

```

1  /*
2  TinyTrackGPS.ino - A simple track GPS to SD card Logger.
3  TinyTrackGPS v0.4
4
5  Copyright © 2019-2021 Francisco Rafael Reyes Carmona.
6  All rights reserved.
7
8  raphael.reyes.carmona@gmail.com
9
10     This file is part of TinyTrackGPS.
11
12     TinyTrackGPS is free software: you can redistribute it and/or
13     • modify
14     it under the terms of the GNU General Public License as published
15     • by
16     the Free Software Foundation, either version 3 of the License, or
17     (at your option) any later version.
18
19     TinyTrackGPS is distributed in the hope that it will be useful,
20     but WITHOUT ANY WARRANTY; without even the implied warranty of
21     MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the
22     GNU General Public License for more details.
23
24     You should have received a copy of the GNU General Public License
25     along with TinyTrackGPS. If not, see <https://www.gnu.org/
26     • licenses/>.
27 */
28
29 /*
30     Programa de Localizacion por gps que graba las posiciones en
31     un fichero de texto cada segundo, de forma diaria.
32
33     Conectar módulo SD con pin CS (naranja) en pin 10 arduino.
34
35     Conectar módulo NMEA-6M (gps) pines 8,9 (9 - pin rx negro)
36
37     Conectar LCD 16x2 pines 2,3,4,5,6,7 (2-amarillo , 3-azul,
38     4-rojo, 5-azul oscuro, 6-verde, 7-blanco)
39 */
40 // Include Libraries.
41 #include <Ticker.h>
42 #include <LiquidCrystal.h>
43 #include <SoftwareSerial.h>
44 #include <TinyGPS.h>
45 #include <SD.h>
46 #include <LowPower.h>
47 #include "UTMconversion.h"
48
49

```

```

46 File GPSFile;
47 char GPSLogFile[] = "YYYYMMDD.csv"; // Formato de nombre de
    • fichero. YYYY-Año, MM-Mes, DD-Día.
48 boolean SDReady;
49 float flat, flon;
50 unsigned long age;
51
52 /* Código de demostración uso de Librería TinyGPS.
53     Requiere uso de librería SoftwareSerial, se presupone que
    • disponemos
54     de un dispositivo GPS serie de 9600-bauds conectado en pines
    • 9(rx) y 8(tx).
55 */
56 TinyGPS gps;
57 GPS_UTM utm;
58 #define UTM_LCD
59 #define PIN_SELECT 8
60 boolean pin = LOW;
61 SoftwareSerial gps_serial(9, 8);
62 int year_actual;
63 byte month_actual, day_actual;
64 byte hour_prev, minute_prev, second_prev;
65
66 void GPSData();
67 Ticker GPSRefresh(GPSData, 1000);
68
69 /* Constantes para declaracion del LCD */
70 const int LCD_NB_ROWS = 2;
71 const int LCD_NB_COLUMNS = 16;
72 /* Crea el objeto Lcd */
73 LiquidCrystal lcd(2, 3, 4, 5, 6, 7);
74
75 // DEFINICION DE CARACTERES PERSONALIZADOS
76 byte alt[8] = {
77     0b00000100,
78     0b00001110,
79     0b00011111,
80     0b00000100,
81     0b00000100,
82     0b00000100,
83     0b00000100,
84     0b00000100,
85 };
86
87 byte ant[8] = {
88     0b00001110,
89     0b00010001,

```

```

90      0b00010101,
91      0b00010001,
92      0b00000100,
93      0b00000100,
94      0b00001110,
95      0b00000000,
96  };
97
98  byte sd[8] = {
99      0b00001110,
100     0b00010001,
101     0b00011111,
102     0b00000000,
103     0b00000000,
104     0b00010111,
105     0b00010101,
106     0b00011101,
107  };
108
109
110  void setup(void) {
111      boolean config = 0;
112      Serial.begin(9600);
113      gps_serial.begin(9600);
114
115      pinMode(10, OUTPUT);
116
117      Serial.print(F("Initializing SD card..."));
118
119      SDReady = SD.begin(10);
120      (SDReady) ? Serial.println(F("Done.))" :
121      • Serial.println(F("FAILED!"));
122
123      /* Declaramos pin para selector visor coordenadas */
124      pinMode(PIN_SELECT, INPUT_PULLUP);
125
126      /* Iniciaización del LCD */
127      lcd.begin(LCD_NB_COLUMNS, LCD_NB_ROWS);
128
129      lcd.createChar(0, alt);
130      lcd.createChar(1, ant);
131      lcd.createChar(2, sd);
132
133      lcd.clear();
134      lcd.setCursor(0, 0);
135      lcd.print(F("Waiting for"));
136      lcd.setCursor(0, 1);
137      lcd.print(F("GPS signal. "));

