Machine Learning and Computational Statistics Project Machine Learning F2023-2024

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Loading Data

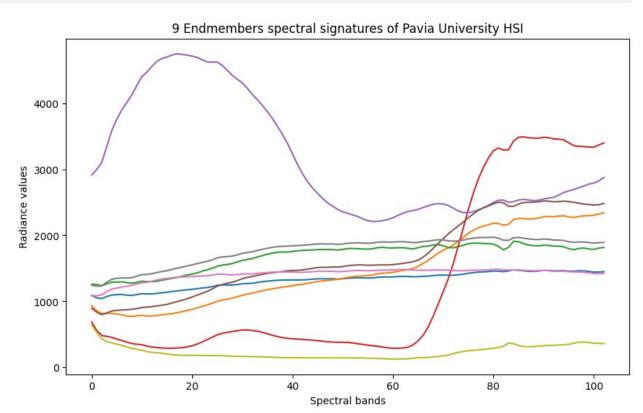
We will define some functions in order to load, plot and check our data.

```
import time
import scipy.io as sio
import matplotlib.pyplot as plt
import numpy as np
from scipy.optimize import minimize, nnls
def load data(file, column name):
    Load matlab data
    my file = sio.loadmat(file)
    data = my file[column name]
    return data
def plot data(dataset, ylabel, xlabel, title):
    Plot lines of a dataset
    plt.figure(figsize=(10, 6))
    plt.plot(dataset)
    plt.ylabel(ylabel)
    plt.xlabel(xlabel)
    plt.title(title)
    plt.show()
def image show(image, band):
    Add an image with the desired spectral band and show it
    plt.figure(figsize=(10, 6))
    plt.imshow(image[:,:,band])
    plt.title(f'RGB Visualization of the {band}th band of Pavia
University HSI')
    plt.show()
```

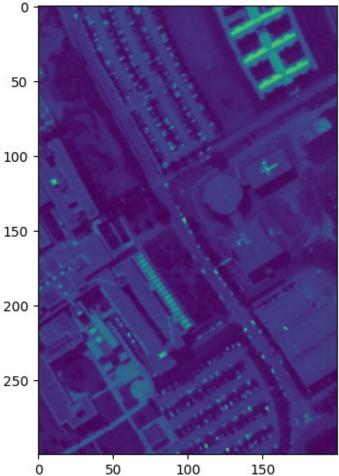
```
image_file = 'data/PaviaU_cube.mat' # Pavia HSI: 300x200x103
endmembers_file = 'data/PaviaU_endmembers.mat' # Endmember's matrix:
103x9
ground_truth_file = 'data/PaviaU_ground_truth.mat'

HSI = load_data(image_file, 'X')
endmembers = load_data(endmembers_file, 'endmembers')

ylabel = 'Radiance values'
xlabel = 'Spectral bands'
title = '9 Endmembers spectral signatures of Pavia University HSI'
plot_data(endmembers, ylabel, xlabel, title)
image_show(HSI, 10)
```







Part 1 Spectral Unmixing

At first, we will use Least Squares method in order to unmix the 9 endmembers of each pixel at the non-zero class labels. We will first create a list with the non-zero class label pixels via the file 'PaviaU_ground_truth'. We will create a function for calculating the parameters theta, using Least Squares and also a function in order to calculate the reconstruction error ($||y_i - X\theta_i||$). I did not use the square in order not to compute a very large value. Finally, we will create a function in order to calculate and store the abundance map for each class (1 to 9).

```
def calc_theta_LS(X, y):
    Calculation of theta via Least Squares method.
        No constraints inserted

XtX = np.dot(np.transpose(X), X)
    XtX_inverse = np.linalg.inv(XtX)
    XtY = np.dot(np.transpose(X), y)
    my_theta = np.dot(XtX_inverse, XtY)
```

```
return my theta
def calc MSE(thetas, X, y):
    Calculation of the reconstruction error
    using the equation ||\mathbf{y}i-X\mathbf{\theta}i||
    MSE = 0
    for i in range(len(thetas)):
        mse = (y[i] - np.dot(X, thetas[i]))
        MSE += np.linalg.norm(mse)
    MSE = MSE/len(thetas)
    return MSE
def calc abundance map(thetas, endmembers, HSI, groundtruth,
num of class=0):
    0.00
    Creating the new map in which the non-zero class pixels have been
    calculated via parameter theta
    step = 0
    for i in range(len(HSI)):
        for j in range(len(HSI[i])):
            if groundtruth[i][j] != 0:
                HSI[i][j] = thetas[step][num_of_class] * endmembers[:,
num of class]
                step += 1
    return HSI
# Load the ground truth file
ground truth = load data(ground truth file, 'y')
sum zero = 0
non zero pixels = []
# Keep and store only the pixels with non zero class label
for i in range(len(ground truth)):
    for j in range(len(ground_truth[i])):
        if ground truth[i][j] == 0:
            sum zero += 1
        else:
            non_zero_pixels.append(HSI[i][j])
non zero pixels = np.array(non zero pixels)
```

a) Using Least squares with no constraints

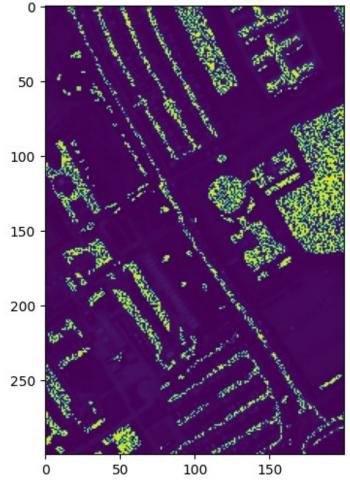
```
# Compute the thetas based on Least Squares, calculate the
reconstruction error (||yi-X0i||) and plot the 9 abundance maps
LS_thetas = []
for pixel in non_zero_pixels:
    LS_thetas.append(calc_theta_LS(endmembers, pixel))

MSE_LS = calc_MSE(LS_thetas, endmembers, non_zero_pixels)
print(f"MSE for the Least Squares method is: {MSE_LS}")

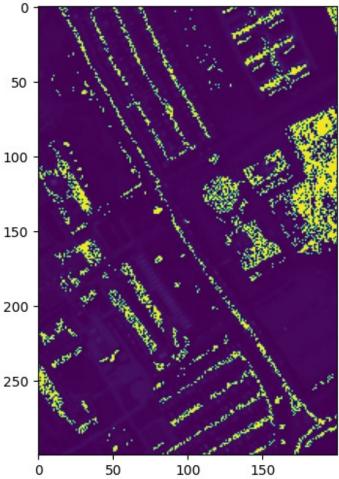
for i in range(9):
    HSI_LS = calc_abundance_map(LS_thetas, endmembers, HSI,
ground_truth, num_of_class=i)
    print(f'Plotting the abundance map for class/endmember: {i+1}')
    image_show(HSI_LS, 10)

MSE for the Least Squares method is: 335.5921598100192
Plotting the abundance map for class/endmember: 1
```

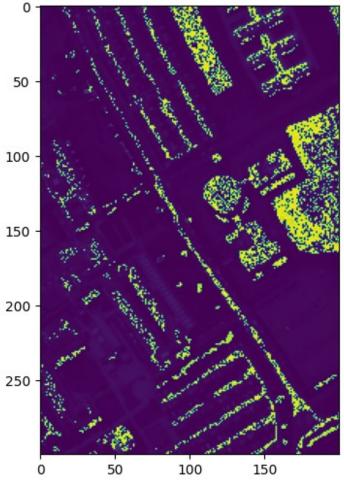
RGB Visualization of the 10th band of Pavia University HSI



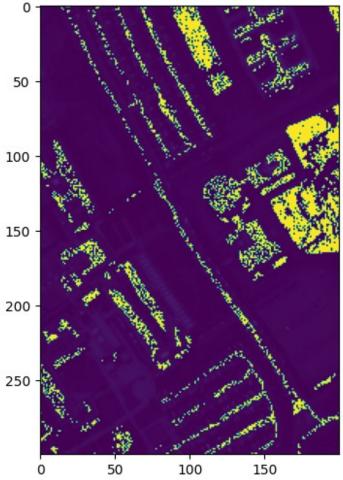
RGB Visualization of the 10th band of Pavia University HSI



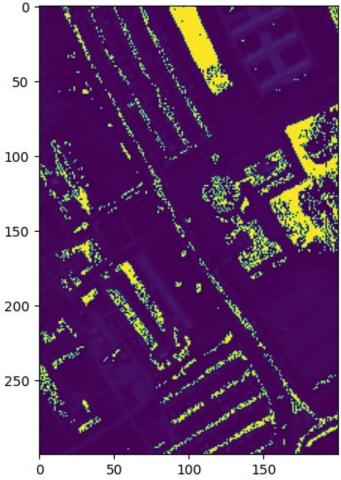
RGB Visualization of the 10th band of Pavia University HSI



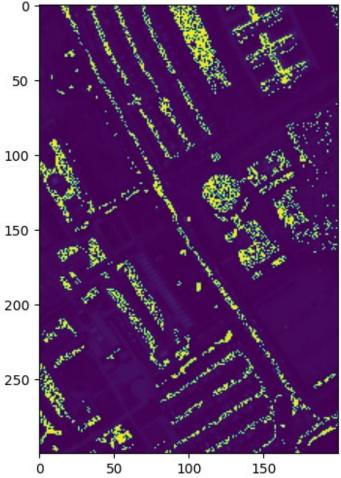
RGB Visualization of the 10th band of Pavia University HSI



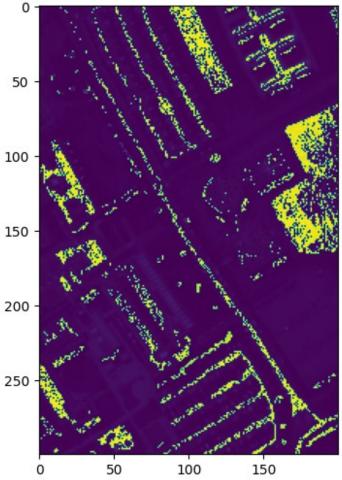
RGB Visualization of the 10th band of Pavia University HSI



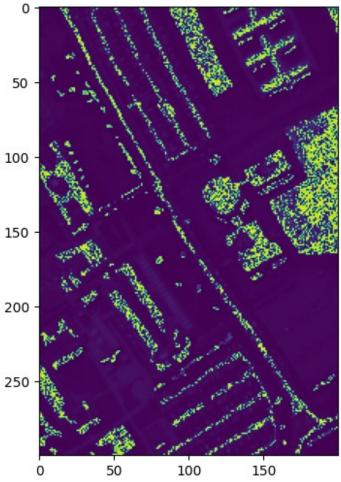
RGB Visualization of the 10th band of Pavia University HSI



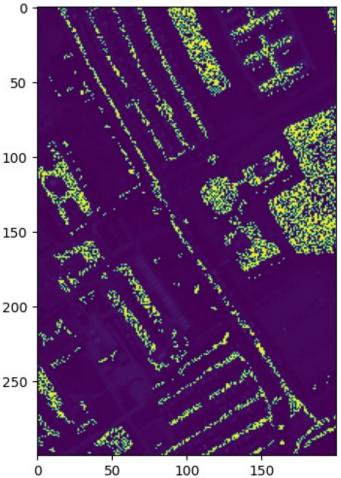
RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



b) Least squares imposing the sum-to-one constraint

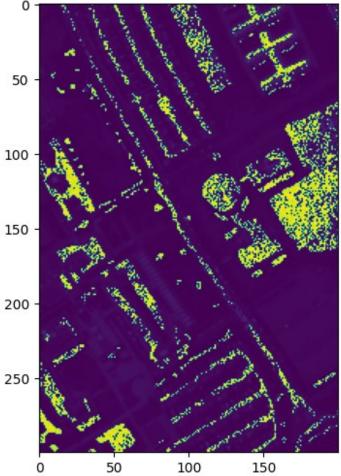
So, we will use Least Squares however the parameters must sum-to-one.

```
def objective_normalize_theta(theta, X, y):
    Normalize the coefficients to ensure sum-to-one constraint
    theta_normalized = theta / np.sum(theta)
    return np.sum((X @ theta_normalized - y) ** 2)

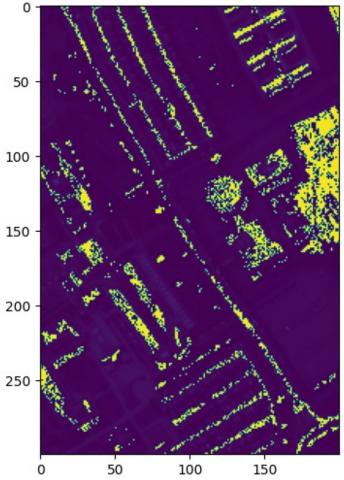
def calc_theta_LS_constraints(X, y, bounds=False):
    Calc theta with constraints
    num_of_theta = np.ones(9) / 9
    if bounds:
        bounds = [(0, None)] * 9
```

```
result = minimize(objective normalize theta, num of theta,
args=(X, y), bounds=bounds)
    else:
        result = minimize(objective normalize theta, num of theta,
args=(X, y)
    my_theta = result.x / np.sum(result.x)
    return my theta
LS thetas sum to one = []
for pixel in non zero pixels:
    LS thetas sum to one.append(calc theta LS constraints(endmembers,
pixel))
MSE sum to one = calc MSE(LS thetas sum to one, endmembers,
non zero pixels)
print(f"MSE for the Least Squares method with constraint sum-to-one
is: {MSE sum to one}")
for i in range(9):
    HSI LS sum to one = calc abundance map(LS thetas sum to one,
endmembers, HSI, ground truth, num of class=i)
    print(f'Plotting the abundance map for class/endmember: {i+1}')
    image_show(HSI_LS_sum_to_one, 10)
MSE for the Least Squares method with constraint sum-to-one is:
385.59855862255944
Plotting the abundance map for class/endmember: 1
```

