

Symplectic Geometry

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Symplectic geometry is a branch of differential geometry that studies symplectic manifolds, which are smooth manifolds equipped with a closed, non-degenerate 2-form called a symplectic form. It originated from classical mechanics.

Definition 1 (Symplectic manifold). Let M be a smooth manifold of even dimension $2m$ and let $\omega \in \Omega^2(M)$ be a closed non degenerate 2-form i.e.

$$d\omega = 0 \text{ and } \omega^m = \omega \wedge \omega \wedge \cdots \wedge \omega \neq 0,$$

Then ω is called a *simplectic form* and the pair (M, ω) is called a *simplectic manifold*.

ekvivalentni definice nede degenerovanosti.

Narozdil od riemannovske geometrie nelze pouzit partitions of unity na konstrukci metriky.

napsat poznamku o koncenci se psanim dimenze manifoldu :D

Example 2 (Canonical symplectic structure). Let $M = \mathbb{R}^{2m}$ with the global coordinates $q_1, \dots, q_m, p_1, \dots, p_m$. and let ω be a form s.t.,

$$\omega = \sum_{i=1}^m dp_i \wedge dq_i.$$

Then

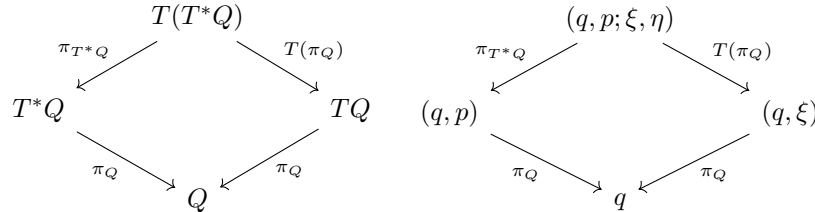
$$\omega^m = m! \cdot (-1)^{m(m-1)/2} \cdot dp_1 \wedge \cdots \wedge dp_m \wedge dq_1 \wedge \cdots \wedge dq_m.$$

We call R^{2m} with the form ω the canonical symplectic structure.

Example 3 (Cotangent bundle is a symplectic manifold.). Let Q be a manifold, and consider the manifold $M = T^*Q$. Then there is a canonical 1-form $\theta \in \Omega^1(M)$ given by

$$\theta(X) = \langle \pi_{T^*Q}(X), T(\pi_Q)(X) \rangle, \quad X \in T(T^*Q), \quad (1)$$

where $\langle \cdot, \cdot \rangle$ is the natural pairing between tangent and cotangent spaces and the projections are the following:



Let $q = (q^1, \dots, q^n) : U \rightarrow \mathbb{R}^n$ be a chart on Q , then we have the induced chart $T^*q : T^*U \rightarrow \mathbb{R}^n \times \mathbb{R}^n$, where $T_x^*q = (T_x q^{-1})^*$, we put $p_i := \langle e_i, T^*q(\cdot) \rangle : T^*U \rightarrow \mathbb{R}$. Then $(q^1, \dots, q^n, p_1, \dots, p_n) : T^*U \rightarrow \mathbb{R}^n \times (\mathbb{R}^n)^*$ are the induced coordinates and locally in these coordinates

$$\theta(q, p) = \sum_{i=1}^n \left(\theta \left(\frac{\partial}{\partial q^i} \right) dq^i + \theta \left(\frac{\partial}{\partial p_i} \right) dp_i \right) = \sum_{i=1}^n p_i dq^i + 0, \quad (2)$$

since $\theta \left(\frac{\partial}{\partial q^i} \right) = \theta_{R^n}((q, p; e_i, 0)) = \langle p, e_i \rangle = p_i$.

Now we define the *canonical symplectic structure* $\omega \in \Omega^2(T^*Q)$ by

$$\omega := -d\theta \stackrel{\text{locally}}{=} \sum_{i=1}^n dq^i \wedge dp_i. \quad (3)$$

We see that the 2-form ω is non-degenerate.

dukaz ze je neni degen?

Definition 4. Let $X : J \times M \rightarrow TM$ be a smooth mapping such that $\pi_M \circ X = pr_2$, where J is open. Then we call X a *time dependent vector field* on a manifold M .

There is an associated vector field $\bar{X} \in \mathfrak{X}(J \times M)$, given by $\bar{X}(t, x) = (\frac{\partial}{\partial t}, X(t, x)) \in T_t\mathbb{R} \times T_xM$.

Definition 5. Let X be a time dependent vector field on a manifold M and let $\Phi^X : J \times J \times M \rightarrow M$ be a map defined on a maximal neighborhood of $\Delta_J \times M$ satisfying the differential equation

$$\begin{aligned} \frac{d}{dt} \Phi^X(t, s, x) &= X(t, \Phi^X(t, s, x)) \\ \Phi^X(s, s, x) &= x \end{aligned} \quad (4)$$

Definition 5 is equivalent with

$$(t, \Phi^X(t, s, x)) = Fl^{\bar{X}}(t - s, (s, x)),$$

so the evolution operator exists and is unique on a maximal integral curve and satisfies

$$\Phi_{t,s}^X = \Phi_{t,r}^X \circ \Phi_{r,s}^X, \text{ where } \Phi_{t,r}^X(x) = \Phi(t, s, x).$$

Lemma 6. Let f_t be a curve of diffeomorphisms on a manifold M locally defined for each t such that $f_0 = Id$. Defined two time dependent vector fields

$$\xi_t(x) := (T_x f_t)^{-1} \frac{\partial}{\partial t} f_t(x), \quad \eta_t(x) := \left(\frac{\partial}{\partial t} f_t \right) (f_t^{-1}(x)) \quad (5)$$

Then $T(f_t) \cdot \xi_t = \frac{\partial}{\partial t} f_t = \eta_t \circ f_t$, so ξ_t and η_t are f_t -related. Let $\omega \in \Omega^k(M)$. Then

$$i_{\xi_t} f_t^* \omega = f_t^* i_{\eta_t} \omega, \quad (6)$$

$$\frac{\partial}{\partial t} f_t^* \omega = f_t^* \mathcal{L}_{\eta_t} \omega = \mathcal{L}_{\xi_t} f_t^* \omega. \quad (7)$$

Proof.

$$\begin{aligned} (i_{\xi_t} f_t^* \omega)_x(X_2, \dots, X_k) &= (f_t^* \omega)_x(\xi_t(x), X_2, \dots, X_k) = \\ &= \omega_{f_t(x)}(T_x f_t \cdot \xi_t(x), T_x f_t \cdot X_2, \dots, T_x f_t \cdot X_k) = \\ &= \omega_{f_t(x)}(\eta_t(f_t(x)), T_x f_t \cdot X_2, \dots, T_x f_t \cdot X_k) = (f_t^* i_{\eta_t} \omega)_x(X_2, \dots, X_k) \end{aligned}$$

This proves (6). Now consider $\bar{\eta} \in \mathfrak{X}(\mathbb{R} \times M)$, $\bar{\eta}(t, x) = (\partial_t, \eta_t(x))$ and let $\Phi^\eta : \mathbb{R} \times \mathbb{R} \times M \rightarrow M$ be the evolution operator, i.e.

$$\frac{\partial}{\partial t} \Phi_{t,s}^\eta(x) = \eta_t(\Phi_{t,s}^\eta(x)), \quad \Phi_{s,s}^\eta(x) = x,$$

such that

$$(t, \Phi_{t,s}^\eta(x)) = Fl_{t-s}^{\bar{\eta}}(s, x), \quad \Phi_{t,s}^\eta = \Phi_{t,r}^\eta \circ \Phi_{r,s}^\eta(x).$$

Since f_t satisfies $\frac{\partial}{\partial t} f_t = \eta_t \circ f_t$ and $f_0 = Id_M$, either $f_t = \Phi_{t,0}^\eta$, or $(t, f_t(x)) = Fl_t^{\bar{\eta}}(0, x)$, so $f_t = pr_2 \circ Fl_t^{\bar{\eta}} \circ ins_0$. Thus

$$\frac{\partial}{\partial t} f_t^* \omega = \frac{\partial}{\partial t} (pr_2 \circ Fl_t^{\bar{\eta}} \circ ins_0)^* \omega = ins_0^* \frac{\partial}{\partial t} (Fl_t^{\bar{\eta}})^* pr_2^* \omega = ins_0^* (Fl_t^{\bar{\eta}})^* \mathbb{L}_{\bar{\eta}} pr_2^* \omega.$$

For time dependant vector fields X_i (tady mozna nejaka vlastnost lie derivative!!!) we have

$$\begin{aligned}
& (\mathcal{L}_{\bar{\eta}} \text{pr}_2^* \omega) (0 \times X_1, \dots, 0 \times X_k)|_{(t,x)} = \bar{\eta}((\text{pr}_2^* \omega)(0 \times X_1, \dots))|_{(t,x)} \\
& \quad - \sum_i (\text{pr}_2^* \omega)(0 \times X_1, \dots, [\bar{\eta}, 0 \times X_i], \dots, 0 \times X_k)|_{(t,x)} \\
& = (\partial_t, \eta_t(x)) (\omega(X_1, \dots, X_k)) - \sum_i \omega(X_1, \dots, [\eta_t, X_i], \dots, X_k)|_x \\
& = (\mathcal{L}_{\eta_t} \omega)_x (X_1, \dots, X_k).
\end{aligned}$$

For $X_i \in T_x M$, this implies

$$\begin{aligned}
\left(\frac{\partial}{\partial t} f_t^* \omega \right)_x (X_1, \dots, X_k) &= \left(\text{ins}^* (\text{Fl}_t^\eta)^* \mathcal{L}_\eta \text{pr}_2^* \omega \right)_x (X_1, \dots, X_k) \\
&= ((\text{Fl}_t^\eta)^* \mathcal{L}_\eta \text{pr}_2^* \omega)_{(0,x)} (0 \times X_1, \dots, 0 \times X_k) \\
&= (\mathcal{L}_\eta \text{pr}_2^* \omega)_{(t, f_t(x))} (0_t \times T_x f_t \cdot X_1, \dots, 0_t \times T_x f_t \cdot X_k) \\
&= (\mathcal{L}_{\eta_t} \omega)_{f_t(x)} (T_x f_t \cdot X_1, \dots, T_x f_t \cdot X_k) \\
&= (f_t^* \mathcal{L}_{\eta_t} \omega)_x (X_1, \dots, X_k),
\end{aligned} \tag{8}$$

We have proven the first part of (7), the second part follow from (6)

$$\begin{aligned}
\frac{\partial}{\partial t} f_t^* \omega &= f_t^* \mathcal{L}_{\eta_t} \omega \\
&= f_t^* (di_{\eta_t} + i_{\eta_t} d) \omega \\
&= df_t^* i_{\eta_t} \omega + f_t^* i_{\eta_t} d\omega \\
&= di_{\xi_t} f_t^* \omega + i_{\xi_t} f_t^* d\omega \\
&= di_{\xi_t} f_t^* \omega + i_{\xi_t} df_t^* \omega \\
&= \mathcal{L}_{\xi_t} f_t^* \omega.
\end{aligned} \tag{9}$$

□

dopsat co je ins a pr2?

Theorem 7 (Darboux). *Let (M, ω) be a symplectic manifold of dimension $2n$. Then for all points $x \in M$ exists a chart (U, u) centered at x such that $\omega|_U = \sum_{i=1}^n du^i \wedge du^{n+i}$.*

Proof. Take a chart (U, u) centered at x and choose coordinates such that $\omega_x = \sum_{i=1}^n du^i \wedge du^{n+i}$ at x . Then $\omega_0 = \omega|_U$ and $\omega_1 = \sum_{i=1}^n du^i \wedge du^{n+i}$ are two symplectic forms that are equal at x . Now interpolate $\omega_t = \omega_0 + t(\omega_1 - \omega_0)$. Then ω_t is a symplectic form on a possibly smaller neighbourhood of x for all $t \in [0, 1]$.

We want to find a curve of diffeomorphisms f_t near x such that $f_0 = id$, $f_t(x) = x$ and such that the pullback condition $f_t^* \omega_t = \omega_0$ is satisfied. Assume that U is contractible, then the second cohomology group $H^2(U) = 0$ and every closed 2-form is exact, so $d(\omega_1 - \omega_0) = 0$ implies $\omega_1 - \omega_0 = d\psi$ for some $\psi \in \Omega^1(U)$. By adding a constant we may assume that $\psi_x = 0$. Now by using Lemma 6, (7), we get a time dependant vector field $\eta_t = \frac{\partial}{\partial t} f_t \circ f_t^{-1}$, then by differentiating with respect to t , (cartan formula!!)

$$0 = \frac{\partial}{\partial t} f_t^* \omega_t = f_t^* \left(\mathcal{L}_{\eta_t} \omega_t + \frac{\partial}{\partial t} \omega_t \right) = f_t^* (di_{\eta_t} \omega_t + i_{\eta_t} d\omega_t + \omega_1 - \omega_0) = f_t^* d(i_{\eta_t} \omega_t + \psi)$$

Since ω_t is non-degenerate, the equation $i_{\eta_t} \omega_t = -\psi$ prescribes the vector field η_t uniquely. Also $\eta_t(x) = 0$ sine $\psi_x = 0$. On some neighbourhood of x the left evolution operator f_t of η_t exists for all $t \in [0, 1]$ and $\frac{\partial}{\partial t} (f_t^* \omega_t) = 0$, so $f_t^* \omega_t = \omega_0$ for all $t \in [0, 1]$. □

tohle je v lsg.pdf

lagrangian subspace? submanifold? embeddings? asi spis ne....

Definition 8 (Lagrangian submanifold). Let (M^{2m}, ω) be a symplectic manifold. We call a submanifold Y of M lagrangian, if at each $p \in Y$, $T_p Y$ is a lagrangian subspace of $T_p M$, i.e., $\omega_p|_{T_p Y} \equiv 0$ and $\dim T_p Y = \frac{1}{2} \dim T_p M$. Equivalently, if $i : Y \rightarrow M$ is the inclusion map, then Y is lagrangian if and only if $i^* \omega = 0$ and $\dim Y = \frac{1}{2} \dim M$

dukazem tehle sracky se napise i priklad ktery chceme napsat

Theorem 9. *the image of a section of T^*M is a lagrangian submanifold iff nejaka forma je close...lsg strana 17.*

lsg dalsi section

Example 10. Let $S \subset X$ be a submanifold, then the conormal bundle N^*S is a lagrangian submanifold of T^*X .

Lemma 11 (Lemmatko). $2 + 2 = 4 - 1 = 3$ *quick maffs.*

A ted si rekneme dulezitou vetu.

Theorem 12 (Hlavni veta o gaystvi). *Jsi gay.*

Corollary 13. *Vlastne dusledek tohoto kratkeho textu je, ze bych se mel jit zabit. Jdu na to!*