

Linear Binary Classification

MATH-412 - Statistical Machine Learning

Outline

- 1 Classification, plug-in predictors and hardness
- 2 Plug-in classification *via* OLS regression
- 3 Logistic regression
- 4 Perceptron
- 5 Stochastic gradient descent
- 6 Fisher discriminant analysis

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Classification and plug-in predictors

Input space \mathcal{X} , output space $\mathcal{Y} = \{-1, 1\}$, decision space $\mathcal{A} = \{-1, 1\}$
and 0-1 loss $\ell(a, y) = 1_{\{a \neq y\}} = 1_{\{ay \leq 0\}}$

- Empirical risk for 0-1 loss and $\gamma : \mathcal{X} \rightarrow \{-1, 1\}$

$$\hat{\mathcal{R}}_n^{0-1}(\gamma) = \frac{1}{n} \sum_{i=1}^n 1_{\{\gamma(x_i) \neq y_i\}}$$

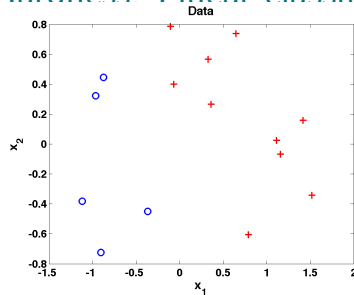
→ Extend the definition of the 0-1 loss to real valued predictors by $\ell(a, y) = 1_{\{ay \leq 0\}}$

- Empirical risk for 0-1 loss and $f : \mathcal{X} \rightarrow \mathbb{R}$

$$\hat{\mathcal{R}}_n^{0-1}(f) = \frac{1}{n} \sum_{i=1}^n 1_{\{y_i f(x_i) \leq 0\}}$$

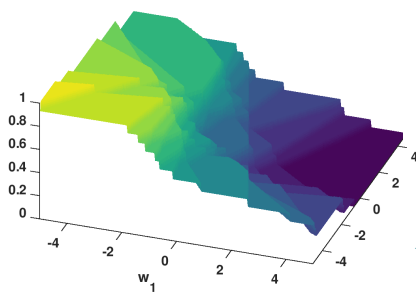
- Then use the *plug-in predictor* $\gamma(x_i) = \text{sign}(f(x_i))$.

Hardness: Linear classification toy-example

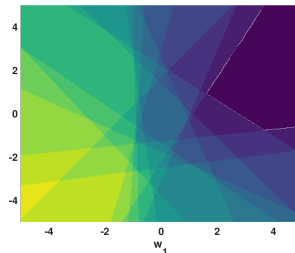


Plot of $\hat{\mathcal{R}}_{0-1}$ as a function of $\mathbf{w} = (w_1, w_2)$ for $b = 1$:

Empirical 0-1 risk



Empirical 0-1 risk



$$\hat{\mathcal{R}}_{0-1} = \frac{1}{n} \sum_{i=1}^n 1_{\{y_i(\mathbf{w}^\top \mathbf{x}_i + b) \leq 0\}}$$

• ER is non-convex and discontinuous

→ NP-hard to optimize...

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Classification *via* OLS regression

For regression, but assuming $Y \in \{-1, 1\}$

- the risk is

$$\mathbb{E}[(f(X) - Y)^2] = \mathbb{E}[(1 - Yf(X))^2]$$

- the target function is $f^*(X) = \mathbb{E}[Y|X] = 2\mathbb{P}(Y = 1|X) - 1$
- the excess risk is $\mathbb{E}[(f(X) - f^*(X))^2]$

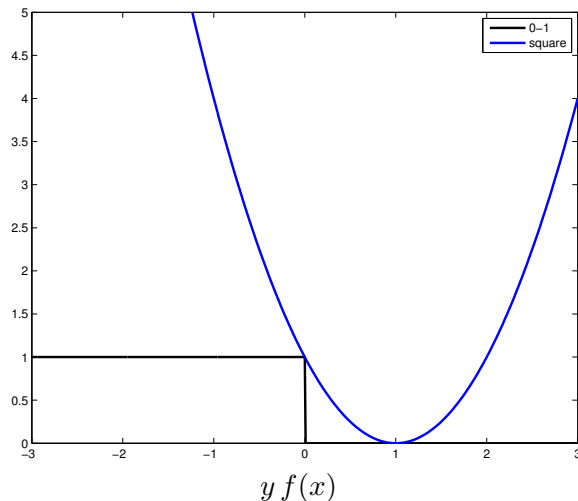
For classification

- the target function is $\arg \max_{y \in \{-1, 1\}} \mathbb{P}(Y = y|x = x) = \text{sign}(f^*(x))$

