

//This program pin is work for the product like [https://www.flyrobo.in/finger\\_print\\_sensor](https://www.flyrobo.in/finger_print_sensor)  
//here wire connection is as  
//fingerprint sensor white wire - pin 3, yellow wire - pin 2, red wire - "+5v" , black wire - "GND"

```
#include <Adafruit_Fingerprint.h>
#include <SoftwareSerial.h>
SoftwareSerial mySerial(2, 3);
```

```
Adafruit_Fingerprint finger = Adafruit_Fingerprint(&mySerial);
```

```
uint8_t id;
```

```
void setup()
{
  Serial.begin(9600);
  while (!Serial); // For Yun/Leo/Micro/Zero/...
  delay(100);
  Serial.println("\n\nFingerprint sensor enrollment");
```

```
// set the data rate for the sensor serial port
finger.begin(57600);
```

```
if (finger.verifyPassword()) {
  Serial.println("Found fingerprint sensor!");
} else {
  Serial.println("Did not find fingerprint sensor :(");
  while (1) { delay(1); }
}
}
```

```
uint8_t readnumber(void) {
  uint8_t num = 0;
```

```
  while (num == 0) {
    while (! Serial.available());
    num = Serial.parseInt();
  }
  return num;
}
```

```
void loop()          // run over and over again
{
```

```

Serial.println("Ready to enroll a fingerprint!");
Serial.println("Please type in the ID # (from 1 to 127) you want to save this finger as...");
id = readnumber();
if (id == 0) { // ID #0 not allowed, try again!
    return;
}
Serial.print("Enrolling ID #");
Serial.println(id);

while (! getFingerprintEnroll() );
}

```

```

uint8_t getFingerprintEnroll() {

    int p = -1;
    Serial.print("Waiting for valid finger to enroll as #"); Serial.println(id);
    while (p != FINGERPRINT_OK) {
        p = finger.getImage();
        switch (p) {
            case FINGERPRINT_OK:
                Serial.println("Image taken");
                break;
            case FINGERPRINT_NOFINGER:
                Serial.println(".");
                break;
            case FINGERPRINT_PACKETRECEIVEERR:
                Serial.println("Communication error");
                break;
            case FINGERPRINT_IMAGEFAIL:
                Serial.println("Imaging error");
                break;
            default:
                Serial.println("Unknown error");
                break;
        }
    }
}

```

// OK success!

```

p = finger.image2Tz(1);
switch (p) {
    case FINGERPRINT_OK:
        Serial.println("Image converted");
        break;

```

```

case FINGERPRINT_IMAGEMESS:
    Serial.println("Image too messy");
    return p;
case FINGERPRINT_PACKETRECEIVEERR:
    Serial.println("Communication error");
    return p;
case FINGERPRINT_FEATUREFAIL:
    Serial.println("Could not find fingerprint features");
    return p;
case FINGERPRINT_INVALIDIMAGE:
    Serial.println("Could not find fingerprint features");
    return p;
default:
    Serial.println("Unknown error");
    return p;
}

```

```

Serial.println("Remove finger");
delay(2000);
p = 0;
while (p != FINGERPRINT_NOFINGER) {
    p = finger.getImage();
}
Serial.print("ID "); Serial.println(id);
p = -1;
Serial.println("Place same finger again");
while (p != FINGERPRINT_OK) {
    p = finger.getImage();
    switch (p) {
    case FINGERPRINT_OK:
        Serial.println("Image taken");
        break;
    case FINGERPRINT_NOFINGER:
        Serial.print(".");
        break;
    case FINGERPRINT_PACKETRECEIVEERR:
        Serial.println("Communication error");
        break;
    case FINGERPRINT_IMAGEFAIL:
        Serial.println("Imaging error");
        break;
    default:
        Serial.println("Unknown error");
        break;
    }
}

```

```
}  
}
```

```
// OK success!
```

```
p = finger.image2Tz(2);  
switch (p) {  
  case FINGERPRINT_OK:  
    Serial.println("Image converted");  
    break;  
  case FINGERPRINT_IMAGEMESS:  
    Serial.println("Image too messy");  
    return p;  
  case FINGERPRINT_PACKETRECEIVEERR:  
    Serial.println("Communication error");  
    return p;  
  case FINGERPRINT_FEATUREFAIL:  
    Serial.println("Could not find fingerprint features");  
    return p;  
  case FINGERPRINT_INVALIDIMAGE:  
    Serial.println("Could not find fingerprint features");  
    return p;  
  default:  
    Serial.println("Unknown error");  
    return p;  
}
```

```
// OK converted!
```

```
Serial.print("Creating model for #"); Serial.println(id);
```

```
p = finger.createModel();  
if (p == FINGERPRINT_OK) {  
  Serial.println("Prints matched!");  
} else if (p == FINGERPRINT_PACKETRECEIVEERR) {  
  Serial.println("Communication error");  
  return p;  
} else if (p == FINGERPRINT_ENROLLMISMATCH) {  
  Serial.println("Fingerprints did not match");  
  return p;  
} else {  
  Serial.println("Unknown error");  
  return p;  
}
```

```
Serial.print("ID "); Serial.println(id);
p = finger.storeModel(id);
if (p == FINGERPRINT_OK) {
    Serial.println("Stored!");
} else if (p == FINGERPRINT_PACKETRECEIVEERR) {
    Serial.println("Communication error");
    return p;
} else if (p == FINGERPRINT_BADLOCATION) {
    Serial.println("Could not store in that location");
    return p;
} else if (p == FINGERPRINT_FLASHERR) {
    Serial.println("Error writing to flash");
    return p;
} else {
    Serial.println("Unknown error");
    return p;
}
}
```