

Machine Learning: Models and Applications

Lecture 6

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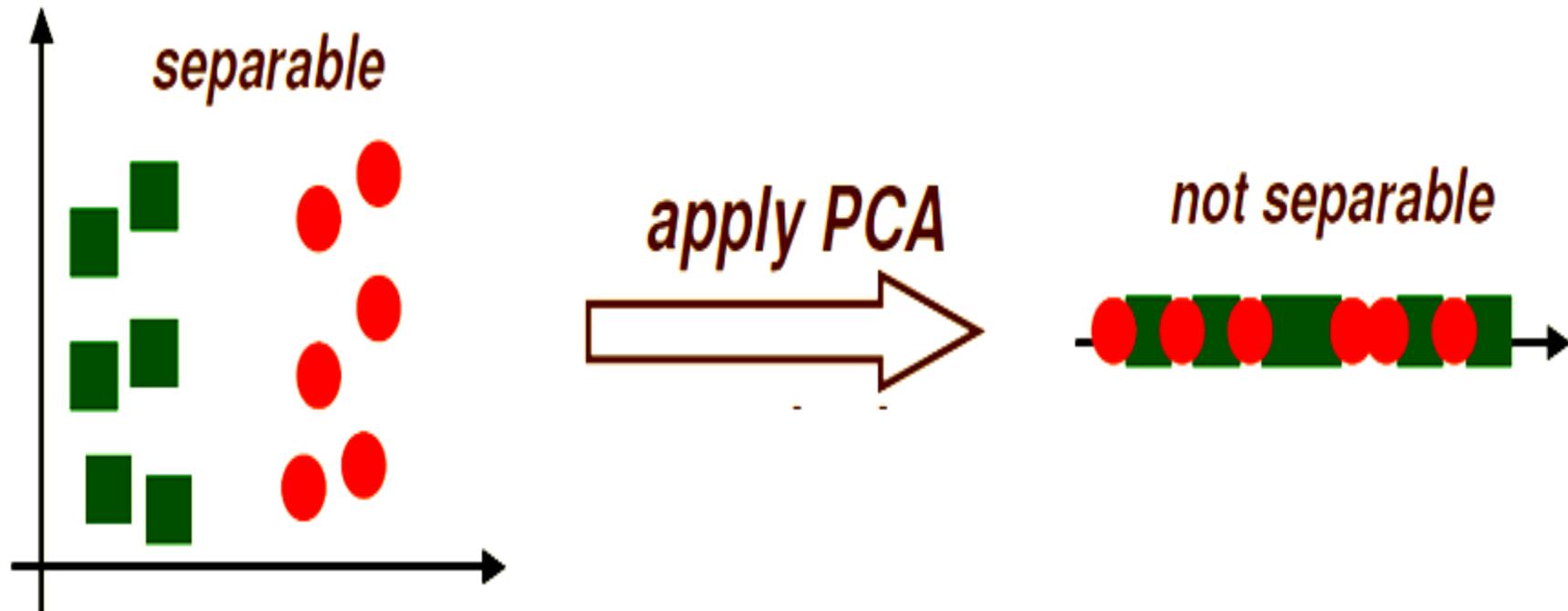
Overview

- Fisher Linear Discriminant (DHS Chapter 3 and notes based on course by Olga Veksler, Univ. of Western Ontario)
- Generative vs. Discriminative Classifiers
- Linear Discriminant Functions (notes based on Olga Veksler's)

Fisher Linear Discriminant Analysis (LDA/FDA/FLDA)

- PCA finds directions to project the data so that variance is maximized
- PCA does not consider *class labels*
- Variance maximization not necessarily beneficial for classification

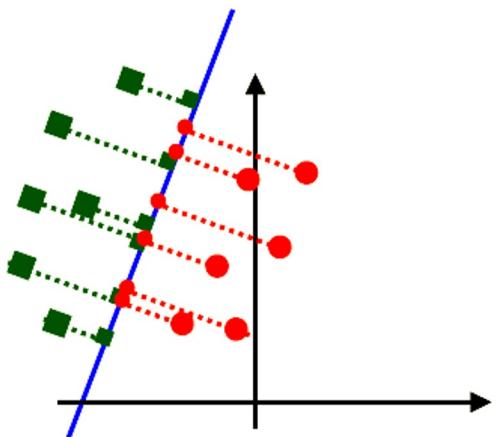
Data Representation vs. Data Classification



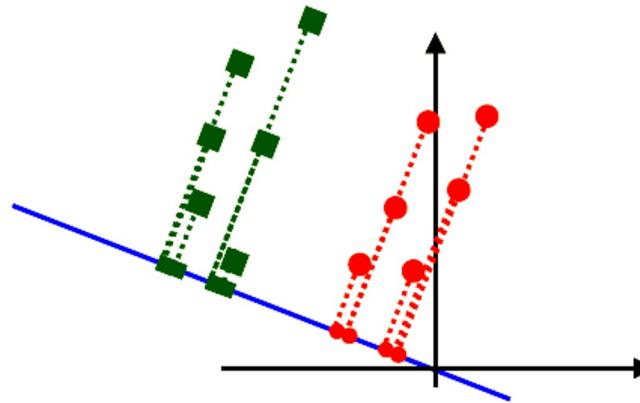
- Fisher Linear Discriminant: project to a line which preserves direction useful for *data classification*

Fisher Linear Discriminant

- Main idea: find projection to a line such that samples from different classes are well separated

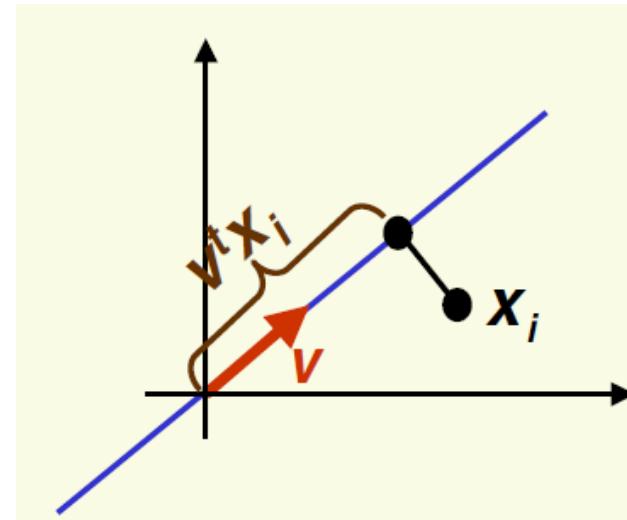


*bad line to project to,
classes are mixed up*



*good line to project to,
classes are well separated*

- Suppose we have 2 classes and d -dimensional samples $\mathbf{x}_1, \dots, \mathbf{x}_n$ where:
 - n_1 samples come from the first class
 - n_2 samples come from the second class
- Consider projection on a line
- Let the line direction be given by unit vector \mathbf{v}
- The scalar $\mathbf{v}^t \mathbf{x}_i$ is the distance of the projection of \mathbf{x}_i from the origin
- Thus, $\mathbf{v}^t \mathbf{x}_i$ is the projection of \mathbf{x}_i into a one dimensional subspace

