

## **Face Detection Python**

### **Files used in this project:**

1. Haarcascade\_frontalface\_default.xml
  - file is a pre-trained classifier file used with OpenCV, a popular computer vision library. This XML file contains data that defines the parameters of a Haar Cascade classifier specifically trained for detecting frontal faces
2. facedet.py
  - This python file contains the code for the implementation of the face detection

### **Module used:**

1. OpenCV
  - This module provides functions and classes for various computer vision tasks such as image and video processing, object detection, machine learning,

## **Explanation of the code:**

1. `import cv2 :`

- Imports the OpenCV library for image and video processing.

2. `cv2.CascadeClassifier('haarcascade_frontalface_default.xml):`

- Initializes a Cascade Classifier object using the Haar Cascade XML file. This file contains the trained data for detecting frontal faces.

3. **`cv2.VideoCapture(0):`**

- Creates a VideoCapture object (`cv2.VideoCapture`) to access the default camera (index 0). This allows capturing frames from the webcam.

4. **`b.read():`**

- Captures a frame (`d_img`) from the webcam using the VideoCapture object (`b`). Returns a tuple (`c_rec, d_img`), where `c_rec` is a boolean indicating success (True if frame was read successfully) and `d_img` is the captured frame.

5. **`cv2.cvtColor(d_img, cv2.COLOR_BGR2GRAY):`**

- Converts the captured frame (`d_img`) from BGR (Blue-Green-Red) color space to grayscale. Grayscale conversion is typically used for face detection as it reduces computational complexity.

6. **`a.detectMultiScale(e, 1.3, 6):`**

- Detects objects (faces in this case) in the grayscale image (`e`) using the Cascade Classifier (`a`). Returns a list of rectangles (`f`), where each rectangle represents the detected face's bounding box.

7. **`cv2.rectangle(d_img, (x1, y1), (x1+w1, y1+h1), (255, 0, 0), 5):`**

- Draws a rectangle on the original color frame (`d_img`) around each detected face.
  - `(x1, y1)` and `(x1+w1, y1+h1)` specify the opposite corners of the rectangle.

- (255, 0, 0) represents the color of the rectangle border in BGR format (blue, green, red).
- 5 is the thickness of the rectangle border in pixels.

**8. cv2.imshow('img', d\_img):**

- Displays the image (d\_img) in a window titled 'img' using cv2.imshow. This function is crucial for visualizing the detection results.

**9. cv2.waitKey(40):**

- Waits for a key press for up to 40 milliseconds (40). If a key is pressed during this time, it returns the ASCII value of the key. If no key is pressed, it returns -1.

**10. b.release():**

- Releases the VideoCapture object (b). This is important to free up resources associated with the webcam after the program finishes.

Output:



