

A woman in a dark suit is shown in profile, looking down. A hand is resting on her shoulder, suggesting support or a comforting gesture. The background is bright and out of focus.

PATHFINDING ALGORITHM FOR SEXUAL HARASSMENT PREVENTION, APPLIED TO MEDELLÍN-COLOMBIA

Presentation of the team



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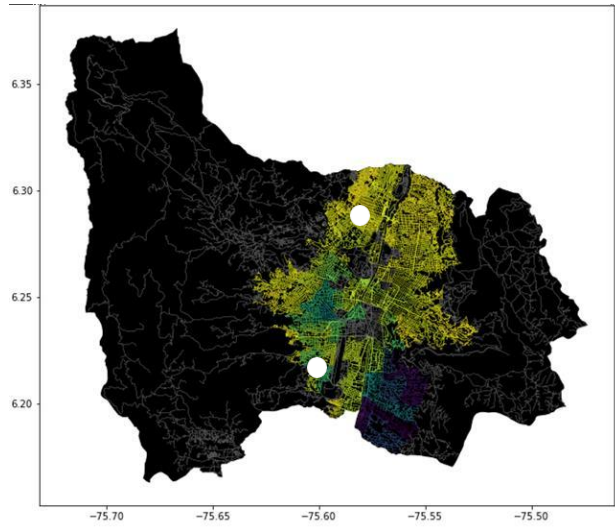
Mauricio Toro
Data preparation



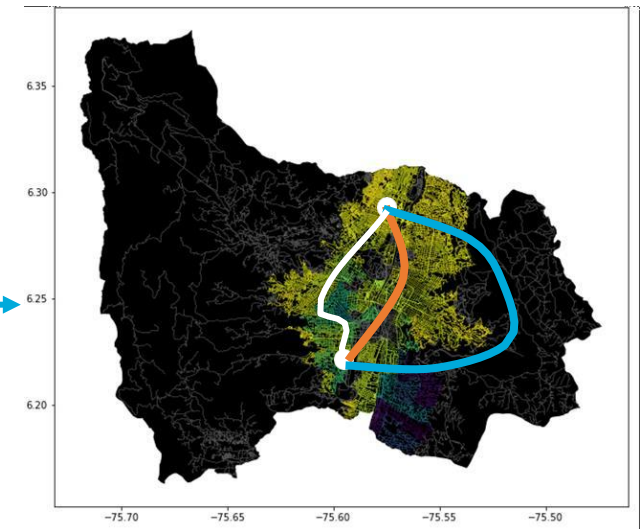
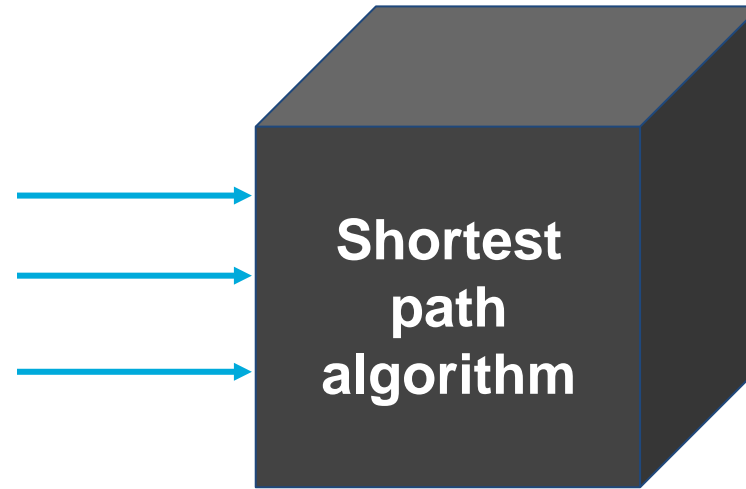
<https://github.com/RafaelUrbina/st245-002>