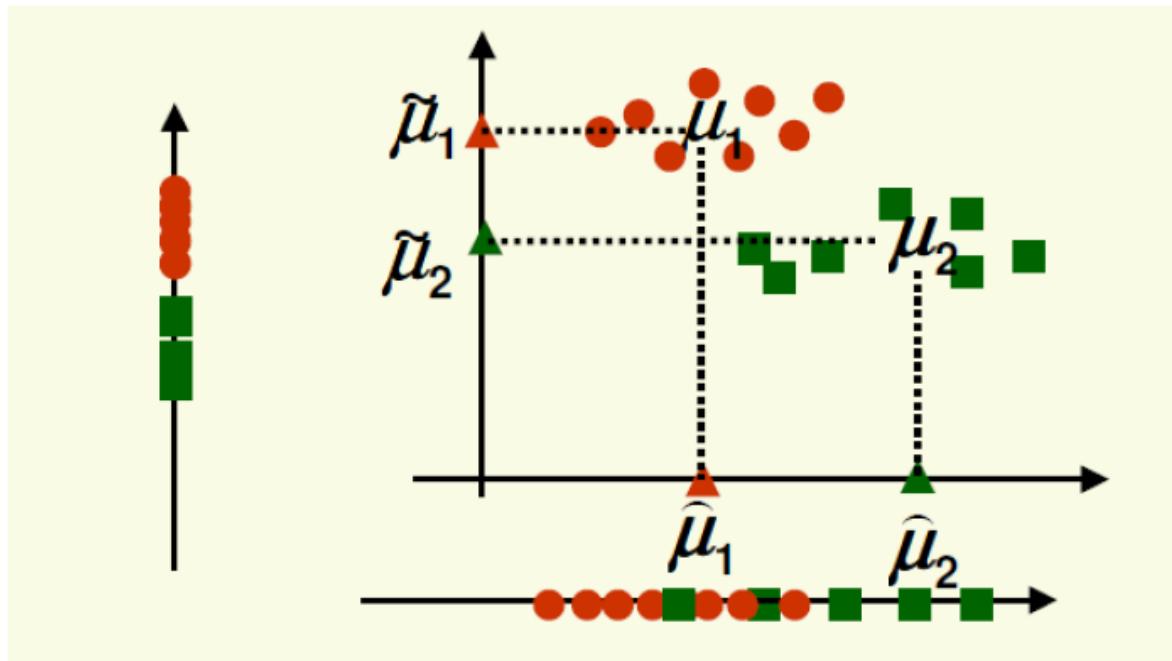


- The projection of sample x_i onto a line in direction v is given by $v^t x_i$
- How to measure separation between projections of different classes?
- Let $\tilde{\mu}_1$ and $\tilde{\mu}_2$ be the means of projections of classes 1 and 2
- Let μ_1 and μ_2 be the means of classes 1 and 2
- $|\tilde{\mu}_1 - \tilde{\mu}_2|$ seems like a good measure

$$\tilde{\mu}_1 = \frac{1}{n_1} \sum_{x_i \in C1} v^t x_i = v^t \left(\frac{1}{n_1} \sum_{x_i \in C1} x_i \right) = v^t \mu_1$$

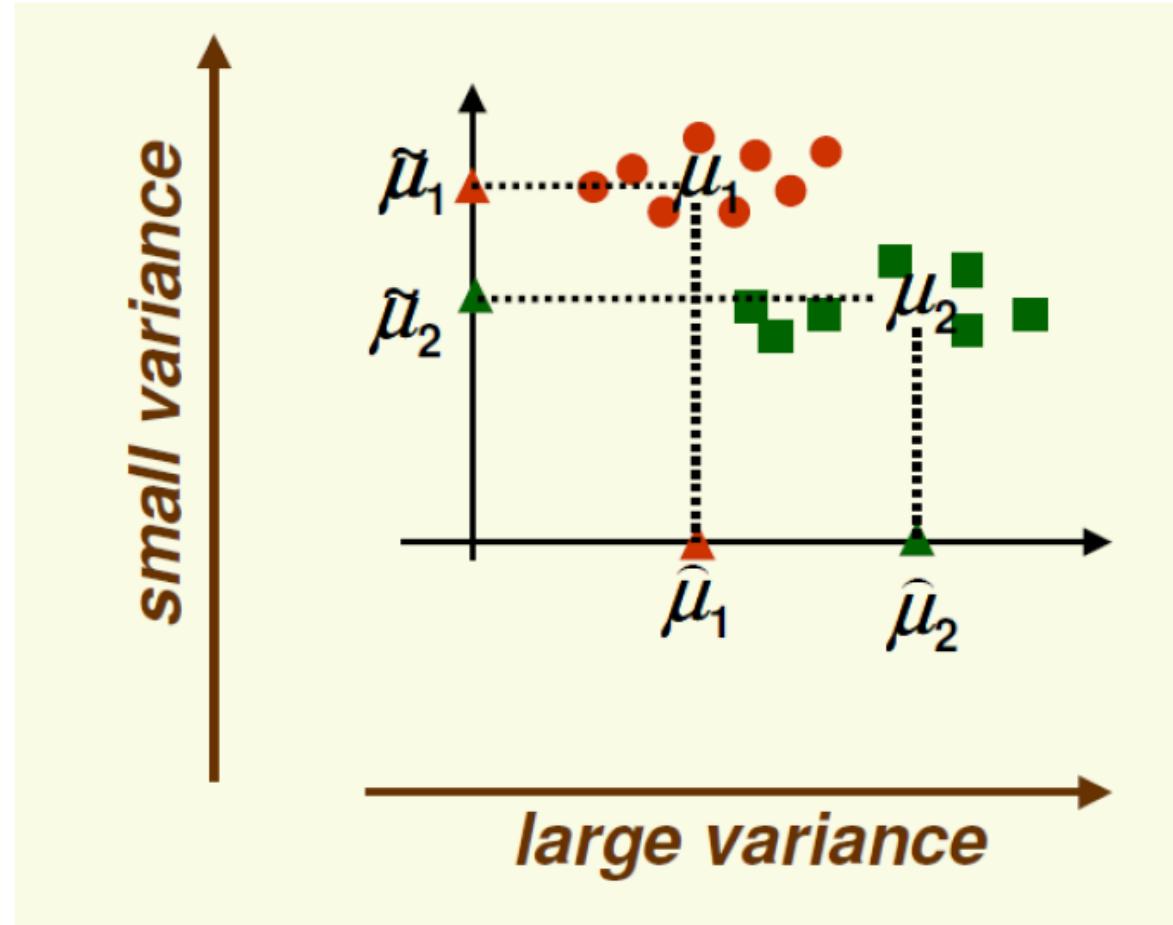
similarly, $\tilde{\mu}_2 = v^t \mu_2$

- How good is $|\tilde{\mu}_1 - \tilde{\mu}_2|$ as a measure of separation?
 - The larger it is, the better the expected separation