Plug-in principle

- Learn $\hat{f}(x)$ using OLS regression
- Use the plug-in predictor for classification $\hat{y} := \hat{\gamma}(x) = \text{sign}(\hat{f}(x))$

Zero one loss vs square loss



0-1 loss

$$\ell(f(x), y) = 1_{\{y f(x) \leq 0\}}$$

Square loss

$$\ell(f(x), y) = (1 - y f(x))^2$$

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Logistic regression

Logistic regression (Berkson, 1944)

Classification setting:

$$\mathcal{X} = \mathbb{R}^p, \mathcal{Y} \in \{0, 1\}.$$

Key assumption:

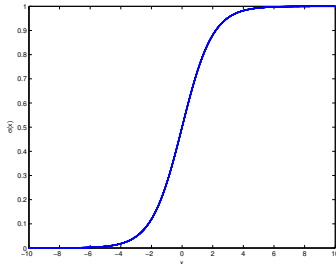
$$\log \frac{\mathbb{P}(Y = 1 \mid X = \mathbf{x})}{\mathbb{P}(Y = 0 \mid X = \mathbf{x})} = \mathbf{w}^\top \mathbf{x}$$

Implies that

$$\mathbb{P}(Y = 1 \mid X = \mathbf{x}) = \sigma(\mathbf{w}^\top \mathbf{x})$$

$$\text{for } \sigma : z \mapsto \frac{1}{1 + e^{-z}},$$

the **logistic function**.



- The logistic function is part of the family of *sigmoid functions*.
- Often called “the” sigmoid function.

Properties:

$$\begin{aligned} \forall z \in \mathbb{R}, \quad \sigma(-z) &= 1 - \sigma(z), \\ \forall z \in \mathbb{R}, \quad \sigma'(z) &= \sigma(z)(1 - \sigma(z)) \\ &= \sigma(z)\sigma(-z). \end{aligned}$$

Likelihood for logistic regression

Let $\eta := \sigma(\mathbf{w}^\top \mathbf{x} + b)$. W.l.o.g. we assume $b = 0$.

By assumption: $Y|X = \mathbf{x} \sim \text{Ber}(\eta)$.

Likelihood

$$p(Y = y|X = \mathbf{x}) = \eta^y(1 - \eta)^{1-y} = \sigma(\mathbf{w}^\top \mathbf{x})^y \sigma(-\mathbf{w}^\top \mathbf{x})^{1-y}$$

because $1 - \sigma(z) = \sigma(-z)$.

Log-likelihood

$$\begin{aligned}\ell(\mathbf{w}) &= y \log \sigma(\mathbf{w}^\top \mathbf{x}) + (1 - y) \log \sigma(-\mathbf{w}^\top \mathbf{x}) \\ &= y \log \eta + (1 - y) \log(1 - \eta) \\ &= y \log \frac{\eta}{1 - \eta} + \log(1 - \eta) \\ &= y\mathbf{w}^\top \mathbf{x} + \log \sigma(-\mathbf{w}^\top \mathbf{x})\end{aligned}$$

Maximizing the log-likelihood

Log-likelihood of a sample

Given an i.i.d. training set $\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$

$$\ell(\mathbf{w}) = \sum_{i=1}^n y_i \mathbf{w}^\top \mathbf{x}_i + \log \sigma(-\mathbf{w}^\top \mathbf{x}_i).$$

The log-likelihood is differentiable and concave.

\Rightarrow Its global maxima are its stationary points.

Gradient of ℓ

$$\begin{aligned} \nabla \ell(\mathbf{w}) &= \sum_{i=1}^n y_i \mathbf{x}_i - \mathbf{x}_i \frac{\sigma(-\mathbf{w}^\top \mathbf{x}_i) \sigma(\mathbf{w}^\top \mathbf{x}_i)}{\sigma(-\mathbf{w}^\top \mathbf{x}_i)} \quad \text{since } \sigma'(z) = \sigma(-z) \sigma(z) \\ &= \sum_{i=1}^n (y_i - \eta_i) \mathbf{x}_i \quad \text{with} \quad \eta_i = \sigma(\mathbf{w}^\top \mathbf{x}_i). \end{aligned}$$

Thus, $\nabla \ell(\mathbf{w}) = 0 \Leftrightarrow \sum_{i=1}^n \mathbf{x}_i (y_i - \sigma(\mathbf{w}^\top \mathbf{x}_i)) = 0$.