Problem Statement

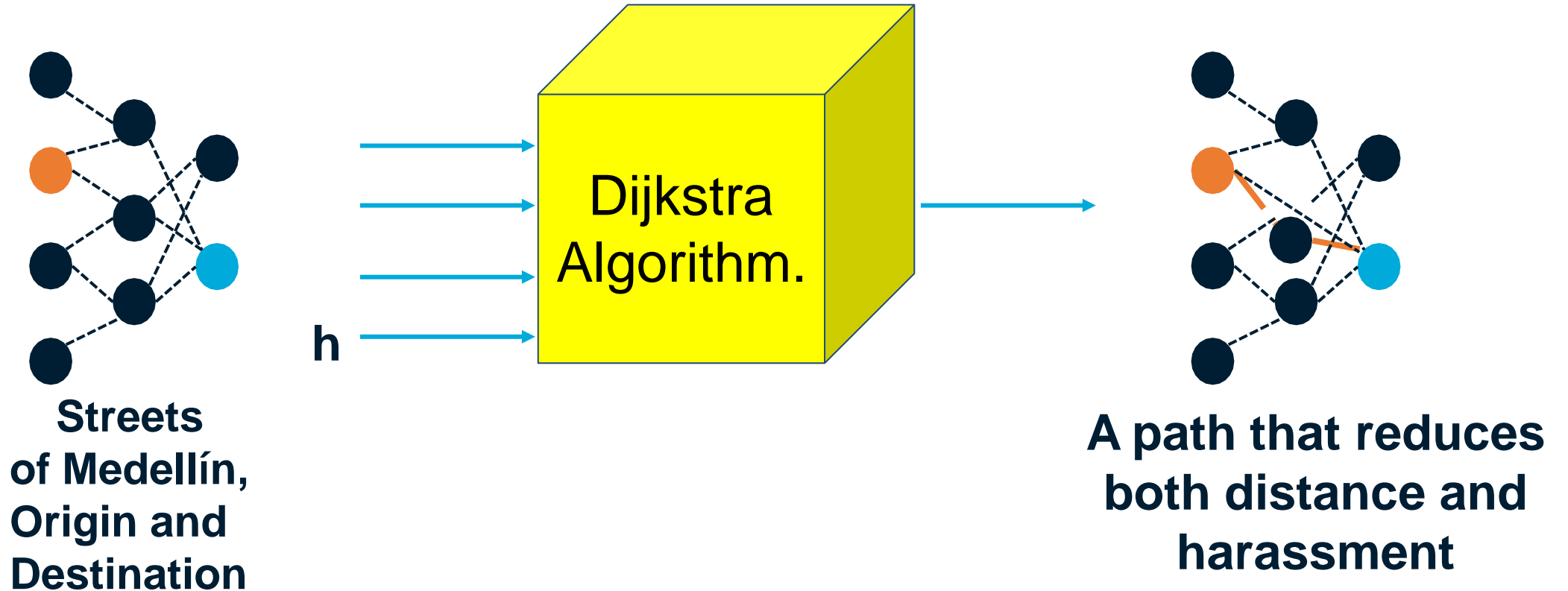


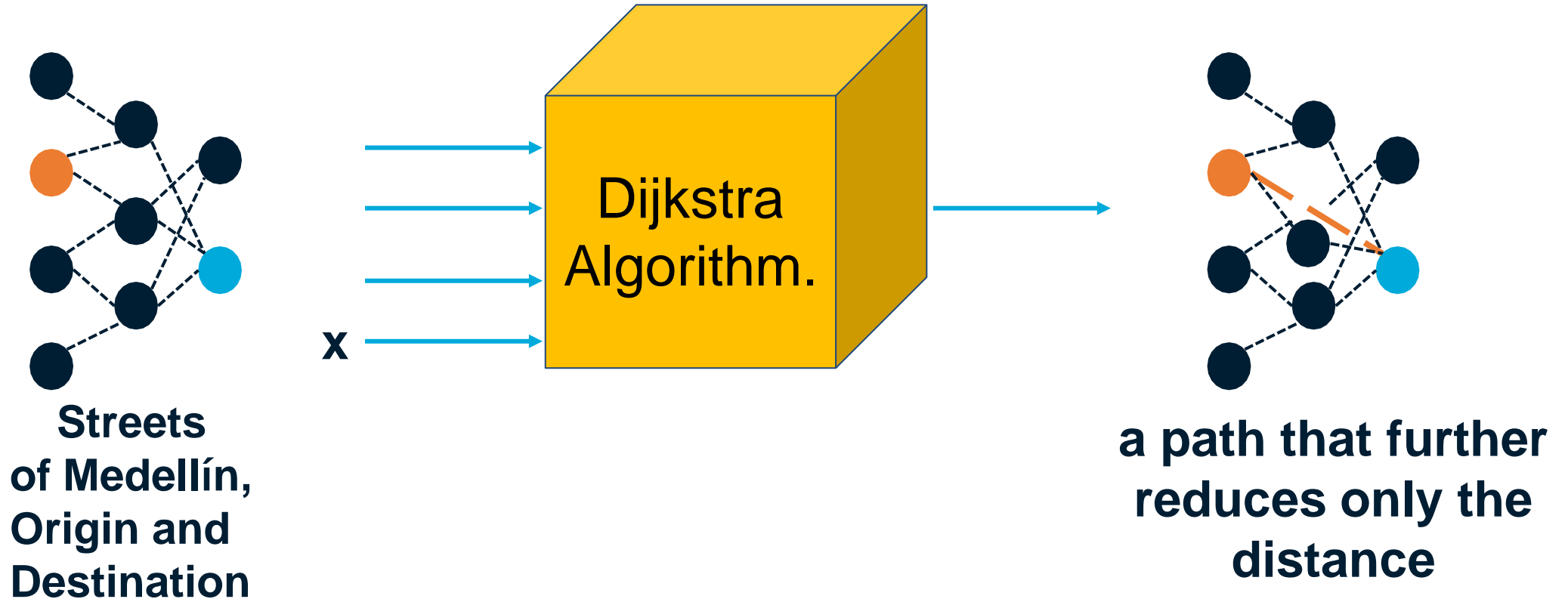
**Streets
of Medellín,
Origin and
Destination**