- The vertical axis is a better line than the horizontal axis to project to for class separability
- However $|\tilde{\mu}_1 - \tilde{\mu}_2| < |\hat{\mu}_1 - \hat{\mu}_2|$

- The problem with $|\tilde{\mu}_1 - \tilde{\mu}_2|$ is that it does not consider the variance of the classes



- We need to normalize $|\tilde{\mu}_1 - \tilde{\mu}_2|$ by a factor which is proportional to variance

- For samples z_1, \dots, z_n , the sample mean is: $\mu_z = \frac{1}{n} \sum_{i=1}^n z_i$
- Define **scatter** as:

$$s = \sum_{i=1}^n (z_i - \mu_z)^2$$

- Thus scatter is just sample variance multiplied by n
 - Scatter measures the same thing as variance, the spread of data around the mean
 - Scatter is just on different scale than variance

larger scatter:



smaller scatter:



- Fisher Solution: normalize $|\tilde{\mu}_1 - \tilde{\mu}_2|$ by scatter
- Let $y_i = v^t x^i$, be the projected samples
- The scatter for projected samples of class 1 is

$$\tilde{s}_1^2 = \sum_{y_i \in \text{Class 1}} (y_i - \tilde{\mu}_1)^2$$

- The scatter for projected samples of class 2 is

$$\tilde{s}_2^2 = \sum_{y_i \in \text{Class 2}} (y_i - \tilde{\mu}_2)^2$$

Fisher Linear Discriminant

- We need to normalize by both scatter of class 1 and scatter of class 2
- The Fisher linear discriminant is the projection on a line in the direction v which maximizes

want projected means far from each other

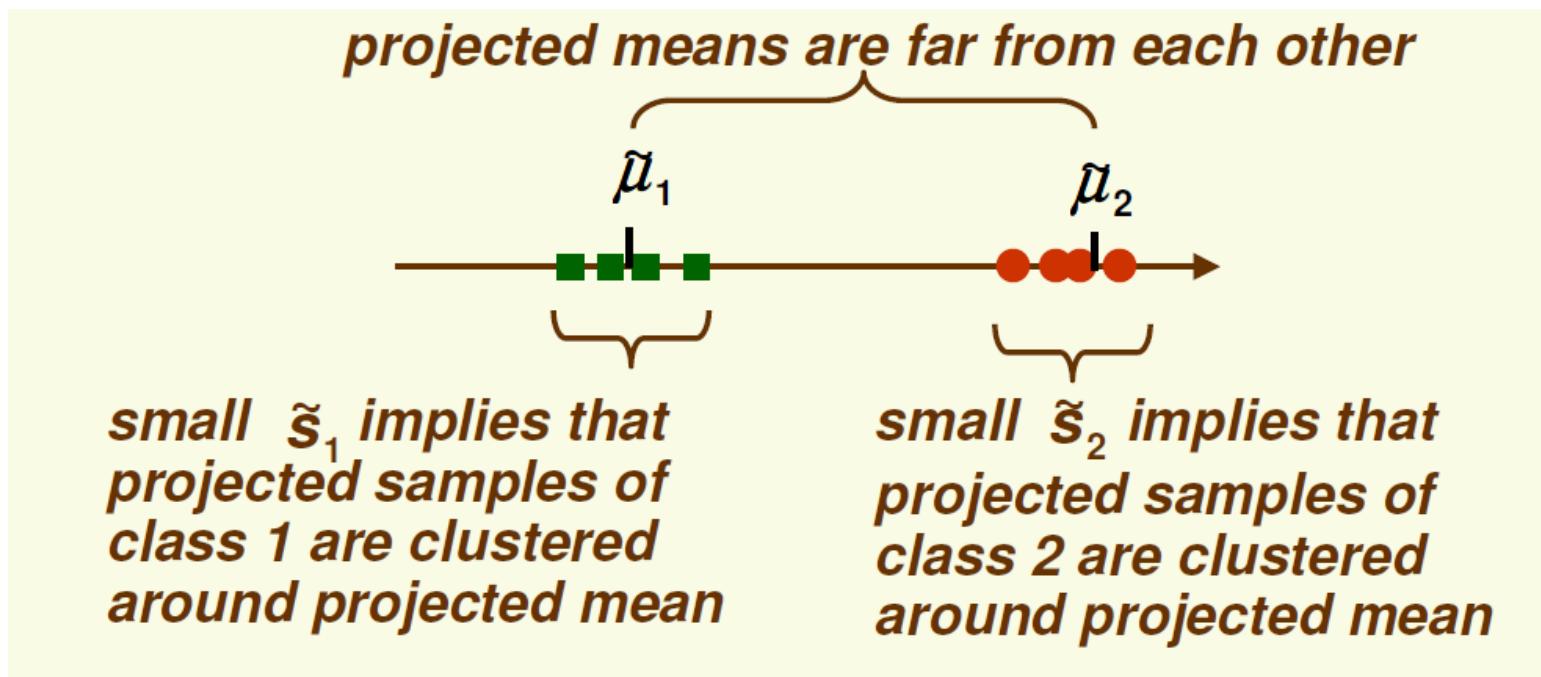
$$J(v) = \frac{(\tilde{\mu}_1 - \tilde{\mu}_2)^2}{\tilde{s}_1^2 + \tilde{s}_2^2}$$

want scatter in class 1 is as small as possible, i.e. samples of class 1 cluster around the projected mean $\tilde{\mu}_1$

want scatter in class 2 is as small as possible, i.e. samples of class 2 cluster around the projected mean $\tilde{\mu}_2$

$$J(v) = \frac{(\tilde{\mu}_1 - \tilde{\mu}_2)^2}{\tilde{s}_1^2 + \tilde{s}_2^2}$$

- If we find v which makes $J(v)$ large, we are guaranteed that the classes are well separated



Fisher Linear Discriminant - Derivation

$$J(\mathbf{v}) = \frac{(\tilde{\mu}_1 - \tilde{\mu}_2)^2}{\tilde{\mathbf{s}}_1^2 + \tilde{\mathbf{s}}_2^2}$$

- All we need to do now is express $J(\mathbf{v})$ as a function of \mathbf{v} and maximize it
 - Straightforward but need linear algebra and calculus
- Define the class scatter matrices \mathbf{S}_1 and \mathbf{S}_2 . These measure the scatter of original samples \mathbf{x}_i (before projection)

$$\mathbf{S}_1 = \sum_{x_i \in \text{Class 1}} (\mathbf{x}_i - \boldsymbol{\mu}_1)(\mathbf{x}_i - \boldsymbol{\mu}_1)^t$$

$$\mathbf{S}_2 = \sum_{x_i \in \text{Class 2}} (\mathbf{x}_i - \boldsymbol{\mu}_2)(\mathbf{x}_i - \boldsymbol{\mu}_2)^t$$

- Define **within class** scatter matrix

$$\mathbf{S}_w = \mathbf{S}_1 + \mathbf{S}_2$$

$$\tilde{\mathbf{s}}_1^2 = \sum_{y_i \in \text{Class 1}} (y_i - \tilde{\mu}_1)^2$$

