

CS540: HW1 (P1)

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(a) The trace for the state of the priority queue is as follows:

Expanding	Frontier	Explored
	{ [b,b,r,o] }	{ }
[b,b,r,o]	{ 1:[b,b,o,r], 2:[b,o,r,b] }	{ }
[b,b,o,r]	{ 2:[b,o,r,b], 2:[b,o,b,r], 3:[o,b,b,r] }	{ [b,b,r,o] }
[b,o,r,b]	{ 2:[b,o,b,r], 3:[o,b,b,r], 3:[o,b,r,b], 3:[b,r,o,b] }	{ [b,b,r,o], [b,b,o,r] }
[b,o,b,r]	{ 3:[o,b,b,r], 3:[o,b,r,b], 3:[b,r,o,b], 4:[b,r,b,o] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b] }
[o,b,b,r]	{ 3:[o,b,r,b], 3:[b,r,o,b], 4:[b,r,b,o] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r] }
[o,b,r,b]	{ 3:[b,r,o,b], 4:[b,r,b,o], 5:[r,b,o,b] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r], [o,b,b,r] }
[b,r,o,b]	{ 4:[b,r,b,o], 5:[r,b,o,b], 5:[o,r,b,b] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r], [o,b,b,r], [o,b,r,b] }
[b,r,b,o]	{ 5:[r,b,o,b], 5:[o,r,b,b] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r], [o,b,b,r], [o,b,r,b], [b,r,o,b] }
[r,b,o,b]		

Hence, the first lowest-cost goal state is [r,b,o,b] with a cost of 5.

(b) The first part of the trace for the priority queue is the same as above, with the following additional steps:

Expanding	Frontier	Explored
[r,b,o,b]	{ 5:[o,r,b,b], 6:[r,o,b,b], 6:[r,b,b,o] }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r], [o,b,b,r], [o,b,r,b], [b,r,o,b], [b,r,b,o] }
[o,r,b,b]	{ 6:[r,o,b,b], 6:[r,b,b,o], }	{ [b,b,r,o], [b,b,o,r], [b,o,r,b], [b,o,b,r], [o,b,b,r], [o,b,r,b], [b,r,o,b], [b,r,b,o], [r,b,o,b] }

So, [r,b,o,b] and [o,r,b,b] are the two lowest-cost goal states (since the only remaining states on the queue have a cost > 5 , we know that no successors of theirs can have cost ≤ 5), each with a cost of 5, and their paths are as follows:

- i. [b,b,r,o] \rightarrow [b,o,r,b] (+2) \rightarrow [o,b,r,b] (+1) \rightarrow [r,b,o,b] (+2)
- ii. [b,b,r,o] \rightarrow [b,o,r,b] (+2) \rightarrow [b,r,o,b] (+1) \rightarrow [o,r,b,b] (+2)