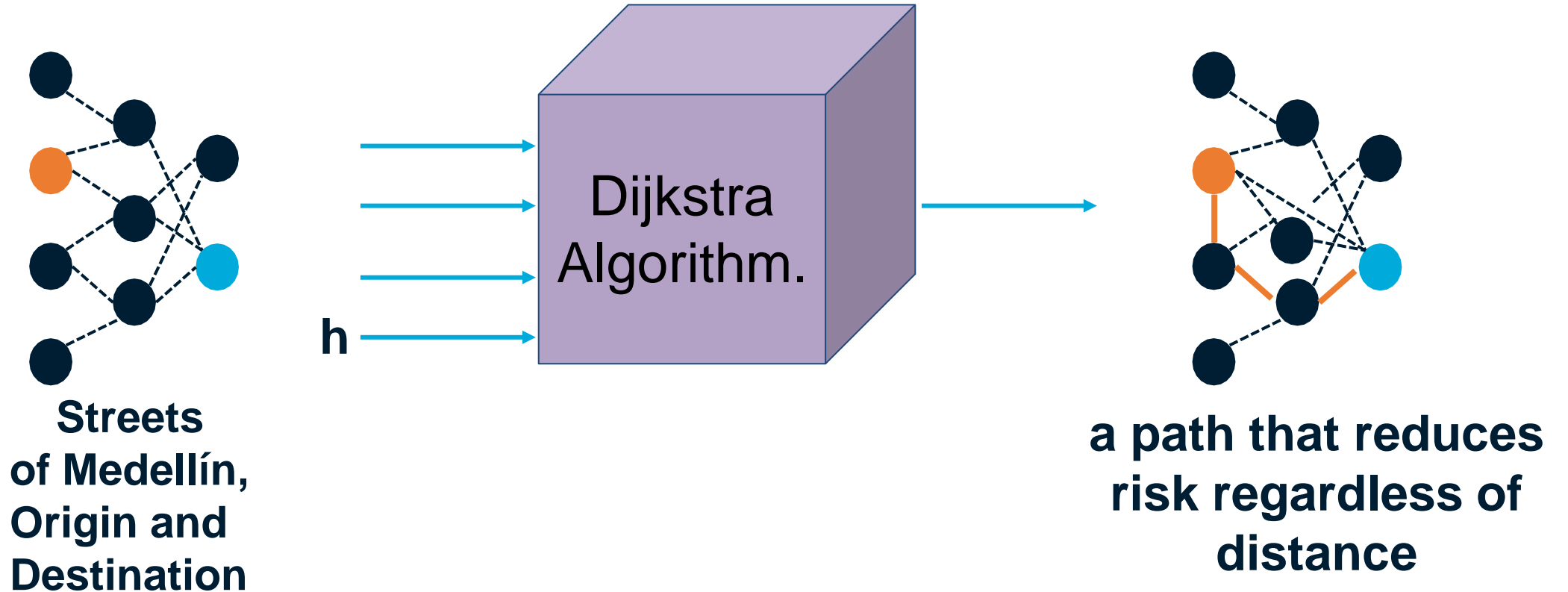


**Three paths that reduce
both the risk of harassment
and distance**











Our data structure is based on an Adjacency list implemented with dictionaries.

```
init_graph = {}
for node in nodes:
    init_graph[node] = {}

for origin, destination, peso in zip(data_arcs["origin"], data_arcs["destination"], data_arcs['peso']):
    init_graph[str(origin)][str(destination)] = [peso]
graph = Graph(nodes, init_graph)
```