- $y_i = \mathbf{v}^t \mathbf{x}_i$ and $\tilde{\mu}_1 = \mathbf{v}^t \mu_1$

$$\begin{aligned}\tilde{\mathbf{s}}_1^2 &= \sum_{y_i \in \text{Class 1}} (\mathbf{v}^t \mathbf{x}_i - \mathbf{v}^t \mu_1)^2 \\ &= \sum_{y_i \in \text{Class 1}} (\mathbf{v}^t (\mathbf{x}_i - \mu_1))^t (\mathbf{v}^t (\mathbf{x}_i - \mu_1)) \\ &= \sum_{y_i \in \text{Class 1}} ((\mathbf{x}_i - \mu_1)^t \mathbf{v})^t ((\mathbf{x}_i - \mu_1)^t \mathbf{v}) \\ &= \sum_{y_i \in \text{Class 1}} \mathbf{v}^t (\mathbf{x}_i - \mu_1)(\mathbf{x}_i - \mu_1)^t \mathbf{v} = \mathbf{v}^t \mathbf{S}_1 \mathbf{v}\end{aligned}$$

- Similarly

$$\tilde{\mathbf{S}}_2^2 = \mathbf{v}^t \mathbf{S}_2 \mathbf{v}$$

$$\tilde{\mathbf{S}}_1^2 + \tilde{\mathbf{S}}_2^2 = \mathbf{v}^t \mathbf{S}_1 \mathbf{v} + \mathbf{v}^t \mathbf{S}_2 \mathbf{v} = \mathbf{v}^t \mathbf{S}_W \mathbf{v}$$

- Define **between class** scatter matrix

$$\mathbf{S}_B = (\mu_1 - \mu_2)(\mu_1 - \mu_2)^t$$

- \mathbf{S}_B measures separation of the means of the two classes before projection
- The separation of the projected means can be written as

$$\begin{aligned}(\hat{\mu}_1 - \hat{\mu}_2)^2 &= (\mathbf{v}^t \mu_1 - \mathbf{v}^t \mu_2)^2 \\&= \mathbf{v}^t (\mu_1 - \mu_2)(\mu_1 - \mu_2)^t \mathbf{v} \\&= \mathbf{v}^t \mathbf{S}_B \mathbf{v}\end{aligned}$$

- Thus our objective function can be written:

$$J(\mathbf{v}) = \frac{(\tilde{\mu}_1 - \tilde{\mu}_2)^2}{\tilde{\mathbf{s}}_1^2 + \tilde{\mathbf{s}}_2^2} = \frac{\mathbf{v}^t \mathbf{S}_B \mathbf{v}}{\mathbf{v}^t \mathbf{S}_W \mathbf{v}}$$

- Maximize $J(\mathbf{v})$ by taking the derivative w.r.t. \mathbf{v} and setting it to 0

$$\begin{aligned}\frac{d}{d\mathbf{v}} J(\mathbf{v}) &= \frac{\left(\frac{d}{d\mathbf{v}} \mathbf{v}^t \mathbf{S}_B \mathbf{v} \right) \mathbf{v}^t \mathbf{S}_W \mathbf{v} - \left(\frac{d}{d\mathbf{v}} \mathbf{v}^t \mathbf{S}_W \mathbf{v} \right) \mathbf{v}^t \mathbf{S}_B \mathbf{v}}{(\mathbf{v}^t \mathbf{S}_W \mathbf{v})^2} \\ &= \frac{(2\mathbf{S}_B \mathbf{v}) \mathbf{v}^t \mathbf{S}_W \mathbf{v} - (2\mathbf{S}_W \mathbf{v}) \mathbf{v}^t \mathbf{S}_B \mathbf{v}}{(\mathbf{v}^t \mathbf{S}_W \mathbf{v})^2} = 0\end{aligned}$$

Need to solve $\mathbf{v}^t \mathbf{S}_W \mathbf{v} (\mathbf{S}_B \mathbf{v}) - \mathbf{v}^t \mathbf{S}_B \mathbf{v} (\mathbf{S}_W \mathbf{v}) = 0$

$$\Rightarrow \frac{\mathbf{v}^t \mathbf{S}_W \mathbf{v} (\mathbf{S}_B \mathbf{v})}{\mathbf{v}^t \mathbf{S}_W \mathbf{v}} - \frac{\mathbf{v}^t \mathbf{S}_B \mathbf{v} (\mathbf{S}_W \mathbf{v})}{\mathbf{v}^t \mathbf{S}_W \mathbf{v}} = 0$$

$$\Rightarrow \mathbf{S}_B \mathbf{v} - \frac{\mathbf{v}^t \mathbf{S}_B \mathbf{v} (\mathbf{S}_W \mathbf{v})}{\mathbf{v}^t \mathbf{S}_W \mathbf{v}} = \lambda$$

$$\Rightarrow \underbrace{\mathbf{S}_B \mathbf{v}}_{\lambda \mathbf{S}_W \mathbf{v}} = \lambda \mathbf{S}_W \mathbf{v}$$

generalized eigenvalue problem

$$\mathbf{S}_B \mathbf{v} = \lambda \mathbf{S}_W \mathbf{v}$$

- If \mathbf{S}_W has full rank (the inverse exists), we can convert this to a standard eigenvalue problem

$$\mathbf{S}_W^{-1} \mathbf{S}_B \mathbf{v} = \lambda \mathbf{v}$$

- But $\mathbf{S}_B \mathbf{x}$ for any vector \mathbf{x} , points in the same direction as $\mu_1 - \mu_2$

$$\mathbf{S}_B \mathbf{x} = (\mu_1 - \mu_2)(\mu_1 - \mu_2)^t \mathbf{x} = (\mu_1 - \mu_2) \underbrace{((\mu_1 - \mu_2)^t \mathbf{x})}_{\alpha} = \alpha(\mu_1 - \mu_2)$$

- Based on this, we can solve the eigenvalue problem directly

$$\mathbf{v} = \mathbf{S}_W^{-1}(\mu_1 - \mu_2)$$

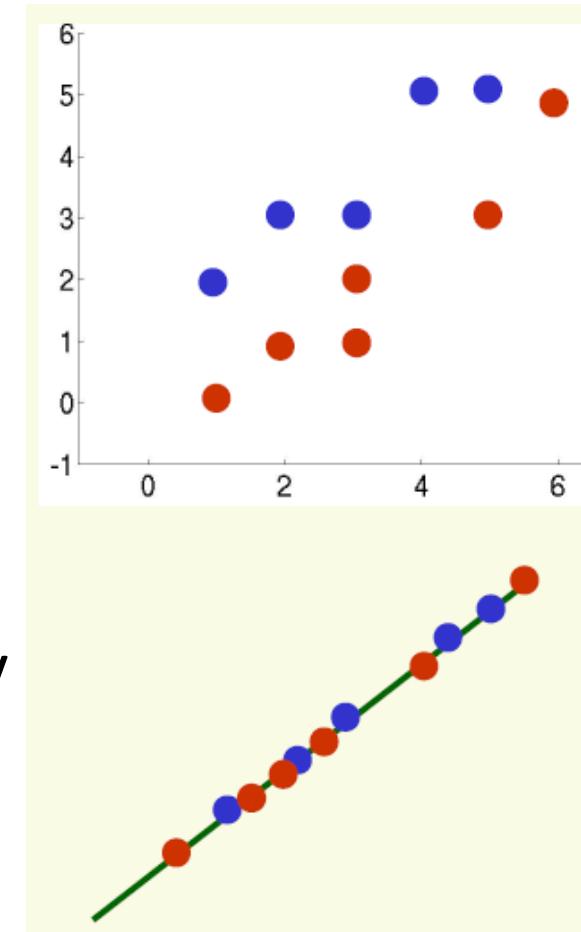
$$\mathbf{S}_W^{-1} \mathbf{S}_B \underbrace{[\mathbf{S}_W^{-1}(\mu_1 - \mu_2)]}_{\mathbf{v}} = \mathbf{S}_W^{-1} [\alpha(\mu_1 - \mu_2)] = \underbrace{\alpha}_{\lambda} \underbrace{[\mathbf{S}_W^{-1}(\mu_1 - \mu_2)]}_{\mathbf{v}}$$

