Classify_imgs

October 7, 2020

```
[13]: from tensorflow import keras
      from imutils import paths
      from tensorflow.keras.preprocessing.image import ImageDataGenerator
      from tensorflow.keras.optimizers import SGD
      import numpy as np
 [2]: # importe de pacotes
      from tensorflow.keras.layers import BatchNormalization
      from tensorflow.keras.layers import Conv2D
      from tensorflow.keras.layers import AveragePooling2D
      from tensorflow.keras.layers import MaxPooling2D
      from tensorflow.keras.layers import ZeroPadding2D
      from tensorflow.keras.layers import Activation
      from tensorflow.keras.layers import Dense
      from tensorflow.keras.layers import Flatten
      from tensorflow.keras.layers import Input
      from tensorflow.keras.models import Model
      from tensorflow.keras.layers import add
      from tensorflow.keras.regularizers import 12
      from tensorflow.keras import backend as K
      class ResNet:
          Ostaticmethod
          def residual module(data, K, stride, chanDim, red=False,
                              reg=0.0001, bnEps=2e-5, bnMom=0.9):
              # the shortcut branch of the ResNet module should be
              # initialize as the input (identity) data
              shortcut = data
              # the first block of the ResNet module are the 1x1 CONVs
              bn1 = BatchNormalization(axis=chanDim, epsilon=bnEps,
                                       momentum=bnMom) (data)
              act1 = Activation("relu")(bn1)
              conv1 = Conv2D(int(K * 0.25), (1, 1), use_bias=False,
                             kernel_regularizer=12(reg))(act1)
```

```
# the second block of the ResNet module are the 3x3 CONVs
    bn2 = BatchNormalization(axis=chanDim, epsilon=bnEps,
                             momentum=bnMom) (conv1)
    act2 = Activation("relu")(bn2)
    conv2 = Conv2D(int(K * 0.25), (3, 3), strides=stride,
                   padding="same", use_bias=False,
                   kernel_regularizer=12(reg))(act2)
    # the third block of the ResNet module is another set of 1x1
    # CONVs
    bn3 = BatchNormalization(axis=chanDim, epsilon=bnEps,
                             momentum=bnMom) (conv2)
    act3 = Activation("relu")(bn3)
    conv3 = Conv2D(K, (1, 1), use_bias=False,
                   kernel_regularizer=12(reg))(act3)
    # if we are to reduce the spatial size, apply a CONV layer to
    # the shortcut
    if red:
        shortcut = Conv2D(K, (1, 1), strides=stride,
                          use_bias=False, kernel_regularizer=12(reg))(act1)
    # add together the shortcut and the final CONV
    x = add([conv3, shortcut])
    # return the addition as the output of the ResNet module
    return x
Ostaticmethod
def build(width, height, depth, classes, stages, filters,
          reg=0.0001, bnEps=2e-5, bnMom=0.9):
    # initialize the input shape to be "channels last" and the
    # channels dimension itself
    inputShape = (height, width, depth)
    chanDim = -1
    # if we are using "channels first", update the input shape
    # and channels dimension
    if K.image_data_format() == "channels_first":
        inputShape = (depth, height, width)
        chanDim = 1
    # set the input and apply BN
    inputs = Input(shape=inputShape)
    x = BatchNormalization(axis=chanDim, epsilon=bnEps,
                           momentum=bnMom)(inputs)
```

```
# apply CONV => BN => ACT => POOL to reduce spatial size
       x = Conv2D(filters[0], (5, 5), use_bias=False,