```

```

136     Serial.print(F("GPS signal..."));
137
138     Serial.print(F("Waiting for GPS signal..."));
139
140     do {
141         while (gps_serial.available())
142         {
143             if (gps.encode(gps_serial.read())) // Comprueba que ha
144             • recibido una sentencia del GPS.
145             {
146                 int year;
147                 byte month, day, hour, minute, second, hundredths;
148                 unsigned long age;
149
150                 gps.crack_datetime(&year, &month, &day, &hour, &minute,
151                 • &second, &hundredths, &age);
152                 if (sprintf(GPSLogFile, "%04d%02d%02d.csv", year, month,
153                 • day) > 0) {
154                     config = true;
155                     Serial.println(F("Done.));
156                     }
157                     year_actual = year;
158                     month_actual = month;
159                     day_actual = day;
160                     hour_prev = hour;
161                     minute_prev = minute;
162                     second_prev = second;
163
164                     // Si no existe el fichero lo crea y añade las cabeceras.
165                     if (SDReady && !SD.exists(GPSLogFile)) {
166                         if (GPSFile = SD.open(GPSLogFile, FILE_WRITE)) {
167                             Serial.print(F("New GPSLogFile, adding heads..."));
168                             GPSFile.println(F("Time,latitude,longitude,alt,utm"))
169                             • ;
170                             Serial.println(F("Done.));
171                             GPSFile.close();
172                         } else {
173                             Serial.println(F("** Error creating GPSLogFile.
174                             • **"));
175                         }
176                     }
177                 }
178             }
179         }
180     } while(!config);
181
182     if (SDReady) {
183         Serial.print(F("Filename: "));
184         Serial.println(GPSLogFile);

```

```

179     }
180     Serial.println(F("Configuration ended.));
181     lcd.clear();
182     GPSRefresh.start();
183 }
184
185 void loop(void) {
186     // boolean gps_ok = false;
187
188     // do {
189         while (gps_serial.available())
190             gps.encode(gps_serial.read()); //{
191         //     gps_ok = true;
192         // }
193     // }while(!gps_ok);
194
195     GPSRefresh.update();
196 }
197
198 void GPSData() {
199     int year;
200     byte month, day, hour, minute, second, hundredths;
201     unsigned long age;
202     int elevation;
203     float f_elevation;
204     char timestr[] = "00:00:00";
205     char utmstr[] = "30S 123456 1234567";
206     long timeidle = millis();
207
208     gps.f_get_position(&flat, &flon, &age);
209     f_elevation = gps.f_altitude();
210     elevation = abs((int)f_elevation);
211     utm.UTM(flat, flon);
212     sprintf(utmstr, "%02d%c %ld %ld", utm.zone(), utm.band(),
    • utm.X(), utm.Y());
213     if (pin != digitalRead(PIN_SELECT)) {
214         lcd.clear();
215         pin = digitalRead(PIN_SELECT);
216     }
217     if (pin == LOW) {
218         lcd.setCursor(0, 0);
219         if (utm.zone() < 10) lcd.print("0");
220         lcd.print(utm.zone());
221         lcd.print(utm.band());
222         lcd.setCursor(4, 0);    //lcd.print(F(" "));
223         lcd.print(utm.X());
224         lcd.setCursor(11, 0);   //lcd.print(F(" "));
225         lcd.write((bvte)1):

