

Reconstructing scenes from photos using Global SfM

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1 Problem

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2 Goals

We intend to implement a Global Structure from Motion technique to reconstruct scenes from photos. We will use the techniques described by [Chatterjee and Govindu 2013] and [Wilson and Snavely 2014]. If we run into time constraints, we will use the code for [Chatterjee and Govindu 2013] (which is available online) and we will implement the translation correction ourselves. We intend to use our implementation with a large dataset obtained from the internet.

3 Schedule

3.1 Plan A

- Week of October 13th: Project Proposal Presentation
- Week of October 20th: Feature Detection and Feature Matching
- Week of October 27th: Homography Computation and Relative Rotation/Translation computation
- Week of November 3rd: Homography Computation and Relative Rotation/Translation computation
- Week of November 10th: Rotation Averaging
- Week of November 17th: Rotation Averaging
- Week of November 24th: Translation Correction
- Week of November 1st: Translation Correction
- Week of November 8th: Evaluation

3.2 Plan B

- Week of October 13th: Project Proposal Presentation
- Week of October 20th: Feature Detection and Feature Matching
- Week of October 27th: Homography Computation and Relative Rotation/Translation computation
- Week of November 3rd: Homography Computation and Relative Rotation/Translation computation
- Week of November 10th: Homography Computation and Relative Rotation/Translation computation
- Week of November 17th: Translation Correction
- Week of November 24th: Translation Correction
- Week of November 1st: Translation Correction
- Week of November 8th: Evaluation

References

- CHATTERJEE, A., AND GOVINDU, V. 2013. Efficient and robust large-scale rotation averaging. In *Computer Vision (ICCV), 2013 IEEE International Conference on*, 521–528.
- LOWE, D. G. 2004. Distinctive image features from scale-invariant keypoints. *International journal of computer vision* 60, 2, 91–110.
- SNAVELY, N., SEITZ, S. M., AND SZELISKI, R. 2006. Photo tourism: exploring photo collections in 3d. *ACM transactions on graphics (TOG)* 25, 3, 835–846.
- WILSON, K., AND SNAVELY, N. 2014. Robust global translations with 1dsfm. In *Computer Vision ECCV 2014*, D. Fleet, T. Pajdla, B. Schiele, and T. Tuytelaars, Eds., vol. 8691 of *Lecture Notes in Computer Science*. Springer International Publishing, 61–75.

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