                  padding="same", kernel_regularizer=12(reg))(x)
       x = BatchNormalization(axis=chanDim, epsilon=bnEps,
                              momentum=bnMom)(x)
       x = Activation("relu")(x)
       x = ZeroPadding2D((1, 1))(x)
       x = MaxPooling2D((3, 3), strides=(2, 2))(x)
       # loop over the number of stages
       for i in range(0, len(stages)):
           # initialize the stride, then apply a residual module
           # used to reduce the spatial size of the input volume
           stride = (1, 1) if i == 0 else (2, 2)
           x = ResNet.residual_module(x, filters[i + 1], stride,
                                       chanDim, red=True, bnEps=bnEps,
→bnMom=bnMom)
           # loop over the number of layers in the stage
           for j in range(0, stages[i] - 1):
               # apply a ResNet module
               x = ResNet.residual_module(x, filters[i + 1],
                                           (1, 1), chanDim, bnEps=bnEps,
\rightarrowbnMom=bnMom)
       # apply BN => ACT => POOL
       x = BatchNormalization(axis=chanDim, epsilon=bnEps,
                              momentum=bnMom)(x)
       x = Activation("relu")(x)
       x = AveragePooling2D((8, 8))(x)
       # sigmoid classifier
       x = Flatten()(x)
       x = Dense(classes, kernel_regularizer=12(reg))(x)
       x = Activation("sigmoid")(x)
       # create the model
       model = Model(inputs, x, name="resnet")
       # return the constructed network architecture
       return model
```

```
[3]: height, width = 224, 224
```

```
[4]: # initialize the number of training epochs and batch size

NUM_EPOCHS = 50

BS = 32
```

```
TRAIN_PATH = '../dados/'
# determine the total number of image paths in training, validation,
# and testing directories
totalTrain = len(list(paths.list_images(TRAIN_PATH)))
```

```
[5]: # initialize the training training data augmentation object
trainAug = ImageDataGenerator(
    rescale=1 / 255.0,
    rotation_range=20,
    zoom_range=0.05,
    width_shift_range=0.05,
    height_shift_range=0.05,
    shear_range=0.05,
    horizontal_flip=True,
    validation_split=0.1)
```

[6]: # initialize the testing data augmentation object testAug = ImageDataGenerator(rescale=1 / 255.0, validation_split=0.1)

```
[7]: # initialize the training generator
trainGen = trainAug.flow_from_directory(
          TRAIN_PATH,
          class_mode="categorical",
          target_size=(height, width),
          color_mode="rgb",
          shuffle=True,
          seed=123,
          batch_size=BS,
          subset='training')
```

Found 3200 images belonging to 2 classes.

```
[8]: # initialize the testing generator
testGen = testAug.flow_from_directory(
          TRAIN_PATH,
          class_mode="categorical",
          target_size=(height, width),
          color_mode="rgb",
          shuffle=False,
          batch_size=BS,
          subset='validation')
```

Found 355 images belonging to 2 classes.

```
[9]: model = ResNet.build(height, width, 3, 2, (2, 2, 3), (32, 64, 128, 256), reg=0.0005)
```

```
[10]: opt = SGD(lr=1e-1, momentum=0.9, decay=1e-1 / NUM_EPOCHS)
     model.compile(loss="binary_crossentropy",
                  optimizer=opt,
                  metrics=["accuracy",
                           keras.metrics.AUC(),
                           keras.metrics.Precision(),
                           keras.metrics.Recall()])
[11]: from PIL import Image, ImageFile
     ImageFile.LOAD_TRUNCATED_IMAGES = True
     # train our Keras model
     H = model.fit(
        trainGen.