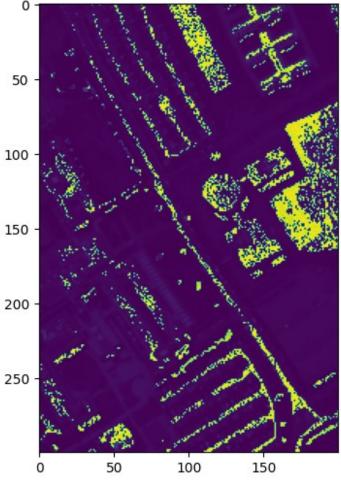
RGB Visualization of the 10th band of Pavia University HSI



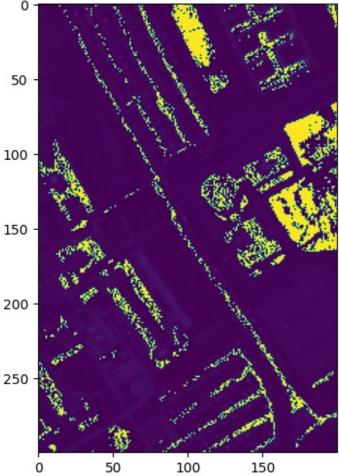
RGB Visualization of the 10th band of Pavia University HSI



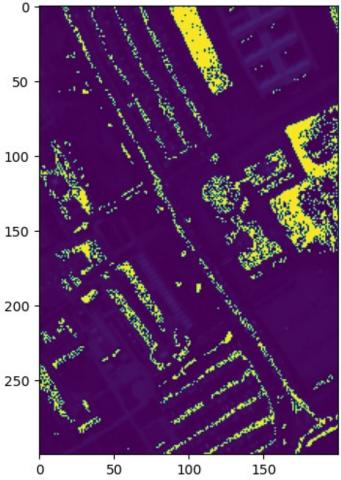
RGB Visualization of the 10th band of Pavia University HSI



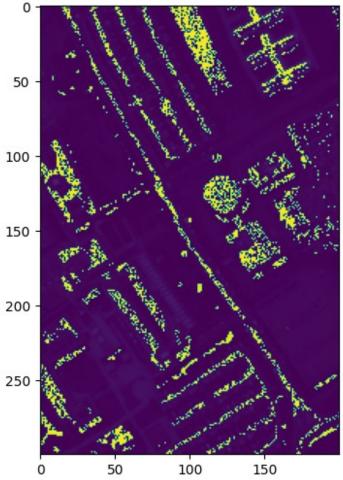
RGB Visualization of the 10th band of Pavia University HSI



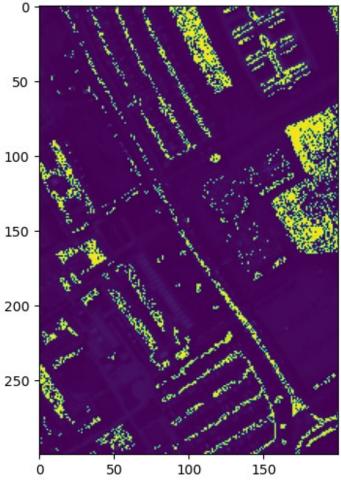
RGB Visualization of the 10th band of Pavia University HSI



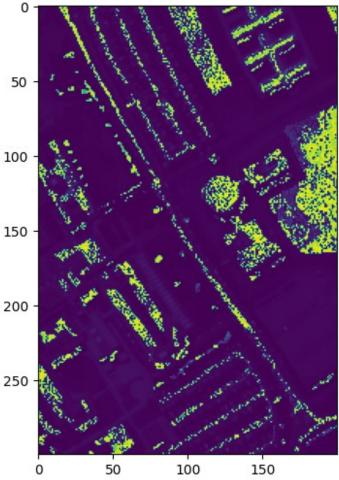
RGB Visualization of the 10th band of Pavia University HSI



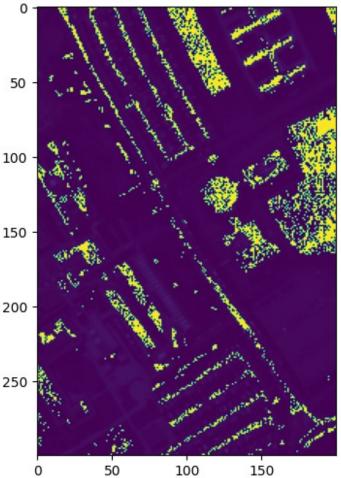
RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



c) Least squares imposing the non-negativity constraint

So, we will use Least Squares however the parameters must be non-negative.

```
from scipy.optimize import nnls

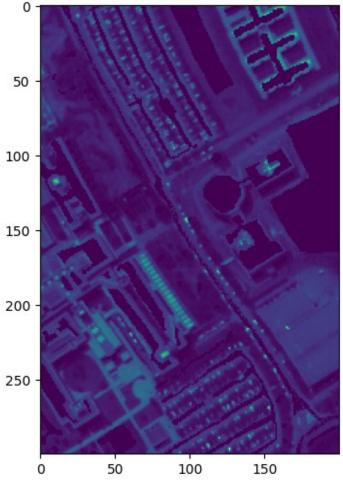
LS_thetas_non_negative = []
for pixel in non_zero_pixels:
    optimal, MSE_non_negative = nnls(endmembers, pixel)
    LS_thetas_non_negative.append(optimal)

print(f"MSE for the Least Squares method with constraint non-negativity is: {MSE_non_negative}")

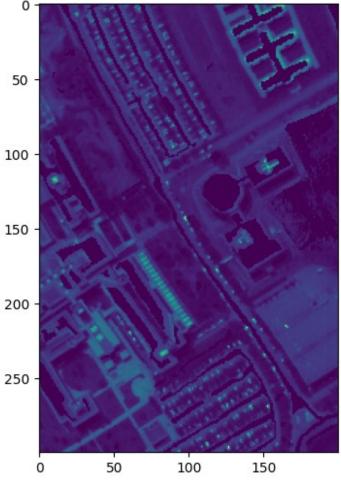
for i in range(9):
    HSI_LS_non_negative = calc_abundance_map(LS_thetas_non_negative, endmembers, HSI, ground_truth, num_of_class=i)
    print(f'Plotting the abundance map for class/endmember: {i+1}')
    image_show(HSI_LS_non_negative, 10)
```

MSE for the Least Squares method with constraint non-negativity is: 452.79891706920523
Plotting the abundance map for class/endmember: 1

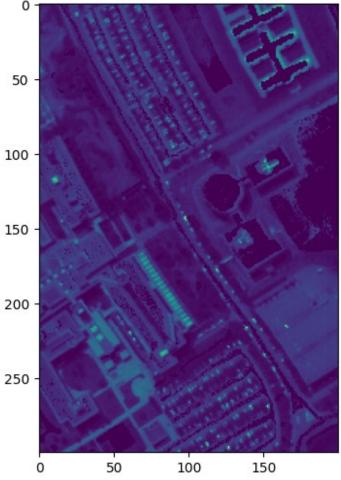
RGB Visualization of the 10th band of Pavia University HSI



