

# Splines

MATH-412 - Statistical Machine Learning

# Polynomial regression is linear w.r.t. parameters

In 1 dimension :

$$f(x) = w_0 + w_1x + w_2x^2 + \dots + w_dx^d$$

In  $p$  dimensions :

$$f(\mathbf{x}) = \beta_0 + \sum_{j=1}^p \beta_j x_j + \sum_{i \leq j} \beta_{ij} x_i x_j + \sum_{i \leq j \leq k} \beta_{ijk} x_i x_j x_k \dots$$

But... global polynomial bases are not always adapted, because

- Changes affect the function globally
- Higher variability of high degree terms

# B-splines : a nice basis for piecewise polynomial functions

## B-splines recursion

$\xi_1 < \dots < \xi_K$  : “inner” knots

Let  $\begin{array}{c|c|c|c|c|c|c|c|c} \tau_0 & \dots & \tau_d & \tau_{d+1} & \dots & \tau_{K+d} & \tau_{K+d+1} & \dots & \tau_{K+2d+1} \\ \hline \xi_0 & \dots & \xi_0 & \xi_1 & \dots & \xi_K & \xi_{K+1} & \dots & \xi_{K+1} \end{array}$

The  $j^{\text{th}}$  spline of degree  $d$ ,  $B_{j,d}$  : is defined by

$$B_{j,0}(x) = 1_{\{\tau_j \leq x \leq \tau_{j+1}\}}$$

$$B_{j,d+1} = \omega_{j,d} B_{j,d} + (1 - \omega_{j+1,d}) B_{j+1,d}$$

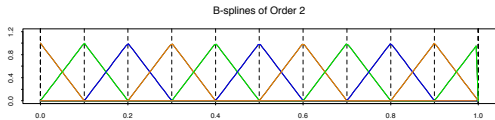
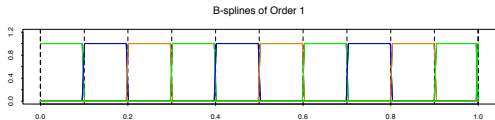
with  $\omega_{j,d}(x) = \frac{x - \tau_j}{\tau_{j+d+1} - \tau_j}$  if  $\tau_j < \tau_{j+d+1}$  and 0 else.

## Cardinal B-splines

If all knots are equidistant (and also outside of the interval) then  $B_{1,d} = B_{1,d-1} * B_{1,0}$

and  $B_{j+1,d}(x) = B_{1,d}(x - jh)$ ,  $j \in \mathbb{Z}$ .

where  $h$  is the inter-knot distance.



Splines of order  $d + 1$  are piecewise polynomial of degree  $d$ .

# Splines with an increasing number of continuous derivatives

We start with  $x \in \mathbb{R}$ , and consider predictors of the form

$$f(x) = \sum_{j=0}^{K+d} w_j B_{j,d}(x)$$

with the  $B_{j,d}$  forming a basis of functions, and  $K$  the number of “inner knots”.

Splines of different orders :

- degree  $d = 0$  (order 1)= piecewise constant functions
- degree  $d = 1$  (order 2)= piecewise linear functions that are  $\mathcal{C}^0$
- degree  $d = 2$  (order 3)= piecewise quadratic functions that are  $\mathcal{C}^1$
- degree  $d = 3$  (order 4)= piecewise cubic functions that are  $\mathcal{C}^2$

## Natural cubic splines

It is often desirable to impose that the part of the predictor extrapolating outside of the data range is **linear**.

The set of cubic spline functions, with  $K$  “inner” knots, that are linear outside of the range of the data form a subspace of dimension  $K$  : the **natural cubic splines**.

For  $K$  “inner” knots, one possible basis for the subspace takes the form :

$$\nu_1(x) = 1, \quad \nu_2(x) = x, \quad \nu_{k+2}(x) = d_k(x) - d_{K-1}(x),$$

with

$$d_k(x) = \frac{(x - \xi_k)_+^3 - (x - \xi_K)_+^3}{\xi_K - \xi_k}, \quad 1 \leq k \leq K - 2.$$

In practice, it is equivalent to use B-splines and impose that the function is linear outside of the interval of interest, via constraints on the coefficients.

