

A Hybrid Approach of ConvLSTM-DT and GPT-4 for Real-time Anomaly Detection Decision Support in Edge-Cloud Environments

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Abstract

Anomaly detection is crucial in various domains for early identification of abnormal behavior. This research introduces an innovative approach that combines prediction-based detectors with Large Language Models (LLMs) for anomaly detection, focusing on indoor air quality data from multiple sensors. The hybrid approach integrates Convolutional Long Short-term Memory with non-parametric dynamic thresholding (ConvLSTM-DT) for prediction-based anomaly detection and fine-tuned GPT-4 for generating human-understandable explanations. Each sensor parameter has its specific model for accurate predictions. Furthermore, Dynamic thresholding and continuous learning adapts to the dynamic environment, update model and setting non-parametric confidence intervals for anomaly detection in rapidly changing scenarios. The system deploys anomaly detection on the edge for reduced latency and fast detection, while LLM processing occurs on the cloud for resource optimization. The results demonstrate accurate anomaly detection and well-explained reasoning for real-time decision-making, offering a novel approach for comprehensive anomaly detection solutions in various applications.

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1. Introduction

In recent years, the rapid increase in data-driven applications and the growing complexity of modern systems have highlighted the critical significance of anomaly detection. Anomalies, often indicative of potentially harmful behavior within systems, can have long-term effects and wide-ranging consequences in various domains, such as industrial operations. Traditional anomaly detection methods, while effective to some extent, often heavily rely on expert analysis, making them resource-intensive and susceptible to human bias. This dependency on expert input can result in scalability, reliability, and consistency challenges within anomaly detection systems[1].

Furthermore, traditional anomaly detection methods based on statistical and machine learning approaches exhibit limitations, particularly when handling time-series data from multiple sensors. Anomalies in this context may be multi-dimensional and not easily characterized by conventional patterns. Consequently, traditional approaches can produce a significant number of false alarms, compromising the effectiveness and trustworthiness of anomaly detection systems[2].

In response to these challenges, this study aims to contribute to the field of anomaly detection by proposing a hybrid approach that harnesses the strength of prediction-based detector algorithms and the capabilities of Large Language Models (LLMs). This work centers on monitoring and detecting anomalies in air quality data collected from various sensors, including temperature, humidity, PM (Particulate Matter), and CO2 levels, all situated within a single indoor room environment. The ability to predict and detect anomalies in this air quality data is of paramount importance, given its profound implications for human health, particularly for

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those occupying the room.

The proposed hybrid approach combines Convolutional Long Short-Term Memory with non-parametric dynamic thresholding (ConvLSTM-DT) for prediction-based anomaly detection and utilizes fine-tuned GPT-4 for LLM-based explainability. This hybrid approach is essential to address the aforementioned limitations and enhance the interpretability and adaptability of anomaly detection models. It not only facilitates anomaly detection across a variety of sensors but also provides human-understandable explanations and potential solutions for addressing anomaly situations. This makes it a powerful tool for real-world implementation where swift decision-making is imperative.

2. Literature Review

Multiple techniques can be employed for anomaly detection on time series and currently, a significant number of researchers are exploring the utilization of various deep learning architectures for anomaly detection. This is due to the inherent power of deep learning methods in modeling data dependencies, particularly in data with complex structures. In deep learning techniques, there are two different approaches that are commonly used for anomaly detection, prediction-based approaches and reconstruction-based approaches.

Malhotra et al [5] introduced LSTM-AD, a model renowned for its long-term memory capabilities. A noteworthy innovation is the combination of hierarchical recurrent processing layers, a groundbreaking approach for detecting anomalies within univariate time series data. A captivating aspect of LSTM-AD is the first deep learning model that has the ability to perform anomaly detection without requiring labeled training data or unsupervised learning. By stacking recurrent hidden layers, this architecture empowers the model to learn higher-order temporal trends without any prior knowledge of their temporal length.

Similarly, in the realm of anomaly detection, Chauhan et al [6] proposed DeepLSTM, a model that leverages a stacked LSTM recurrent network. This approach begins by training on normal data and subsequently employs maximum likelihood estimation to predict the error vector based on multivariate Gaussian distributions. Following this, the model is used to forecast a combination of both abnormal and normal validation data, while concurrently recording the probability density function (PDF) values associated with the error. Notably, this method offers the unique benefit of direct application to raw time series data, bypassing the need for preprocessing steps.

On another front, Hundmand et al. [7] embarked on the implementation of a non-parametric, dynamic, and unsupervised thresholding technique to assess errors for anomaly detection. LSTM-NDT combines multiple techniques, including LSTM, to achieve superior predictive performance. A key feature of this approach is the integration of dynamic thresholding and anomaly scoring, both of which can be automatically adjusted to accommodate the diverse, unstable, and noisy characteristics often encountered in dynamic data.

Thill et al [8] introduced the Temporal Convolution Network coupled with an autoencoder framework (TCN-AE), for prediction-based anomaly detection. In contrast to a vanilla autoencoder, TCN-AE replaces the dense layer architecture with a more potent and flexible CNN architecture, making it adaptable to varying input sizes. This architecture incorporates two temporal convolutional networks (TCNs)[9] for both encoding and decoding processes. Concurrently, Dai et al [10] developed the Graph-Augmented Normalizing Flow (GANF) as an anomaly detection framework, grounded in graph neural networks (GNNs), to harness spatial feature correlations. Normalizing flow functions as a profound generative model in unsupervised learning, enabling the investigation of the inherent data distribution and addressing the issue of limited labels. GANF is cast as a Bayesian model, offering an estimate of the density for each data instance. This estimation aligns with the hypothesis that anomalies are more likely to be found in low-density regions.