No closed form solution !

Alternate formulation of logistic regression

If $y \in \{-1, 1\}$, then

$$\mathbb{P}(Y = y | X = \mathbf{x}) = \sigma(y \mathbf{w}^\top \mathbf{x})$$

Log-likelihood

$$\ell(\mathbf{w}) = \log \sigma(y \mathbf{w}^\top \mathbf{x}) = -\log(1 + \exp(-y \mathbf{w}^\top \mathbf{x}))$$

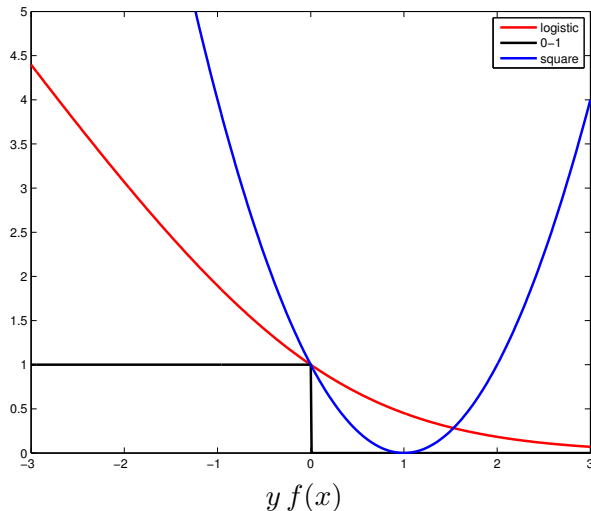
Log-likelihood for a training set

$$\ell(\mathbf{w}) = -\sum_{i=1}^n \log(1 + \exp(-y_i \mathbf{w}^\top \mathbf{x}_i))$$

The negative log-likelihood takes the form of an empirical risk with loss

$$\ell(a, y) = \log(1 + e^{-y a})$$

Comparing losses



0-1 loss

$$\ell(f(x), y) = 1_{\{y f(x) \leq 0\}}$$

Square loss

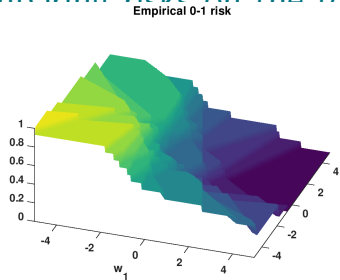
$$\ell(f(x), y) = (1 - y f(x))^2$$

Logistic loss

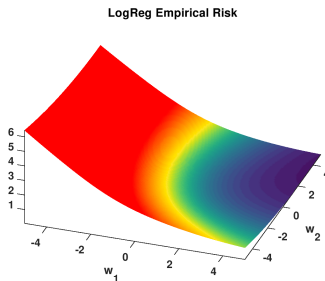
$$\frac{\ell(f(x), y)}{\log 2} = \frac{\log(1 + e^{-y f(x)})}{\log 2}$$

Comparing risks on the toy example

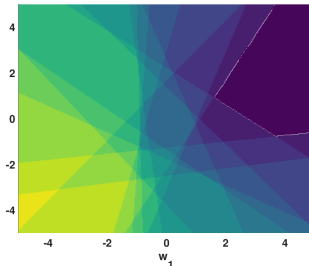
0-1 Risk



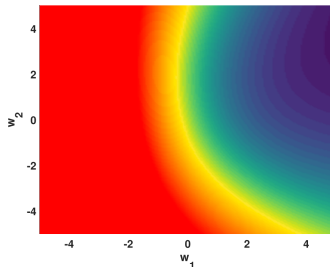
Logistic Risk



Empirical 0-1 risk



LogReg Empirical Risk



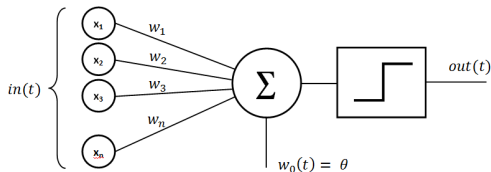
Risks for the 0-1 and logistic loss of the predictor $\hat{f}(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b$ as a function of $\mathbf{w} = (w_1, w_2)$ for fixed $b = 1$.