```



```

226 //lcd.setCursor(13, 0); //lcd.print(F(" "));
227 if (gps.satellites() < 10) lcd.print(F("0"));
228 lcd.print(gps.satellites());
229 lcd.setCursor(15, 0);
230 SDReady ? lcd.write((byte)2) : lcd.print(F("-"));
231
232 // New Line
233 lcd.setCursor(1, 1); // lcd.setCursor(0, 1); lcd.print(F("
•   "));
234 lcd.print(utm.Y());
235 lcd.setCursor(9, 1); //lcd.print(F(" "));
236 lcd.write((byte)0);
237 if (elevation >= 1000) lcd.setCursor(10, 1) ;
238     else if (elevation >= 1000) lcd.print(F(" "));
239     else if (elevation >= 100) lcd.print(F(" "));
240     else if (elevation >= 10) lcd.print(F(" "));
241     else lcd.print(F(" "));
242 lcd.print(elevation);
243 lcd.print(F("m"));
244 }
245 else {
246     lcd.setCursor(0, 0);
247     lcd.print(F("LAT="));
248     lcd.print(flat == TinyGPS::GPS_INVALID_F_ANGLE ? 0.0 : flat, 6);
249     lcd.setCursor(0, 1);
250     lcd.print(F("LON="));
251     lcd.print(flon == TinyGPS::GPS_INVALID_F_ANGLE ? 0.0 : flon, 6);
252 };
253
254 gps.crack_datetime(&year, &month, &day, &hour, &minute, &second,
•   &hundredths, &age);
255 if (age != TinyGPS::GPS_INVALID_AGE){
256     sprintf(timestr, "%02d:%02d:%02d,", hour, minute, second);
257     Serial.print(timestr);
258 }
259
260 if (year != year_actual || month != month_actual || day !=
•   day_actual) {
261     sprintf(GPSLogFile, "%04d%02d%02d.csv", year, month, day);
262     year_actual = year;
263     month_actual = month;
264     day_actual = day;
265
266     // Si no existe el fichero lo crea y añade las cabeceras.
267     if (SDReady && !SD.exists(GPSLogFile)) {
268         if (GPSFile = SD.open(GPSLogFile, FILE_WRITE)) {
269             Serial.print(F("New GPSLogFile, adding heads..."));

```

```

270         GPSFile.println(F("Time,latitude,longitude,alt,utm"));
271         Serial.println(F("Done.));
272         GPSFile.close();
273     }
274     else {
275         Serial.println(F("** Error creating GPSLogFile. **"));
276     }
277 }
278 }
279 if (!((hour_prev == hour) && (minute_prev == minute) &&
    • (second_prev == second))) {
280     if (SDReady && (GPSFile = SD.open(GPSLogFile, FILE_WRITE))) {
281         Serial.print(F("Open GPSLogFile to write..."));
282         GPSFile.print(timestr);
283         GPSFile.print(flat,6);
284         GPSFile.print(",");
285         GPSFile.print(flon,6);
286         GPSFile.print(",");
287         GPSFile.print(elevation);
288         GPSFile.print(",");
289         GPSFile.println(utmstr);
290         GPSFile.close();
291         Serial.println(F("Done.));
292         hour_prev = hour;
293         minute_prev = minute;
294         second_prev = second;
295     } else if (!GPSFile){
296         Serial.println(F("** Error opening GPSLogFile. **"));
297     }
298 } else Serial.println(F("** GPS signal lost. **"));
299 timeidle -= millis();
300 timeidle += 1000L;
301 Serial.println(timeidle);
302 if (timeidle > 500L)
303     LowPower.idle(SLEEP_500MS, ADC_OFF, TIMER2_ON, TIMER1_ON,
    • TIMER0_ON, SPI_ON, USART0_ON, TWI_OFF);
304 else if(timeidle > 250L)
305     LowPower.idle(SLEEP_250MS, ADC_OFF, TIMER2_ON, TIMER1_ON,
    • TIMER0_ON, SPI_ON, USART0_ON, TWI_OFF);
306 else if(timeidle > 120L)
307     LowPower.idle(SLEEP_120MS, ADC_OFF, TIMER2_ON, TIMER1_ON,
    • TIMER0_ON, SPI_ON, USART0_ON, TWI_OFF);
308 else if(timeidle > 60L)
309     LowPower.idle(SLEEP_60MS, ADC_OFF, TIMER2_ON, TIMER1_ON,
    • TIMER0_ON, SPI_ON, USART0_ON, TWI_OFF);
310 }
311

```