**Cornell Caustic**

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# Abstract

In this report explains the entire process of a brief analysis under the subject of Computer Graphics, more specifically about Photorealistic Image Rendering through the Ray Tracing technique. The project was carefully structured in order to easily understand its real purpose. First of all, we start by identifying the actual problem which is, in a few words, the simulation of caustic shadows. Caustics are defined as a group of light rays that are reflected or refracted by curved transparent objects. The next step was planning the experimentation and predict some of the possible results according to each possible approach. Then, it’s time to proceed to the rendering experimentation where beyond the final image, it is also taken into account the elapsed time. At last, comes the study of the obtained results and the choice of the best relation between image quality and time spent on it.

# Introduction

This project pretends to evaluate different global illumination algorithms’ performance and quality. To do this, the group was given a scene to work with (represented on Figure 1). This image’s resolution is 1024 by 1024 and was rendered using PBRT version 2 (using the surface integrator “path”). The PBRT will also be used to fulfil the purpose of this project, by rendering the various experiments. The scene to be studied has various typical surfaces seen on global illumination demos, such as a glossy teapot and ceiling, a mirror, and a crystal-like “killeroo” model. Out particular focus will be on the “killeroo” model, by trying to get the best caustic shadow possible.



Figure 1. Default scene, rendered with path tracing.

# Experiments

In order to achieve the best result, and have a basis for comparison, there were selected some surface integrators and samplers to test. Each surface integrator is tested with a different sampler. The planned elements are shown on Table 1.

Table 1. Planned experiments.

|  |  |
| --- | --- |
| Surface Integrators | Samplers |
| Path | Adaptive |
| Photon Map | Best Candidate |
|  | Halton |
|  | Low Discrepancy |
|  | Random |
|  | Stratified |

The result of each connection should generate an image, and the time it took to render, for example, the path surface integrator with an unknown sampler generated Figure 1, which as given to the group to present the scene. The imagens to be rendered will have a width and a height of 800 pixels. The samplers’ “pixelsamples” argument will be 256, at the exception of the adaptive (“minsamples” set to 128 and “maxsamples” set to 256) and stratified samplers (“xsamples” and “ysamples” set to 16, with jitter). The Photon Map surface integrator receives the argument “causticphotons” as 10.000 and the “indirectphotons” as 20.000.

# Hypotheses

Caustics are the consequence of light rays being focused in specific regions as a result of refraction (light rays passing through the “killeroo” model on this case). In the current case study, it is believed that the photon map surface integrator will produce a better result than the rest. This is simply because the path tracing is unable to produce a caustic, due to its random nature, when a ray hits a point that should be a caustic, a random ray is generated, and the probability of this ray being on the right direction (the “killeroo” model) is very low (shown in Figure 2 as red rays). And so the caustic would be no more than a normal shadow using path tracing. The photon map, on the other hand, is the ideal algorithm for this scene, and can generate very realistic caustics.

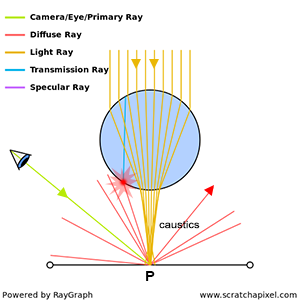
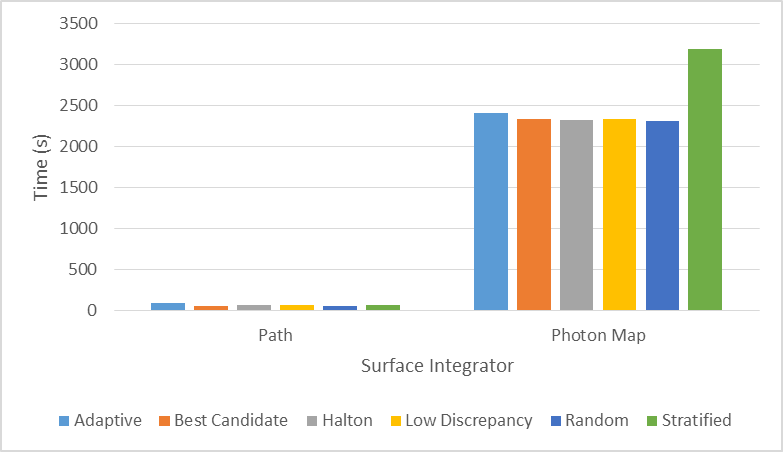


Figure . How a caustic shadow is formed.