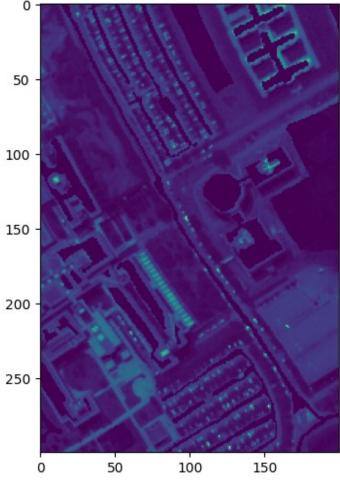
RGB Visualization of the 10th band of Pavia University HSI



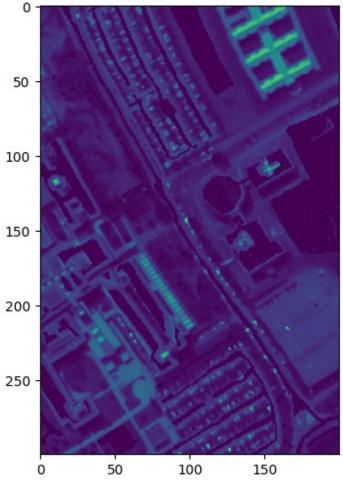
RGB Visualization of the 10th band of Pavia University HSI



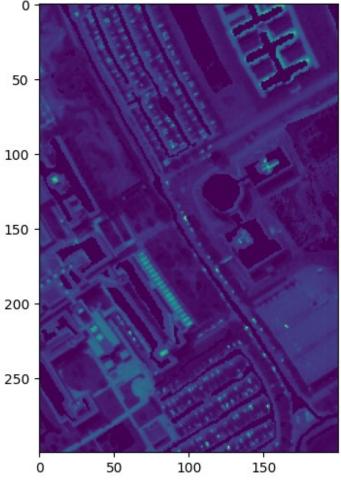
RGB Visualization of the 10th band of Pavia University HSI



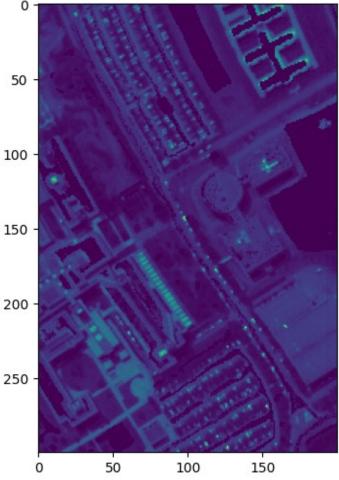
RGB Visualization of the 10th band of Pavia University HSI



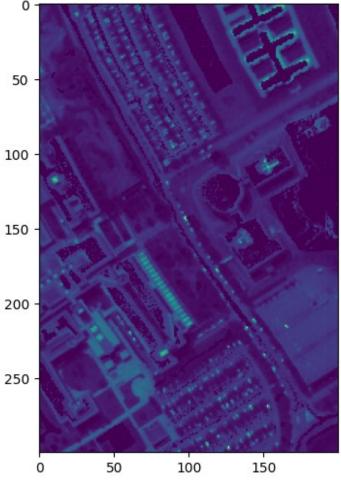
RGB Visualization of the 10th band of Pavia University HSI



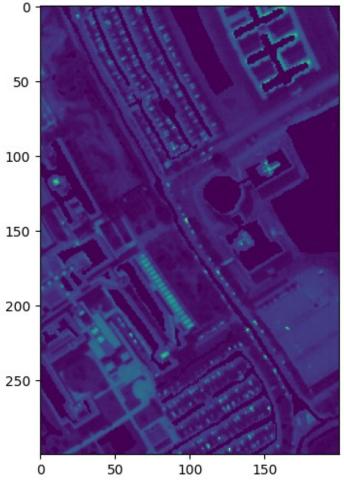
RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



d) Least squares imposing the non-negativity AND sum-to-one constraints

So, we will use Least Squares, however the parameters must be non-negative and sum-to-one.

```
LS_thetas_constraints = []
for pixel in non_zero_pixels:
    LS_thetas_constraints.append(calc_theta_LS_constraints(endmembers,
pixel, bounds=True))

MSE_constraints = calc_MSE(LS_thetas_constraints, endmembers,
non_zero_pixels)
print(f"MSE for the Least Squares method with constraints non-
negativity and sum-to-one is: {MSE_constraints}")

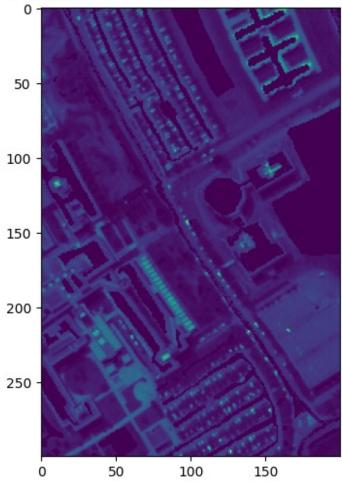
for i in range(9):
    HSI_LS_constraints = calc_abundance_map(LS_thetas_constraints,
endmembers, HSI, ground_truth, num_of_class=i)
```

```
print(f'Plotting the abundance map for class/endmember: {i+1}')
    image_show(HSI_LS_constraints, 10)

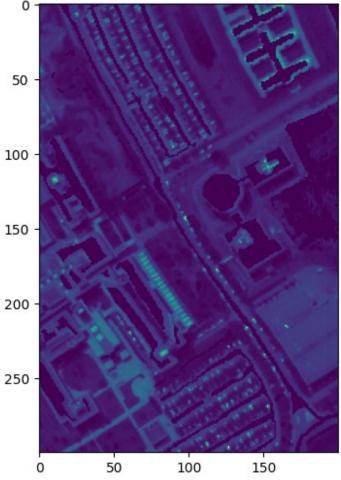
C:\Users\joker\AppData\Local\Temp\ipykernel_18704\3001419531.py:5:
RuntimeWarning: divide by zero encountered in divide
    theta_normalized = theta / np.sum(theta)
C:\Users\joker\AppData\Local\Temp\ipykernel_18704\3001419531.py:5:
RuntimeWarning: invalid value encountered in divide
    theta_normalized = theta / np.sum(theta)

MSE for the Least Squares method with constraints non-negativity and sum-to-one is: 1231.949520474831
Plotting the abundance map for class/endmember: 1
```

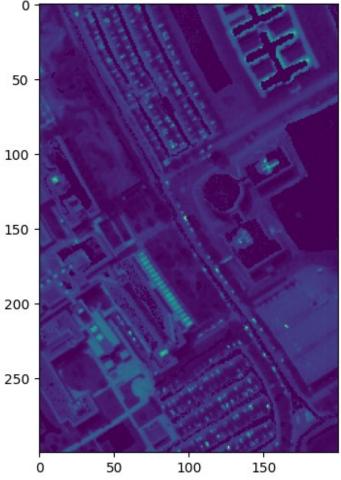
RGB Visualization of the 10th band of Pavia University HSI