A class Graph is used since this allow us to implement the creation of the graph easily if we want to use it on another script

```
class Graph(object):
    def __init__(self, nodes, init_graph):
        self.nodes = nodes
        self.graph = self.construct_graph(nodes, init_graph)

    def construct_graph(self, nodes, init_graph):

        graph = {}
        for node in nodes:
            graph[node] = {}
        graph.update(init_graph)

        return graph

    def get_nodes(self):
        return self.nodes

    def get_outgoing_edges(self, node):
        connections = []
        for out_node in self.nodes:
            if self.graph[node].get(out_node, False) != False:
                connections.append(out_node)
        return connections

    def value(self, node1, node2):
        return self.graph[node1][node2][0]
```




Dijkstra setting all
nodes value close to
infinity

```
def dijkstra_algorithm(graph, start_node):  
    unvisited_nodes = list(graph.get_nodes())  
  
    shortest_path = {}  
  
    previous_nodes = {}  
  
    max_value = sys.maxsize  
    for node in unvisited_nodes:  
        shortest_path[node] = max_value  
    shortest_path[start_node] = 0
```



Dijkstra finding the shortest path

```
while unvisited_nodes:
    current_min_node = None
    for node in unvisited_nodes:
        if current_min_node == None:
            current_min_node = node
        elif shortest_path[node] < shortest_path[current_min_node]:
            current_min_node = node

    neighbors = graph.get_outgoing_edges(current_min_node)
    for neighbor in neighbors:
        tentative_value = shortest_path[current_min_node] + graph.value(current_min_node, neighbor)
        if tentative_value < shortest_path[neighbor]:
            shortest_path[neighbor] = tentative_value
            previous_nodes[neighbor] = current_min_node

    unvisited_nodes.remove(current_min_node)

return previous_nodes, shortest_path
```

