{k}\right) \\ &= \omega_{f_{t}(x)}\left(\eta_{t}\left(f_{t}(x)\right),T_{x}f_{t}\cdot X_{2},\ldots,T_{x}f_{t}\cdot X_{k}\right) \\ &= \left(f_{t}^{*}i_{\xi_{t}}\omega\right)_{x}\left(X_{2},\ldots,X_{k}\right) \end{split}$$

This proves (6). Now consider $\bar{\eta} \in \mathfrak{X}(\mathbb{R} \times M), \bar{\eta}(t,x) = (\partial_t, \eta_t(x))$ and let $\Phi^{\eta} : \mathbb{R} \times \mathbb{R} \times M \to M$ be the evolution operator, i.e.

$$\frac{\partial}{\partial t} \Phi_{t,s}^{\eta}(x) = \eta_t \left(\Phi_{t,s}^{\eta}(x) \right), \quad \Phi_{s,s}^{\eta}(x) = x,$$

such that

$$\left(t,\Phi^{\eta}_{t,s}(x)\right)=\mathrm{Fl}^{\bar{\eta}}_{t-s}(s,x),\ \Phi^{\eta}_{t,s}=\Phi^{\eta}_{t,r}\circ\Phi^{\eta}_{r,s}(x).$$

Since f_t satisfies $\frac{\partial}{\partial t} f_t = \eta_t \circ f_t$ and $f_0 = Id_M$, either $f_t = \Phi_{t,0}^{\eta}$, or $(t, f_t(x)) = Fl_t^{\bar{\eta}}(0, x)$, so $f_t = pr_2 \circ Fl_t^{\bar{\eta}} \circ ins_0$. Thus

$$\frac{\partial}{\partial t} f_t^* \omega = \frac{\partial}{\partial t} \left(\operatorname{pr}_2 \circ Fl_t^{\bar{\eta}} \circ ins_0 \right)^* \omega = ins_0^* \frac{\partial}{\partial t} (Fl_t^{\bar{\eta}})^* pr_2^* \omega = ins_0^* (Fl_t^{\bar{\eta}})^* \mathbb{L}_{\bar{\eta}} pr_2^* \omega.$$

For time dependant vector fields X_i (tady mozna nejaka vlastnost lie derivative!!!) we have

$$\begin{split} (\mathcal{L}_{\bar{\eta}} \operatorname{pr}_{2}^{*} \omega) & (0 \times X_{1}, \dots, 0 \times X_{k})|_{(t,x)} = \bar{\eta}((\operatorname{pr}_{2}^{*} \omega)(0 \times X_{1}, \dots))|_{(t,x)} \\ & - \sum_{i} (\operatorname{pr}_{2}^{*} \omega)(0 \times X_{1}, \dots, [\bar{\eta}, 0 \times X_{i}], \dots, 0 \times X_{k})|_{(t,x)} \\ & = (\partial_{t}, \eta_{t}(x)) \left(\omega \left(X_{1}, \dots, X_{k}\right)\right) - \sum_{i} \omega \left(X_{1}, \dots, [\eta_{t}, X_{i}], \dots, X_{k}\right)|_{x} \\ & = (\mathcal{L}_{\eta_{t}} \omega)_{x} \left(X_{1}, \dots, X_{k}\right). \end{split}$$

For $X_i \in T_xM$, this implies

$$\left(\frac{\partial}{\partial t} f_t^* \omega\right)_x (X_1, \dots, X_k) = \left(\operatorname{ins}^* \left(\operatorname{Fl}_t^{\eta}\right)^* \mathcal{L}_{\eta} \operatorname{pr}_2^* \omega\right)_x (X_1, \dots, X_k)
= \left(\left(\operatorname{Fl}_t^{\eta}\right)^* \mathcal{L}_{\eta} \operatorname{pr}_2^* \omega\right)_{(0,x)} (0 \times X_1, \dots, 0 \times X_k)
= \left(\mathcal{L}_{\eta} \operatorname{pr}_2^* \omega\right)_{(t,f_t(x))} \left(0_t \times T_x f_t \cdot X_1, \dots, 0_t \times T_x f_t \cdot X_k\right)
= \left(\mathcal{L}_{\eta_t} \omega\right)_{f_t(x)} \left(T_x f_t \cdot X_1, \dots, T_x f_t \cdot X_k\right)
= \left(f_t^* \mathcal{L}_{\eta_t} \omega\right)_x (X_1, \dots, X_k),$$
(8)

We have proven the first part of (7), the second part follow from (6)

$$\frac{\partial}{\partial t} f_t^* \omega = f_t^* \mathcal{L}_{\eta_t} \omega
= f_t^* (di_{\eta_t} + i_{\eta_t} d) \omega
= df_t^* i_{\eta_t} \omega + f_t^* i_{\eta_t} d\omega
= di_{\xi_t} f_t^* \omega + i_{\xi_t} f_t^* d\omega
= di_{\xi_t} f_t^* \omega + i_{\xi_t} df_t^* \omega
= \mathcal{L}_{\xi_t} f_t^* \omega.$$
(9)

dopsat co je ins a pr2?