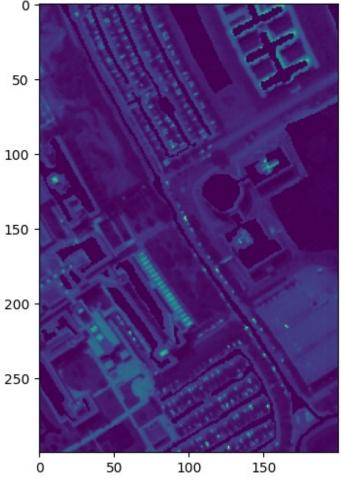
RGB Visualization of the 10th band of Pavia University HSI



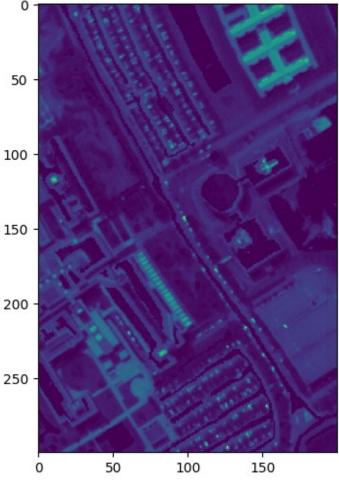
RGB Visualization of the 10th band of Pavia University HSI



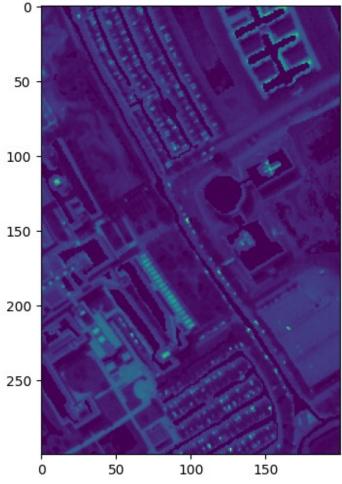
RGB Visualization of the 10th band of Pavia University HSI



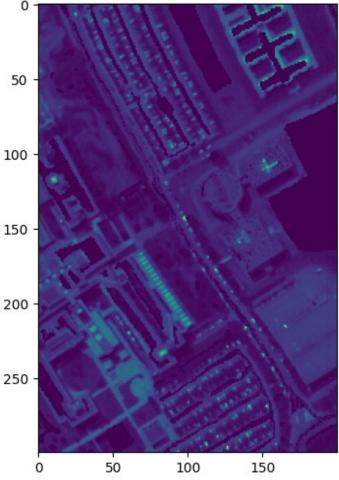
RGB Visualization of the 10th band of Pavia University HSI



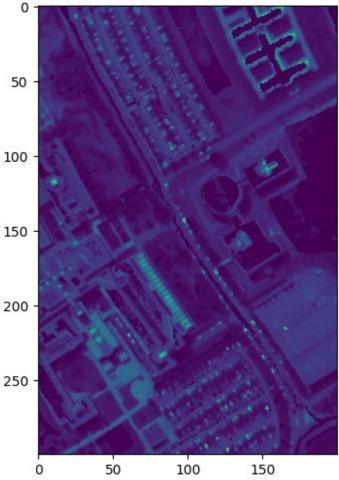
RGB Visualization of the 10th band of Pavia University HSI



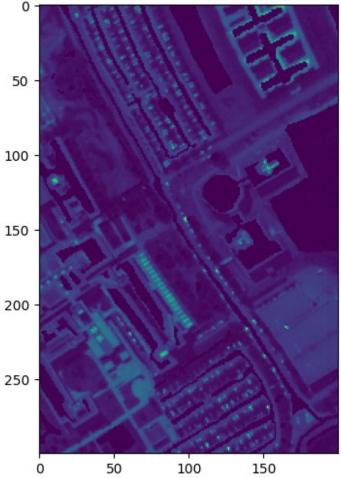
RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI

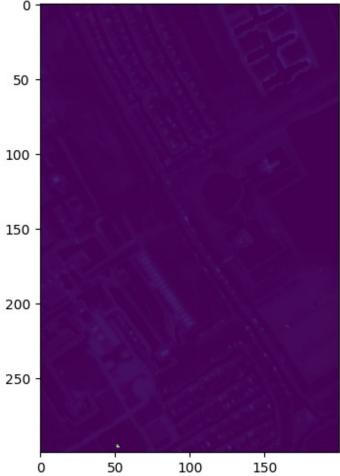


e) LASSO, where impose sparsity on θ via l1 norm minimization.

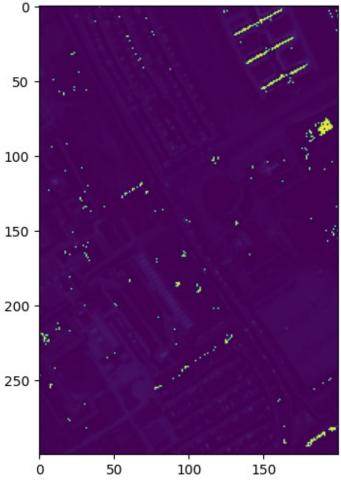
So, we will use various values of hyperparameter λ in order to find the best combination. We started by λ =0.1 and we reached until 900. We spotted that around value λ =870 the reconstraint error started increase, thus we stopped at value λ =900 and searched around value = 850 in order to find the optimum one.

```
lasso model = Lasso(alpha=1)
        for pixel in non zero pixels:
            lasso model.fit(endmembers, pixel)
            thetas lasso.append(lasso model.coef)
        MSE lasso = calc MSE(thetas lasso, endmembers,
non_zero_pixels)
        if comp MSE lasso == -1:
            comp MSE lasso = MSE_lasso
        if MSE lasso < comp MSE lasso:</pre>
            best MSE_lasso = {}
            best_MSE_lasso[l] = MSE_lasso
            best_theta_lasso = thetas_lasso
for key, value in best MSE lasso.items():
    print(f"Best hyperparameter \lambda for the Lasso method is: {key:.2f}
with reconstruction error: {value:.3f}")
Best hyperparameter \lambda for the Lasso method is: 865.00 with
reconstruction error: 4659.383
for i in range(9):
    HSI Lasso = calc abundance map(best theta lasso, endmembers, HSI,
ground truth, num of class=i)
    print(f'Plotting the abundance map for class/endmember: {i+1}')
    image show(HSI Lasso, 10)
Plotting the abundance map for class/endmember: 1
```

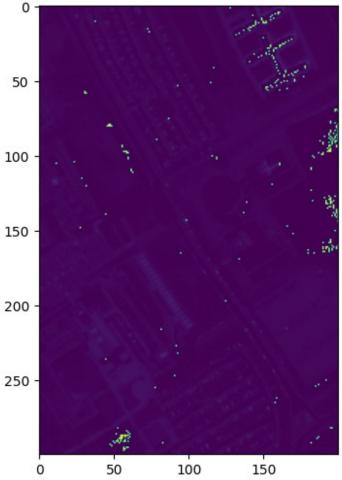
RGB Visualization of the 10th band of Pavia University HSI