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Perceptron (Rosenblatt, 1957)

Setting of classification with $\mathcal{X} = \mathbb{R}^p$, $\mathcal{Y} = \{-1, 1\}$.



$$\hat{\gamma}(\mathbf{x}) = \text{sign}(\hat{f}(\mathbf{x})) \quad \text{with} \quad \hat{f}(\mathbf{x}) = \mathbf{w}^\top \mathbf{x}$$

Perceptron loss:

- If \mathbf{x}_i is well classified pay 0
- If \mathbf{x}_i is miss-classified pay the distance to the classification boundary

Perceptron loss function

Corresponds to using the loss function:

$$\ell(a, y) = \max(-ay, 0)$$



Perceptron algorithm: separable case

Stochastic gradient descent with fixed step-size

repeat

for $i = 1 \dots n$ **do**

if $y_i \mathbf{w}^\top \mathbf{x}_i < 0$ **then**

$\mathbf{w} \leftarrow \mathbf{w} + \gamma y_i \mathbf{x}_i$

end if

end for

until all training points well classified

- If the data are separable the algorithm converges in a finite number of steps to a hyperplane that separates them
- The solution found depends on the initialization
- In practice take $\gamma = 1$
- But if the data are not separable the algorithm **does not converge**

Perceptron algorithm: non separable-case

Stochastic gradient descent with decreasing step size

repeat

$t \rightarrow t + 1$

Pick a training pair (x_i, y_i) at random

if $y_i \mathbf{w}^\top \mathbf{x}_i < 0$ **then**

$\mathbf{w} \leftarrow \mathbf{w} + \gamma_t y_i \mathbf{x}_i$

end if

until \mathbf{w} stabilizes

with

$$\sum_t \gamma_t^2 < \infty \quad \sum_t \gamma_t = \infty.$$

- Always converges
- But slow

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Stochastic gradient descent (SGD) algorithm

Let

- \mathcal{D} be a closed set
- $f : \mathcal{D} \subset \mathbb{R}^p \rightarrow \mathbb{R}$ be a differentiable function,
- G a stochastic process defining for all $\theta \in \mathcal{D}$ a r.v. such that $\mathbb{E}[G(\theta)] = \nabla f(\theta)$

e.g., $f(\theta) := \mathcal{R}(h_\theta) = \mathbb{E}[\ell(h_\theta(X), Y)]$ and $G(\theta) = \nabla_\theta(\ell(h_\theta(X), Y))$.

Algorithm 1 Projected stochastic gradient descent

- 1: Initialize θ_0
 - 2: **for** $k = 1$ to $n - 1$ **do**
 - 3: $\theta_k = \Pi_{\mathcal{D}}(\theta_{k-1} - \gamma_k G_k(\theta_{k-1}))$ where $\Pi_{\mathcal{D}}$ is the Euclidean projection on \mathcal{D}
 - 4: **end for**
 - 5: **return** $\bar{\theta}_n := \frac{1}{n} \sum_{k=0}^{n-1} \theta_k$ (Polyak-Ruppert averaging)
-

Convergence of the algorithm

- The algorithm is shown to be convergent for $\gamma_k = Ck^{-\alpha}$ with $0 < \alpha < 1$.
- The idea of computing a Cesàro mean $\bar{\theta}_n$ was proposed independently by Polyak et Ruppert in the 80ies and is thus called *Polyak-Ruppert averaging*. They showed it was more efficient to allow θ_k to take larger steps and to stabilize the sequence with averaging.

Theorem (SGD convergence rate)

For $f : \mathcal{D} \subset \mathbb{R}^p \rightarrow \mathbb{R}$ convex differentiable, B -Lipschitz with \mathcal{D} a closed convex set such that $\mathcal{D} \subset \{\theta \mid \|\theta\|_2 \leq D\}$, if G is such that $\|G(\theta)\|_2^2 \leq B$ a.s., then for $\gamma_k = \frac{D}{B} \frac{1}{\sqrt{k}}$,

$$\forall \theta_* \in \mathcal{D}, \quad \mathbb{E}[f(\bar{\theta}_n)] - f(\theta_*) \leq \frac{3BD}{\sqrt{n}}.$$

- If f is strongly convex, and with $\gamma_k = \frac{c}{k}$ for c sufficiently large $\mathbb{E}[f(\theta_n)] - f(\theta_*) = O(\frac{1}{n})$

Applying SGD to learn in supervised learning

Let $H = \{h_\theta \mid \theta \in \Theta\}$ be a hypothesis/predictor set.