Theorem 8 (Darboux). Let (M, ω) be a symplectic manifold of dimension 2n. Then for all points $x \in M$ exists a chart (U, u) centered at x such that $\omega|_U = \sum_{i=1}^n du^i \wedge du^{n+i}$.

Proof. Take a chart (U, u) centered at x and choose coordinates such that $\omega_x = \sum_{i=1}^n du^i \wedge du^{n+i}$ at x. Then $\omega_0 = \omega|_U$ and $\omega_1 = \sum_{i=1}^n du^i \wedge du^{n+i}$ are two symplectic forms that are equal at x. Now interpolate $\omega_t = \omega_0 + t(\omega_1 + \omega_0)$. Then ω_t is a symplectic form on a possibly smaller neighbourhood of x for all $t \in [0,1]$.

We want to find a curve of diffeomorphisms f_t near x such that $f_0 = id$, $f_t(x) = x$ and such that the pullback condition $f_t^*\omega_t = \omega_0$ is satisfied. Assume that U is contractible, then the second cohomology group $H^2(U) = 0$ and every closed 2-form is exact, so $d(\omega_1 - \omega_0) = 0$ implies $\omega_1 - \omega_0 = d\psi$ for some $\psi \in \Omega^1(U)$. By adding a constant we may assume that $\psi_x = 0$. Now by using Lemma 7, (7), we get a time dependant vector field $\eta_t = \frac{\partial}{\partial t} f_t \circ f_t^{-1}$, then by differentiating with respect to t, (cartan formula!!)

$$0 = \frac{\partial}{\partial t} f_t^* \omega_t = f_t^* \left(\mathcal{L}_{\eta_t} \omega_t + \frac{\partial}{\partial t} \omega_t \right) = f_t^* \left(di_{\eta_t} \omega_t + i_{\eta_t} d\omega_t + \omega_1 - \omega_0 \right) = f_t^* d \left(i_{\eta_t} \omega_t + \psi \right)$$

Since ω_t is non-degenerate, the equation $i_{\eta_t}\omega_t = -\psi$ prescribes the vector field η_t uniquely. Also $\eta_t(x) = 0$ sine $\psi_x = 0$. On some neighbourhood of x the left evolution operator f_t of η_t exists for all $t \in [0,1]$ and $\frac{\partial}{\partial t}(f_t^*\omega_t) = 0$, so $f_t^*\omega_t = \omega_0$ for all $t \in [0,1]$.

NOW lets study symplectomorphisms. mozna dopsat definici lagrangian manifold

Definition 9 (Lagrangian submanifold). Let (M^{2m}, ω) be a symplectic manifold. We call a submanifold Y of M lagrangian, if at each $p \in Y$, $T_p Y$ is a lagrangian subspace of $T_p M$, that is, $\omega_p|_{T_p Y} \equiv 0$ and $\dim T_p Y = \frac{1}{2} \dim T_p M$.

Equivalently, if $i: Y \to M$ is the inclusion map, then Y is lagrangian if and only if $i*\omega = 0$ and $\dim Y = \frac{1}{2} \dim M$

Example 10 (The zero section of T^*M). Let M^m be a manifold and consider its cotangent bundle T^*M with the local coordinates $x_1, \ldots, x_m, \xi_1, \ldots, \xi_m$ on T^*U . Then the zero section of T^*M is the set

$$M_0 = (x, \xi) \in T^*M | \xi = 0 in T_x^* M$$

is an m-dimensional submanifold of T^*M whose intersection with T*U is given by the equations $\xi_1 = \ldots = \xi_n = 0$. Then clearly the tautological 1-form $\theta(x,\xi)$ vanishes on $M_0 \cap T^*U$. Let $i_0: M_0 \to T^*M$ be the inclusion map, then $i_0^*\theta = 0$. Hence $i_0^*\omega = i_0^*d\theta = 0$ and so M_0 is lagrangian.