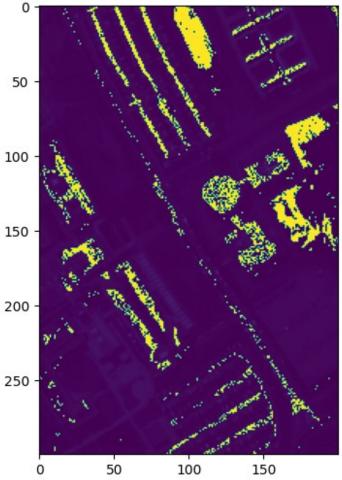
RGB Visualization of the 10th band of Pavia University HSI



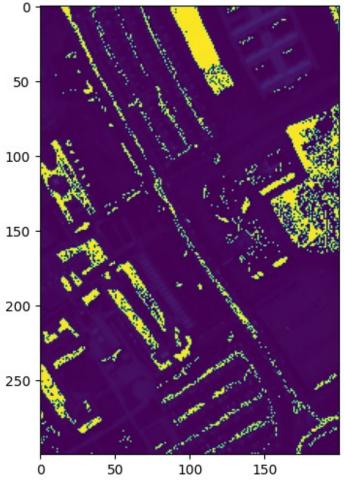
RGB Visualization of the 10th band of Pavia University HSI



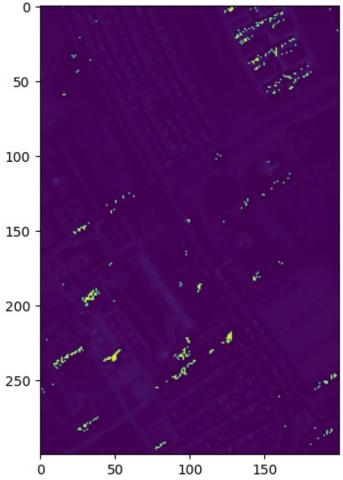
RGB Visualization of the 10th band of Pavia University HSI



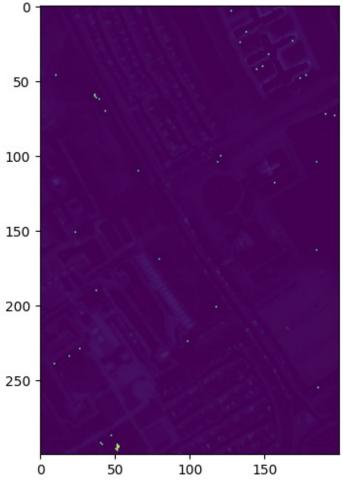
RGB Visualization of the 10th band of Pavia University HSI



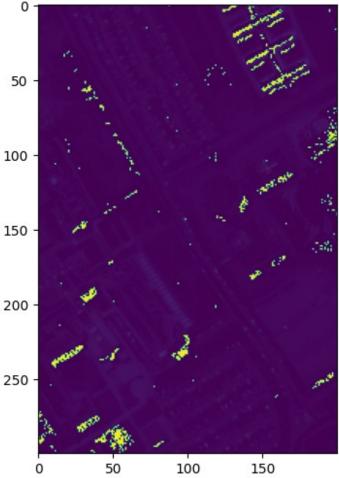
RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



RGB Visualization of the 10th band of Pavia University HSI



50 100 150 200 250

RGB Visualization of the 10th band of Pavia University HSI

Comments on the Results

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Taking into consideration the above results we can make the following observations for each method:

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a) Least Squares: Provides a baseline, but may overlook constraints inherent in realworld scenarios like this. So despite the fact that the reconstruction error had the smallest value it had mistaken parameters θ .

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- b) Sum-to-One Constraint: Ensures physically meaningful results by adhering to abundance sum constraints, however the parameters where not so close to the real ones for the reason that many of them were negative.
- c) Non-negativity Constraint: Incorporates realism by preventing negative abundance values. It could not achieve the realest results for the reason that parameters theta did not sum to one, thus many pixel was consisted of more than 100% of the size of a pixel. However, as we can see from the abundance maps the

results are quite efficient so the non-negativity constraint can give efficient result for this specific problem.

- d) Combined Constraints: Achieves a balance by considering both sum-to-one and non-negativity constraints. Despite the fact that the reconstruction error was almost the worst the abundance maps gave us the best results. We expected these results from this method for the reason that the constraints were very well suited for this problem.
- e) LASSO: Introduces sparsity, potentially leading to more interpretable abundance maps. However, regarding the abundance maps we did not see the best results from these which we expected to.

Part 2 - Classification

So, in order to train our non-zero pixels and evaluate their accuracy based on (i) the naïve Bayes classifier, (ii) the Bayesian classifier, (iii) the minimum Euclidean distance classifier and (iv) the knearest neighbor classifier we implemented training via k-fold cross validation (k=10) and computed the average accuracy and standard deviation. Finally we trained our classifiers in the whole training set. For cases (i) and (iv) we used some ready for use libraries.

For cases (ii) and (iii) which are the Bayes classifier and Minimun Euclidean distance classifier, we created the necessary functions in order to calculate the mean and covariance for each class based on the training set (that is splitted via k-fold cross validation), and estimated the classes of x_{total} to the training.

So, for all the classifiers we tested them in order to see the accuracy, validation errors, standard deviation and finally the confusion matrix.

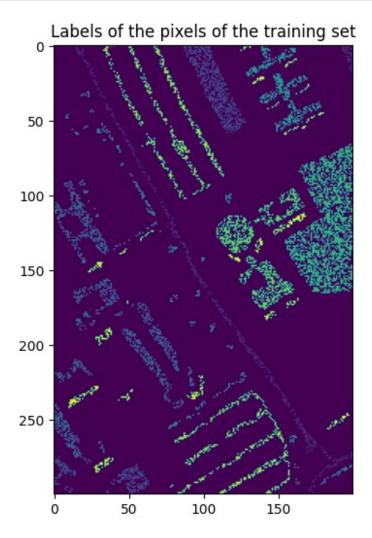
```
import scipy.io as sio
import numpy as np
from sklearn.metrics import confusion matrix
from sklearn.naive bayes import GaussianNB
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy score
from scipy.stats import multivariate normal
from sklearn.model selection import KFold
from sklearn.model selection import cross val score
import matplotlib.pyplot as plt
def split_training_set(X, y, Xtest):
    X train = []
    y train = []
    X \text{ test} = []
    y test = []
    for i in range(len(y)):
        for j in range(len(y[i])):
            if y[i][j] != 0:
                X train.append(X[i][i])
```

```
y_train.append(y[i][j])
            elif \overline{X}test[i][j] != 0:
                X test.append(X[i][j])
                y test.append(Xtest[i][i])
    return np.array(X_train), np.array(y_train), np.array(X_test),
np.array(y test)
def model classify(model, model name, n splits, X train, y train,
X test):
    my model = model
    kf = KFold(n splits=n splits, shuffle=True, random state=42)
    # Make predictions on the test data
    cv results = cross val score(my model, X train, y train, cv=kf)
    mean = cv results.mean()
    std = cv results.std()
    print(f"Mean Validation Error of {model name} model is: {(1 -
mean) *100: .3f %")
    print(f"Standard Deviation error of {model name} model is:
{std: .3f}")
    print("")
    # Train the classifier on the whole training data
    my_model.fit(X_train, y_train)
    y pred all = my model.predict(X test)
    return y pred all
    # Train the classifier on the whole training data
    my_model.fit(X_train, y_train)
    y pred all = my model.predict(X test)
    return y pred all, y test
def calc confusion matrix (model name, y test, y pred):
    cm = confusion_matrix(y_test, y_pred)
    print(f"The confusion matrix for {model name} model is: {cm}")
    diagonal sum = np.sum(np.diagonal(cm))
    sum cm = np.sum(cm)
    accuracy = diagonal_sum/sum_cm
    print(f"The success rate of {model name} model is:
{accuracy*100: .3f}%")
    print("")
    return accuracy
image_file = 'data/PaviaU_cube.mat' # Pavia HSI: 300x200x103
endmembers file = 'data/PaviaU endmembers.mat' # Endmember's matrix:
103x9
ground truth file = 'data/PaviaU ground truth.mat'
HSI = load data(image file, 'X')
```

```
# Training set for classification
Pavia_labels = sio.loadmat('data/classification_labels_Pavia.mat')
Training_Set = (np.reshape(Pavia_labels['training_set'],(200,300))).T
Test_Set = (np.reshape(Pavia_labels['test_set'],(200,300))).T
Operational_Set = (np.reshape(Pavia_labels['operational_set'],(200,300))).T

# Create the training and test set via the above labels
X_train, y_train, X_test, y_test = split_training_set(HSI, Training_Set, Test_Set)

fig = plt.figure(figsize=(12,6))
plt.imshow(Training_Set)
plt.title('Labels of the pixels of the training set')
plt.show()
```