Example

- Data
 - Class 1 has 5 samples
 $c_1 = [(1,2), (2,3), (3,3), (4,5), (5,5)]$
 - Class 2 has 6 samples
 $c_2 = [(1,0), (2,1), (3,1), (3,2), (5,3), (6,5)]$
- Arrange data in 2 separate matrices

$$c_1 = \begin{bmatrix} 1 & 2 \\ \vdots & \vdots \\ 5 & 5 \end{bmatrix} \quad c_2 = \begin{bmatrix} 1 & 0 \\ \vdots & \vdots \\ 6 & 5 \end{bmatrix}$$

- Notice that PCA performs very poorly on this data because the direction of largest variance is not helpful for classification



- First compute the mean for each class

$$\mu_1 = \text{mean}(\mathbf{c}_1) = [3 \quad 3.6]^t \quad \mu_2 = \text{mean}(\mathbf{c}_2) = [3.3 \quad 2]^t$$

- Compute scatter matrices \mathbf{S}_1 and \mathbf{S}_2 for each class

$$\mathbf{S}_1 = 4 * \text{cov}(\mathbf{c}_1) = \begin{bmatrix} 10 & 8.0 \\ 8.0 & 7.2 \end{bmatrix} \quad \mathbf{S}_2 = 5 * \text{cov}(\mathbf{c}_2) = \begin{bmatrix} 17.3 & 16 \\ 16 & 16 \end{bmatrix}$$

- Within class scatter: $\mathbf{S}_w = \mathbf{S}_1 + \mathbf{S}_2 = \begin{bmatrix} 27.3 & 24 \\ 24 & 23.2 \end{bmatrix}$

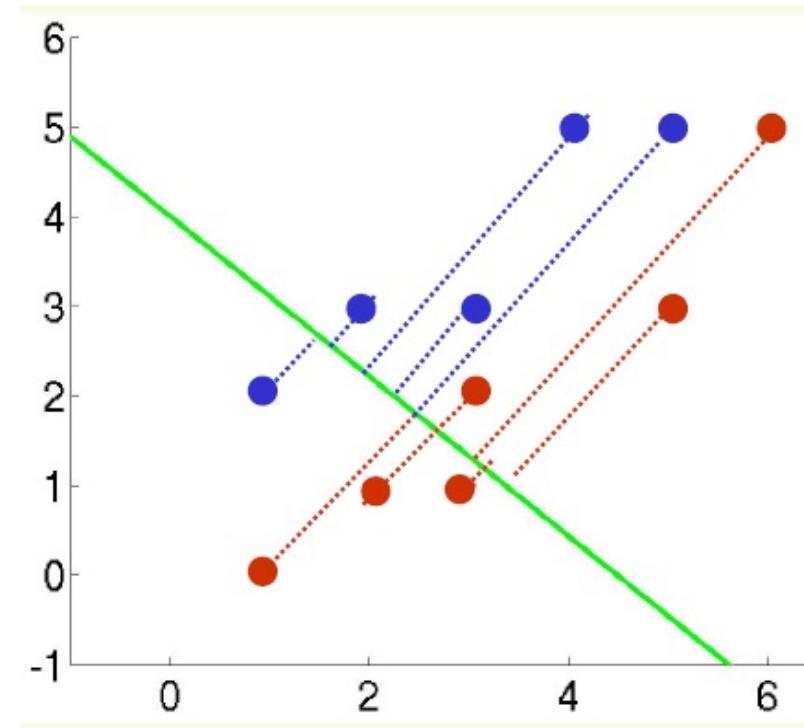
– it has full rank, don't have to solve for eigenvalues

- The inverse of \mathbf{S}_w is: $\mathbf{S}_w^{-1} = \text{inv}(\mathbf{S}_w) = \begin{bmatrix} 0.39 & -0.41 \\ -0.41 & 0.47 \end{bmatrix}$

- Finally, the optimal line direction \mathbf{v} is:

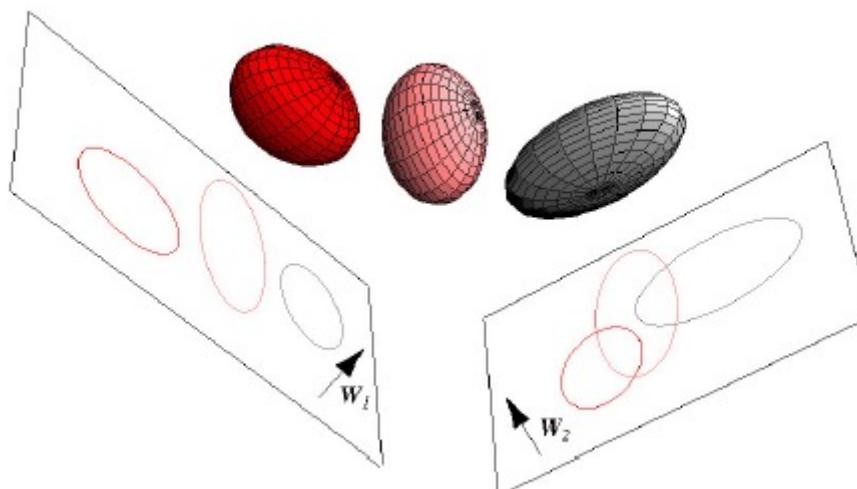
$$\mathbf{v} = \mathbf{S}_w^{-1}(\mu_1 - \mu_2) = \begin{bmatrix} -0.79 \\ 0.89 \end{bmatrix}$$

- As long as the line has the right direction, its exact position does not matter
- The last step is to compute the actual 1D vector y
 - Separately for each class



Multiple Discriminant Analysis

- Can generalize FLD to multiple classes
 - In case of c classes, we can reduce dimensionality to 1, 2, 3, ..., $c-1$ dimensions
 - Project sample \mathbf{x}_i to a linear subspace $\mathbf{y}_i = \mathbf{V}^t \mathbf{x}_i$
 - \mathbf{V} is called projection matrix