        validation_data=testGen,
         epochs=NUM_EPOCHS)
    Epoch 1/50
    100/100 [============= ] - 293s 3s/step - loss: 0.5292 -
    accuracy: 0.8944 - auc: 0.9509 - precision: 0.8944 - recall: 0.8922 - val loss:
    0.6406 - val accuracy: 0.8789 - val auc: 0.9368 - val precision: 0.8789 -
    val recall: 0.8789
    Epoch 2/50
    100/100 [============== ] - 304s 3s/step - loss: 0.3887 -
    accuracy: 0.9350 - auc: 0.9785 - precision: 0.9353 - recall: 0.9356 - val_loss:
    0.5573 - val_accuracy: 0.8901 - val_auc: 0.9472 - val_precision: 0.8901 -
    val_recall: 0.8901
    Epoch 3/50
    100/100 [============ ] - 299s 3s/step - loss: 0.3592 -
    accuracy: 0.9447 - auc: 0.9821 - precision: 0.9450 - recall: 0.9447 - val_loss:
    0.3716 - val_accuracy: 0.9324 - val_auc: 0.9797 - val_precision: 0.9298 -
    val recall: 0.9324
    Epoch 4/50
    100/100 [============ ] - 302s 3s/step - loss: 0.3387 -
    accuracy: 0.9466 - auc: 0.9844 - precision: 0.9466 - recall: 0.9466 - val_loss:
    0.3940 - val_accuracy: 0.9127 - val_auc: 0.9763 - val_precision: 0.9129 -
    val recall: 0.9155
    Epoch 5/50
    accuracy: 0.9475 - auc: 0.9838 - precision: 0.9475 - recall: 0.9478 - val_loss:
    0.3413 - val_accuracy: 0.9408 - val_auc: 0.9838 - val_precision: 0.9408 -
    val_recall: 0.9408
    Epoch 6/50
    accuracy: 0.9519 - auc: 0.9861 - precision: 0.9516 - recall: 0.9519 - val_loss:
    0.3414 - val_accuracy: 0.9352 - val_auc: 0.9824 - val_precision: 0.9352 -
    val recall: 0.9352
```

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Epoch 7/50
accuracy: 0.9559 - auc: 0.9881 - precision: 0.9563 - recall: 0.9566 - val_loss:
0.3147 - val_accuracy: 0.9521 - val_auc: 0.9869 - val_precision: 0.9494 -
val recall: 0.9521
Epoch 8/50
accuracy: 0.9525 - auc: 0.9872 - precision: 0.9522 - recall: 0.9528 - val_loss:
0.3235 - val_accuracy: 0.9465 - val_auc: 0.9845 - val_precision: 0.9466 -
val recall: 0.9493
Epoch 9/50
accuracy: 0.9569 - auc: 0.9876 - precision: 0.9569 - recall: 0.9569 - val_loss:
0.3086 - val_accuracy: 0.9465 - val_auc: 0.9869 - val_precision: 0.9465 -
val_recall: 0.9465
Epoch 10/50
100/100 [============= ] - 308s 3s/step - loss: 0.2869 -
accuracy: 0.9553 - auc: 0.9884 - precision: 0.9562 - recall: 0.9550 - val_loss:
0.3248 - val_accuracy: 0.9493 - val_auc: 0.9838 - val_precision: 0.9493 -
val recall: 0.9493
Epoch 11/50
100/100 [============= ] - 307s 3s/step - loss: 0.2845 -
accuracy: 0.9572 - auc: 0.9889 - precision: 0.9575 - recall: 0.9572 - val_loss:
0.3348 - val_accuracy: 0.9296 - val_auc: 0.9803 - val_precision: 0.9322 -
val_recall: 0.9296
Epoch 12/50
100/100 [============ ] - 304s 3s/step - loss: 0.2738 -
accuracy: 0.9594 - auc: 0.9900 - precision: 0.9585 - recall: 0.9591 - val_loss:
0.2905 - val_accuracy: 0.9437 - val_auc: 0.9890 - val_precision: 0.9437 -
val_recall: 0.9437
Epoch 13/50
accuracy: 0.9541 - auc: 0.9892 - precision: 0.9544 - recall: 0.9541 - val_loss:
0.3087 - val_accuracy: 0.9324 - val_auc: 0.9851 - val_precision: 0.9324 -
val recall: 0.9324
Epoch 14/50
100/100 [============= ] - 303s 3s/step - loss: 0.2618 -
accuracy: 0.9609 - auc: 0.9912 - precision: 0.9609 - recall: 0.9609 - val_loss:
0.2941 - val_accuracy: 0.9493 - val_auc: 0.9879 - val_precision: 0.9493 -
val_recall: 0.9493
Epoch 15/50
100/100 [============ ] - 294s 3s/step - loss: 0.2678 -
accuracy: 0.9594 - auc: 0.9896 - precision: 0.9591 - recall: 0.9597 - val_loss:
0.3215 - val_accuracy: 0.9211 - val_auc: 0.9831 - val_precision: 0.9211 -
val_recall: 0.9211
Epoch 16/50
accuracy: 0.9572 - auc: 0.9908 - precision: 0.9572 - recall: 0.9572 - val_loss:
```

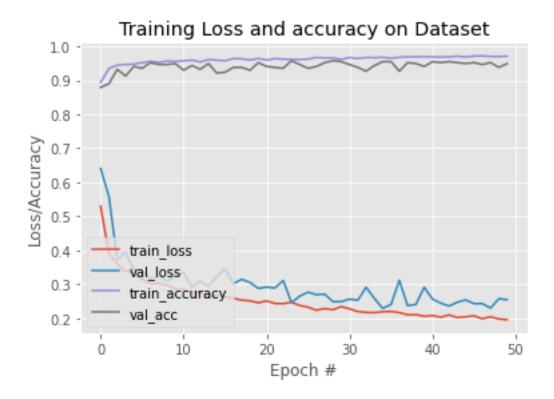
```
0.3454 - val_accuracy: 0.9239 - val_auc: 0.9762 - val_precision: 0.9239 -
val_recall: 0.9239
Epoch 17/50
100/100 [============= ] - 296s 3s/step - loss: 0.2586 -
accuracy: 0.9641 - auc: 0.9909 - precision: 0.9641 - recall: 0.9641 - val loss:
0.3015 - val_accuracy: 0.9380 - val_auc: 0.9854 - val_precision: 0.9380 -
val recall: 0.9380
Epoch 18/50
accuracy: 0.9631 - auc: 0.9919 - precision: 0.9631 - recall: 0.9628 - val_loss:
0.3146 - val_accuracy: 0.9380 - val_auc: 0.9849 - val_precision: 0.9380 -
val_recall: 0.9380
Epoch 19/50
accuracy: 0.9600 - auc: 0.9914 - precision: 0.9600 - recall: 0.9600 - val_loss:
0.3051 - val_accuracy: 0.9296 - val_auc: 0.9836 - val_precision: 0.9296 -
val_recall: 0.9296
Epoch 20/50
accuracy: 0.9641 - auc: 0.9926 - precision: 0.9641 - recall: 0.9641 - val_loss:
0.2878 - val_accuracy: 0.9521 - val_auc: 0.9888 - val_precision: 0.9521 -
val recall: 0.9521
Epoch 21/50
100/100 [============ ] - 298s 3s/step - loss: 0.2508 -
accuracy: 0.9597 - auc: 0.9915 - precision: 0.9597 - recall: 0.9600 - val_loss:
0.2917 - val_accuracy: 0.9408 - val_auc: 0.9858 - val_precision: 0.9408 -
val_recall: 0.9408
Epoch 22/50
100/100 [=========== ] - 300s 3s/step - loss: 0.2433 -
accuracy: 0.9638 - auc: 0.9921 - precision: 0.9632 - recall: 0.9641 - val_loss:
0.2887 - val_accuracy: 0.9380 - val_auc: 0.9874 - val_precision: 0.9380 -
val_recall: 0.9380
Epoch 23/50
100/100 [============= ] - 299s 3s/step - loss: 0.2427 -
accuracy: 0.9622 - auc: 0.9914 - precision: 0.9622 - recall: 0.9622 - val loss:
0.3109 - val_accuracy: 0.9352 - val_auc: 0.9818 - val_precision: 0.9352 -
val recall: 0.9352
Epoch 24/50
accuracy: 0.9616 - auc: 0.9911 - precision: 0.9616 - recall: 0.9613 - val_loss:
0.2460 - val_accuracy: 0.9577 - val_auc: 0.9928 - val_precision: 0.9577 -
val_recall: 0.9577
Epoch 25/50
