```
In [6]: import matplotlib.pyplot as plt
    from itertools import product
    import numpy as np
    from collections import Counter
    from sklearn.base import BaseEstimator, RegressorMixin, ClassifierMixin
    from sklearn.tree import DecisionTreeClassifier, DecisionTreeRegressor, export_gr
    import graphviz

from IPython.display import Image

%matplotlib inline
```

Load Data

```
In [7]: data_train = np.loadtxt('svm-train.txt')
    data_test = np.loadtxt('svm-test.txt')
    x_train, y_train = data_train[:, 0: 2], data_train[:, 2].reshape(-1, 1)
    x_test, y_test = data_test[:, 0: 2], data_test[:, 2].reshape(-1, 1)
In [8]: # Change target to 0-1 label
```

y_train_label = np.array(list(map(lambda x: 1 if x > 0 else 0, y_train))).reshape

Decision Tree Class

```
In [5]: class Decision Tree(BaseEstimator):
            def init (self, split loss function, leaf value estimator,
                         depth=0, min sample=5, max depth=10):
                Initialize the decision tree classifier
                :param split loss function: method for splitting node
                :param leaf_value_estimator: method for estimating leaf value
                :param depth: depth indicator, default value is 0, representing root node
                :param min sample: an internal node can be splitted only if it contains p
                :param max depth: restriction of tree depth.
                self.split loss function = split loss function
                self.leaf_value_estimator = leaf_value_estimator
                self.depth = depth
                self.min_sample = min_sample
                self.max depth = max depth
            def fit(self, X, y=None):
                This should fit the tree classifier by setting the values self.is_leaf,
                self.split id (the index of the feature we want ot split on, if we're spl
                self.split value (the corresponding value of that feature where the split
                and self.value, which is the prediction value if the tree is a leaf node.
                splitting the node, we should also init self.left and self.right to be De
                objects corresponding to the left and right subtrees. These subtrees show
                the data that fall to the left and right, respectively, of self.split valu
                This is a recurisive tree building procedure.
                :param X: a numpy array of training data, shape = (n, m)
                :param y: a numpy array of labels, shape = (n, 1)
                :return self
                if self.depth == self.max depth:
                    self.is leaf = True
                # Your code goes here
                return self
            def predict instance(self, instance):
                Predict label by decision tree
                :param instance: a numpy array with new data, shape (1, m)
                :return whatever is returned by leaf value estimator for leaf containing
                if self.is leaf:
                    return self.value
                if instance[self.split_id] <= self.split_value:</pre>
                    return self.left.predict instance(instance)
                else:
                    return self.right.predict instance(instance)
```

Decision Tree Classifier

```
In [ ]: def compute entropy(label array):
            Calulate the entropy of given label list
            :param label_array: a numpy array of labels shape = (n, 1)
            :return entropy: entropy value
            # Your code goes here
            return entropy
        def compute gini(label_array):
            Calulate the gini index of label list
            :param label_array: a numpy array of labels shape = (n, 1)
            :return gini: gini index value
            # Your code goes here
            return gini
In [ ]: def most common label(y):
            Find most common label
            label cnt = Counter(y.reshape(len(y)))
            label = label cnt.most common(1)[0][0]
            return label
In [ ]: class Classification Tree(BaseEstimator, ClassifierMixin):
            loss function dict = {
                'entropy': compute_entropy,
                'gini': compute gini
            }
            def __init__(self, loss_function='entropy', min_sample=5, max_depth=10):
                :param loss_function(str): loss function for splitting internal node
                self.tree = Decision_Tree(self.loss_function_dict[loss_function],
                                         most common label,
                                         0, min_sample, max_depth)
            def fit(self, X, y=None):
                self.tree.fit(X,y)
                return self
            def predict_instance(self, instance):
                value = self.tree.predict instance(instance)
                return value
```