- Within class scatter matrix:

$$\mathbf{S}_W = \sum_{i=1}^c \mathbf{S}_i = \sum_{i=1}^c \sum_{x_k \in \text{class } i} (\mathbf{x}_k - \boldsymbol{\mu}_i)(\mathbf{x}_k - \boldsymbol{\mu}_i)^t$$

- Between class scatter matrix

$$\mathbf{S}_B = \sum_{i=1}^c n_i (\boldsymbol{\mu}_i - \boldsymbol{\mu})(\boldsymbol{\mu}_i - \boldsymbol{\mu})^t$$

maximum rank is c - 1

mean of all data
mean of class i

- Objective function

$$J(\mathbf{V}) = \frac{\det(\mathbf{V}^t \mathbf{S}_B \mathbf{V})}{\det(\mathbf{V}^t \mathbf{S}_W \mathbf{V})}$$

$$J(V) = \frac{\det(V^t S_B V)}{\det(V^t S_W V)}$$

- Solve generalized eigenvalue problem

$$S_B v = \lambda S_W v$$

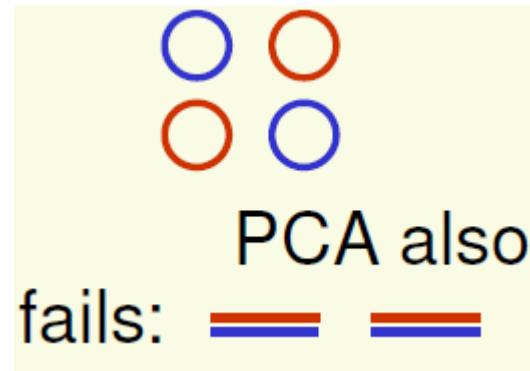
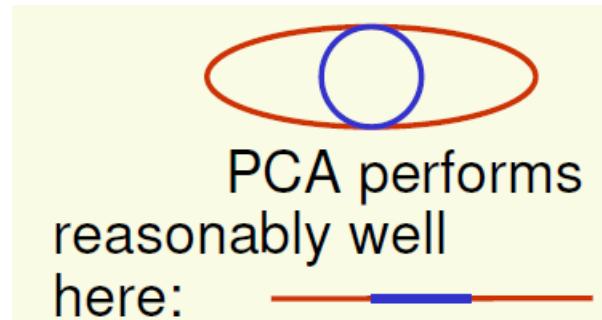
- There are at most $c-1$ distinct eigenvalues
 - with $v_1 \dots v_{c-1}$ corresponding eigenvectors
- The optimal projection matrix V to a subspace of dimension k is given by the eigenvectors corresponding to the largest k eigenvalues
- Thus, we can project to a subspace of dimension at most $c-1$

FDA and MDA Drawbacks

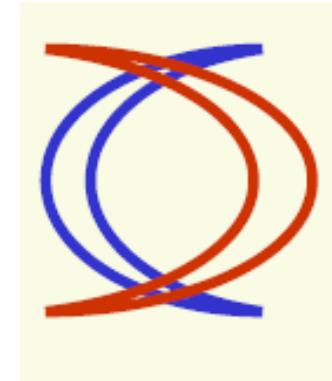
- Reduces dimension only to $k = c-1$
 - Unlike PCA where dimension can be chosen to be smaller or larger than $c-1$
- For complex data, projection to even the best line may result in non-separable projected samples

FDA and MDA Drawbacks

- FDA/MDA will fail:
 - If $J(v)$ is always 0: when $\mu_1 = \mu_2$



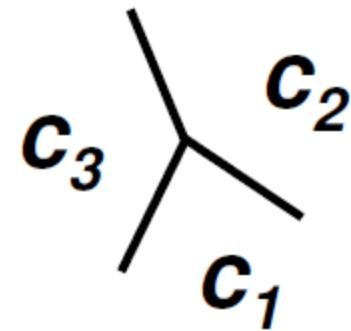
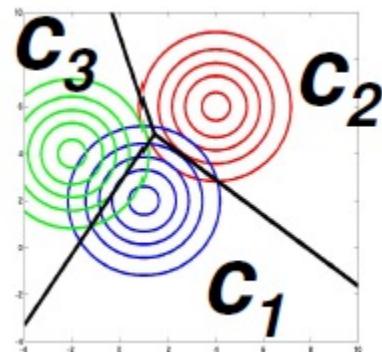
- If $J(v)$ is always small: classes have large overlap when projected to any line (PCA will also fail)



Generative vs. Discriminative Approaches

Parametric Methods vs. Discriminant Functions

- Assume the shape of density for classes is known $p_1(x|\theta_1)$, $p_2(x|\theta_2), \dots$
- Estimate $\theta_1, \theta_2, \dots$ from data
- Use a Bayesian classifier to find decision regions
- Assume discriminant functions are of known shape $I(\theta_1), I(\theta_2), \dots$, with parameters $\theta_1, \theta_2, \dots$
- Estimate $\theta_1, \theta_2, \dots$ from data
- Use discriminant functions for classification



Parametric Methods vs. Discriminant Functions

- In theory, Bayesian classifier minimizes the risk
 - In practice, we may be uncertain about our assumptions about the models
 - In practice, we may not really need the actual density functions
- Estimating accurate density functions is much harder than estimating accurate discriminant functions
 - Why solve a harder problem than needed?

Generative vs. Discriminative Models

Training classifiers involves estimating $f: X \rightarrow Y$, or $P(Y|X)$

Discriminative classifiers

1. Assume some functional form for $P(Y|X)$
2. Estimate parameters of $P(Y|X)$ directly from training data

Generative classifiers

1. Assume some functional form for $P(X|Y)$, $P(X)$
2. Estimate parameters of $P(X|Y)$, $P(X)$ directly from training data
3. Use Bayes rule to calculate $P(Y|X=x_i)$

Generative vs. Discriminative Example

- The task is to determine the language that someone is speaking
- Generative approach:
 - Learn each language and determine which language the speech belongs to
- Discriminative approach:
 - Determine the linguistic differences without learning any language – a much easier task!

