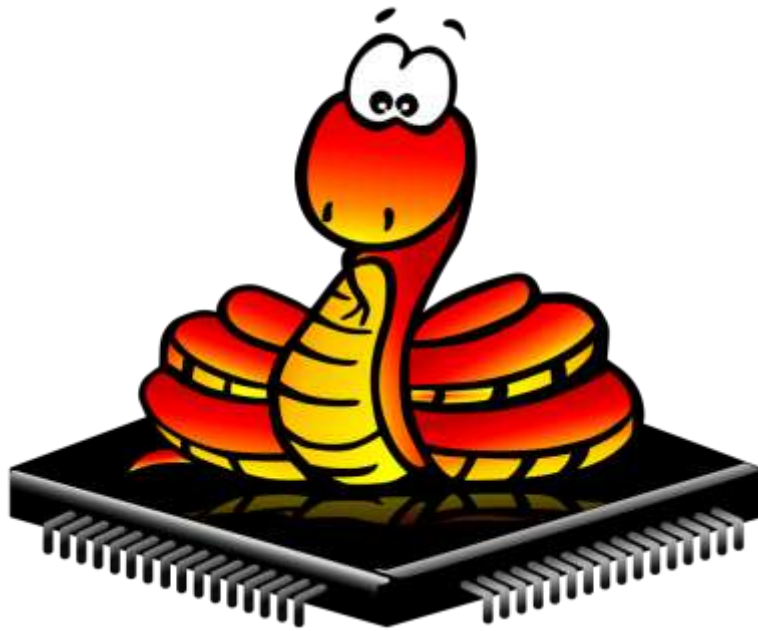


EasyPython.py



Library Creator

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```
from EasyPython import *  
from EasyPython2 import *
```

```
while True:
```

```
    #blynk(pin,time_on,time_off)  
    #digitalWrite(pin,Logic)  
    #digitalRead(pin)  
    #delay(ms)  
    #analogRead()  
    #analogWrite(pin,value)  
    #looping(m,n)  
    #lcd(message)  
    #clear()  
    #map(x,min1,max1,min2,max2)  
    #constrain(x,mi,mx)  
    #increasing(c)  
    #decreasing(c)  
    #Serial_write(x)|
```

```
class RTC():
```

```
    from machine import RTC
```

```
    rtc = RTC()
```

```
    rtc.datetime((2017, 8, 23, 1, 12, 48, 0, 0)) # set a specific date and time
```

```
try:
```

```
    def add(a,b):
```

```
        return a+b
```

```
    def sub(a,b):
```

```
        return a-b
```

```
def blynk(pin,time_on,time_off):
```

```
    from machine import Pin
```

```
    import time
```

```
    p0 = Pin(pin,Pin.OUT)
```

```
    p0.on()
```

```
    time.sleep(time_on)
```

```
    p0.off()
```

```
    time.sleep(time_off)
```

```
def digitalWrite(pin,Logic):
```

```
    from machine import Pin
```

```
    p0 = Pin(pin,Pin.OUT)
```

```
p0.value(Logic)
```

```
def digitalRead(pin):
```

```
    from machine import Pin
```

```
    p0 = Pin(pin,Pin.IN)
```

```
    return p0.value()
```

```
def delay(ms):
```

```
    import time
```

```
    time.sleep(ms/1000)
```

```
def analogRead():
```

```
    from machine import ADC
```

```
    adc = ADC(0) # create ADC object on ADC pin
```

```
    v = adc.read() # read value, 0-1024
```

```
    return v
```

```
# unc
```

```
def analogWrite(pin,value):
```

```
    from machine import Pin, PWM
```

```
    value = int(map(value,0,255,0,1023))
```

```
    pwm2 = PWM(Pin(pin), freq=500, duty=value)
```

```
#unc
```

```
#test
```

```
def looping(a,b,c,d,e,m,n,time):
```

```
    from machine import Pin
```

```
    import time
```

```

for i in range(m,n):
    listt = [a,b,c,d,e] #pin number
    cc = listt[i]
    Pin(cc,Pin.OUT).on()
    time.sleep(int(time/1000))
    Pin(cc,Pin.OUT).off()

```

```

def lcd(message):

```

```

    import machine
    from machine import Pin,I2C
    from lcd_api import LcdApi
    from i2c_lcd import I2cLcd
    from time import sleep
    I2C_ADDR = 0x27
    totalRows = 2
    totalColumns = 16
    i2c = I2C(scl=Pin(5), sda=Pin(4), freq=10000)    #initializing the I2C method for
    lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalColumns)
    lcd.putstr(f"{message}")

```

ESP8266

```

def clear():

```

```

    import machine
    from machine import Pin,I2C
    from lcd_api import LcdApi
    from i2c_lcd import I2cLcd
    from time import sleep
    I2C_ADDR = 0x27
    totalRows = 2

```

```
totalColumns = 16
i2c = I2C(scl=Pin(5), sda=Pin(4), freq=10000)    #initializing the I2C method for
ESP8266
```

```
lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalColumns)
lcd.clear()
```

```
def map(x,min1,max1,min2,max2):
```

```
    x = constrain(x,min1,max1)
```

```
    try:
```

```
        c = (x/max1)*max2
```

```
        return c
```

```
    except:
```

```
        c = 0
```

```
def constrain(x,mi,mx):
```

```
    if x < mi :
```

```
        return mi
```

```
    elif x > mx:
```

```
        return mx
```

```
    else :
```

```
        return x
```

```
#formate
```

```
#c = f
```

```
#f = decreasing(c)
```

```
def increasing(c,step):
```

```
    c = c + step
```

```
    return c
```

```
def decreasing(c,step):
```

```
    c = c - step
```

```
    return c
```

```
def Serial_write(x):
```

```
    from machine import UART
```

```
    uart = UART(0, baudrate=115200)
```

```
    uart.write(f'{x}\n')
```

```
except:
```

```
    pass
```

Code 1

```
#from EasyPython2 import *
```

```
class lcdbegin():
```

```
    import machine
```

```
    from machine import Pin,I2C
```

```
    from lcd_api import LcdApi
```

```

from i2c_lcd import I2cLcd
I2C_ADDR = 0x27
totalRows = 2
totalColumns = 16
i2c = I2C(scl=Pin(5), sda=Pin(4), freq=10000)
lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalColumns)

```

Code2

#from EasyPython2 import *

```

class lcdbegin():
    import machine
    from machine import Pin,I2C
    from lcd_api import LcdApi
    from i2c_lcd import I2cLcd
    I2C_ADDR = 0x27
    totalRows = 2
    totalColumns = 16
    i2c = I2C(scl=Pin(5), sda=Pin(4), freq=10000)
    lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalColumns)

```

code3

"""Provides an API for talking to HD44780 compatible character LCDs."""

```
import time
```

```
class LcdApi:
```

"""Implements the API for talking with HD44780 compatible character LCDs.
This class only knows what commands to send to the LCD, and not how to get them to the LCD.

It is expected that a derived class will implement the hal_xxx functions.

""

The following constant names were lifted from the avrlib lcd.h
header file, however, I changed the definitions from bit numbers
to bit masks.

#

HD44780 LCD controller command set

LCD_CLR = 0x01 # DB0: clear display

LCD_HOME = 0x02 # DB1: return to home position

LCD_ENTRY_MODE = 0x04 # DB2: set entry mode

LCD_ENTRY_INC = 0x02 # --DB1: increment

LCD_ENTRY_SHIFT = 0x01 # --DB0: shift

LCD_ON_CTRL = 0x08 # DB3: turn lcd/cursor on

LCD_ON_DISPLAY = 0x04 # --DB2: turn display on

LCD_ON_CURSOR = 0x02 # --DB1: turn cursor on

LCD_ON_BLINK = 0x01 # --DB0: blinking cursor

LCD_MOVE = 0x10 # DB4: move cursor/display

LCD_MOVE_DISP = 0x08 # --DB3: move display (0-> move cursor)

LCD_MOVE_RIGHT = 0x04 # --DB2: move right (0-> left)

LCD_FUNCTION = 0x20 # DB5: function set

LCD_FUNCTION_8BIT = 0x10 # --DB4: set 8BIT mode (0->4BIT mode)

LCD_FUNCTION_2LINES = 0x08 # --DB3: two lines (0->one line)
LCD_FUNCTION_10DOTS = 0x04 # --DB2: 5x10 font (0->5x7 font)
LCD_FUNCTION_RESET = 0x30 # See "Initializing by Instruction" section

LCD_CGRAM = 0x40 # DB6: set CG RAM address
LCD_DDRAM = 0x80 # DB7: set DD RAM address

LCD_RS_CMD = 0
LCD_RS_DATA = 1

LCD_RW_WRITE = 0
LCD_RW_READ = 1

```
def __init__(self, num_lines, num_columns):  
    self.num_lines = num_lines  
    if self.num_lines > 4:  
        self.num_lines = 4  
    self.num_columns = num_columns  
    if self.num_columns > 40:  
        self.num_columns = 40  
    self.cursor_x = 0  
    self.cursor_y = 0  
    self.implied_newline = False  
    self.backlight = True  
    self.display_off()  
    self.backlight_on()  
    self.clear()  
    self.hal_write_command(self.LCD_ENTRY_MODE | self.LCD_ENTRY_INC)
```

```
self.hide_cursor()
```

```
self.display_on()
```

```
def clear(self):
```

```
    """Clears the LCD display and moves the cursor to the top left  
    corner.
```

```
    """
```

```
    self.hal_write_command(self.LCD_CLR)
```

```
    self.hal_write_command(self.LCD_HOME)
```

```
    self.cursor_x = 0
```

```
    self.cursor_y = 0
```

```
def show_cursor(self):
```

```
    """Causes the cursor to be made visible."""
```

```
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |  
                           self.LCD_ON_CURSOR)
```

```
def hide_cursor(self):
```

```
    """Causes the cursor to be hidden."""
```

```
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY)
```

```
def blink_cursor_on(self):
```

```
    """Turns on the cursor, and makes it blink."""
```

```
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |  
                           self.LCD_ON_CURSOR | self.LCD_ON_BLINK)
```

```
def blink_cursor_off(self):
```

```
    """Turns on the cursor, and makes it no blink (i.e. be solid)."""
```

```
self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |
                        self.LCD_ON_CURSOR)
```

```
def display_on(self):
```

```
    """Turns on (i.e. unblanks) the LCD."""
```

```
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY)
```

```
def display_off(self):
```

```
    """Turns off (i.e. blanks) the LCD."""
```

```
    self.hal_write_command(self.LCD_ON_CTRL)
```

```
def backlight_on(self):
```

```
    """Turns the backlight on.
```

This isn't really an LCD command, but some modules have backlight controls, so this allows the hal to pass through the command.

```
    """
```

```
    self.backlight = True
```

```
    self.hal_backlight_on()
```

```
def backlight_off(self):
```

```
    """Turns the backlight off.
```

This isn't really an LCD command, but some modules have backlight controls, so this allows the hal to pass through the command.

```
    """
```

```
    self.backlight = False
```

```
    self.hal_backlight_off()
```

```

def move_to(self, cursor_x, cursor_y):
    """Moves the cursor position to the indicated position. The cursor
    position is zero based (i.e. cursor_x == 0 indicates first column).
    """
    self.cursor_x = cursor_x
    self.cursor_y = cursor_y
    addr = cursor_x & 0x3f
    if cursor_y & 1:
        addr += 0x40 # Lines 1 & 3 add 0x40
    if cursor_y & 2: # Lines 2 & 3 add number of columns
        addr += self.num_columns
    self.hal_write_command(self.LCD_DDRAM | addr)

def putchar(self, char):
    """Writes the indicated character to the LCD at the current cursor
    position, and advances the cursor by one position.
    """
    if char == '\n':
        if self.implied_newline:
            # self.implied_newline means we advanced due to a wraparound,
            # so if we get a newline right after that we ignore it.
            pass
        else:
            self.cursor_x = self.num_columns
    else:
        self.hal_write_data(ord(char))
        self.cursor_x += 1

```

```
if self.cursor_x >= self.num_columns:
    self.cursor_x = 0
    self.cursor_y += 1
    self.implied_newline = (char != '\n')
if self.cursor_y >= self.num_lines:
    self.cursor_y = 0
self.move_to(self.cursor_x, self.cursor_y)
```

```
def putstr(self, string):
    """Write the indicated string to the LCD at the current cursor
    position and advances the cursor position appropriately.
    """
    for char in string:
        self.putchar(char)
```

```
def custom_char(self, location, charmap):
    """Write a character to one of the 8 CGRAM locations, available
    as chr(0) through chr(7).
    """
    location &= 0x7
    self.hal_write_command(self.LCD_CGRAM | (location << 3))
    self.hal_sleep_us(40)
    for i in range(8):
        self.hal_write_data(charmap[i])
        self.hal_sleep_us(40)
    self.move_to(self.cursor_x, self.cursor_y)
```

```
def hal_backlight_on(self):
```

"""Allows the hal layer to turn the backlight on.

If desired, a derived HAL class will implement this function.

"""

pass

def hal_backlight_off(self):

"""Allows the hal layer to turn the backlight off.

If desired, a derived HAL class will implement this function.

"""

pass

def hal_write_command(self, cmd):

"""Write a command to the LCD.

It is expected that a derived HAL class will implement this function.

"""

raise NotImplementedError

def hal_write_data(self, data):

"""Write data to the LCD.

It is expected that a derived HAL class will implement this function.

"""

raise NotImplementedError

```
def hal_sleep_us(self, usecs):  
    """Sleep for some time (given in microseconds)."""  
    time.sleep_us(usecs)
```

Code4

```
try:
```

```
    a = "
```

```
    b = "
```

```
def begin(a,b):
```

```
    import ntptime
```

```
    import network
```

```
    #import time
```

```
    from machine import RTC #
```

```
    import time #sleep
```

```
    timeout =0
```

```
    wifi = network.WLAN(network.STA_IF)
```

```
    # Restarting WiFi
```

```
    wifi.active(False)
```

```
    time.sleep(0.5)
```

```
    wifi.active(True)
```

```
    wifi.connect(a,b)
```

```
    if not wifi.isconnected():
```

```
        print('connecting..')
```

```
        while (not wifi.isconnected() and timeout < 5):
```



```
print(5 - timeout)
timeout = timeout + 1
time.sleep(1)
```

```
if(wifi.isconnected()):
    print('Connected')
else:
    print('Time Out')
```

```
 #(2000, 1, 1, 0, 40, 8, 5, 1)
```

```
def operate(utf):
    utf = int(utf)
    from machine import RTC #
    import time #sleep
    import ntptime
    import network
    from machine import RTC
    rtc = RTC()
    ntptime.settime()
    UTC_OFFSET = +utf * 60 * 60 #>>for bd +6
    actual_time = time.localtime(time.time() + UTC_OFFSET)
    c = actual_time
    return c
```

except:

pass

Code 5