accuracy: 0.9613 - auc: 0.9921 - precision: 0.9613 - recall: 0.9616 - val_loss:
0.2649 - val_accuracy: 0.9465 - val_auc: 0.9899 - val_precision: 0.9465 -
val_recall: 0.9465
Epoch 26/50
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accuracy: 0.9625 - auc: 0.9929 - precision: 0.9628 - recall: 0.9634 - val_loss:
0.2767 - val_accuracy: 0.9352 - val_auc: 0.9882 - val_precision: 0.9350 -
val recall: 0.9324
Epoch 27/50
accuracy: 0.9675 - auc: 0.9935 - precision: 0.9672 - recall: 0.9675 - val loss:
0.2689 - val_accuracy: 0.9408 - val_auc: 0.9894 - val_precision: 0.9408 -
val recall: 0.9408
Epoch 28/50
accuracy: 0.9659 - auc: 0.9928 - precision: 0.9662 - recall: 0.9656 - val loss:
0.2708 - val_accuracy: 0.9521 - val_auc: 0.9870 - val_precision: 0.9521 -
val recall: 0.9521
Epoch 29/50
accuracy: 0.9663 - auc: 0.9935 - precision: 0.9669 - recall: 0.9666 - val_loss:
0.2484 - val_accuracy: 0.9577 - val_auc: 0.9917 - val_precision: 0.9577 -
val recall: 0.9577
Epoch 30/50
accuracy: 0.9613 - auc: 0.9919 - precision: 0.9622 - recall: 0.9613 - val_loss:
0.2487 - val_accuracy: 0.9549 - val_auc: 0.9911 - val_precision: 0.9549 -
val_recall: 0.9549
Epoch 31/50
accuracy: 0.9672 - auc: 0.9931 - precision: 0.9672 - recall: 0.9672 - val_loss:
0.2562 - val_accuracy: 0.9465 - val_auc: 0.9905 - val_precision: 0.9465 -
val_recall: 0.9465
Epoch 32/50
100/100 [============ ] - 283s 3s/step - loss: 0.2194 -
accuracy: 0.9641 - auc: 0.9940 - precision: 0.9641 - recall: 0.9641 - val_loss:
0.2529 - val_accuracy: 0.9380 - val_auc: 0.9908 - val_precision: 0.9380 -
val recall: 0.9380
Epoch 33/50
accuracy: 0.9672 - auc: 0.9935 - precision: 0.9672 - recall: 0.9669 - val loss:
0.2908 - val_accuracy: 0.9268 - val_auc: 0.9841 - val_precision: 0.9268 -
val_recall: 0.9268
Epoch 34/50
accuracy: 0.9666 - auc: 0.9942 - precision: 0.9663 - recall: 0.9666 - val_loss:
0.2580 - val_accuracy: 0.9437 - val_auc: 0.9898 - val_precision: 0.9437 -
val recall: 0.9437
Epoch 35/50
accuracy: 0.9678 - auc: 0.9939 - precision: 0.9681 - recall: 0.9678 - val_loss:
0.2287 - val_accuracy: 0.9549 - val_auc: 0.9937 - val_precision: 0.9549 -
```

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val_recall: 0.9549
Epoch 36/50
accuracy: 0.9650 - auc: 0.9937 - precision: 0.9653 - recall: 0.9650 - val_loss:
0.2404 - val accuracy: 0.9549 - val auc: 0.9923 - val precision: 0.9522 -
val recall: 0.9549
Epoch 37/50
accuracy: 0.9678 - auc: 0.9944 - precision: 0.9681 - recall: 0.9678 - val_loss:
0.3116 - val_accuracy: 0.9268 - val_auc: 0.9837 - val_precision: 0.9268 -
val_recall: 0.9268
Epoch 38/50
accuracy: 0.9691 - auc: 0.9950 - precision: 0.9691 - recall: 0.9691 - val_loss:
0.2366 - val_accuracy: 0.9521 - val_auc: 0.9926 - val_precision: 0.9521 -
val recall: 0.9521
Epoch 39/50
