(%i1) load("cliffordan")\$

package name: clifford.mac author: Dimiter Prodanov

version: v24

Recommended location: share/contrib

last update: 20 Feb 2019 warning: redefining @ package name: cliffordan.mac author: Dimiter Prodanov

version: v18

Recommended location: share/contrib

last update: 04 Feb 2018

Euclidean 3D space

(%i2) clifford(e,3);

(r)
$$e_1 x + e_2 y + e_3 z$$

Green function

(%i4) G:r/sqrt(-cnorm(r))
$$^3/(4*\%$$
pi);

(G)
$$\frac{\frac{1}{4} \left(e_1 x + e_2 y + e_3 z \right)}{\pi \left(x^2 + y^2 + z^2 \right)^{3/2}}$$

(%i5)
$$mvectdiff(G,r)=0;$$

$$(\%05) 0=0$$

Potential

(P)
$$-\frac{\frac{1}{4}}{\pi \sqrt{x^2+y^2+z^2}}$$

(%i7) mvectdiff(P,r)=G;

$$(\%07) \frac{e_1 x + e_2 y + e_3 z}{\sqrt{x^2 + y^2 + z^2} \left(4 \pi x^2 + 4 \pi y^2 + 4 \pi z^2\right)} = \frac{\frac{1}{4} \left(e_1 x + e_2 y + e_3 z\right)}{\pi \left(x^2 + y^2 + z^2\right)^{3/2}}$$

Homogeneous Poisson equation

(%i8) dependsv(
$$F,[x,y,z]$$
)\$

(%i9)
$$mvectdiff(F,r,2)=0$$
;

(%09)
$$\frac{d^2}{dx^2} F + \frac{d^2}{dx^2} F + \frac{d^2}{dx^2} F = 0$$

potential.wxmx 2 / 2

P solves the equation

(%i10) mvectdiff(P,r,2)=0;

(%010) 0=0

Define cyclindrical coordinates

(%i11) declare([rho, phi], scalar)\$

(%i12) cyl_eq:[x=rho*cos(phi), y=rho*sin(phi)];

(cyl_eq) $[x = \cos(\varphi) \rho, y = \sin(\varphi) \rho]$

(%i13) r_c:coordsubst(r, cyl_eq);

(r_c) $(e_1 \cos(\varphi) + e_2 \sin(\varphi)) \rho + e_3 z$

Green function in cylindrical coordinates

(%i14) GG_c:coordsubst(G, cyl_eq),factor;

$$(GG_c)\frac{\frac{1}{4}\left(e_{1}\cos\left(\varphi\right)\rho+e_{2}\sin\left(\varphi\right)\rho+e_{3}z\right)}{\pi\left(\rho^{2}+z^{2}\right)^{3/2}}$$

(%i15) mvectdiff(GG c,r c)=0;

(%015) 0=0

(%i16) dependsv(F,[x,y,z,rho, phi])\$

Homogeneous Poisson equation

(%i17) $mvectdiff(F,r_c,2)=0$;

$$\frac{\frac{d^2}{d\varphi^2}F + \left(\frac{d}{d\rho}F\right)\rho + \left(\frac{d^2}{d\rho^2}F + \frac{d^2}{dz^2}F\right)\rho^2}{\rho^2} = 0$$

(%i18) V:coordsubst(P,cyl_eq);

$$(V) \qquad -\frac{\frac{\cdot}{4}}{\pi\sqrt{\rho^2+z^2}}$$

(%i19) mvectdiff(V,r_c)=GG_c;

$$(\%019) \frac{e_1 \cos(\varphi) \rho + e_2 \sin(\varphi) \rho + e_3 z}{\sqrt{\rho^2 + z^2} \left(4 \pi \rho^2 + 4 \pi z^2\right)} = \frac{\frac{1}{4} \left(e_1 \cos(\varphi) \rho + e_2 \sin(\varphi) \rho + e_3 z\right)}{\pi \left(\rho^2 + z^2\right)^{3/2}}$$

V solves the equation

(%i20) $mvectdiff(V,r_c,2)=0$;

(%020) 0=0

→