



Workshop 7

COMP90051 Statistical Machine Learning
Semester 1, 2023

Learning Outcomes

By the end of this workshop you should be able to:

1. Be able to define and fit models in **PyTorch**
2. Be able to explain the architecture of a basic **convolutional neural network**
3. Be able to implement **autoencoder**

Convolutional neural nets

- Convolutional layers
 - * Complex input representations based on convolution operation
 - * Filter weights are learned from training data
- Downsampling, usually via Max Pooling
 - * Re-scales to smaller resolution, limits parameter explosion
- Fully connected parts and output layer
 - * Merges representations together

Convolutional in 2D

- Use kernel to perform element-wise multiplication and sum for every local patch

Stride:1



| | | | |
|----|---|----|----|
| 2 | 3 | 5 | 0 |
| 1 | 5 | 7 | -9 |
| -5 | 2 | 1 | 1 |
| 2 | 0 | -2 | 4 |

Input

| | |
|---|----|
| 1 | 0 |
| 0 | -1 |

Kernel



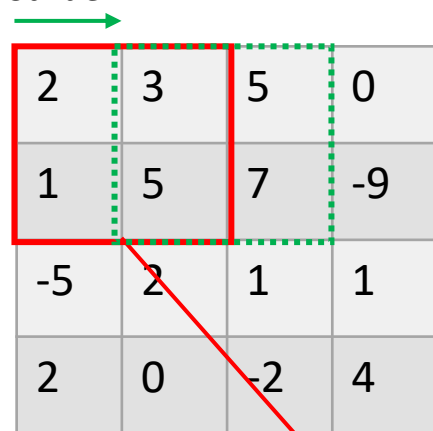
| | | |
|--|--|--|
| | | |
| | | |
| | | |

Output

Convolutional in 2D

- Use kernel to perform element-wise multiplication and sum for every local patch

Stride:1



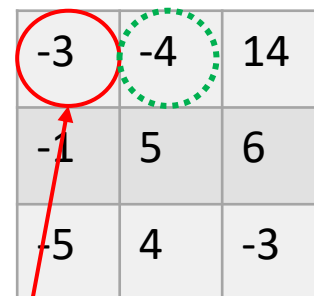
| | | | |
|----|---|----|----|
| 2 | 3 | 5 | 0 |
| 1 | 5 | 7 | -9 |
| -5 | 2 | 1 | 1 |
| 2 | 0 | -2 | 4 |

Input



| | |
|---|----|
| 1 | 0 |
| 0 | -1 |

Kernel



| | | |
|----|----|----|
| -3 | -4 | 14 |
| -1 | 5 | 6 |
| -5 | 4 | -3 |

Output

$$2 \times 1 + 3 \times 0 + 1 \times 0 + 5 \times (-1) = -3$$

Max Pooling in 2D

- Use kernel to perform element-wise multiplication and sum for every local patch

Stride:1



| | | | |
|----|---|----|----|
| 2 | 3 | 5 | 0 |
| 1 | 5 | 7 | -9 |
| -5 | 2 | 1 | 1 |
| 2 | 0 | -2 | 4 |

