SETUP:
Download link:
https://github.com/SakshayMahna/Robotics-Playground/tree/main/turtlebot3_ws

Unzip into home dir.

Open terminal
               roscore
Open another terminal
               sudo apt-get install ros-noetic-navigation
Open another terminal
               cd turtlebot3_ws/
               catkin_make
               source devel/setup.bash

TO RUN TURTLEBOT3:

Terminal 1
               roscore
Terminal 2
               cd turtlebot3_ws/
               catkin_make
               source devel/setup.bash
               roslaunch ros_world turtlebot3_world.launch

Terminal 3
               cd turtlebot3_ws/
               catkin_make
               source devel/setup.bash
               roslaunch global_path_planning turtlebot3_ros_world.launch

Terminal 4
               cd turtlebot3_ws/
               catkin_make
               source devel/setup.bash
               rosrun global_path_planning path_planning_server.py