

H - Bridge -

Define Motor - IN1 12

Define Motor - IN2 13

void motor - Forward (void);

// a Function that will be called at to start the rotation

click wire

void motor - stop (void);

// a Function that will be called to stop the rotation

void setup() {

Pin Mode(Motor - IN1, OUTPUT);

// Set the First Pin of the relay as output

Pin Mode(Motor - IN2, OUTPUT);

// Set the 2nd Pin of the relay as output

}

void Loop() {

motor - Forward(); // move Forward / clock wise

delay - stop();

delay(3000); // keep rotating CW For 3 seconds

Motor - stop(); // stop rotating -

delay(3000); // stand still For 3 seconds

Motor - reverse(); // revers the rotation direction / CCW

delay(3000); // keep rotating direction For 3 seconds

delay(3000); // stand still For 3 seconds.