Explanation of the algorithm

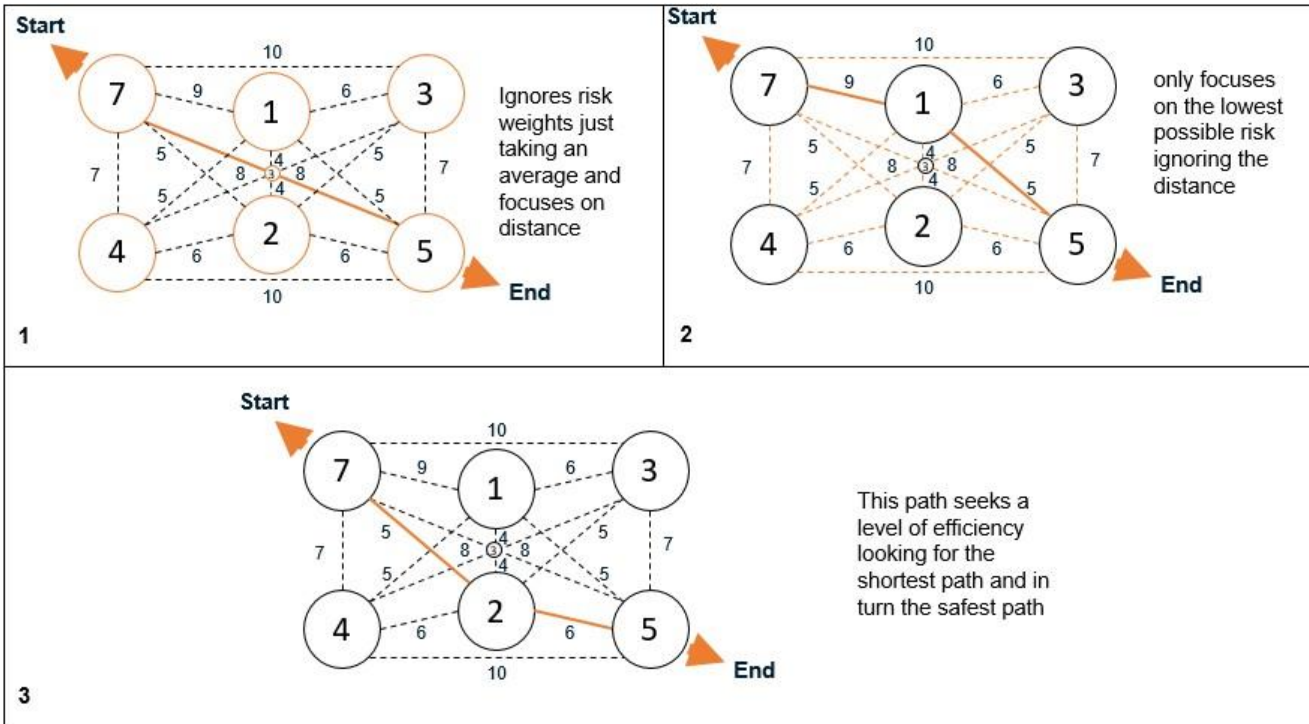


Figure 1: <https://www.proclamadelcauca.com/dejame-caminar-por-la-calle-tranquila/>

Dijkstra algorithm by three paths, One that takes both distance and risk¹, one that further reduces distance², one that gives the safest path³.



<https://github.com/RafaelUrbina/st245-002>

Complexity of the algorithm



	Time complexity	Complexity of memory
Dijkstra Algorithm	$O(V^2)$ $O((V+E) \log V)$	$O(V)$

Time and memory complexity of the Dijkstra.
where V is the number of vertices or nodes and E is the number of edges in the graph.

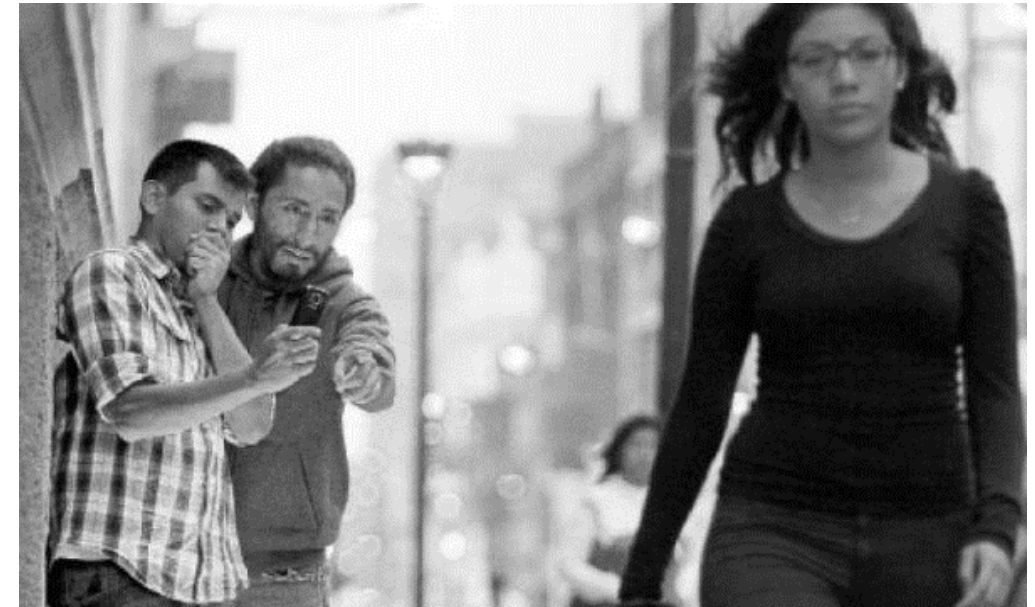


Figure 2: <http://www.mujereslibresdeviolencia.usmp.edu.pe/6-cosas-que-debes-hacer-si-eres-victima-de-acoso-sexual-callejero/>



First path minimizing $d = \text{Length}$



Origin	Destination	Distance (meters)	Risk of harassment (between 0 and 1)
EAFIT University	National University	7966.87	60.14

Distance and risk of harassment for the path that minimizes $d = \text{Length}$ Execution time of 163.56 seconds.



<https://github.com/RafaelUrbina/st245-002>



Second path minimizing d = Both



Origin	Destination	Distance (meters)	Risk of harassment (between 0 and 1)
EAFIT University	National University	9671.59	35.10

Distance and risk of harassment for the path that minimizes d = Both Execution time of 164.24 seconds.