Generative vs. Discriminative Taxonomy

- Generative Methods
 - Model class-conditional pdfs and prior probabilities
 - “Generative” since sampling can generate synthetic data points
 - Popular models
 - Multi-variate Gaussians, Naïve Bayes
 - Mixtures of Gaussians, Mixtures of experts, Hidden Markov Models (HMM)
 - Sigmoidal belief networks, Bayesian networks, Markov random fields
- Discriminative Methods
 - Directly estimate posterior probabilities
 - No attempt to model underlying probability distributions
 - Focus computational resources on given task– better performance
 - Popular models
 - Logistic regression
 - SVMs
 - Traditional neural networks
 - Nearest neighbor
 - Conditional Random Fields (CRF)

Generative Approach

- Advantage
 - Prior information about the structure of the data is often most naturally specified through a generative model $P(X|Y)$
 - For example, for male faces, we would expect to see heavier eyebrows, a more square jaw, etc.
- Disadvantages
 - The generative approach does not directly target the classification model $P(Y|X)$ since the goal of generative training is $P(X|Y)$
 - If the data x are complex, finding a suitable generative data model $P(X|Y)$ is a difficult task
 - Since each generative model is separately trained for each class, there is no competition amongst the models to explain the data
 - The decision boundary between the classes may have a simple form, even if the data distribution of each class is complex

Discriminative Approach

- Advantages
 - The discriminative approach directly addresses finding an accurate classifier $P(Y|X)$ based on modelling the decision boundary, as opposed to the class conditional data distribution
 - Whilst the data from each class may be distributed in a complex way, it could be that the decision boundary between them is relatively easy to model
- Disadvantages
 - Discriminative approaches are usually trained as “black-box” classifiers, with **little prior knowledge** built used to describe how data for a given class is distributed
 - **Domain knowledge** is often more easily expressed using the generative framework

Linear Discriminant Functions

LDF: Introduction

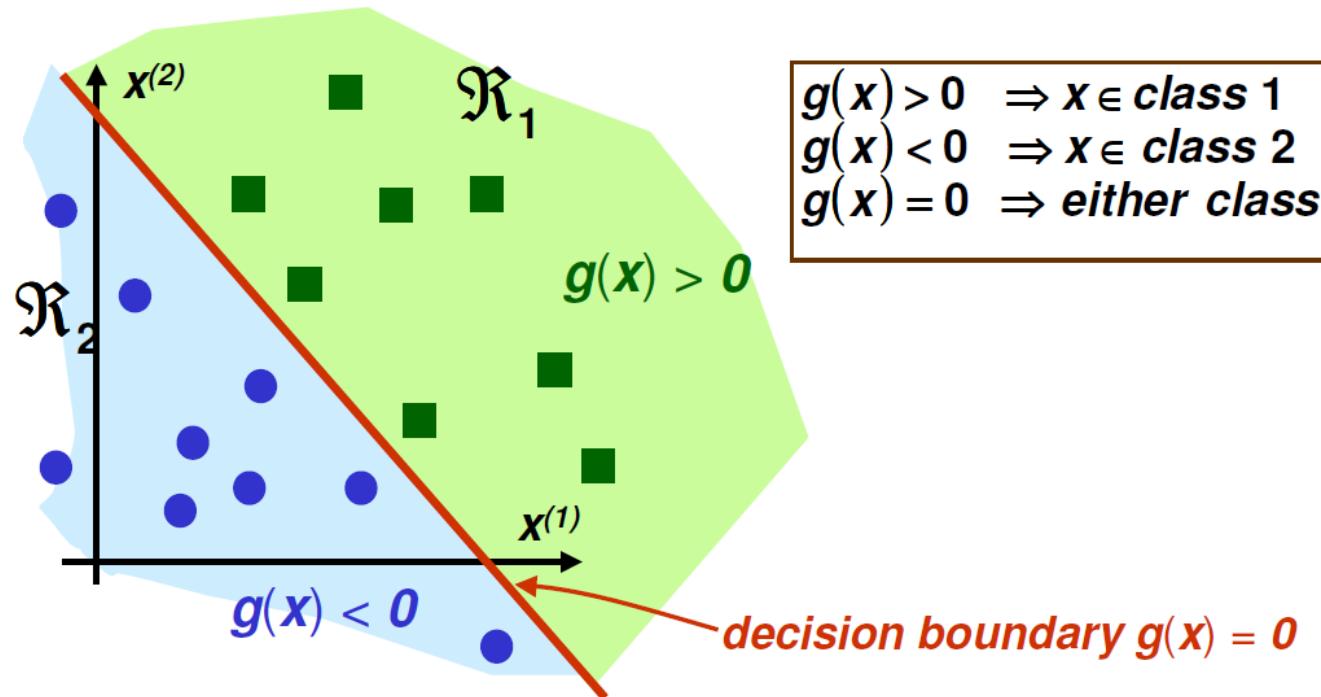
- Discriminant functions can be more general than linear
- For now, focus on linear discriminant functions
 - Simple model (should try simpler models first)
 - Analytically tractable
- Linear Discriminant functions are optimal for **Gaussian distributions** with **equal covariance**
- May not be optimal for other data distributions, but they are very simple to use

LDF: Two Classes

- A discriminant function is linear if it can be written as

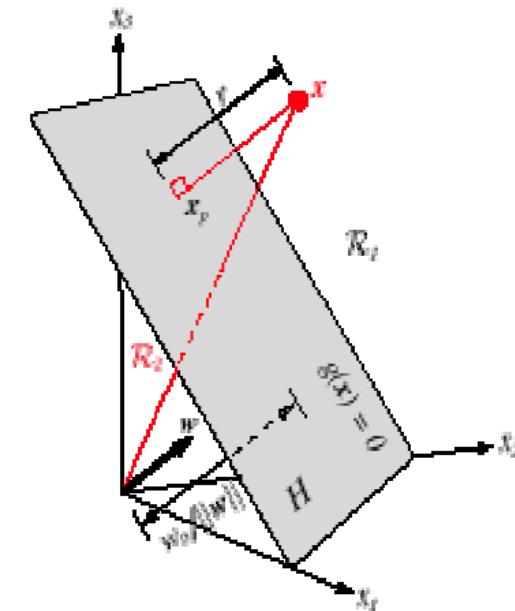
$$g(\mathbf{x}) = \mathbf{w}^t \mathbf{x} + w_0$$

- \mathbf{w} is called the weight vector and w_0 is called the bias or threshold



LDF: Two Classes

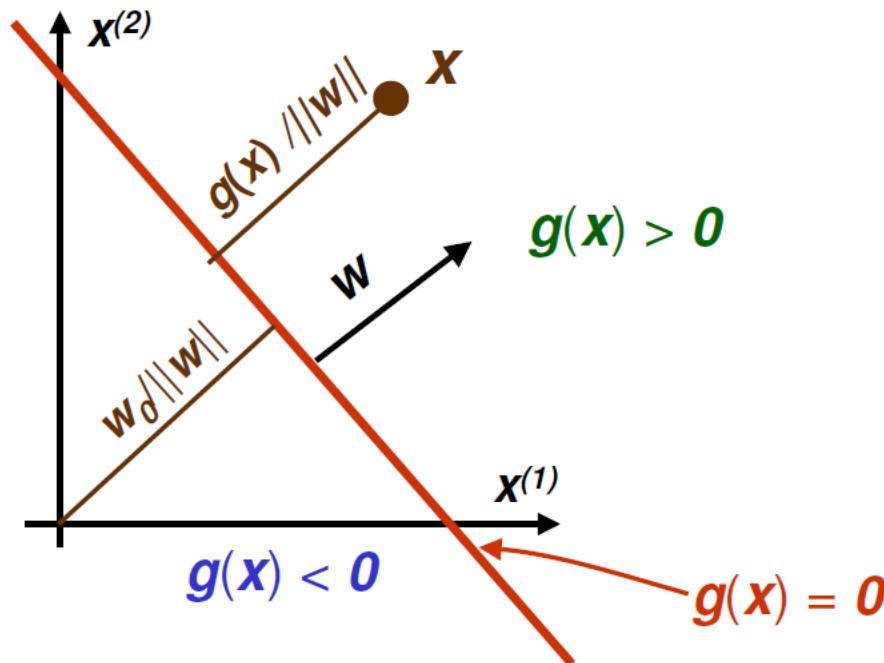
- Decision boundary $g(\mathbf{x}) = \mathbf{w}^t \mathbf{x} + w_0 = 0$ is a hyperplane
 - Set of vectors \mathbf{x} , which for some scalars a_0, \dots, a_d , satisfy $a_0 + a_1 x^{(1)} + \dots + a_d x^{(d)} = 0$
 - A hyperplane is:
 - a point in 1D
 - a line in 2D
 - a plane in 3D