Train each classifier, calculate mean estimated validation error and standard deviation - Plot confusion matrix

i) Naive Bayes Classifier cases

```
# Train Naive Bayes model
nb model = GaussianNB()
nb_preds = model_classify(nb_model, 'Naive Bayes', 10, X_train,
y_train, X_test)
# Compute the confusion matrix and success rate for Naive Bayes
nb_accuracy = calc_confusion_matrix('Naive Bayes', y_test, nb_preds)
Mean Validation Error of Naive Bayes model is:
Standard Deviation error of Naive Bayes model is: 0.018
The confusion matrix for Naive Bayes model is: [[131
                                                       0 37
0 80 13
            01
    0 326
            4
                6
                    0
                       17
                             0
                                 0
                                     01
  25
        2 127
                0
                       13
                            70 299
                                     0]
        0
            0 154
                    1
                        1
                             0
                                     0]
               0 166
                        1
                             0
        0
            1
                                     01
                   32 363
    0 312
           2
              55
                                     0]
  18
          26
                        0 277
        0
                0
                    0
                                     01
        1 67
                        1
                             2 388
                0
                    0
                                     01
                2
    0
        0
            0
                    0
                        0
                             0
                                 0 185]]
The success rate of Naive Bayes model is:
                                            66.012%
```

Comments on Naive Bayes Confusion Matrix

As we can spot from the confusion matrix we have many classes that are NOT well separated by the classifier. More specifically, for class 3 (Asphalt) 75% of the values are misclassified. Also, for class 6 (Tiles) more than 50% of the values are misclassified. Moreover, class 1 (Water), and class 8 (Meadows) have many misclassified values. The rest classes are well separated. Overall, as we can see from the success rate we do not have a very efficient classification from Naive Bayes Classifier.

iv) Bayesian classifier case

So for the Bayesian we did not use any ready for use library. We created two (2) functions (create_mean & create_cov) in order to calculate the means and covariances based on the training dataset. We use k-fold cross validation in order to train each time our classifier and calculate the means and covariances. We built functions in order to train and evaluate our model. We must take into consideration that the functions we created can use the minimun Euclidean distance classifier for the reason that this classifier just calculates the $||x - \mu j|| = \min q = 1,...M ||x - \mu q||$ and assigned in the class with the minimun distance. Finally, we trained our classifiers based on the whole dataset and predict the classes on the X_test values

```
def create_mean(set_y, set_x, num_class=9):
    Estimate mean of a multivariate
    Gaussian distribution
    num dimensions = len(set x[0])
    mean = np.zeros(num dimensions)
    num of values = 0
    for i in range(len(set y)):
        if set y[i] == num class:
            mean += set x[i]
            num of values += 1
    if num of values>0:
        mean = np.array(mean / num_of_values)
        prob_w_class = num_of_values/len(set_y)
        return mean, prob w class
    else:
        print('No values assigned in this class')
        return None
def create_cov(y, X, mean, num_class=9):
    Estimate covariance of a multivariate
    Gaussian distribution
    num dimensions = len(X[0])
    cov = np.zeros((num_dimensions, num dimensions))
    num of values = 0
    for i in range(len(y)):
        if y[i] == num class:
            cov += np.outer((X[i] - mean), (X[i] - mean))
            num of values += 1
    if num of values>0:
        cov = cov / num of values
        return cov
    else:
        print('No values assigned in this class')
        return None
def estimate_values(X, probs_w, means, covariances):
    Calculate the probability of a new point x via
    the estimated pdf p(x/wj)
    prob y = []
    pdf of classes = []
    for i in range(len(means)):
```

```
my pdf = multivariate normal(mean=means[i],
cov=covariances[i])
        pdf of classes.append(my pdf)
    for i in range(len(X)):
        max = 0
        best class = 0
        for j in range(len(pdf of classes)):
            if pdf of classes[j] is None:
                prob x = 0
            else:
                prob_x = pdf_of_classes[j].pdf(X[i]) * probs_w[j]
            if prob x \ge max:
                max = prob x
                best class = j + 1
        prob y.append(best class)
    return prob y
def calc min euclidean(X, means):
    prob y = []
    for i in range(len(X)):
        min = -1
        best class = 0
        for j in range(len(means)):
            eucl_dist = np.sqrt(np.sum((X[i] - means[j]) ** 2))
            if min == -1:
                min = eucl_dist
            if eucl dist < min:</pre>
                min = eucl dist
                best class = j+1
        prob y.append(best class)
    return prob y
def train and evaluate(model name, X, y, Xtest, k fold=10,
num classes=9):
    kf = KFold(n splits=k fold, shuffle=True, random state=42)
    accuracy_scores = []
    for train index, test index in kf.split(X):
        X_train, X_test = X[train_index], X[test_index]
        y_train, y_test = y[train_index], y[test_index]
        class\ means = []
        class covariances = []
        class_probs_w = []
        for class_number in range(1, num_classes+1):
            mean, prob_w = create_mean(y_train, X_train, class_number)
```

```
cov = create_cov(y_train, X_train, mean, class_number)
            class probs w.append(prob w)
            class means.append(mean)
            class covariances.append(cov)
        if model name == "Bayes Classifier":
            predictions = estimate values(X test, class probs w,
class means, class covariances)
            accuracy = accuracy score(y test, predictions)
            accuracy scores.append(accuracy)
        else:
            predictions = calc min euclidean(X test, class means)
            accuracy = accuracy_score(y_test, predictions)
            accuracy_scores.append(accuracy)
    avg accuracy = np.mean(accuracy scores)
    std = np.std(accuracy scores)
    print(f"Mean Validation Error of {model name} model is: {(1-
avg accuracy) *100: .3f %")
    print(f"Standard Deviation error of Bayes classifier model is:
{std: .3f}")
    print("")
    # Train it in the whole training set
    class means all = []
    class covariances all = []
    class probs w all = []
    for class number in range(1, num classes + 1):
        mean, prob_w = create_mean(y, X, class_number)
        cov = create_cov(y, X, mean, class_number)
        class probs w all.append(prob w)
        class means all.append(mean)
        class_covariances_all.append(cov)
    if model name == "Bayes Classifier":
        y pred all = estimate values(Xtest, class probs w all,
class means all, class covariances all)
    else:
        y pred all = calc min euclidean(Xtest, class means all)
    return y pred all
# Train Bayes Classifier model
bayes preds = train and evaluate('Bayes Classifier', X train, y train,
X test)
# Compute the confusion matrix and success rate for Bayesian
Classifier
bayes accuracy = calc confusion matrix('Bayes Classifier', y test,
bayes preds)
Mean Validation Error of Bayes Classifier model is: 12.034%
Standard Deviation error of Bayes classifier model is: 0.010
```

```
The confusion matrix for Bayes Classifier model is: [[155
                                                                               0
    2
        10
            48
                  01
    0
      328
              0
                  3
                       0
                           22
                                0
                                          01
         1 430
                  0
   10
                       0
                            0
                                0
                                    95
                                          01
              0 154
                       0
                            2
                                0
                                     0
    0
         0
                                          01
                  0 168
                            0
                                0
                                     0
    0
         0
              0
                                          0]
    0
         1
              0
                  1
                       0 762
                                0
                                          01
                            2 291
                                     4
   14
         0
            10
                  0
                       0
   19
            73
                            2
                                0 367
         0
                  0
                       0
                                          01
              0
                  1
                       2
                            0
                                     0 18111
                                0
The success rate of Bayes Classifier model is: 88.432%
```

Comments on Bayesian Classifier Confusion Matrix

As we can spot from the confusion matrix we have very few classes that are NOT well separated by the classifier. More specifically, class 1 (Water), class 3 (Asphalt) and class 8 (Meadows) have some misclassified values. The rest classes are very efficiently separated. Overall, as we can see from the success rate we have a very efficient classification from Bayesian Classifier.

ii) Minimum Euclidean distance Classifier case

```
# Train minimun Euclidean distance Classifier model
euclidean preds = train and evaluate('minimun Euclidean distance
classifier', X_train, y_train, X_test)
# Compute the confusion matrix and success rate for minimun Euclidean
distance Classifier
euclidean accuracy = calc confusion matrix('minimun Euclidean distance
classifier', y_test, euclidean preds)
Mean Validation Error of minimun Euclidean distance classifier model
is:
     49.103%
Standard Deviation error of Bayes classifier model is: 0.022
The confusion matrix for minimun Euclidean distance classifier model
is: [[
            0
                 0
                              0
                     0
                         0
                                  0
                                      0
                                               01
 [152]
        0
            0
                46
                     0
                         0
                              0
                                 61
                                      2
                                           01
                                      3
    1
        0 188
                 0
                     5
                         0 156
                                  0
                                           01
            2 198
                         0
                                 39 230
   66
        0
                     0
                              1
                                           0]
    0
        0
            0
                 0 154
                         0
                              0
                                  0
                                           21
        0
            0
                 0
                     0 128
                              0
                                  0
                                     40
    0
                                           01
  11
        0 317
                 0
                    12
                        16 240
                                  0 168
                                           01
                              0 237
   61
        0
                23
                         0
            0
                     0
                                           01
    2
        0
             1 145
                     0
                         0
                              1
                                  7 305
                                           01
                 0
                         0
                              0
                                  0
                                      0 18711
The success rate of minimun Euclidean distance classifier model is:
51.045%
```

Comments on Minimum Euclidean distance Confusion Matrix

As we can spot from the confusion matrix we have many classes that are NOT well separated by the classifier. More specifically, for classes 1(Water), 2 (Trees), 3 (Asphalt) and class 6(Tiles) 75% of the values are misclassified. Also, for classes 5 (Tiles), 7(Shadows) and 8 (Meadows) we have many misclassified values. The rest classes are relatively well separated. Overall, as we can see from the success rate we do not have a very efficient classification from Minimum Euclidean distance Classifier.

iv) k-Nearest Neighbor Classifier case

```
# Train k-Nearest Neighbor model
knn model = KNeighborsClassifier()
knn preds = model classify(knn model, 'k-nearest neighbor', 10,
X train, y train, X test)
# Compute the confusion matrix and success rate for k-nearest neighbor
knn accuracy = calc confusion matrix('k-nearest neighbor', y test,
knn_preds)
Mean Validation Error of k-nearest neighbor model is:
Standard Deviation error of k-nearest neighbor model is: 0.014
The confusion matrix for k-nearest neighbor model is: [[195]
                                                                0 15
        0 24
              27
                    0]
    0 322
            0
                0
                       31
                    0
                            0
                                 0
                                     01
  10
        1 448
                0
                    0
                        4
                            1
                                72
                                     0]
            0 155
        0
                    0
                        1
                            0
    0
                                     01
        0
            1 0 166
                            0
                        0
                                     01
       56
            2
                    1 704
                            0
    0
                0
                                 1
                                     01
                        0 303
 [ 12
           5
                0
                    0
                                 1
        0
                                     0]
        2
   9
           85
                0
                    0
                        0
                            2 363
                                     01
                0
                                 0 18711
                    0
                        0
                             0
The success rate of k-nearest neighbor model is: 88.650%
```

Comments on k-nearest neighbor Confusion Matrix

As we can spot from the confusion matrix we have very few classes that are NOT well separated by the classifier. More specifically, class 1 (Water), class 3 (Asphalt), class 6 (Tiles) and class 8 (Meadows) have some misclassified values. The rest classes are very efficiently separated. Overall, as we can see from the success rate we have a very efficient classification from knearest neighbor Classifier.

Part 3 - Comment on the combination of the results of parts I & II

As we can see from the results both the unmixing and classification methods we can spot a correlation between them. If we take our best classifiers (k-nn and Bayes classifier) with our best

unmixing methods (LS with non-negative constraint and LS with non-negative & sum-to-one constraints) regarding the abundance map we can observe that many of the non-zero class pixels contain a high percentage of a pure pixel. If we check the confusion matrix we can observe that many non-zero class pixels will be assigned to the correct class, thus these pixels contain a high rate of a pure pixel. We can can verify the above clarification by checking the abundance maps of our best unmixing methods, in which we see that the result of these abundance maps are very close to the real ones.

On the other hand, for classifiers whose accuracy were not very efficient and for unmixing methods in which the abundance maps where not very clear, we can observe that there is no strong correlation that verifies any good estimation or clarification.