

Formulae List1) Laplace / Inverse

$$1) L[f(t)] = \int_0^{\infty} e^{-st} f(t) dt$$

$$2) L[e^{-at}] = \frac{1}{s-a} \Rightarrow L^{-1}\left[\frac{1}{s-a}\right] = e^{-at}$$

$$3) L[\sin at] = \frac{a}{s^2+a^2} \Rightarrow L^{-1}\left[\frac{1}{s^2+a^2}\right] = \frac{\sin at}{a}$$

$$4) L[\cos at] = \frac{s}{s^2+a^2} \Rightarrow L^{-1}\left[\frac{s}{s^2+a^2}\right] = \cos at$$

$$5) L[\sinh at] = \frac{a}{s^2-a^2} \Rightarrow L^{-1}\left[\frac{1}{s^2-a^2}\right] = \frac{\sinh at}{a}$$

$$6) L[\cosh at] = \frac{s}{s^2-a^2} \Rightarrow L^{-1}\left[\frac{s}{s^2-a^2}\right] = \cosh at$$

$$7) L[t^n] = \frac{n!}{s^{n+1}} \Rightarrow L^{-1}\left[\frac{1}{s^{n+1}}\right] = \frac{t^n}{n!}$$

8) Linearity Property

$$L[af(t) + bg(t)] = aL[f(t)] + bL[g(t)]$$

$$L^{-1}[a\phi_1(s) + b\phi_2(s)] = aL^{-1}[\phi_1(s)] + bL^{-1}[\phi_2(s)]$$

9) Change of Scale

$$L[f(at)] = \frac{1}{a} \phi(s/a)$$

10) First Shifting

$$L[e^{at} f(t)] = \phi(s-a) \Rightarrow L^{-1}[\phi(s-a)] = e^{at} f(t)$$

$$L[e^{-at} f(t)] = \phi(s+a) \Rightarrow L^{-1}[\phi(s+a)] = e^{-at} f(t)$$

4)

11) Second shifting

$$g(t) = \begin{cases} f(t-a) & \text{for } t > a \\ 0 & \text{for } t < a \end{cases}$$

$$L[g(t)] = e^{-as} \phi(s)$$

$$L^{-1}[e^{-as} \phi(s)] = g(t) = \begin{cases} f(t-a) & t > a \\ 0 & t < a \end{cases}$$

12) Multiplication by t

$$L[t^n f(t)] = (-1)^n \frac{d^n}{ds^n} \phi(s)$$

$$L^{-1}[\phi^n(s)] = (-1)^n t^n L^{-1}[\phi(s)]$$

13) Division by t

$$L\left[\frac{f(t)}{t}\right] = \int_s^{\infty} \phi(s) ds$$

14) Derivative Property

$$L[f^n(t)] = s^n \phi(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots$$

15) Laplace of Integration Property

$$L\left[\int_0^t f(u) du\right] = \frac{\phi(s)}{s}$$

Note: $\text{erf} \sqrt{x} = \frac{2}{\sqrt{\pi}} \int_0^{\sqrt{x}} e^{-u^2} du$

16) Convolution theorem

$$L^{-1}[\phi_1(s) \times \phi_2(s)] = \int_0^t f_1(u) f_2(t-u) du$$

17) Periodic function

$$L[f(t)] = \frac{1}{1 - e^{-as}} \int_0^a e^{-st} f(t) dt$$

18) Heaviside's unit step function

$$i) L[H(t-a)] = \frac{e^{-as}}{s} \Rightarrow L^{-1}\left[\frac{e^{-as}}{s}\right] = H(t-a)$$

$$ii) L[f(t-a)H(t-a)] = e^{-as} L[f(t)]$$

$$iii) L[f(t)H(t-a)] = e^{-as} L[f(t+a)]$$

$$iv) \text{ If } f(t) = \begin{cases} f_1(t) & 0 \leq t < a \\ f_2(t) & a < t \leq b \\ f_3(t) & t > b \end{cases}$$

$$f(t) = f_1(t)[H(t) - H(t-a)] + f_2(t)[H(t-a) - H(t-b)] + f_3(t)[H(t-b)]$$

19) Dirac Delta function

$$i) L[\delta(t-a)] = e^{-as}$$

$$ii) L^{-1}[1] = \delta(t)$$

$$iii) L^{-1}[f(t)\delta(t-a)] = e^{-as} f(a)$$

2] Fourier

$$i) f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left(\frac{a_n \cos n\pi x}{L} + \frac{b_n \sin n\pi x}{L} \right)$$

$$\text{where, } a_0 = \frac{1}{L} \int_a^{a+2L} f(x) dx, \quad a_n = \frac{1}{L} \int_a^{a+2L} f(x) \cos n\pi x dx$$

$$b_n = \frac{1}{L} \int_a^{a+2L} f(x) \sin n\pi x dx$$

2) For $(-L, L)$ & $(-\pi, \pi)$

$$\text{Odd} \Rightarrow b_n = 0$$

$$\text{Even} \Rightarrow a_n = a_0 = 0$$

$$2 \int_{-L}^L \text{ or } \int_{-\pi}^{\pi} = 2 \int_0^{\pi \text{ or } L} \text{ for even}$$

$$= 0 \text{ for odd}$$

3) Parseval's

$$\frac{1}{L} \int_0^{a+2L} f^2(x) dx = \frac{a_0^2}{2} + \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

4) HRS of cosine

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos n\pi x$$

$$a_0 = \frac{2}{L} \int_0^L f(x) dx$$

$$a_n = \frac{2}{L} \int_0^L f(x) \cos n\pi x dx$$

$$\frac{2}{L} \int_0^L f^2(x) dx = \sum_{n=1}^{\infty} (a_n^2) + \frac{a_0^2}{2}$$

5) HRFS of sine

$$f(x) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L}$$

$$b_n = \frac{2}{L} \int_0^L b_n \sin \frac{n\pi x}{L} dx$$

$$\frac{2}{L} \int_0^L f^2(x) dx = \sum_{n=1}^{\infty} b_n^2$$

6) Complex form

$$f(x) = \sum_{n=-\infty}^{\infty} c_n e^{-\frac{in\pi x}{L}}$$

$$c_n = \frac{1}{2L} \int_a^{a+2L} f(x) e^{-\frac{in\pi x}{L}} dx$$

$$c_0 = \frac{a_0}{2}$$

$$c_n = \frac{1}{2} (a_n - ib_n)$$

$$c_{-n} = \frac{1}{2} [a_n + ib_n]$$

7) Fourier Integral

$$i) f(x) = \frac{1}{\pi} \int_{w=0}^{\infty} \int_{s=-\infty}^{\infty} f(s) \cos w(s-x) dw ds$$

ii) Cosine

$$f(x) = \frac{2}{\pi} \int_{w=0}^{\infty} \cos wx \left[\int_{s=0}^{\infty} f(s) \cos ws ds \right] dw \rightarrow \text{dis even}$$

iii) Sine

$$f(\omega) = \frac{2}{\pi} \int_{\omega=0}^{\infty} \sin \omega x \left[\int_{s=0}^{\infty} f(s) \sin \omega s ds \right] d\omega$$

f is odd

8) Fourier Transform

i) $F[f(t)] = \int_{-\infty}^{\infty} f(t) e^{ist} dt$

$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(s) e^{-ist} ds$

2) $F_s[f(t)] = \int_0^{\infty} f(t) \sin st dt$

$f(t) = \frac{2}{\pi} \int_0^{\infty} F_s[f(t)] \sin st ds$

3) $F_c[f(t)] = \int_0^{\infty} f(t) \cos st dt$

$f(t) = \frac{2}{\pi} \int_0^{\infty} F_c[f(t)] \cos st ds$

i) $F[f(x) \cos ax] = \frac{1}{2} [F(s+a) + F(s-a)]$

ii) $F_s[f(x) \cos ax] = \frac{1}{2} [F_s(s+a) + F_s(s-a)]$

iii) $F_c[f(x) \sin ax] = \frac{1}{2} [F_c(s+a) - F_c(s-a)]$

iv) $F_s[f(x) \sin ax] = \frac{1}{2} [F_c(s-a) - F_c(s+a)]$

v) $F_c[f(x) \cos ax] = \frac{1}{2} [F_s(s+a) + F_s(s-a)]$

3) Vector Algebra

$$1) (\bar{a} \times \bar{b}) \cdot \bar{c} = [\bar{a} \ \bar{b} \ \bar{c}]$$

$$2) \bar{a} \times (\bar{b} \times \bar{c}) = (\bar{a} \cdot \bar{c}) \bar{b} - (\bar{a} \cdot \bar{b}) \bar{c}$$

$$3) (\bar{a} \times \bar{b}) \cdot (\bar{c} \times \bar{d}) = \begin{vmatrix} \bar{a} \cdot \bar{c} & \bar{b} \cdot \bar{c} \\ \bar{a} \cdot \bar{d} & \bar{b} \cdot \bar{d} \end{vmatrix}$$

$$4) (\bar{a} \times \bar{b}) \times (\bar{c} \times \bar{d}) = [\bar{a} \ \bar{b} \ \bar{d}] \bar{c} - [\bar{a} \ \bar{b} \ \bar{c}] \bar{d}$$

4) Differentiation

4) Vector Differentiation

$$1) \nabla f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

$$2) \nabla \cdot \bar{F} = \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z}$$

$$3) \nabla \times \bar{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix}$$

4) Directional Derivative

$$D_{\hat{u}} f(a) = \nabla f(a) \cdot \hat{u} \\ = |\nabla f(a)| \cos \theta$$

$$i) \theta = 0 \Rightarrow \max$$

$$ii) \theta = 180 \Rightarrow \min$$

5) Total Differentiation

$$d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz$$

$$6) \nabla f(r) = f'(r) \frac{\bar{r}}{r}$$

$$7) \nabla \cdot (\phi \vec{J}) = \phi (\nabla \cdot \vec{J}) + \vec{J} \cdot (\nabla \phi)$$

5) Vector [Integration]

i) Theorem

i) $\int \vec{F} \cdot d\vec{r}$ is independent of path joining the end point of curve 'c' but only depends only on the end point of curve 'c'

ii) \vec{F} is conservative that is there exist ϕ such that $\vec{F} = \nabla \phi$

iii) For any closed curve 'c' $\oint \vec{F} \cdot d\vec{r} = 0$

2) $\nabla \times \vec{F} = \vec{0} \Rightarrow$ irrotational (iff conservative)

3) Green's Theorem

$$\int_C P dx + Q dy = \iint_R \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$$

4) Stoke's Theorem

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \hat{n} \cdot (\nabla \times \vec{F}) ds$$

Unit outward Normal

$$ds = dx dy \quad \text{Projection}$$

$$|\hat{n} \cdot \hat{k}| \rightarrow xy \text{ plane}$$

$$dx = dy dz \quad \text{Projection}$$

$$|\hat{n} \cdot \hat{j}| \rightarrow yz \text{ plane}$$

$$ds = dx dz \quad \text{Projection}$$

$$|\hat{n} \cdot \hat{i}| \rightarrow xz \text{ plane}$$

5) Gauss Thm Divergence Thm

$$\oint_S \hat{n} \cdot \vec{F} ds = \iiint_V \nabla \cdot \vec{F} dv$$

6) Z-transform

$$1) Z[f(k)] = \sum_{k=-\infty}^{\infty} f(k) z^{-k}$$

2) Change of scale

$$Z[a^k f(k)] = F\left(\frac{z}{a}\right)$$

$$Z[a^{-k} f(k)] = F(az)$$

3) Shifting Prop

$$Z[f(k \pm n)] = z^{\pm n} F(z)$$

4) Linearity

$$Z[af(k) + bg(k)] = a Z[f(k)] + b Z[g(k)]$$

5) Multiplication by k

$$Z[k^n f(k)] = \left(-z \frac{d}{dz}\right)^n F(z)$$

6) Convolution

$$h(k) = g(k) * f(k)$$

$$h(k) = \sum_{n=-\infty}^{\infty} f(n) g(k-n) = \sum_{n=-\infty}^{\infty} g(n) f(k-n)$$

Then

$$Z[h(k)] = Z[g(k)] \cdot Z[f(k)]$$

7) Inverse Z-Transform

1) $z^{-1}\{F(z)\} = f(k)$

2) Methods

2) Direct Division method

$$F(z) = \frac{P(z)}{Q(z)}$$

3) Binomial Expansion method

4) Partial Fraction method