LDF: Two Classes

$$g(\mathbf{x}) = \mathbf{w}^t \mathbf{x} + w_0$$

- \mathbf{w} determines the orientation of the decision hyperplane
- w_0 determines the location of the decision surface



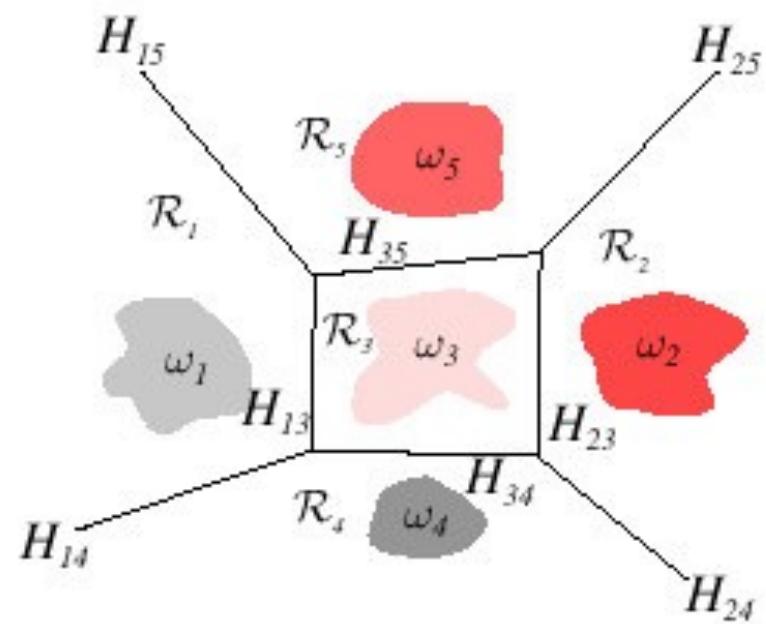
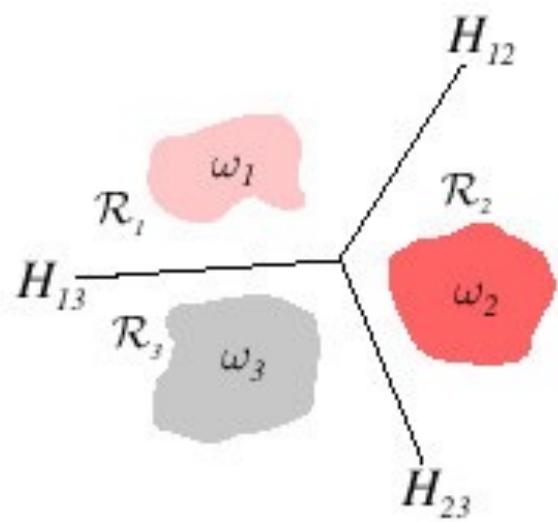
LDF: Multiple Classes

- Suppose we have m classes
- Define m linear discriminant functions

$$g_i(x) = w_i^t x + w_{i0}$$

- Given x , assign to class c_i if
 - $g_i(x) > g_j(x), i \neq j$
- Such a classifier is called a **linear machine**
- A linear machine divides the feature space into c decision regions, with $g_i(x)$ being the largest discriminant if x is in the region R_i

LDF: Multiple Classes



LDF: Multiple Classes

- For two contiguous regions R_i and R_j , the boundary that separates them is a portion of the hyperplane H_{ij} defined by:

$$\begin{aligned}g_i(x) = g_j(x) &\Leftrightarrow \mathbf{w}_i^t \mathbf{x} + w_{i0} = \mathbf{w}_j^t \mathbf{x} + w_{j0} \\&\Leftrightarrow (\mathbf{w}_i - \mathbf{w}_j)^t \mathbf{x} + (w_{i0} - w_{j0}) = 0\end{aligned}$$

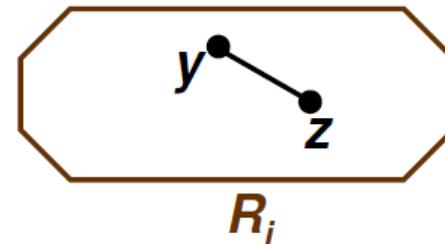
- Thus $\mathbf{w}_i - \mathbf{w}_j$ is normal to H_{ij}
- The distance from x to H_{ij} is given by:

$$d(x, H_{ij}) = \frac{|g_i(x) - g_j(x)|}{\|\mathbf{w}_i - \mathbf{w}_j\|}$$

LDF: Multiple Classes

- Decision regions for a linear machine are **convex**

$$y, z \in R_i \Rightarrow \alpha y + (1 - \alpha)z \in R_i$$

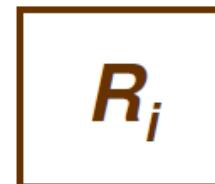


$$\begin{aligned} \forall j \neq i \quad g_i(y) \geq g_j(y) \text{ and } g_i(z) \geq g_j(z) &\Leftrightarrow \\ \Leftrightarrow \forall j \neq i \quad g_i(\alpha y + (1 - \alpha)z) \geq g_j(\alpha y + (1 - \alpha)z) \end{aligned}$$

- In particular, decision regions must be spatially contiguous



*R_j is a valid
decision region*

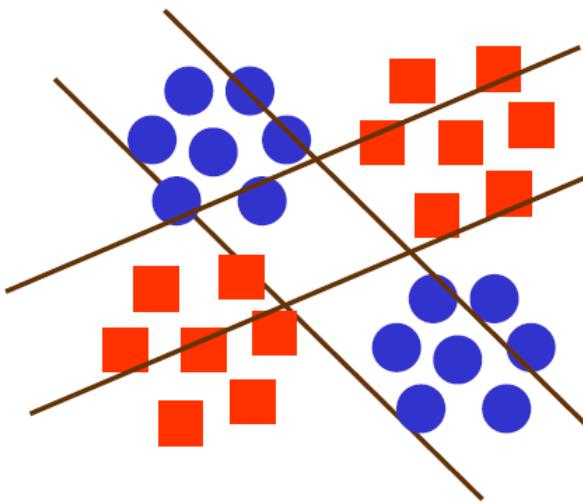


*R_j is not a valid
decision region*

LDF: Multiple Classes

- Thus applicability of linear machine mostly limited to unimodal conditional densities $p(x|\theta)$

- Example:



- Need non-contiguous decision regions
- Linear machine will fail