Input

no trainable parameters

| | |
|--|--|
| | |
| | |

Kernel

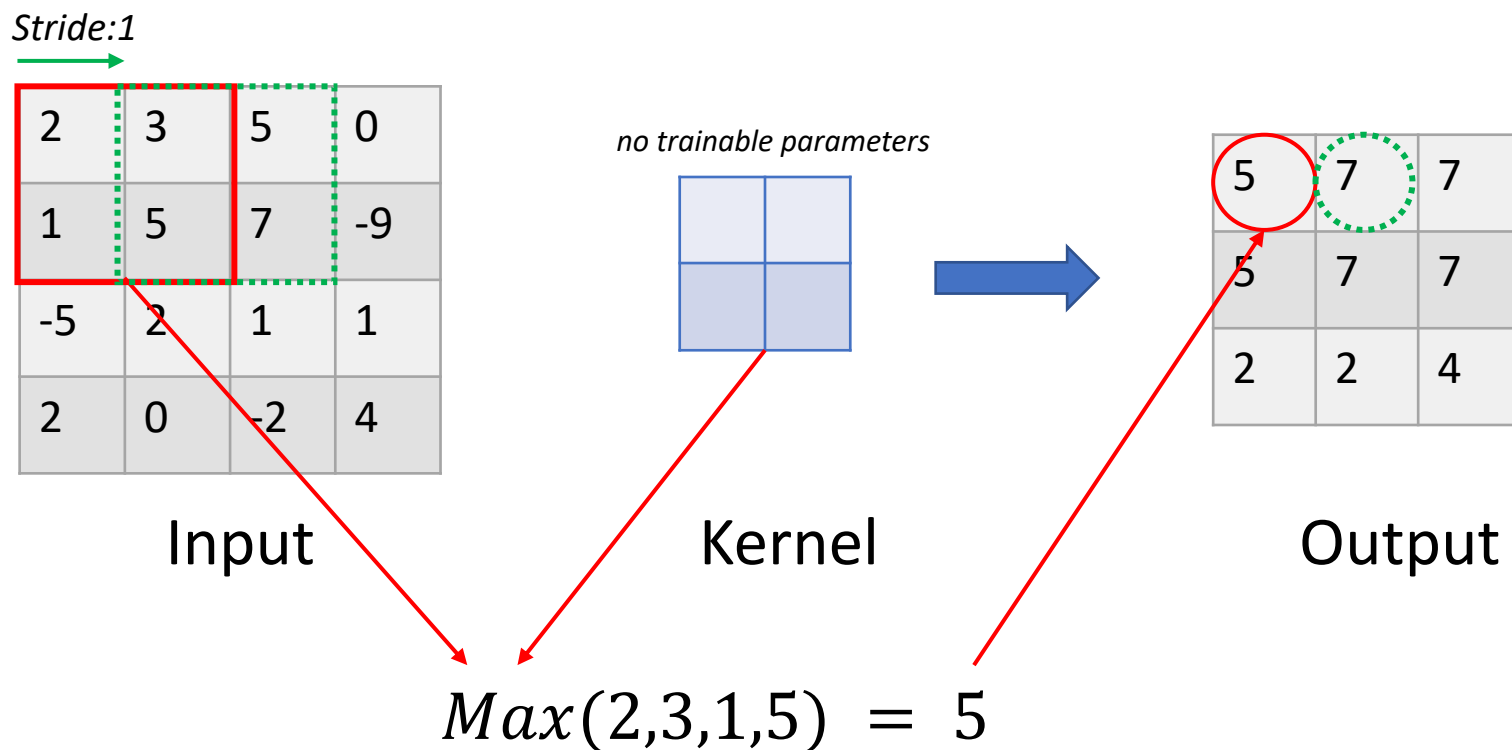


| | | |
|--|--|--|
| | | |
| | | |
| | | |

Output

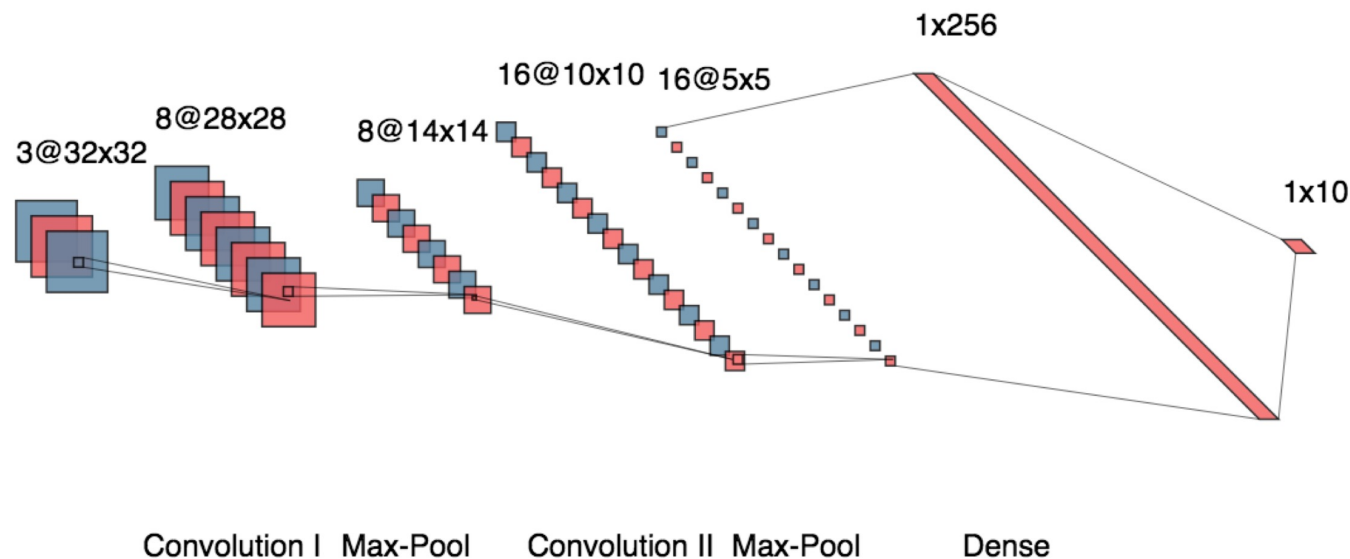
Max Pooling in 2D

- Use kernel to perform element-wise multiplication and sum for every local patch



Convolutional neural nets

- **Local connectivity** pattern between adjacent layers
- **Shared weights**—filters are replicated across the spatial dimensions of the input
- **Pooling** reduces the spatial extent deeper into the network



We'll implement this architecture for CIFAR-10

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