# Results

On this section will be displayed all the images obtained, such as their rendering time. On Graph 1 is shown a global comparison between surface integrators and samplers.



Graph . Global comparison between the studied algorithms.

## Path Tracing

This subsection is dedicated to the experiments with path tracing. On Graph 2 is displayed the rendering time of the images produced. It can be verified that the elapsed time was similar with a peak on the adaptive sampler.

Graph . Comparison between samplers using the path tracing surface integrator.

### Adaptive



Figure . Scene rendered with path tracing and an adaptive sampler.

### Best Candidate



Figure 4. Scene rendered with path tracing and a best candidate sampler.

### Halton

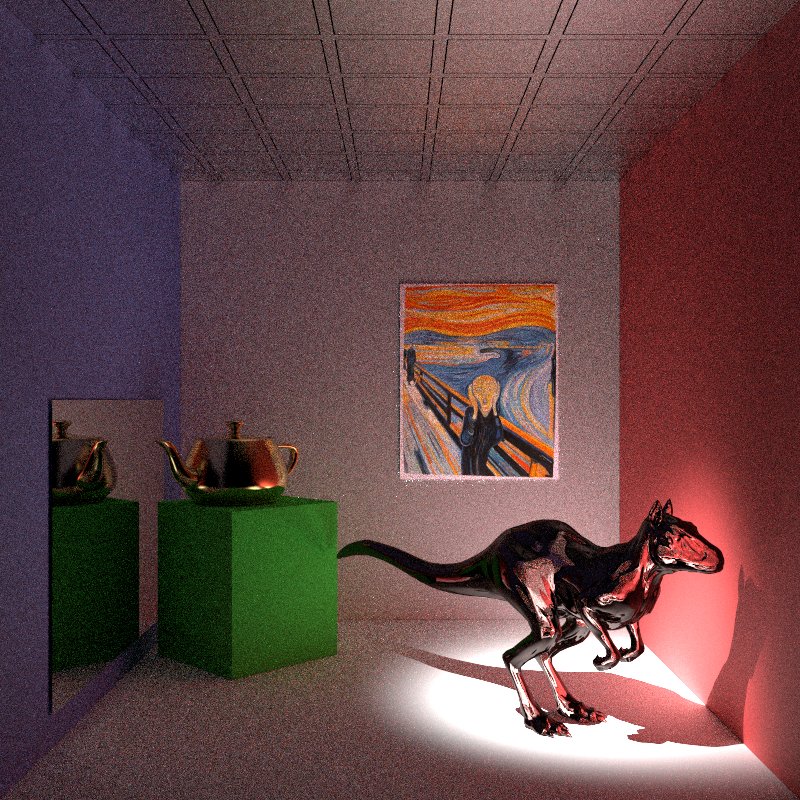


Figure 5. Scene rendered with path tracing and a halton sampler.

### Low Discrepancy



Figure 6. Scene rendered with path tracing and a low discrepancy sampler.

### Random



Figure 7. Scene rendered with path tracing and a random sampler.

### Stratified



Figure 8. Scene rendered with path tracing and a stratified sampler.

## Photon Map

### Adaptive

### Best Candidate

### Halton

### Low Discrepancy

### Random

### Stratified

# Conclusion

* espirito critico!
* trade of entre X e Y
* refletir sobre os resultados obtidos e porque