100/100 [============== ] - 285s 3s/step - loss: 0.2104 -
accuracy: 0.9691 - auc: 0.9947 - precision: 0.9688 - recall: 0.9688 - val_loss:
0.2405 - val_accuracy: 0.9493 - val_auc: 0.9923 - val_precision: 0.9493 -
val recall: 0.9493
Epoch 40/50
accuracy: 0.9694 - auc: 0.9953 - precision: 0.9694 - recall: 0.9697 - val_loss:
0.2908 - val_accuracy: 0.9408 - val_auc: 0.9835 - val_precision: 0.9408 -
val_recall: 0.9408
Epoch 41/50
accuracy: 0.9688 - auc: 0.9948 - precision: 0.9684 - recall: 0.9688 - val_loss:
0.2563 - val_accuracy: 0.9549 - val_auc: 0.9888 - val_precision: 0.9549 -
val_recall: 0.9549
Epoch 42/50
accuracy: 0.9684 - auc: 0.9957 - precision: 0.9691 - recall: 0.9688 - val_loss:
0.2443 - val accuracy: 0.9521 - val auc: 0.9911 - val precision: 0.9521 -
val recall: 0.9521
Epoch 43/50
100/100 [============= ] - 294s 3s/step - loss: 0.2095 -
accuracy: 0.9688 - auc: 0.9942 - precision: 0.9688 - recall: 0.9691 - val_loss:
0.2357 - val_accuracy: 0.9549 - val_auc: 0.9919 - val_precision: 0.9549 -
val_recall: 0.9549
Epoch 44/50
100/100 [============= ] - 297s 3s/step - loss: 0.2021 -
accuracy: 0.9712 - auc: 0.9952 - precision: 0.9713 - recall: 0.9716 - val_loss:
0.2470 - val_accuracy: 0.9521 - val_auc: 0.9912 - val_precision: 0.9521 -
val_recall: 0.9521
Epoch 45/50
100/100 [============= ] - 305s 3s/step - loss: 0.2041 -
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accuracy: 0.9688 - auc: 0.9949 - precision: 0.9688 - recall: 0.9688 - val_loss:
     0.2538 - val_accuracy: 0.9493 - val_auc: 0.9902 - val_precision: 0.9493 -
     val_recall: 0.9493
     Epoch 46/50
     100/100 [============= ] - 301s 3s/step - loss: 0.2070 -
     accuracy: 0.9712 - auc: 0.9941 - precision: 0.9706 - recall: 0.9712 - val_loss:
     0.2430 - val accuracy: 0.9521 - val auc: 0.9918 - val precision: 0.9521 -
     val recall: 0.9521
     Epoch 47/50
     100/100 [============ ] - 301s 3s/step - loss: 0.1982 -
     accuracy: 0.9719 - auc: 0.9951 - precision: 0.9719 - recall: 0.9716 - val_loss:
     0.2429 - val_accuracy: 0.9465 - val_auc: 0.9911 - val_precision: 0.9465 -
     val_recall: 0.9465
     Epoch 48/50
     100/100 [============= ] - 305s 3s/step - loss: 0.2042 -
     accuracy: 0.9703 - auc: 0.9945 - precision: 0.9703 - recall: 0.9700 - val_loss:
     0.2299 - val_accuracy: 0.9521 - val_auc: 0.9927 - val_precision: 0.9521 -
     val_recall: 0.9521
     Epoch 49/50
     100/100 [============= ] - 304s 3s/step - loss: 0.1975 -
     accuracy: 0.9700 - auc: 0.9955 - precision: 0.9694 - recall: 0.9700 - val_loss:
     0.2574 - val_accuracy: 0.9380 - val_auc: 0.9884 - val_precision: 0.9380 -
     val recall: 0.9380
     Epoch 50/50
     accuracy: 0.9709 - auc: 0.9960 - precision: 0.9706 - recall: 0.9706 - val_loss:
     0.2542 - val_accuracy: 0.9493 - val_auc: 0.9899 - val_precision: 0.9493 -
     val_recall: 0.9493
[25]: import matplotlib.pyplot as plt
     N = NUM_EPOCHS
     plt.style.use("ggplot")
     plt.figure()
     plt.plot(np.arange(0, N), H.history["loss"], label="train_loss")
     plt.plot(np.arange(0, N), H.history["val_loss"], label="val_loss")
     plt.plot(np.arange(0, N), H.history["accuracy"], label="train_accuracy")
     plt.plot(np.arange(0, N), H.history["val_accuracy"], label="val_acc")
     plt.title("Training Loss and accuracy on Dataset")
     plt.xlabel("Epoch #")
     plt.ylabel("Loss/Accuracy")
     plt.legend(loc="lower left")
     plt.savefig('Training Loss and accuracy on Dataset')
     H.history.keys()
[25]: dict keys(['loss', 'accuracy', 'auc',
```

' val_accuracy', ' val_auc', ' val_precision', ' val_recall'])



```
[27]: plt.style.use("ggplot")
   plt.figure()
   plt.plot(np.arange(0, N), H.history["auc"], label="train_auc")
   plt.plot(np.arange(0, N), H.history["val_auc"], label="val_auc")
   plt.plot(np.arange(0, N), H.history["recall"], label="train_recall")
   plt.plot(np.arange(0, N), H.history["val_recall"], label="val_recall")
   plt.plot(np.arange(0, N), H.history["precision"], label="train_precision")
   plt.plot(np.arange(0, N), H.history["val_precision"], label="val_precision")

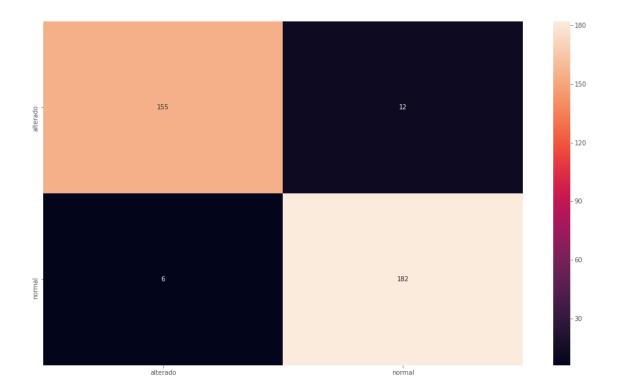
   plt.title("Training AUC and Recall on Dataset")
   plt.xlabel("Epoch #")
   plt.ylabel("AUC/Recall/Precision")
   plt.legend(loc="lower left")
   plt.savefig('Training AUC, Recall and Precision on Dataset')
```



```
[32]: from sklearn.metrics import classification_report
      from sklearn.metrics import confusion_matrix
      import pandas as pd
      import seaborn as sns
      testGen.reset()
      predIdxs = model.predict(testGen, batch_size=BS)
      # for each image in the testing set we need to find the index of the
      # label with corresponding largest predicted probability
      predIdxs = np.argmax(predIdxs, axis=1)
      conf_mat = confusion_matrix(testGen.classes, predIdxs)
      class_names = ['alterado', 'normal']
      fig = plt.figure(figsize=(17,10))
      df_cm = pd.DataFrame(conf_mat, index=class_names, columns=class_names)
      heatmap = sns.heatmap(df_cm, annot=True, fmt='d')
      heatmap
      # show a nicely formatted classification report
      print(classification_report(testGen.classes, predIdxs,
```

target_names=testGen.class_indices.keys()))

	precision	recall	f1-score	support
rx-alterado-anonim	0.96	0.93	0.95	167
rx-normal-anonim	0.94	0.97	0.95	188
accuracy			0.95	355
macro avg	0.95	0.95	0.95	355
weighted avg	0.95	0.95	0.95	355



[29]: model.save('Models/H{}W{}.h5'.format(height, width))