Now let $\mu \in \Omega^1(M)$ be a 1-form and consider the set

$$M_{\mu} = \{(x, \mu_x) \mid x \in X, \mu_x \in T_x^* X\}$$
 (10)

Then M_{μ} is a submanifold of T^*M . When is M_{μ} lagrangian?

Lemma 11. Let M_{μ} be of the form (10). Denote by $s_{\mu}: M \to T^*M, x \to (x, \mu_x)$ the 1-form μ regarded as a map. Let θ be the tautological 1-form on T^*M . Then

$$s_{\mu}^*\theta = \mu$$

Proof. By definition of θ , $\theta_p = (d\pi)^*\xi$ at $p = (x,\xi) \in M$. For $p = s_\mu(x) = (x,\mu_x)$, we have $\theta_p = (d\pi_p)^*\mu_x$. Then

$$(s_{\mu}^*\theta)_x = (ds_{\mu})_x^*\theta_p = (ds_{\mu})_x^*(d\pi_p)^*\mu_x = (d(\pi \circ s_{\mu}))_x^*\mu_x = \mu_x.$$

Lemma 12. Let M_{μ} be of the form (10). Then M_{μ} is lagrangian iff. μ is closed.

Proof. The map $s_{\mu}: M \to T^*M, x \to (x, \mu_x)$ is an embedding with image M_{μ} . Then there is a diffeomorphism $\tau: M \to M_{\mu}$, $\tau(x) := (x, \mu_x)$, such that the following diagram commutes:



We want to express the condition of M_{μ} being Lagrangian in terms of the form μ :

$$M_{\mu}$$
 is Lagrangian $\iff i^*d\theta = 0$
 $\iff \tau^*i^*d\theta = 0$
 $\iff (i \circ \tau)^*d\theta = 0$
 $\iff s_{\mu}^*d\theta = 0$
 $\iff ds_{\mu}^*\theta = 0$
 $\iff d\mu = 0$
 $\iff \mu$ is closed. (11)

Therefore, there is a one-to-one correspondence between the set of Lagrangian submanifolds of T^*M of the form (10) and the set of closed 1-forms on M.

There are other lagrangian submanifolds of T^*M . Lets study the conormal bundles.

Definition 13. Let S^k be submanifold of M^m , then the conormal space at x is the set

$$N_x^* S = \{ \xi \in T_x^* M \mid \xi(v) = 0 , v \in T_x M \}.$$

The conormal bundle of S is

$$N^*S = \{(x,\xi) \in T^*M \mid x \in S, \xi \in N_x^*S\}.$$

Example 14. Let $S \subset X$ be a submanifold, then the conormal bundle N^*S is a lagrangian submanifold of T^*x .

Lemma 15. The conormal bundle N^*S is an n-dimensional submanifold of T^*M .

Lemma 16. Let $i: N^*S \hookrightarrow T^*M$ be the inclusion and θ the tautological 1-form on T^*M . Then

$$i^*\theta = 0$$

Proof. Let (U, x_1, \ldots, x_n) be a coordinate system on M centered at $x \in S$ and adapted to M, so that $U \cap S$ is described by

$$x_{k+1} = \ldots = x_n = 0$$
. and $\xi_1 = \ldots = \xi_k = 0$

Let $(U, x_1, \ldots, x_n, \xi_1, \ldots, \xi_n)$ be the associated cotangent coordinate system. The submanifold $N^*S \cap T^*U$ is then described by

$$x_{k+1} = \dots = x_n = 0 \text{ and } \xi_1 = \dots = \xi_k = 0.$$
 (12)

Since $\theta = \sum \xi_i dx_i$ on T^*U , we conclude that, at $p \in N^*S$,

$$(i^*\theta)_p = \theta_p|_{T_p(N^*S)} = \sum_{i>k} \xi_i dx_i \bigg|_{\text{span}\left\{\frac{\partial}{\partial x_i}, i \le k\right\}} = 0.$$
(13)

Corollary 17. For any submanifold S of M, the conormal bundle N^*S is a lagrangian submanifold of T^*M .

Notice that taking $S = \{x\}$ to be a point, then the conormal bundle $N^*S = T_x^*M$ is a cotangent fiber. Taking S = X, the conormal bundle is the zero section M_0 .

Lemma 18 (Lemmatko). 2 + 2 = 4 - 1 = 3 quick maffs.

A ted si rekneme dulezitou vetu.

Theorem 19 (Hlavni veta o gaystvi). *Jsi gay*.

Corollary 20. Vlastne dusledek tohoto kratkeho textu je, ze bych se mel jit zabit. Jdu na to!