Decision Tree Boundary

```
In [ ]: | # Training classifiers with different depth
         clf1 = Classification Tree(max depth=1)
         clf1.fit(x_train, y_train_label)
         clf2 = Classification Tree(max depth=2)
         clf2.fit(x_train, y_train_label)
         clf3 = Classification Tree(max depth=3)
         clf3.fit(x_train, y_train_label)
         clf4 = Classification_Tree(max_depth=4)
         clf4.fit(x train, y train label)
         clf5 = Classification Tree(max depth=5)
         clf5.fit(x_train, y_train_label)
         clf6 = Classification_Tree(max_depth=6)
         clf6.fit(x_train, y_train_label)
         # Plotting decision regions
         x \min, x \max = x \operatorname{train}[:, 0] \cdot \min() - 1, x \operatorname{train}[:, 0] \cdot \max() + 1
         y \min, y \max = x \operatorname{train}[:, 1].\min() - 1, x \operatorname{train}[:, 1].\max() + 1
         xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.1),
                               np.arange(y min, y max, 0.1))
         f, axarr = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(10, 8))
         for idx, clf, tt in zip(product([0, 1], [0, 1, 2]),
                                   [clf1, clf2, clf3, clf4, clf5, clf6],
                                   ['Depth = {}'.format(n) for n in range(1, 7)]):
             Z = np.array([clf.predict instance(x) for x in np.c [xx.ravel(), yy.ravel()]]
             Z = Z.reshape(xx.shape)
             axarr[idx[0], idx[1]].contourf(xx, yy, Z, alpha=0.4)
             axarr[idx[0], idx[1]].scatter(x_train[:, 0], x_train[:, 1], c=y_train_label,
             axarr[idx[0], idx[1]].set title(tt)
         plt.show()
```

Compare decision tree with tree model in sklearn

Decision Tree Regressor

```
In [ ]: # Regression Tree Specific Code
        def mean absolute deviation around median(y):
            Calulate the mean absolute deviation around the median of a given target list
            :param y: a numpy array of targets shape = (n, 1)
            :return mae
            # Your code goes here
            return mae
In [ ]: | class Regression Tree():
            :attribute loss_function_dict: dictionary containing the loss functions used
            :attribute estimator dict: dictionary containing the estimation functions use
            loss_function_dict = {
                 'mse': np.var,
                 'mae': mean absolute deviation around median
            }
            estimator_dict = {
                 'mean': np.mean,
                 'median': np.median
            }
```

Initialize Regression Tree

def predict_instance(self, instance):

value = self.tree.predict instance(instance)

def fit(self, X, y=None):
 self.tree.fit(X,y)

return self

return value

def __init__(self, loss_function='mse', estimator='mean', min_sample=5, max_d

self.tree = Decision Tree(self.loss function dict[loss function],

:param loss function(str): loss function used for splitting internal node

self.estimator dict[estimator],

0, min sample, max depth)

```
Fit regression tree to one-dimensional regression data
```

:param estimator(str): value estimator of internal node

```
In [21]: data krr train = np.loadtxt('krr-train.txt')
         data krr test = np.loadtxt('krr-test.txt')
         x_krr_train, y_krr_train = data_krr_train[:,0].reshape(-1,1),data krr_train[:,1].
         x_krr_test, y_krr_test = data_krr_test[:,0].reshape(-1,1),data_krr_test[:,1].resh
         # Training regression trees with different depth
         clf1 = Regression_Tree(max_depth=1, min_sample=1, loss_function='mae', estimator
         clf1.fit(x krr train, y krr train)
         clf2 = Regression Tree(max depth=2, min sample=1, loss function='mae', estimator
         clf2.fit(x_krr_train, y_krr_train)
                                              min sample=1, loss function='mae', estimator
         clf3 = Regression Tree(max depth=3,
         clf3.fit(x krr train, y krr train)
         clf4 = Regression_Tree(max_depth=4, min_sample=1, loss_function='mae', estimator
         clf4.fit(x_krr_train, y_krr_train)
         clf5 = Regression Tree(max depth=5, min sample=1, loss function='mae', estimator
         clf5.fit(x_krr_train, y_krr_train)
         clf6 = Regression_Tree(max_depth=6, min_sample=1, loss_function='mae', estimator
         clf6.fit(x krr train, y krr train)
         plot size = 0.001
         x range = np.arange(0., 1., plot size).reshape(-1, 1)
         f2, axarr2 = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(15, 10))
         for idx, clf, tt in zip(product([0, 1], [0, 1, 2]),
                                 [clf1, clf2, clf3, clf4, clf5, clf6],
                                 ['Depth = {}'.format(n) for n in range(1, 7)]):
             y range predict = np.array([clf.predict instance(x) for x in x range]).reshap
             axarr2[idx[0], idx[1]].plot(x_range, y_range_predict, color='r')
             axarr2[idx[0], idx[1]].scatter(x_krr_train, y_krr_train, alpha=0.8)
             axarr2[idx[0], idx[1]].set_title(tt)
             axarr2[idx[0], idx[1]].set_xlim(0, 1)
         plt.show()
```

8 Gradient Boosting Implementations

NameError: name 'Regression Tree' is not defined

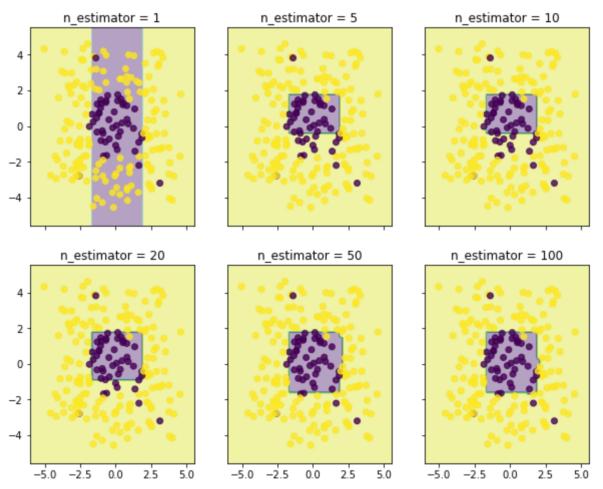
8.1 Gradient Boosting Method

```
In [50]: class gradient boosting():
             Gradient Boosting regressor class
             :method fit: fitting model
                   init (self, n estimator, pseudo residual func, learning rate=0.1, min
             def
                 Initialize gradient boosting class
                 :param n estimator: number of estimators (i.e. number of rounds of gradie
                 :pseudo residual func: function used for computing pseudo-residual
                 :param learning rate: step size of gradient descent
                 self.n estimator = n estimator
                 self.pseudo_residual_func = pseudo_residual func
                 self.learning_rate = learning_rate
                 self.min_sample = min_sample
                 self.max depth = max depth
                 #create param to save base models
                 self.base_models = []
                 self.h 0 = DecisionTreeRegressor(max depth=self.max depth,min samples lea
             def fit(self, train data, train target):
                 Fit gradient boosting model
                 # Your code goes here
                 #NOTE: HERE I START FROM m=0, USE "n estimator" as upper bound M(m=0,1,..
                 #initialize first prediction f0(x) as 0
                 train prediction = 0
                 #for step m 1 to M:
                 for step in range(1,self.n_estimator+1):
                     #calculate (-qm)
                     residual = self.pseudo residual func(train target.reshape(-1),train p
                     #fit regression to residual(-gm)
                     hm = DecisionTreeRegressor(max depth=self.max depth,min samples leaf=
                     hm.fit(train_data,residual)
                     #save hm to base models
                     self.base models.append(hm)
                     \#compute fm(x)
                     train prediction += self.learning rate * hm.predict(train data)
                 return self
             def predict(self, test data):
                 Predict value
                 # Your code goes here
                 prediction = 0
                 for i in range(len(self.base_models)):
                     prediction += self.learning_rate * self.base_models[i].predict(test_d
                 return prediction
```

```
In [51]: y_train_label.shape
Out[51]: (200, 1)
```

2-D GBM visualization - SVM data

```
In [52]: # Plotting decision regions
         x_{min}, x_{max} = x_{train}[:, 0].min() - 1, <math>x_{train}[:, 0].max() + 1
         y \min, y \max = x train[:, 1].min() - 1, x train[:, 1].max() + 1
         xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.1),
                               np.arange(y min, y max, 0.1))
         f, axarr = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(10, 8))
         for idx, i, tt in zip(product([0, 1], [0, 1, 2]),
                                 [1, 5, 10, 20, 50, 100],
                                 ['n_estimator = {}'.format(n) for n in [1, 5, 10, 20, 50,
             gbt = gradient boosting(n_estimator=i, pseudo_residual_func=pseudo_residual_I
             gbt.fit(x_train, y_train)
             Z = np.sign(gbt.predict(np.c_[xx.ravel(), yy.ravel()]))
             Z = Z.reshape(xx.shape)
             axarr[idx[0], idx[1]].contourf(xx, yy, Z, alpha=0.4)
             axarr[idx[0], idx[1]].scatter(x train[:, 0], x train[:, 1], c=y train label.r
             axarr[idx[0], idx[1]].set_title(tt)
```