Risk minimization

$$f(\theta) := \mathcal{R}(h_\theta) = \mathbb{E}[\ell(h_\theta(X_i), Y_i)].$$

and $G_i(\theta) = \nabla_\theta \ell(h_\theta(X_i), Y_i)$ is a stochastic gradient.

Note that many loss functions are Lipschitz w.r.t. θ (e.g. logistic, perceptron)

Empirical risk minimization

$$f(\theta) := \hat{\mathcal{R}}_n(h_\theta) = \frac{1}{n} \sum_{i=1}^n \ell(h_\theta(X_i), Y_i).$$

and $G_i(\theta) = \nabla_\theta \ell(h_\theta(X_i), Y_i)$ is a stochastic gradient.

What is the difference?

SGD on the risk vs on the empirical risk

- From the risk, we can only draw n independent stochastic gradients, since we only have a training set of size n .
- From the empirical risk, we can draw as many as we want since the distribution is exactly

$$P_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$$

So

- The first pass through the data starts to optimize the risk
- Subsequent passes over the data then optimize the empirical risk (and possibly gradually overfit)
- The best generalization is usually obtained for more than one pass...
- SGD and its fancier cousins Adagrad and Adam are the method of choice if you have a very large dataset.

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Fisher discriminant analysis

Generative classification

$X \in \mathbb{R}^p$ and $Y \in \{0, 1\}$. Instead of modeling directly $p(y \mid \mathbf{x})$ model $p(y)$ and $p(\mathbf{x} \mid y)$ and deduce $p(y \mid \mathbf{x})$ using Bayes rule.

In classification $\mathbb{P}(Y = 1 \mid X = \mathbf{x}) =$

$$\frac{\mathbb{P}(X = \mathbf{x} \mid Y = 1) \mathbb{P}(Y = 1)}{\mathbb{P}(X = \mathbf{x} \mid Y = 1) \mathbb{P}(Y = 1) + \mathbb{P}(X = \mathbf{x} \mid Y = 0) \mathbb{P}(Y = 0)}$$

For example one can assume

- $\mathbb{P}(Y = 1) = \pi$
- $\mathbb{P}(X = \mathbf{x} \mid Y = 1) \sim \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1)$
- $\mathbb{P}(X = \mathbf{x} \mid Y = 0) \sim \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0).$

Fisher's discriminant aka Linear Discriminant Analysis (LDA)

Previous model with the constraint $\Sigma_1 = \Sigma_0 = \Sigma$. Given a training set, the different model parameters can be estimated using the maximum likelihood principle, which leads to

$$(\hat{\pi}, \hat{\mu}_1, \hat{\mu}_0, \hat{\Sigma}_1, \hat{\Sigma}_0).$$

Then we have

$$\begin{aligned}\mathbb{P}(Y = 1 \mid X = \mathbf{x}) &= \left(1 + \frac{p(\mathbf{x} \mid Y = 0) \mathbb{P}(Y = 0)}{p(\mathbf{x} \mid Y = 1) \mathbb{P}(Y = 1)} \right)^{-1} \\ &= \left(1 + \frac{1 - \pi}{\pi} \frac{\exp\left(-\frac{1}{2}(\mathbf{x} - \mu_0)^\top \Sigma^{-1}(\mathbf{x} - \mu_0)\right)}{\exp\left(-\frac{1}{2}(\mathbf{x} - \mu_1)^\top \Sigma^{-1}(\mathbf{x} - \mu_1)\right)} \right)^{-1} \\ &= \left(1 + \exp\left((\mu_1 - \mu_0)^\top \Sigma^{-1} \mathbf{x} + b\right) \right)^{-1} \\ &= \sigma(\mathbf{w}^\top \mathbf{x} + b)\end{aligned}$$

with $\mathbf{w} = \Sigma^{-1}(\mu_1 - \mu_0)$ and $b = \log \frac{1-\pi}{\pi} + \frac{1}{2}\mu_0^\top \Sigma^{-1} \mu_0 - \frac{1}{2}\mu_1^\top \Sigma^{-1} \mu_1$.