In the case of reconstruction-based approaches, models such as Autoencoders (AE), LSTM-AE, and LSTM Variational Autoencoders (LSTM-VAE) have gained recognition. In contrast to prediction-based anomaly detection, which typically relies on identifying anomalies through deviations between actual and predicted values, this approach involves learning a latent low-dimensional representation to reconstruct the original input. Consequently, reconstruction-based approaches are often better suited for capturing contextual and collective anomalies[11]. While there has been extensive research on time series anomaly detection, the author has identified only one study that incorporated anomaly detection through explanation (ADE)[12]. In this context, Gilpin[12] employed reasonableness monitors based on anomaly detection within the context of simulated semi-autonomous vehicles. These simulations were designed to replicate real-world, anomalous driving scenarios. Furthermore, Gilpin utilized argument trees to generate reasoning and explanations for the detected anomalies. Gilpin[12] work represents a pioneering effort that has introduced the emerging field of

explanatory anomaly detection, particularly in the realm of system-level explanations.

In the domain of Internet of Things (IoT) and air quality monitoring, the author could not find any study that integrates both anomaly detection and LLMs. Most existing approaches primarily rely on either prediction-based or reconstruction-based anomaly detection methods to identify anomalous behavior, without offering comprehensive explanations or reasoning. This study addresses this gap by introducing a hybrid approach that combines prediction-based anomaly detection with LLMs to provide a robust framework for constructing explanations and reasoning in the context of air quality monitoring within IoT systems.

3. Proposed Method

3.1. Data Collection and Data Preprocessing

3.2. ConvLSTM-PBNN

3.3. Dynamic Thresholding

3.4. GPT-4 Integration

4. Result and Discussion

The main document with the manuscript text, figures, and tables should be prepared in an MS Word or LaTeX format in English. The manuscript should be written in 10-point font with single line spacing on A4 sized (21.0 x 29.7 cm) paper with 1.3 cm margins on the top, bottom, right, and left. The standard order of sections in the manuscript is title page, abstract, introduction, system model and methods, results, discussion, references. Figures and tables with legends should be embedded in the proper place in the text. The number of all manuscript pages should be specified, starting with the title page as page 1. A single file is permitted for initial submission, but figures and tables can be uploaded separately.

5. Conclusion

In conclusion, this research introduces a novel hybrid approach that combines prediction-based anomaly detection using Convolutional Long Short-term Memory with non-parametric dynamic thresholding (ConvLSTM-DT) and the fine-tuned GPT-4 model for Large Language Model (LLM)-based explanation generation. This hybrid approach significantly improves the interpretability and adaptability of anomaly detection models. By integrating the strengths of both prediction-based algorithms and LLMs, the model not only detects anomalies but also provides human-understandable explanations and potential solutions,

making it a powerful tool for real-world applications where quick decision-making is crucial.

Furthermore, the implementation of this approach on an edge-cloud architecture enhances its performance by reducing latency and ensuring fast detection. The use of custom fine-tuning with GPT-4 tailored to the specific anomaly detection task further amplifies its accuracy. This study emphasizes the importance of domain-specific fine-tuning in achieving precise and meaningful explanations. As the field of anomaly detection continues to evolve, the presented hybrid approach, along with the use of advanced LLMs, promises to play a pivotal role in improving anomaly detection across various domains, ultimately leading to safer and more efficient operations in complex systems.

For the future work, there is significant potential for enhancing anomaly detection by incorporating commonsense reasoning trees. This addition could further bolster the accuracy and depth of anomaly reasoning and provide a more comprehensive understanding of complex situations. Moreover, the integration of multimodal sensor fusion, which combines time-series data with visual and auditory inputs, could lead to more holistic anomaly detection solutions capable of capturing anomalies that span various data modalities. Additionally, exploring the integration of reliable control systems to facilitate intelligent decision-making services in real-time scenarios offers an exciting avenue for improving anomaly detection systems, ultimately advancing their capabilities and impact across diverse domains.

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Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Table 1
An example of a table.

Column heading	Column A	Column B
And an entry	1	2
And another entry	3	4
And another entry	5	6
And another entry	7	8

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The Title page should include a full title, running title (no more than 40 characters in length) of the article and authors' information.

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The text is recommended to be arranged in this order, if possible: Introduction, System Model and Methods, Result, Discussion, and Conclusions.



Figure 1. Example of a figure.

Introduction. the purpose and the background should be written simply and lucidly.

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References should be obviously related to documents. Indicate references by number(s) in square brackets in line with the text. The numbered references are listed in the order in which they appear in the text. The actual authors can be referred to, but the reference number(s) must always be given. Example: '..... as demonstrated [3,6]. Barnaby and Jones [8] obtained a different result'

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The Equations should be punctuated and aligned to bring out their structure and numbered on the right as

$$y = Hx + n. \quad (1)$$

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Units of measure should be presented according to the International System (SI) of Units. If other units are mentioned, please give their equivalent in SI.

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Each Table should be numbered with Arabic numerals in the order of their appearance in the text. Tables should have a concise and informative title with the table content between horizontal lines. The structure should be clear, with simple column headings giving all units. A table should not exceed one page when printed. Use lower case letters in superscripts a, b, c ... for special remarks. An example of a table is given in Table 1.

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