1-D GBM visualization - KRR data

```
In [54]: plot size = 0.001
          x_range = np.arange(0., 1., plot_size).reshape(-1, 1)
          f2, axarr2 = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(15, 10))
          for idx, i, tt in zip(product([0, 1], [0, 1, 2]),
                                    [1, 5, 10, 20, 50, 100],
                                    ['n estimator = {}'.format(n) for n in [1, 5, 10, 20, 50,
              gbm 1d = gradient boosting(n estimator=i, pseudo residual func=pseudo residual
              gbm_ld.fit(x_krr_train, y_krr_train)
              y range predict = gbm ld.predict(x range)
              axarr2[idx[0], idx[1]].plot(x range, y range predict, color='r')
              axarr2[idx[0], idx[1]].scatter(x_krr_train, y_krr_train, alpha=0.8)
              axarr2[idx[0], idx[1]].set_title(tt)
              axarr2[idx[0], idx[1]].set_xlim(0, 1)
                                                                                n estimator = 10
                      n estimator = 1
                                                   n estimator = 5
           1 00
           0.75
           0.50
           0.25
           0.00
          -0.25
          -0.50
          -0.75
                     n_estimator = 20
                                                  n_estimator = 50
                                                                               n_estimator = 100
           1.00
```

8.2 Logistic loss

0.75 0.50 0.25 0.00 -0.25 -0.50

```
In [55]: #Pseudo-residual function.
#Here you can assume that we are using Logistic loss

def pseudo_residual_logistic(train_target,train_predict):
    y = train_target
    f = train_predict
    m = y*f
    return (y*np.exp(-m))/(1+np.exp(-m))
```

2-D GBM visualization - SVM data

1.0

```
In [61]: | # Plotting decision regions
          x_{min}, x_{max} = x_{train}[:, 0].min() - 1, <math>x_{train}[:, 0].max() + 1
          y_{min}, y_{max} = x_{train}[:, 1].min() - 1, <math>x_{train}[:, 1].max() + 1
          xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.1),
                                np.arange(y min, y max, 0.1))
          f, axarr = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(10, 8))
          for idx, i, tt in zip(product([0, 1], [0, 1, 2]),
                                   [1, 5, 10, 20, 50, 100],
                                   ['n_estimator = {}'.format(n) for n in [1, 5, 10, 20, 50,
              gbt = gradient boosting(n_estimator=i, pseudo_residual_func=pseudo_residual_l
              gbt.fit(x_train, y_train)
              Z = np.sign(gbt.predict(np.c_[xx.ravel(), yy.ravel()]))
              Z = Z.reshape(xx.shape)
              axarr[idx[0], idx[1]].contourf(xx, yy, Z, alpha=0.4)
              axarr[idx[0], idx[1]].scatter(x_train[:, 0], x_train[:, 1], c=y_train_label.r
              axarr[idx[0], idx[1]].set_title(tt)
                 n estimator = 1
                                           n estimator = 5
                                                                    n estimator = 10
           2
           -2
                 n estimator = 20
                                          n estimator = 50
                                                                   n estimator = 100
           2
           0
           -2
```

1-D GBM visualization - KRR data

-5.0 -2.5

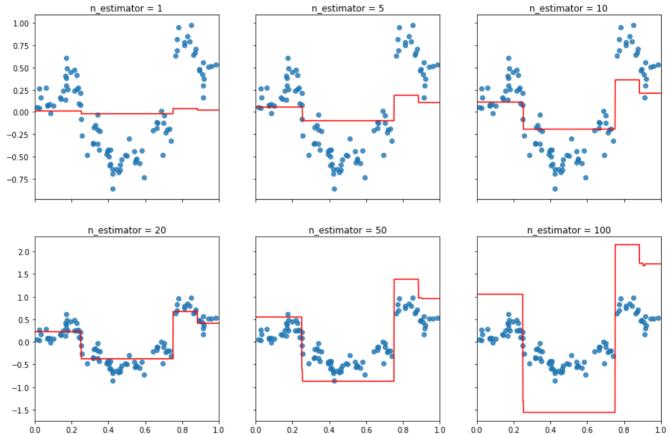
5.0

-2.5

-4

-2.5

```
In [57]: plot size = 0.001
         x range = np.arange(0., 1., plot size).reshape(-1, 1)
         f2, axarr2 = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(15, 10))
         for idx, i, tt in zip(product([0, 1], [0, 1, 2]),
                                  [1, 5, 10, 20, 50, 100],
                                  ['n estimator = {}'.format(n) for n in [1, 5, 10, 20, 50,
              gbm 1d = gradient boosting(n estimator=i, pseudo residual func=pseudo residual
              gbm_ld.fit(x_krr_train, y_krr_train)
             y range predict = gbm ld.predict(x range)
              axarr2[idx[0], idx[1]].plot(x_range, y_range_predict, color='r')
              axarr2[idx[0], idx[1]].scatter(x_krr_train, y_krr_train, alpha=0.8)
              axarr2[idx[0], idx[1]].set_title(tt)
              axarr2[idx[0], idx[1]].set_xlim(0, 1)
                    n estimator = 1
                                                n estimator = 5
                                                                           n estimator = 10
```



In []: