

# Distributed Systems

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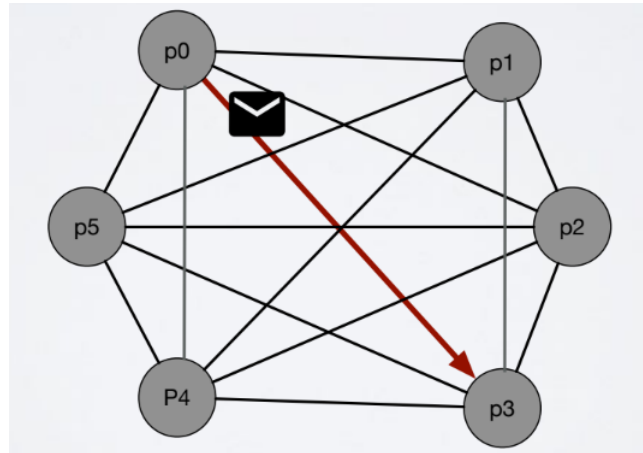
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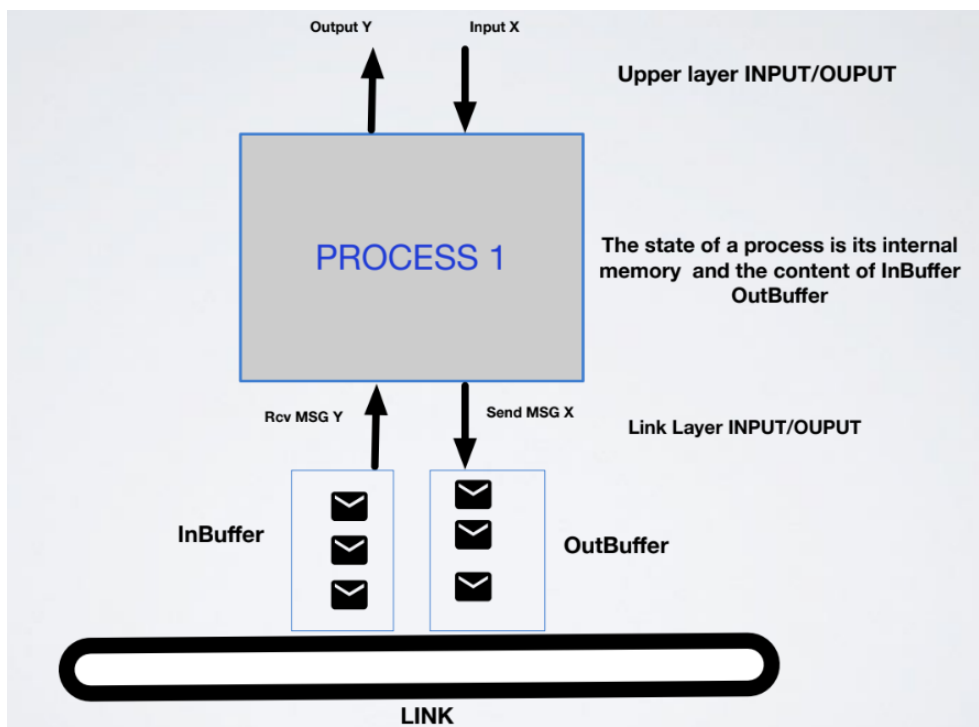
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# 1 Introduction

**Definition 1.** In a system we have  $n$  processes in  $\Pi : p_0 \dots, p_{n-1}$  each with a distinct identity they communicate by utilizing a communication graph  $G : (\Pi, E)$ , the communication is done by exchanging messages.



**Definition 2.** A process is a (possibly infinite) State Machine (I/O Automaton).



Each process has multiple qualities:

- A set of internal states  $Q$
- A set of initial states  $Q_i \subset Q$
- A set of all possible messages  $M$  in the form  $\langle \text{sender}, \text{receiver}, \text{payload} \rangle_i$
- Multiset of delivered messages  $InBuf_j$
- Multiset of inflight messages  $OutBuf_j$

We can formally describe this as follows: (this isnt part of the exam btw)

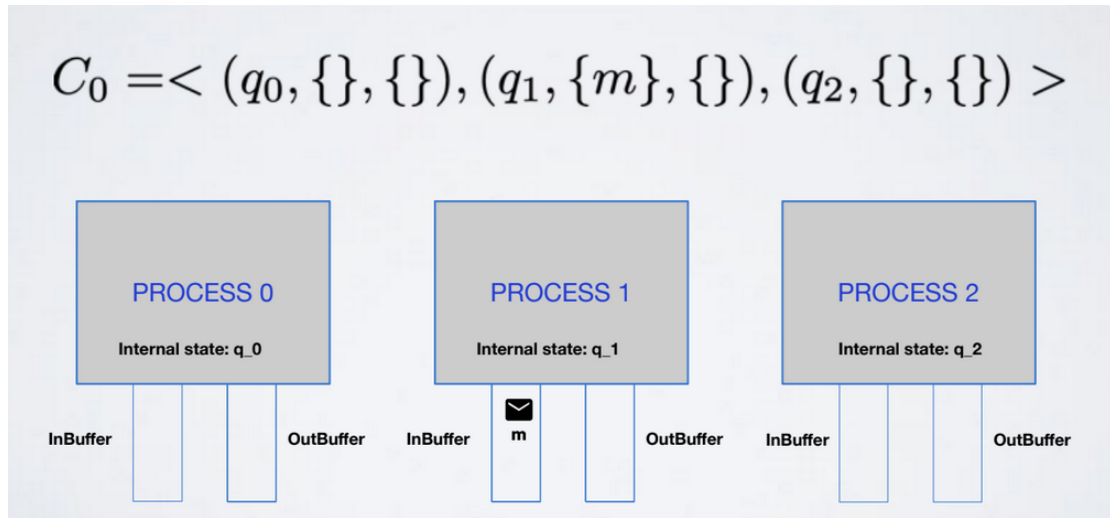
$$P_j(q \in Q \cup Q_{in}, InBuf_j) = (q' \in Q, SendMsg \subset M)$$

$$OutBuf_j = OutBuf_j \cup SendMsg$$

$$InBuf_j = \emptyset$$

To execute a process we have an adversary that schedules a set of events (scheduler), these events may be for example a delivery (e.g.  $Del(m, i, j)$ ) or it can be one step of the step machine of process  $i$  ( $Exec(i)$ )

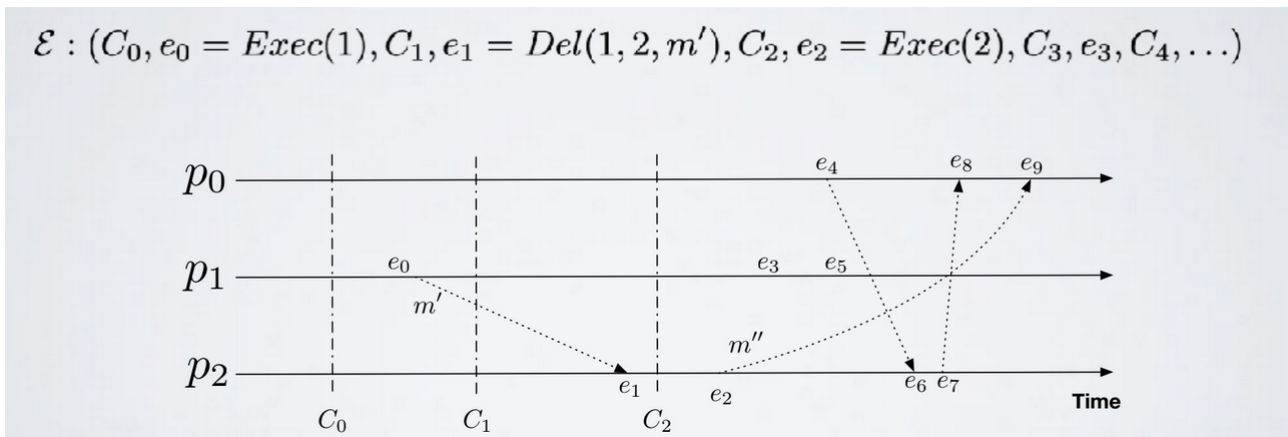
**Definition 3.** A configuration  $C_t$  is a vector of  $n$  components, component  $j$  indicates the state of process  $j$ .



An event is **enabled** in configuration  $c$  if it can happen.

**Definition 4.** An execution is an infinite sequence that alternates configurations and events:  $(C_0, e_0, C_1, e_1, C_2, e_2, \dots)$  such that each event  $e_t$  is enabled in configuration  $C_t$  and  $C_t$  is obtained by applying  $e_{t-1}$  to  $C_{t-1}$

It may be useful to visualize how an execution involving multiple processes works, here we have an example:



**Definition 5.** A *fair execution* is an execution  $E$  where each process  $p_i$  executes an infinite number of local computations ( $Exec(i)$  events are not finite) and each message  $m$  is eventually delivered (we can't stall messages)

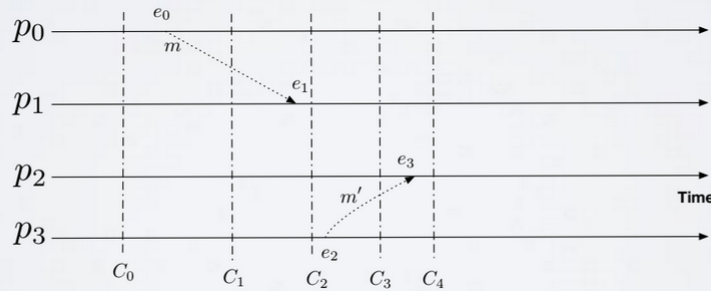
We will always use fair executions unless stated otherwise.

**Definition 6.** Given an execution  $E$  and a process  $p_j$ , we define the local view/ local execution of  $E|p_j$  the subset of events in  $E$  that impact  $p_j$

$\mathcal{E} = (C_0, e_0 = Exec(0), C_1, e_1 = Del(0, 1, m), C_2, e_2 = Exec(3), C_3, e_3 = Del(3, 2, m'), \dots)$

$\mathcal{E}|p_1 = (Del(0, 1, m), \dots)$

$\mathcal{E}|p_2 = (Del(3, 2, m'), \dots)$



But these executions do not account for time, so we may have executions that are the same even though the events happened at different times, in case this does happen, we say that two executions are *indistinguishable*.

**Theorem 1.** In the asynch. model there is no distributed algorithm capable of reconstructing the system execution.

## 1.1 Synchronous Vs Asynchronous

We have 3 main types of synchrony:

- Asynchronous Systems
- Eventually Synchronous Systems
- Synchronous systems

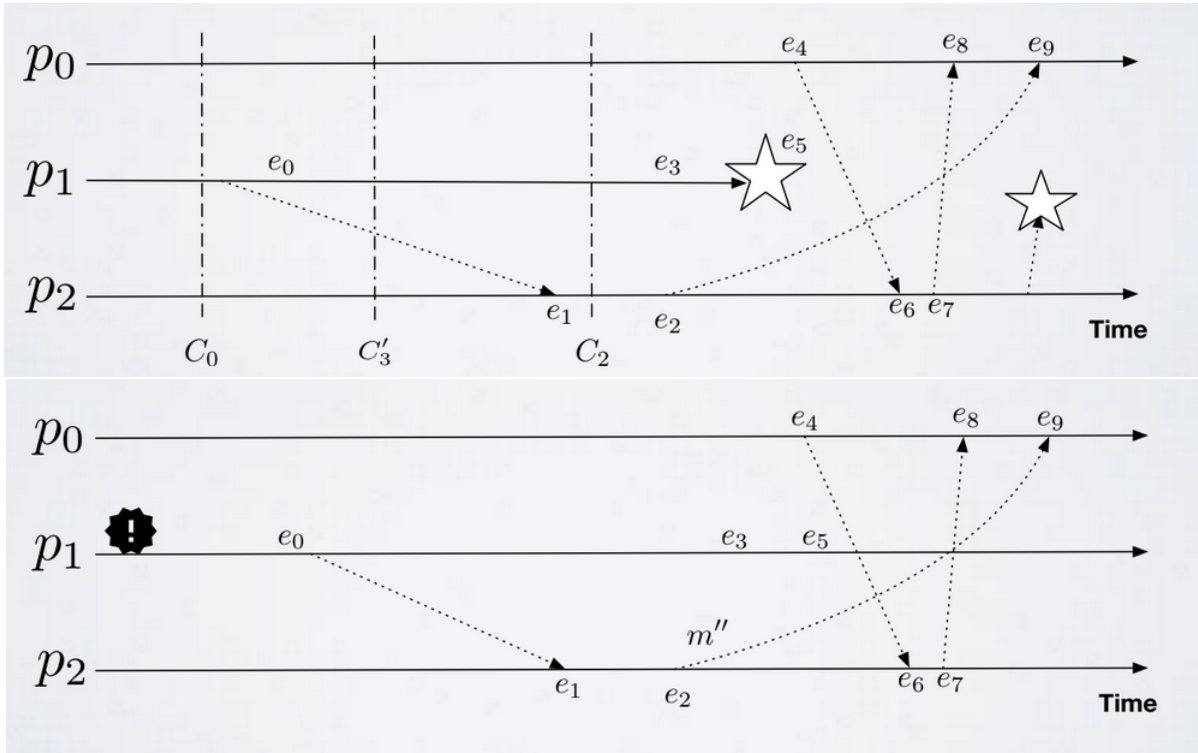
We can say that a system is synchronous if it has a fixed bound on the delay of messages, on the time of actions executed by processes, and a fixed bound between execution of actions.

## 1.2 Failures

We have 2 main models for failures:

- Crash-stop Failures (The program crashes, and doesn't respond)
- Byzantine Failures (The behaviour of the program is random)

We signal crash failures with a star sign and byzantine failures with a !



Byzantine failures are a superset of Crashstop failures, so algorithms that will work on byzantine failures will always work on crash stop failures, but not the contrary.

A process is **correct** if it does not experience a failure, every algorithm has a maximum number  $f$  of failures that it can experience.

### 1.3 Different types of links

**Definition 7.** An **Abstraction** is the formalization of a problem/object, to build one we must define the system model and formalize a problem/object so that there is no ambiguity regarding the properties of our abstraction

For example let us abstract a link: it is something that may lose a message with a certain probability  $pr$ , the messages can be duplicated a finite number of times and they must come from somewhere. Inside a link we have two main events:

- **Requests:**  $\downarrow \text{Send} \rightarrow q, m_i$  sends message  $m$  to process  $q$
- **Indication:**  $\downarrow \text{Deliver} \rightarrow p, m_i$  delivers a message  $m$  from process  $p$  (this might just be an identifier, e.g. an ip address or mac address)

Now let us formalize this further via its properties:

- **FL1:** (Fair loss) If a correct process  $p$  sends infinitely often  $m$ , a process  $q$  then delivers  $m$  an infinite number of times. (e.g. suppose we have  $\frac{1}{2}$  probability and we send it over 10 times, then the probability will be  $1 - \frac{1}{2^{10}}$  as events are independent aka if we try hard enough we get the message)
- **FL2:** (Finite duplication) if a correct process  $p$  send  $m$  a finite number of times to  $q$ , then  $q$  cannot deliver  $m$  an infinite number of times (we'll receive a finite number of duplicated packets)
- **FL3:** (No creation) If a certain process  $q$  sends a message  $m$  with  $\text{send}(p)$ , then  $m$  was sent by  $p$  to  $q$

Our objective is hiding the probability behind infinity.