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Third path minimizing $d = \text{Risk}$



Origin	Destination	Distance (meters)	Risk of harassment (between 0 and 1)
EAFIT University	National University	9680.52	35.10

Distance and risk of harassment for the path that minimizes $d = \text{Risk}$ Execution time of 166.48 seconds.



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Other route d = all



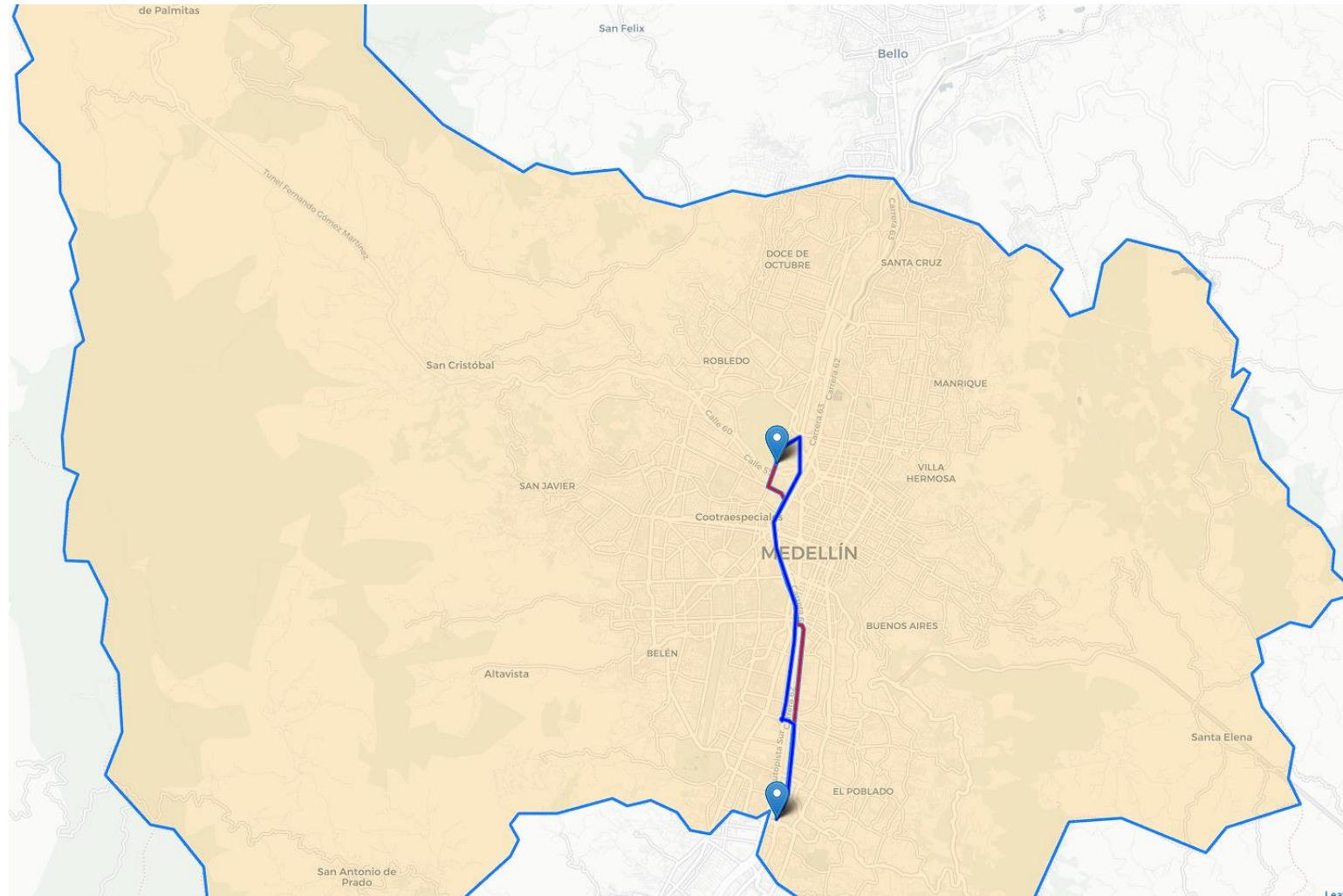
Origin	Destination	Distance (meters)	Risk of harassment (between 0 and 1)
Las Palmas	La America	5603.60	67.66
Las Palmas	La America	6309.87	61.29
Las Palmas	La America	6365.76	61.28

Distance and risk of harassment for the path that minimizes d = all Execution time of 162 seconds.