## In practice : solving a regression problem with splines

Say with natural cubic splines.

$$f(x) = \sum_{j=1}^K w_j \nu_j(x)$$

Given a training set  $\{(x_1, y_1), \dots, (x_n, y_n)\}$

- Build a corresponding design matrix

$$\mathbf{N} = \begin{bmatrix} \nu_1(x_1) & \dots & \nu_K(x_1) \\ \nu_1(x_2) & \dots & \nu_K(x_2) \\ \vdots & \vdots & \vdots \\ \nu_1(x_n) & \dots & \nu_K(x_n) \end{bmatrix}$$

- Solve the linear regression problem

$$\min_{\mathbf{w}} \sum_{i=1}^n (y_i - \boldsymbol{\nu}(x_i)^\top \mathbf{w})^2$$

## In practice : solving a regression problem with splines

The previous equation can be written vectorially

$$\min_{\mathbf{w}} \|\mathbf{y} - \mathbf{N}\mathbf{w}\|_2^2$$

It leads to the *normal equations*

$$\boxed{\mathbf{N}^\top \mathbf{N} \mathbf{w} - \mathbf{N}^\top \mathbf{y} = 0}$$

so that provided  $\mathbf{N}^\top \mathbf{N}$  is invertible, we have

$$\hat{\mathbf{w}} = (\mathbf{N}^\top \mathbf{N})^{-1} \mathbf{N}^\top \mathbf{y}$$

## Smoothing splines

**Theorem :** The solution of the optimization problem

$$\min_f \sum_{i=1}^n (y_i - f(x_i))^2 + \lambda \int (f''(t))^2 dt$$

is a *natural cubic spline* function with knots at *all* the  $x_i$ s. It is thus of the form

$$f(x) = \sum_{j=1}^K \hat{w}_j \nu_j(x) \quad \text{with} \quad K = n,$$

with  $\hat{w}$  the solution of

$$\min_{\mathbf{w}} \|\mathbf{y} - \mathbf{N}\mathbf{w}\|_2^2 + \lambda \mathbf{w}^\top \mathbf{\Omega} \mathbf{w}, \quad \text{with} \quad \Omega_{jk} = \int \nu_j''(t) \nu_k''(t) dt,$$

namely

$$\hat{\mathbf{w}} = (\mathbf{N}^\top \mathbf{N} + \lambda \mathbf{\Omega})^{-1} \mathbf{N}^\top \mathbf{y}.$$



# Working with splines

Need to choose

- The degree  $d$ 
  - Most of the time :  $d = 0, 1$  or  $3$  (constant, linear or cubic splines).
- The number of “inner” knots  $K$ 
  - Most of the time :  $K$  is chosen by cross-validation
  - Possible to choose  $K = n$  with regularization  $\Rightarrow$  *smoothing splines*
- The position of the knots
  - Most of the time : quantiles (=percentiles) of the data
  - or on a regular grid
- Whether to use *regression splines* vs *smoothing splines*

## Computation efficiency of splines

- Since B-splines have small support, if  $\mathbf{B}$  is the  $B$ -spline design matrix,  $\mathbf{B}^\top \mathbf{B}$  is a **banded** matrix, with inversion linear in  $K$ .
- For smoothing splines, it is possible to solve the problem using the  $B$ -spline basis and  $\hat{\mathbf{y}} = \mathbf{N}\hat{\mathbf{w}} = \mathbf{N}(\mathbf{N}^\top \mathbf{N} + \lambda \mathbf{\Omega})^{-1} \mathbf{N}^\top \mathbf{y}$  can thus be computed in  $O(n)$  time.

## Multivariate splines

**Idea :** Use *tensor product basis* :

For a function of  $(x_1, x_2)$  and given two spline bases :

$$(h_j(x_1))_j \quad \text{and} \quad (\tilde{h}_k(x_2))_k$$

use basis elements of the form

$$g_{jk}(x_1, x_2) = h_j(x_1)\tilde{h}_k(x_2).$$

Then find functions of the form :

$$f(x_1, x_2) = \sum_{j,k} w_{jk} g_{jk}(x_1, x_2).$$

## Extensions

- The theorem characterizing the form of the solution of

$$\min_f \hat{\mathcal{R}}_{n,2}(f) + \lambda \int f''(\mathbf{x})^2 d\mathbf{x},$$

for  $\hat{\mathcal{R}}_{n,2}$  the empirical quadratic risk, can be extended to multiple dimensions with *thin-plate splines*, which are different than the tensor product splines.

- Possible to use splines as feature vectors for the input data for other problems than least square regression : the splines provide a particular form of *feature map*.