<https://github.com/RafaelUrbina/st245-002>

Visual comparison of the three paths (Eafit- Unal)



Shortest

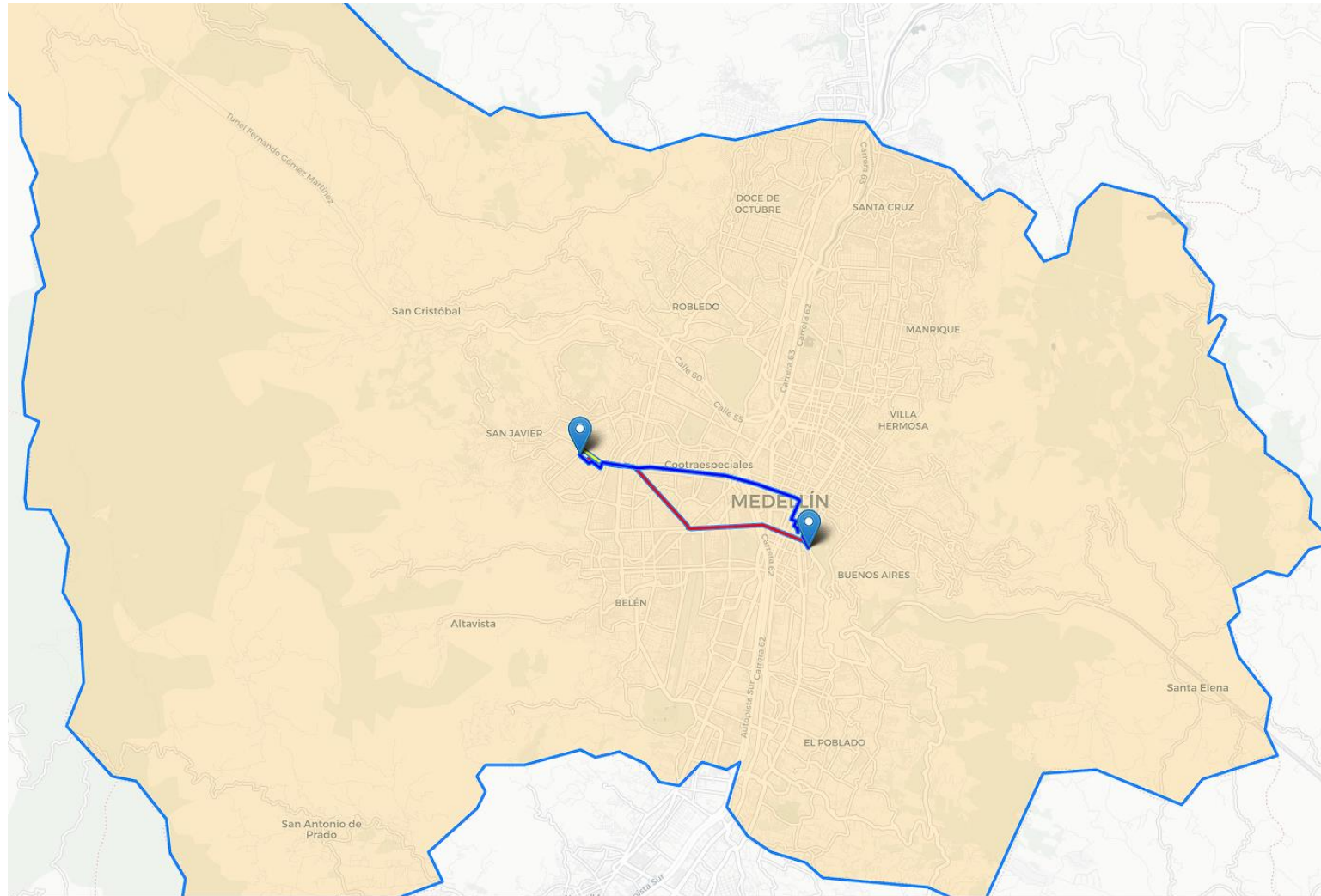


Safest



Combination

Visual comparison of the three paths (Las Palmas – La America)



Shortest



Safest



Combination

Future work directions



Databases

Other
variables

Other
algorithms

Project 1

Web
application

Software Engineering

Mobile
application

Project 2

Include ML
or VR



THANK YOU!

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